

# EECS150 - Digital Design

## Lecture 23 - Arithmetic Blocks,

### Part 2 + Shifters

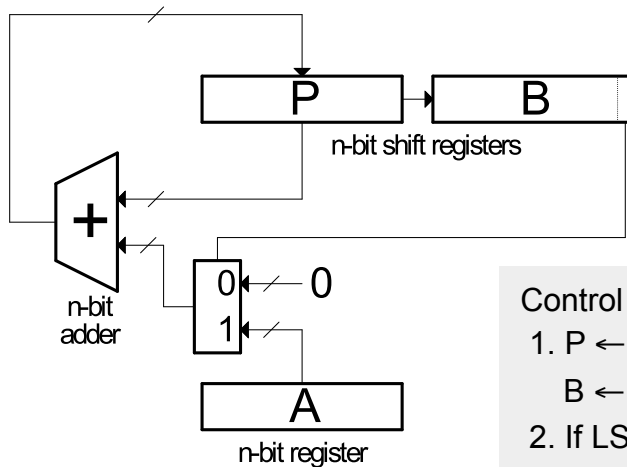
April 12, 2011  
John Wawrzynek

### Multiplication

$a_3$	$a_2$	$a_1$	$a_0$	← <i>Multiplicand</i>				
$b_3$	$b_2$	$b_1$	$b_0$	← <i>Multiplier</i>				
	$X$	$a_3b_0$	$a_2b_0$	$a_1b_0$	$a_0b_0$	}	<i>Partial products</i>	
	$a_3b_1$	$a_2b_1$	$a_1b_1$	$a_0b_1$				
	$a_3b_2$	$a_2b_2$	$a_1b_2$	$a_0b_2$				
$a_3b_3$	$a_2b_3$	$a_1b_3$	$a_0b_3$					
					$\dots$	$a_1b_0 + a_0b_1$	$a_0b_0$	← <i>Product</i>

*Many different circuits exist for multiplication. Each one has a different balance between speed (performance) and amount of logic (cost).*

## “Shift and Add” Multiplier



- Sums each partial product, one at a time.
- In binary, each partial product is shifted versions of A or 0.

### Control Algorithm:

1.  $P \leftarrow 0$ ,  $A \leftarrow$  multiplicand,  
 $B \leftarrow$  multiplier
2. If LSB of  $B=1$  then add  $A$  to  $P$   
else add 0
3. Shift  $[P][B]$  right 1
4. Repeat steps 2 and 3  $n-1$  times.
5.  $[P][B]$  has product.

- Cost  $\propto n$ ,  $T = n$  clock cycles.
- What is the critical path for determining the min clock period?

## “Shift and Add” Multiplier

### Signed Multiplication:

*Remember* for 2's complement numbers MSB has negative weight:

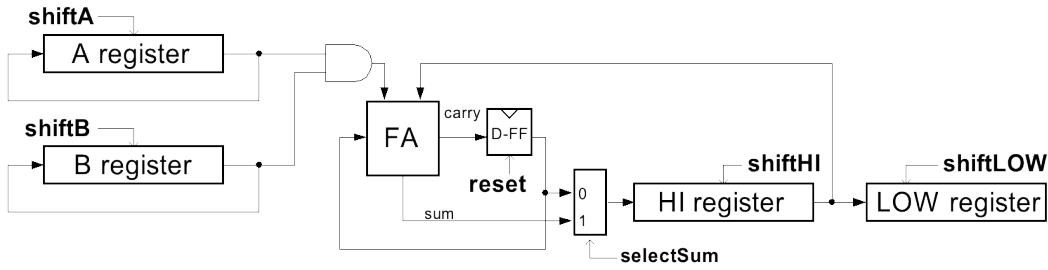
$$X = \sum_{i=0}^{N-2} x_i 2^i - x_{n-1} 2^{n-1}$$

$$\begin{aligned} \text{ex: } -6 &= 11010_2 = 0 \cdot 2^0 + 1 \cdot 2^1 + 0 \cdot 2^2 + 1 \cdot 2^3 - 1 \cdot 2^4 \\ &= 0 + 2 + 0 + 8 - 16 = -6 \end{aligned}$$

- Therefore for multiplication:
  - a) subtract final partial product
  - b) sign-extend partial products
- Modifications to shift & add circuit:
  - a) adder/subtractor
  - b) sign-extender on P shifter register

# Bit-serial Multiplier

- Bit-serial multiplier ( $n^2$  cycles, one bit of result per  $n$  cycles):



- Control Algorithm:

```

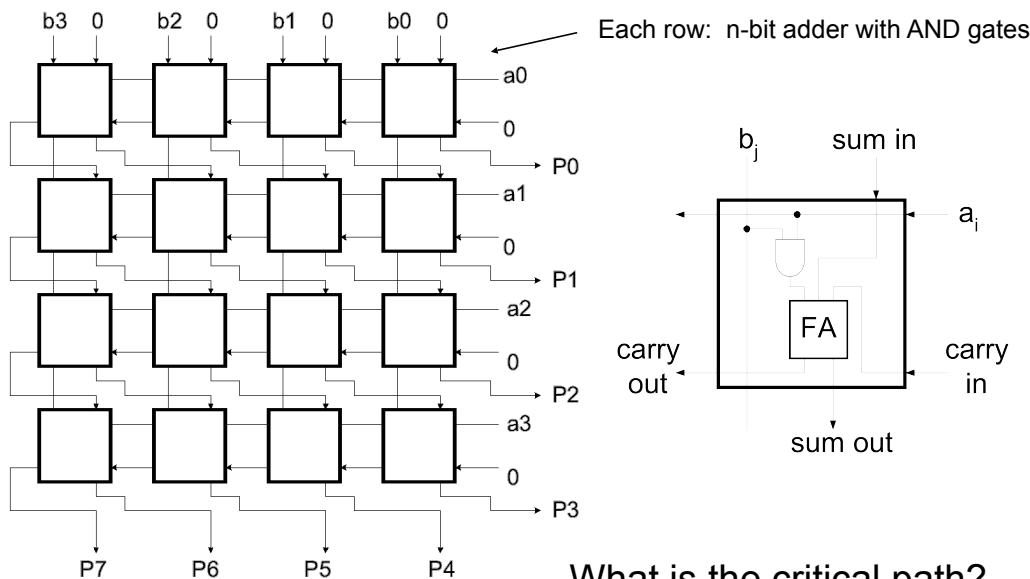
repeat n cycles { // outer (i) loop
  repeat n cycles{ // inner (j) loop
    shiftA, selectSum, shiftHI
  }
  shiftB, shiftHI, shiftLOW, reset
}

```

**Note:** The occurrence of a control signal  $x$  means  $x=1$ . The absence of  $x$  means  $x=0$ .

# Array Multiplier

Single cycle multiply: Generates all  $n$  partial products simultaneously.



What is the critical path?

# Carry-Save Addition

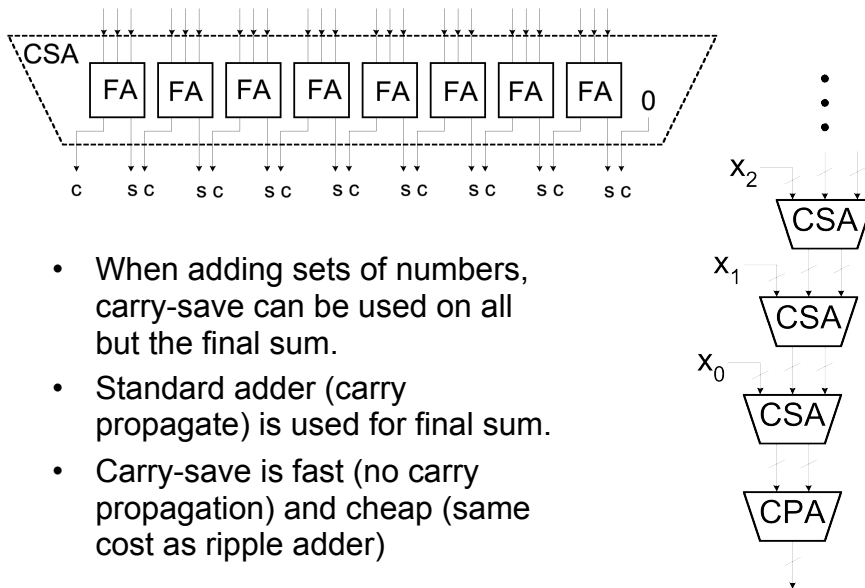
- Speeding up multiplication is a matter of speeding up the summing of the partial products.
- “Carry-save” addition can help.
- Carry-save addition passes (saves) the carries to the output, rather than propagating them.
- Example: sum three numbers,  $3_{10} = 0011$ ,  $2_{10} = 0010$ ,  $3_{10} = 0011$

$$\begin{array}{r}
 3_{10} \quad 0011 \\
 + 2_{10} \quad 0010 \\
 \hline
 c \quad 0100 = 4_{10} \\
 s \quad 0001 = 1_{10} \\
 \hline
 3_{10} \quad 0011 \\
 + \quad \quad \quad \\
 \hline
 c \quad 0010 = 2_{10} \\
 s \quad 0110 = 6_{10} \\
 \hline
 1000 = 8_{10}
 \end{array}$$

} carry-save add
} carry-propagate add

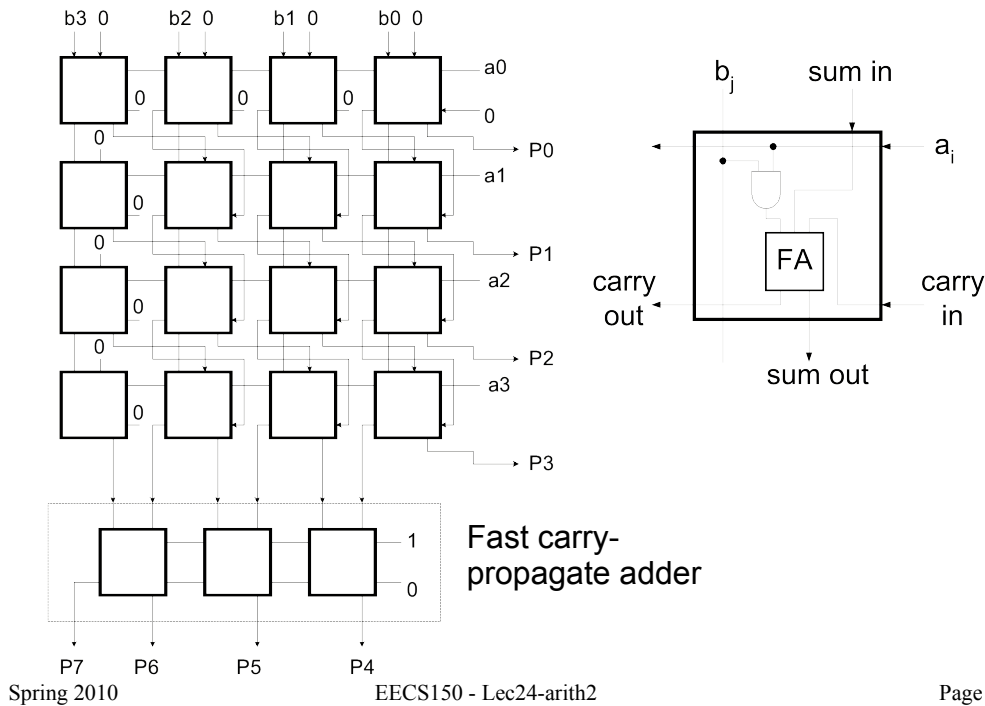
- In general, *carry-save* addition takes in 3 numbers and produces 2.
- Whereas, *carry-propagate* takes 2 and produces 1.
- With this technique, we can avoid carry propagation until final addition

# Carry-save Circuits



- When adding sets of numbers, carry-save can be used on all but the final sum.
- Standard adder (carry propagate) is used for final sum.
- Carry-save is fast (no carry propagation) and cheap (same cost as ripple adder)

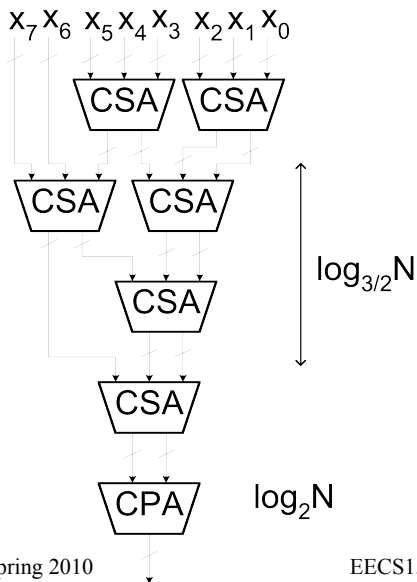
# Array Multiplier using Carry-save Addition



## Carry-save Addition

CSA is associative and commutitive. For example:

$$(((X_0 + X_1) + X_2) + X_3) = ((X_0 + X_1) + (X_2 + X_3))$$



- A balanced tree can be used to reduce the logic delay.
- This structure is the basis of the **Wallace Tree Multiplier**.
- Partial products are summed with the CSA tree. Fast CPA (ex: CLA) is used for final sum.
- Multiplier delay  $\propto \log_{3/2} N + \log_2 N$

## Constant Multiplication

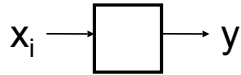
- Our discussion so far has assumed both the multiplicand (A) and the multiplier (B) can vary at runtime.

- What if one of the two is a constant?

$$Y = C * X$$

- “Constant Coefficient” multiplication comes up often in signal processing and other hardware. Ex:

$$y_i = \alpha y_{i-1} + x_i$$



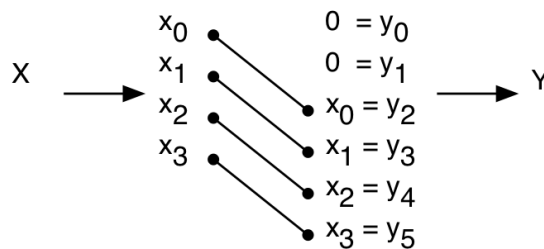
where  $\alpha$  is an application dependent constant that is hard-wired into the circuit.

- How do we build an array style (combinational) multiplier that takes advantage of the constancy of one of the operands?

## Multiplication by a Constant

- If the constant C in  $C * X$  is a power of 2, then the multiplication is simply a shift of X.

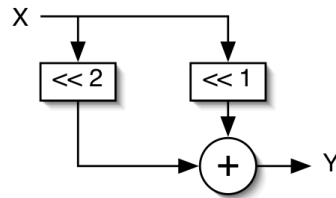
- Ex:  $4 * X$



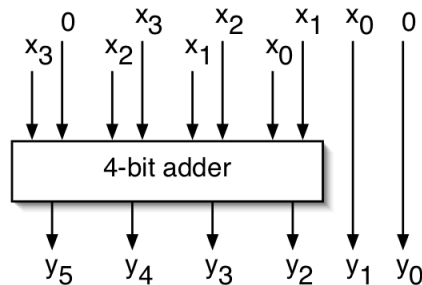
- What about division?
- What about multiplication by non-powers of 2?

## Multiplication by a Constant

- In general, a combination of fixed shifts and addition:
  - Ex:  $6 \cdot X = 0110 \cdot X = (2^2 + 2^1) \cdot X$

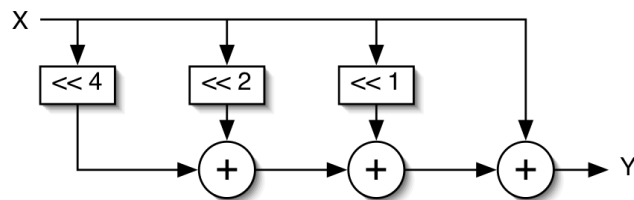


– Details:



## Multiplication by a Constant

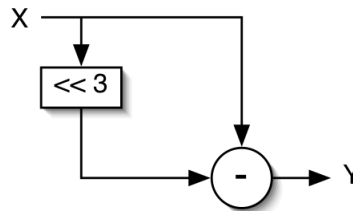
- Another example:  $C = 23_{10} = 010111$



- In general, the number of additions equals the number of 1's in the constant minus one.*
- Using carry-save adders (for all but one of these) helps reduce the delay and cost, but the number of adders is still the number of 1's in C minus 2.
- Is there a way to further reduce the number of adders (and thus the cost and delay)?

## Multiplication using Subtraction

- *Subtraction is ~ the same cost and delay as addition.*
- Consider  $C \cdot X$  where  $C$  is the constant value  $15_{10} = 01111$ .  
 $C \cdot X$  requires 3 additions.
- We can “recode” 15  
     from  $01111 = (2^3 + 2^2 + 2^1 + 2^0)$   
     to  $1000\bar{1} = (2^4 - 2^0)$   
     where  $\bar{1}$  means negative weight.
- Therefore,  $15 \cdot X$  can be implemented with only one subtractor.



## Canonic Signed Digit Representation

- CSD represents numbers using 1,  $\bar{1}$ , & 0 with the least possible number of non-zero digits.
  - Strings of 2 or more non-zero digits are replaced.
  - Leads to a unique representation.
- To form CSD representation might take 2 passes:
  - First pass: replace all occurrences of 2 or more 1's:  
 $01..10$  by  $10..\bar{1}0$
  - Second pass: same as above, plus replace  $0\bar{1}10$  by  $00\bar{1}0$
- Examples:

$$011101 = 29$$

$$100\bar{1}01 = 32 - 4 + 1$$

$$0010111 = 23$$

$$001100\bar{1}$$

$$010\bar{1}00\bar{1} = 32 - 8 - 1$$

$$0110110 = 54$$

$$10\bar{1}10\bar{1}0$$

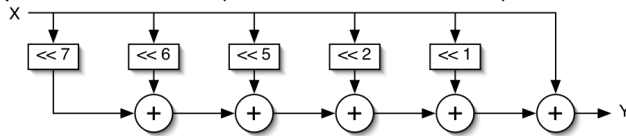
$$100\bar{1}0\bar{1}0 = 64 - 8 - 2$$

- Can we further simplify the multiplier circuits?



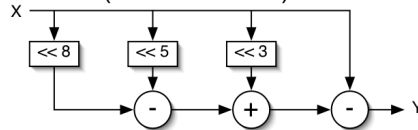
# “Constant Coefficient Multiplication” (KCM)

Binary multiplier:  $Y = 231 * X = (2^7 + 2^6 + 2^5 + 2^2 + 2^1 + 2^0) * X$



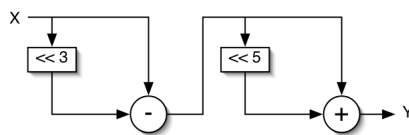
- CSD helps, but the multipliers are limited to shifts followed by adds.

- CSD multiplier:  $Y = 231 * X = (2^8 - 2^5 + 2^3 - 2^0) * X$



- How about shift/add/shift/add ...?

- KCM multiplier:  $Y = 231 * X = 7 * 33 * X = (2^3 - 2^0) * (2^5 + 2^0) * X$



- No simple algorithm exists to determine the optimal KCM representation.
- Most use exhaustive search method.

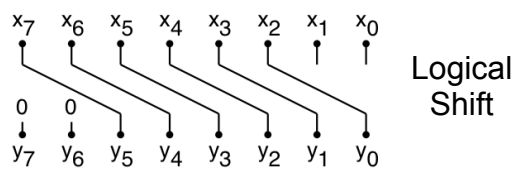
## Fixed Shifters / Rotators

- “fixed” shifters  
“hardwire” the shift amount into the circuit.

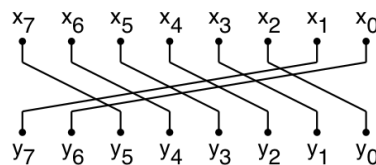
- Ex: verilog: `X >> 2`  
- (right shift X by 2 places)

- Fixed shift/rotator is nothing but wires!

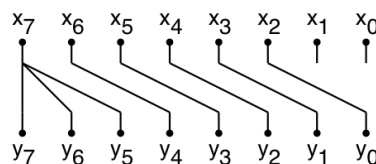
So what?



Logical Shift



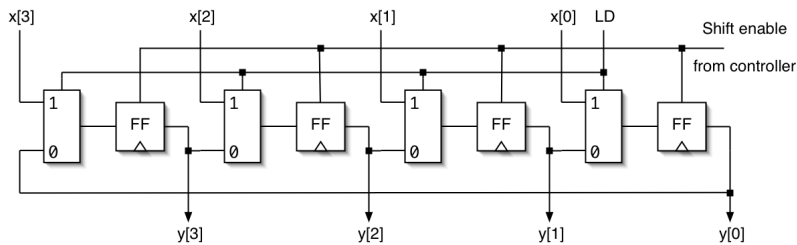
Rotate



Arithmetic Shift

# Variable Shifters / Rotators

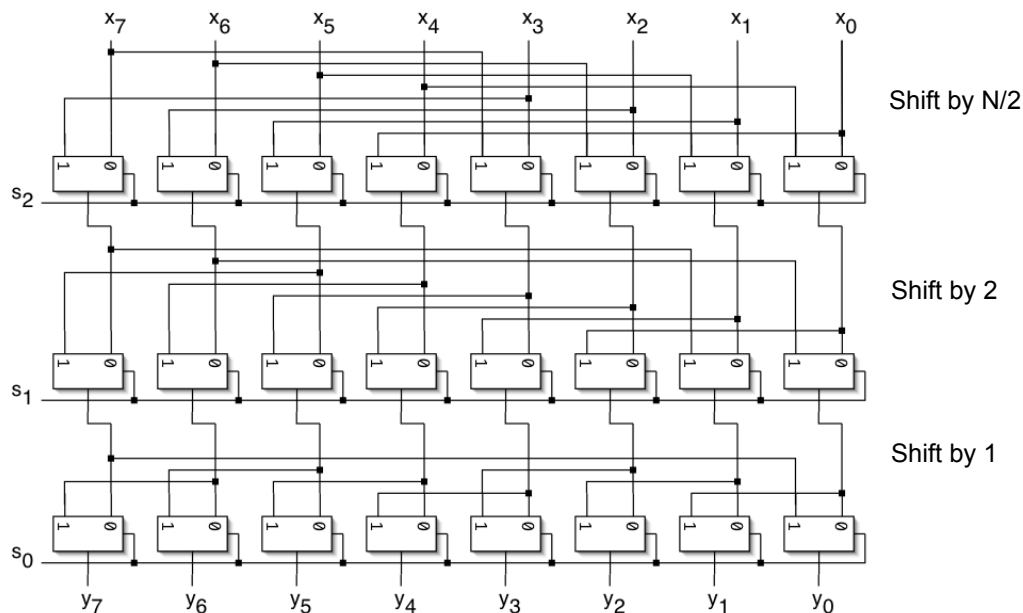
- Example:  $X \gg S$ , where  $S$  is unknown when we synthesize the circuit.
- Uses: shift instruction in processors (ARM includes a shift on every instruction), floating-point arithmetic, division/multiplication by powers of 2, etc.
- One way to build this is a simple shift-register:
  - a) Load word, b) shift enable for  $S$  cycles, c) read word.



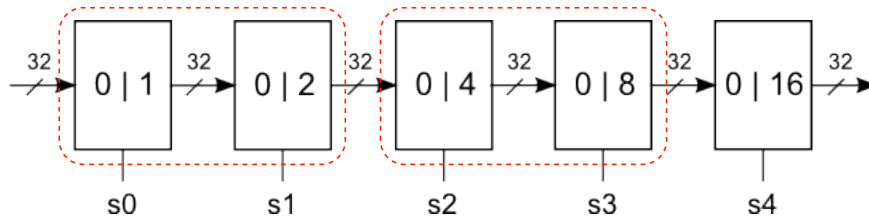
- Worst case delay  $O(N)$ , not good for processor design.
- Can we do it in  $O(\log N)$  time and fit it in one cycle?

# Log Shifter / Rotator

- $\log(N)$  stages, each shifts (or not) by a power of 2 places,  $S =$

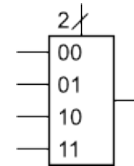


# LUT Mapping of Log shifter

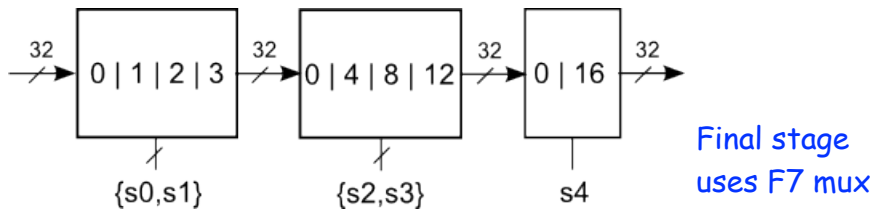


Efficient with 2to1 multiplexors, for instance, 3LUTs.

Virtex5 has 6LUTs. Naturally makes 4to1 muxes:

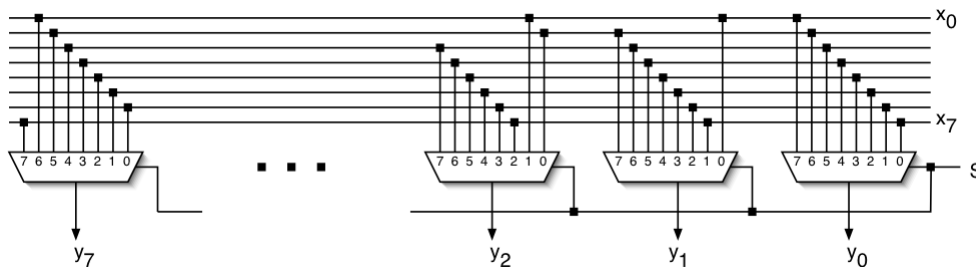


Reorganize shifter to use 4to1 muxes.



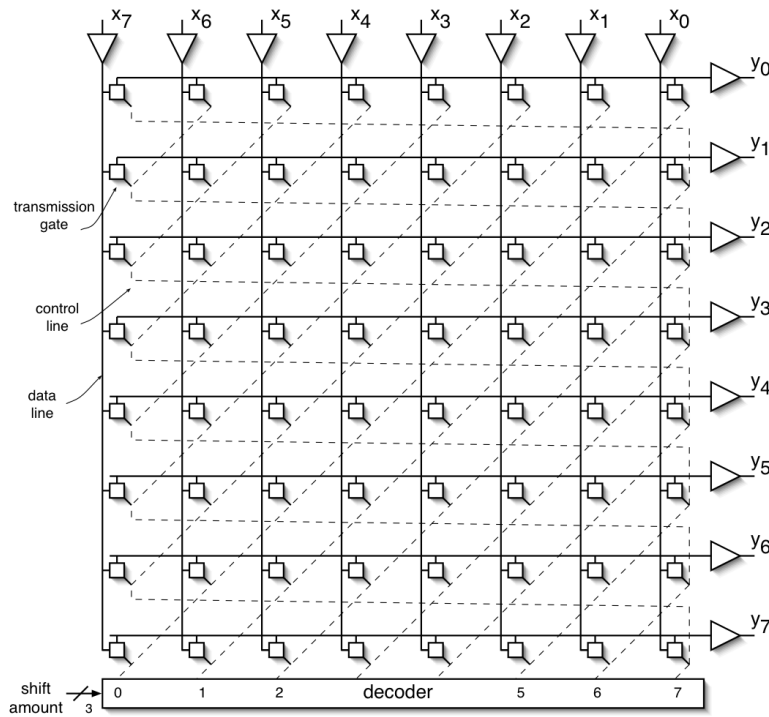
# “Improved” Shifter / Rotator

- How about this approach? Could it lead to even less delay?



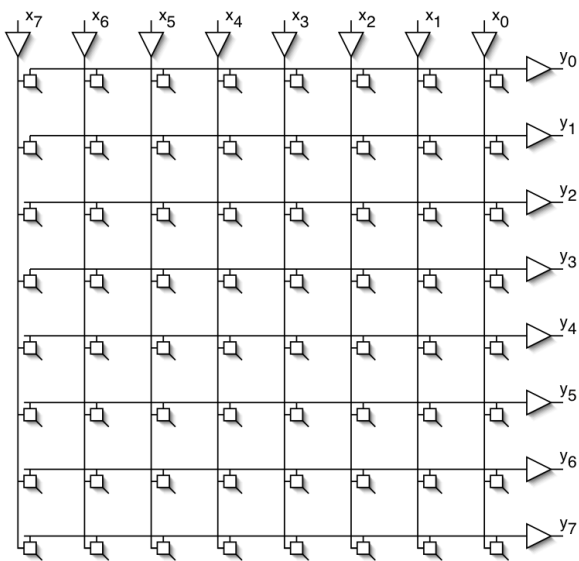
- What is the delay of these big muxes?
- Look a transistor-level implementation?

# Barrel Shifter



Cost/delay?  
 - (don't forget the decoder)

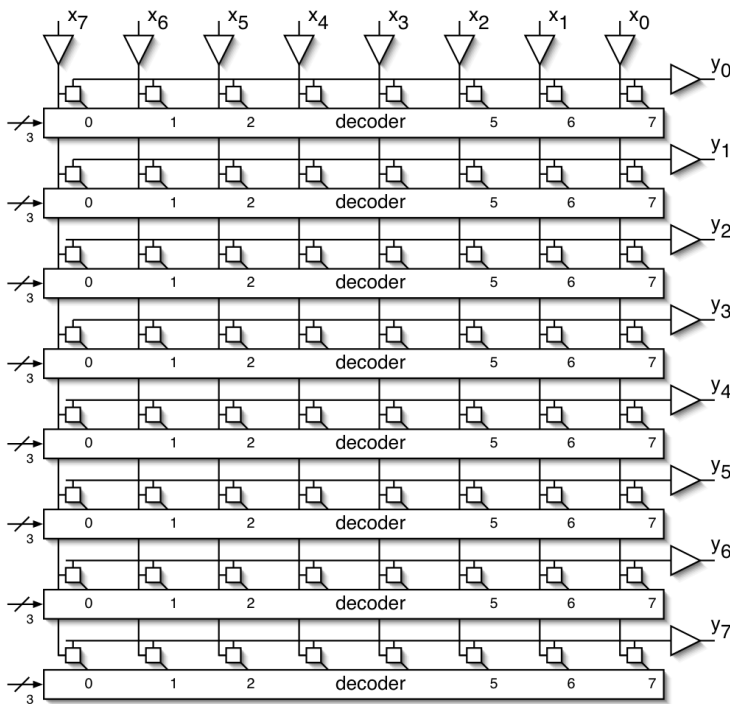
# Connection Matrix



Generally useful structure:

- $N^2$  control points.
- What other interesting functions can it do?

# Cross-bar Switch



- $N \log(N)$  control signals.
- Supports all interesting permutations
  - All one-to-one and one-to-many connections.
- Commonly used in communication hardware (switches, routers).