CS 152 Computer Architecture and Engineering

Lecture 18: Multithreading

Krste Asanovic
Electrical Engineering and Computer Sciences
University of California, Berkeley

http://www.eecs.berkeley.edu/~krste
http://inst.cs.berkeley.edu/~cs152

Last Time: Vector Computers

- Vectors provide efficient execution of data-parallel loop codes
- Vector ISA provides compact encoding of machine parallelism
- ISAs scale to more lanes without changing binary code
- Vector registers provide fast temporary storage to reduce memory bandwidth demands, & simplify dependence checking between vector instructions
- Scatter/gather, masking, compress/expand operations increase set of vectorizable loops
- Requires extensive compiler analysis (or programmer annotation) to be certain that loops can be vectorized
- Full "long" vector support still only in supercomputers (NEC SX9, Cray X1E); microprocessors have limited "short" vector operations
  - Intel x86 MMX/SSE/AVX
  - IBM/Motorola PowerPC VMX/Altivec

Multithreading

- Difficult to continue to extract instruction-level parallelism (ILP) or data-level parallelism (DLP) from a single sequential thread of control
- Many workloads can make use of thread-level parallelism (TLP)
  - TLP from multiprogramming (run independent sequential jobs)
  - TLP from multithreaded applications (run one job faster using parallel threads)
- Multithreading uses TLP to improve utilization of a single processor

Pipeline Hazards

	t0	t1	t2	t3	t4	t5	t6	t7	t8	t9	t10	t11	t12	t13	t14
LW r1, 0(r2)	F	D	X	M	W										
LW r5, 12(r1)		F	D	D	D	D	X	M	W						
ADDI r5, r5, #12			F	F	F	F	D	D	D	D	X	M	W		
SW 12(r1), r5							F	F	F	F	D	D	D	D	

- Each instruction may depend on the next

What is usually done to cope with this?

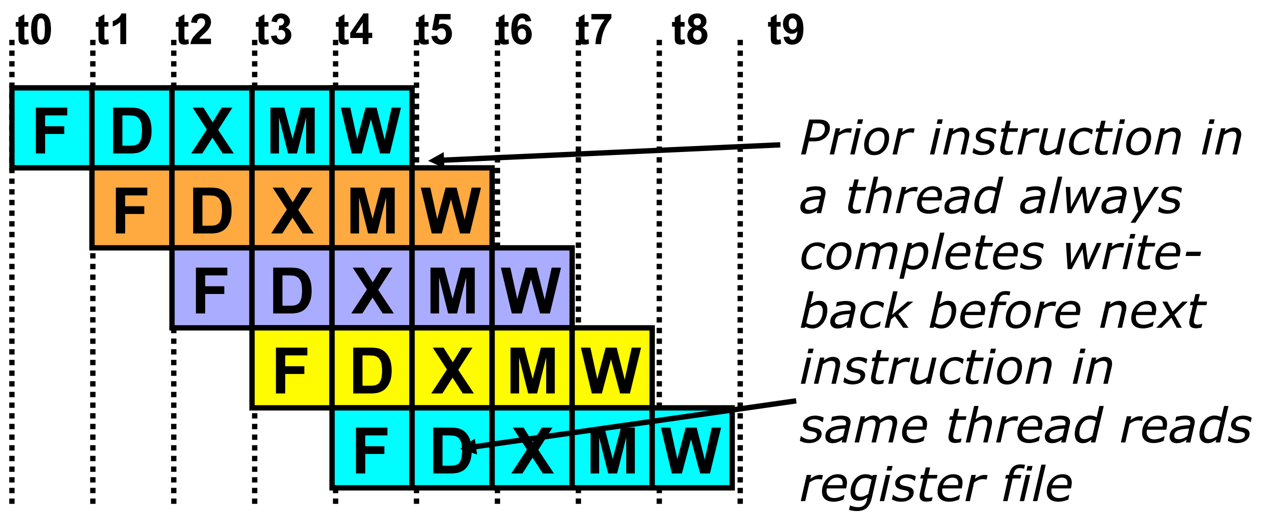
Multithreading

How can we guarantee no dependencies between instructions in a pipeline?

-- One way is to interleave execution of instructions from different program threads on same pipeline

Interleave 4 threads, T1-T4, on non-bypassed 5-stage pipe

T1: LW r1, 0(r2)
T2: ADD r7, r1, r4
T3: XORI r5, r4, #12
T4: SW 0(r7), r5
T1: LW r5, 12(r1)

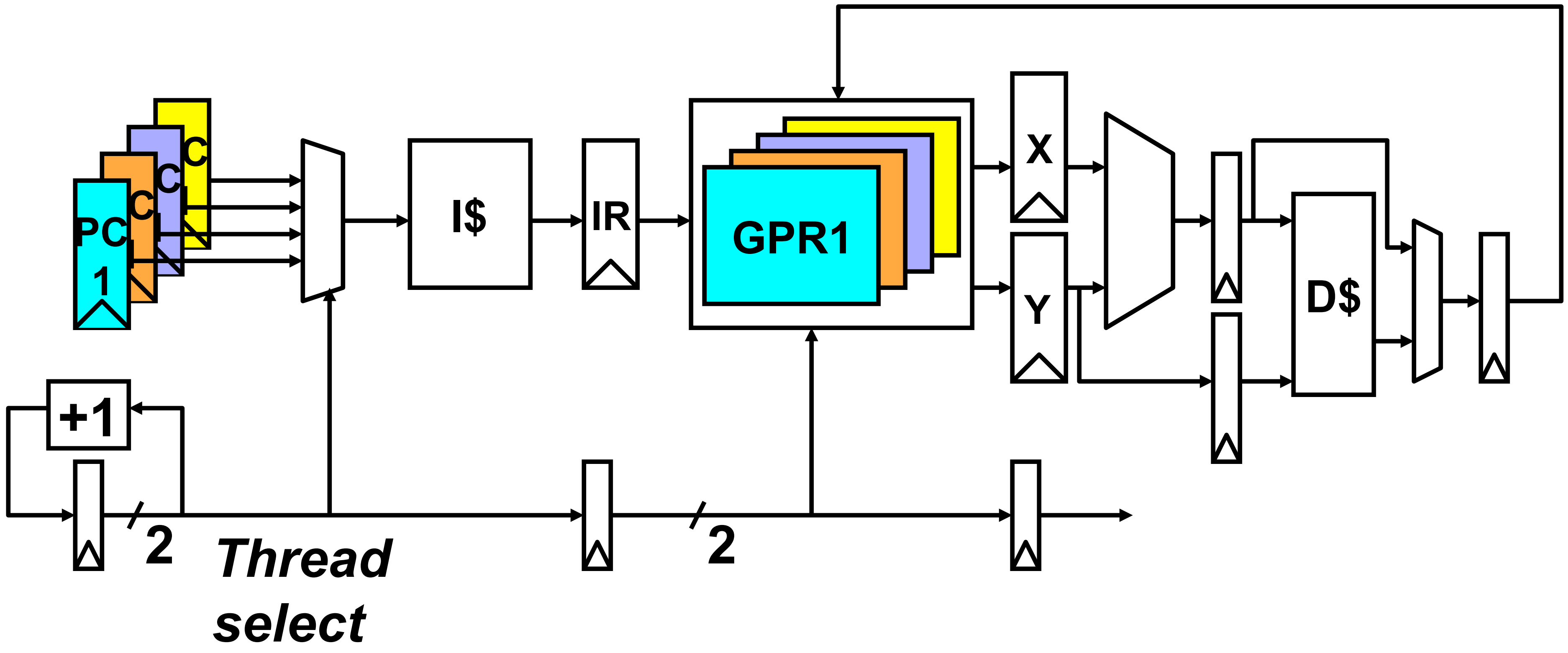


t0
t1
t2
t3
t4
t5
t6
t7
t8
t9
F D X M W
F D X M W
F D X M W
F D X M W
F D X M W
Prior instruction in a thread always completes write-back before next instruction in same thread reads register file

CDC 6600 Peripheral Processors
(Cray, 1964)

- First multithreaded hardware
- 10 “virtual” I/O processors
- Fixed interleave on simple pipeline
- Pipeline has 100ns cycle time
- Each virtual processor executes one instruction every 1000ns
- Accumulator-based instruction set to reduce processor state

Simple Multithreaded Pipeline



- Have to carry thread select down pipeline to ensure correct state bits read/written at each pipe stage
- Appears to software (including OS) as multiple, albeit slower, CPUs

Multithreading Costs

- Each thread requires its own user state
  - PC
  - GPRs

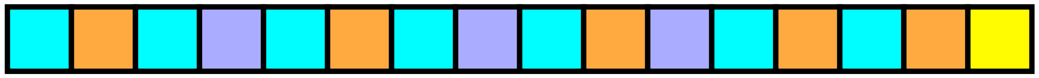
- Also, needs its own system state
  - virtual memory page table base register
  - exception handling registers

- *Other overheads:*
  - Additional cache/TLB conflicts from competing threads
  - (or add larger cache/TLB capacity)
  - More OS overhead to schedule more threads (where do all these threads come from?)

Thread Scheduling Policies

- Fixed interleave *(CDC 6600 PPUs, 1964)*
  - Each of N threads executes one instruction every N cycles
  - If thread not ready to go in its slot, insert pipeline bubble

- Software-controlled interleave *(TI ASC PPUs, 1971)*
  - OS allocates S pipeline slots amongst N threads
  - Hardware performs fixed interleave over S slots, executing whichever thread is in that slot



- Hardware-controlled thread scheduling *(HEP, 1982)*
  - Hardware keeps track of which threads are ready to go
  - Picks next thread to execute based on hardware priority scheme

Denelcor HEP
(Burton Smith, 1982)

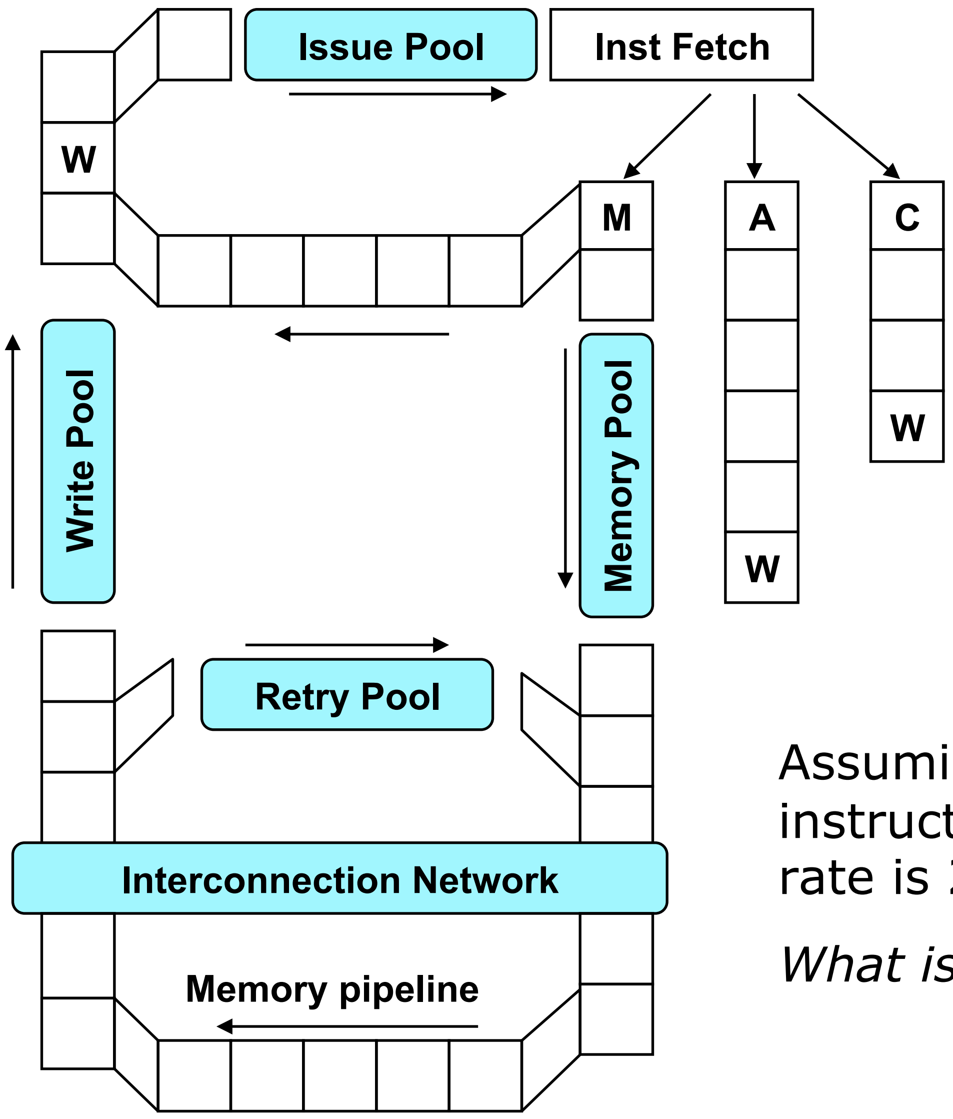
First commercial machine to use hardware threading in main CPU

- 120 threads per processor
- 10 MHz clock rate
- Up to 8 processors
- precursor to Tera MTA (Multithreaded Architecture)

Tera MTA (1990-)

- Up to 256 processors
- Up to 128 active threads per processor
- Processors and memory modules populate a sparse 3D torus interconnection fabric
- Flat, shared main memory
  - No data cache
  - Sustains one main memory access per cycle per processor
- GaAs logic in prototype, 1KW/processor @ 260MHz
  - Second version CMOS, MTA-2, 50W/processor
  - New version, XMT, fits into AMD Opteron socket, runs at 500MHz

MTA Pipeline



- Every cycle, one VLIW instruction from one active thread is launched into pipeline
- Instruction pipeline is 21 cycles long
- Memory operations incur ~150 cycles of latency

Assuming a single thread issues one instruction every 21 cycles, and clock rate is 260 MHz…

What is single-thread performance?

Coarse-Grain Multithreading

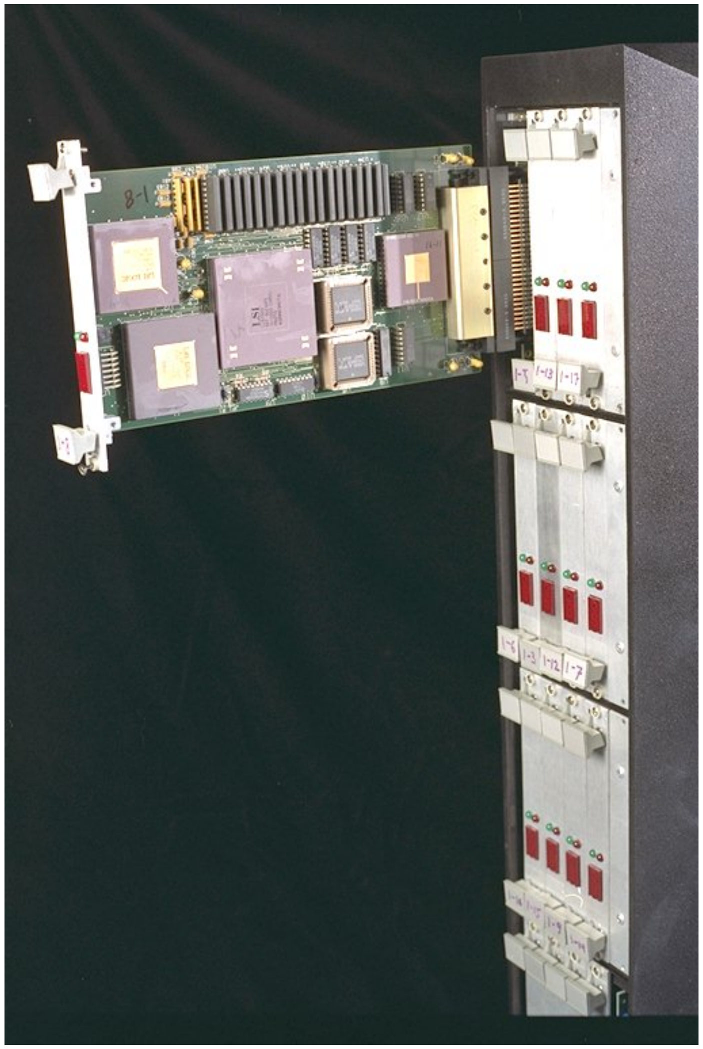
Tera MTA designed for supercomputing applications with large data sets and low locality

- No data cache
- Many parallel threads needed to hide large memory latency

Other applications are more cache friendly

- Few pipeline bubbles if cache mostly has hits
- Just add a few threads to hide occasional cache miss latencies
- Swap threads on cache misses

MIT Alewife (1990)



- Modified SPARC chips
  - register windows hold different thread contexts
- Up to four threads per node
- Thread switch on local cache miss

IBM PowerPC RS64-IV (2000)

- Commercial coarse-grain multithreading CPU
- Based on PowerPC with quad-issue in-order five-stage pipeline
- Each physical CPU supports two virtual CPUs
- On L2 cache miss, pipeline is flushed and execution switches to second thread
  - short pipeline minimizes flush penalty (4 cycles), small compared to memory access latency
  - flush pipeline to simplify exception handling

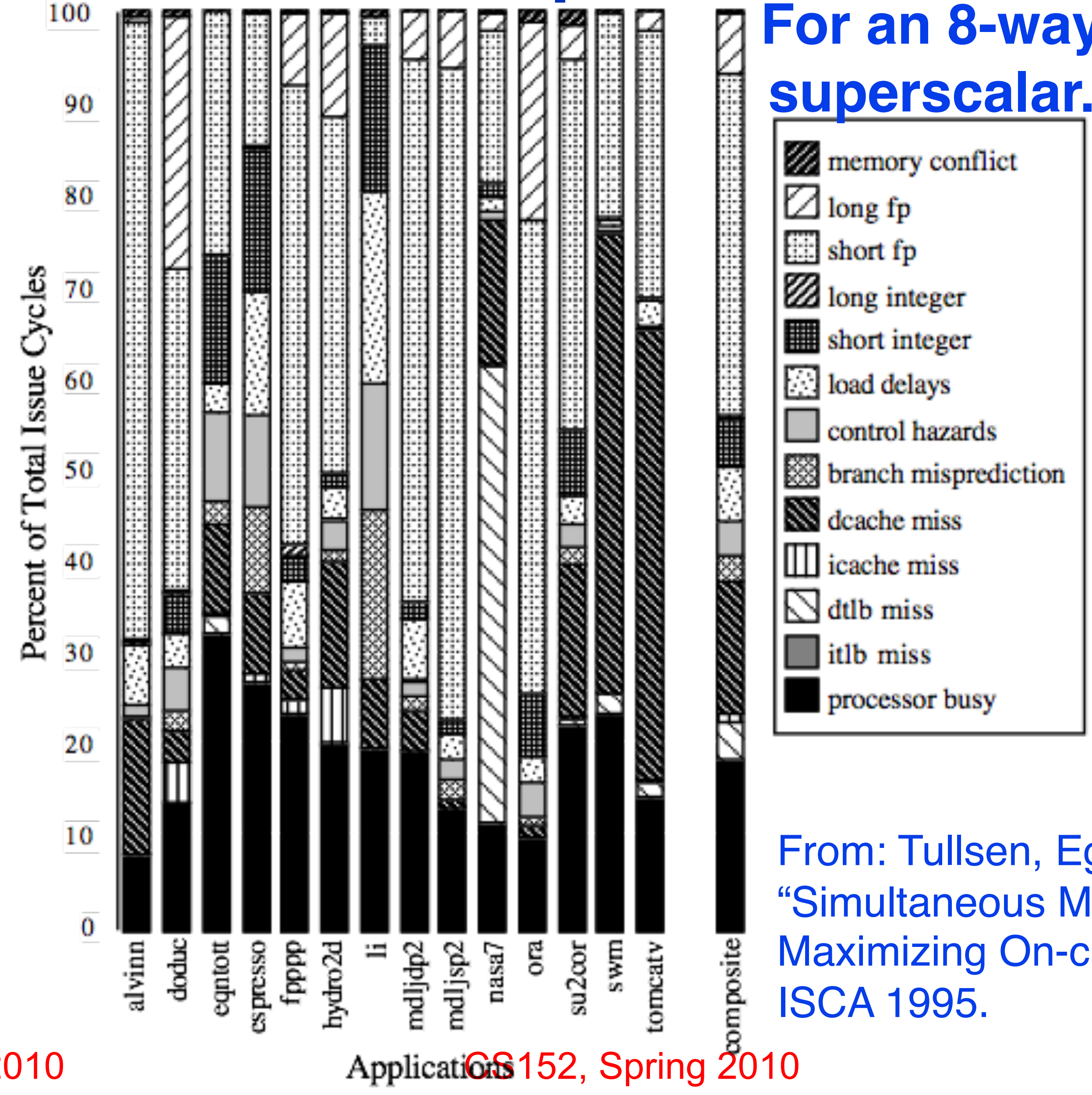
CS152 Administrivia

- Quiz 4, Tuesday April 13
- VLIW, Vectors, Multithreading (lectures 15-18)

Simultaneous Multithreading (SMT) for OoO Superscalars

- Techniques presented so far have all been “vertical” multithreading where each pipeline stage works on one thread at a time
- SMT uses fine-grain control already present inside an OoO superscalar to allow instructions from multiple threads to enter execution on same clock cycle. Gives better utilization of machine resources.

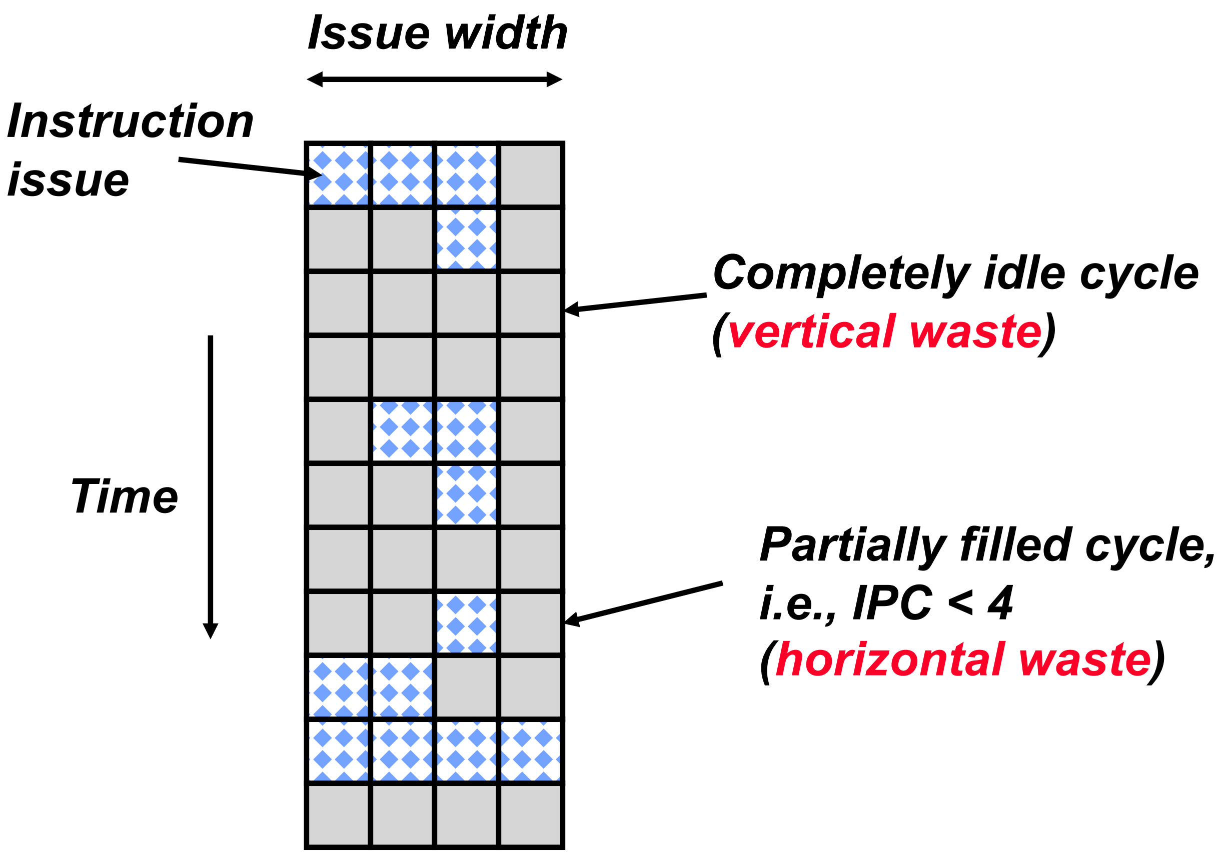
For most apps, most execution units lie idle in an OoO superscalar



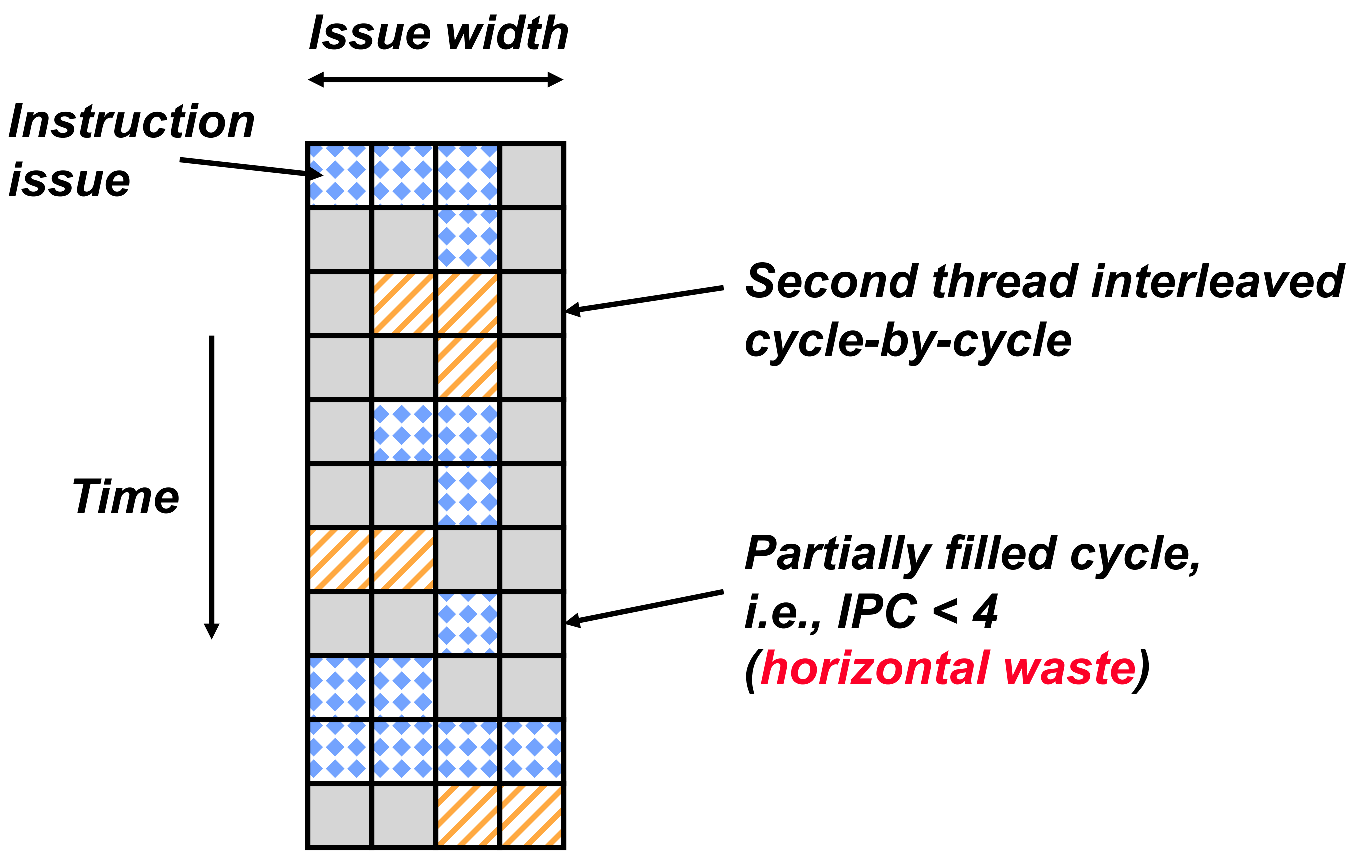
For an 8-way superscalar.

From: Tullsen, Eggers, and Levy, "Simultaneous Multithreading: Maximizing On-chip Parallelism", ISCA 1995.

Superscalar Machine Efficiency

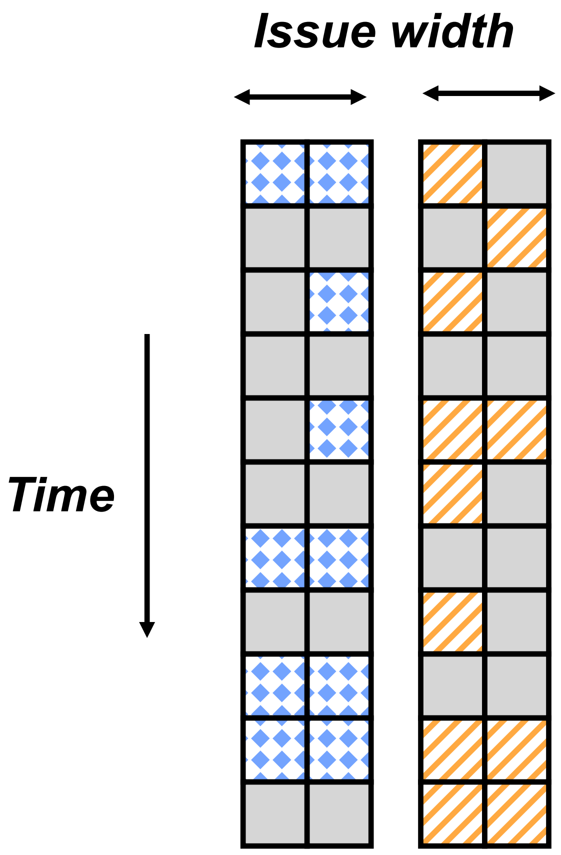

Issue width
Instruction issue
Time
Completely idle cycle (vertical waste)
Partially filled cycle, i.e., IPC < 4 (horizontal waste)

Vertical Multithreading


Issue width
Instruction issue
Time
Second thread interleaved cycle-by-cycle
Partially filled cycle, i.e., IPC < 4
(horizontal waste)

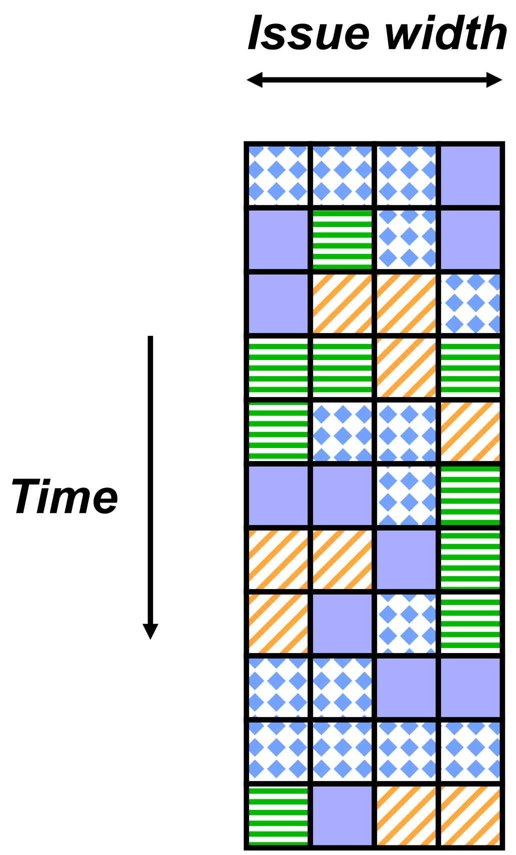
- What is the effect of cycle-by-cycle interleaving?

Chip Multiprocessing (CMP)



- What is the effect of splitting into multiple processors?

Ideal Superscalar Multithreading
[Tullsen, Eggers, Levy, UW, 1995]



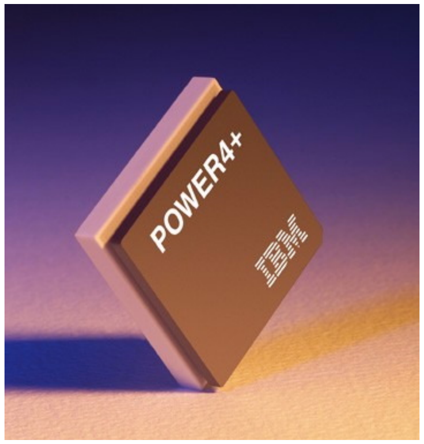
- Interleave multiple threads to multiple issue slots with no restrictions

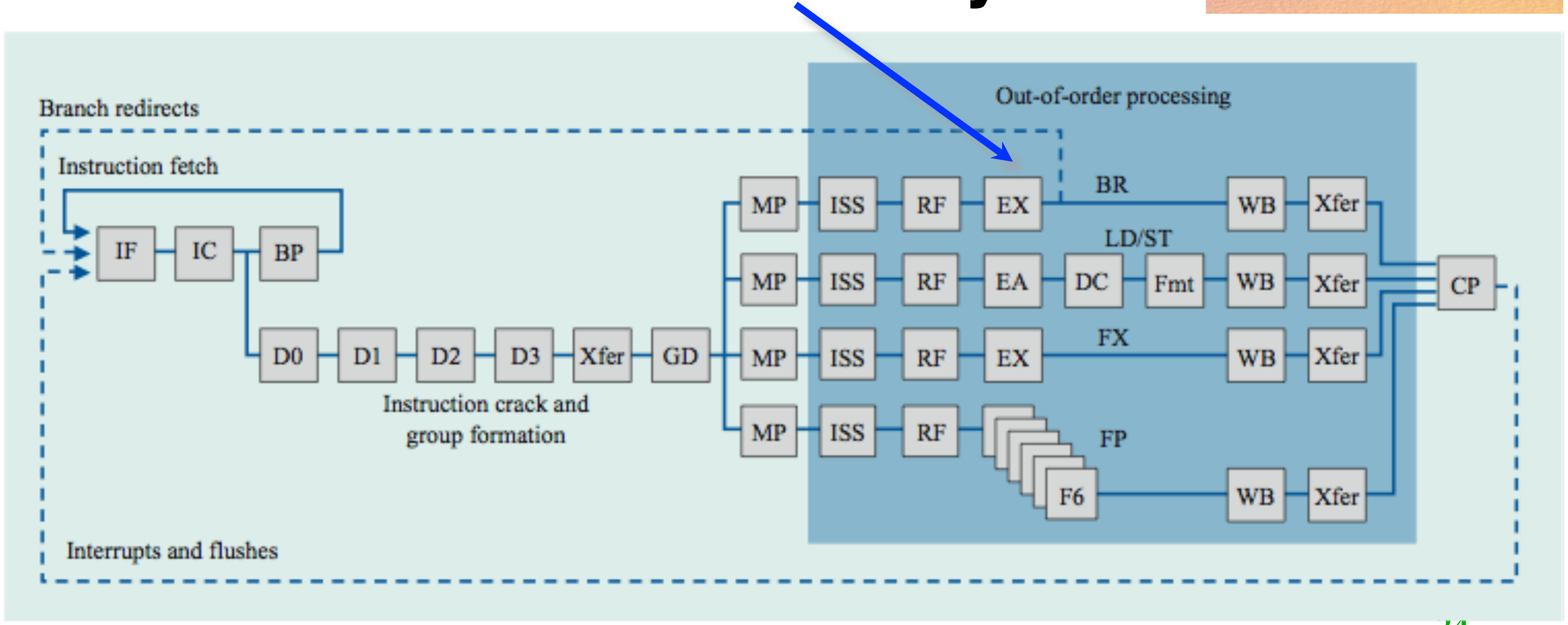
O-o-O Simultaneous Multithreading
[Tullsen, Eggers, Emer, Levy, Stamm, Lo, DEC/UW, 1996]

- Add multiple contexts and fetch engines and allow instructions fetched from different threads to issue simultaneously
- Utilize wide out-of-order superscalar processor issue queue to find instructions to issue from multiple threads
- OOO instruction window already has most of the circuitry required to schedule from multiple threads
- Any single thread can utilize whole machine

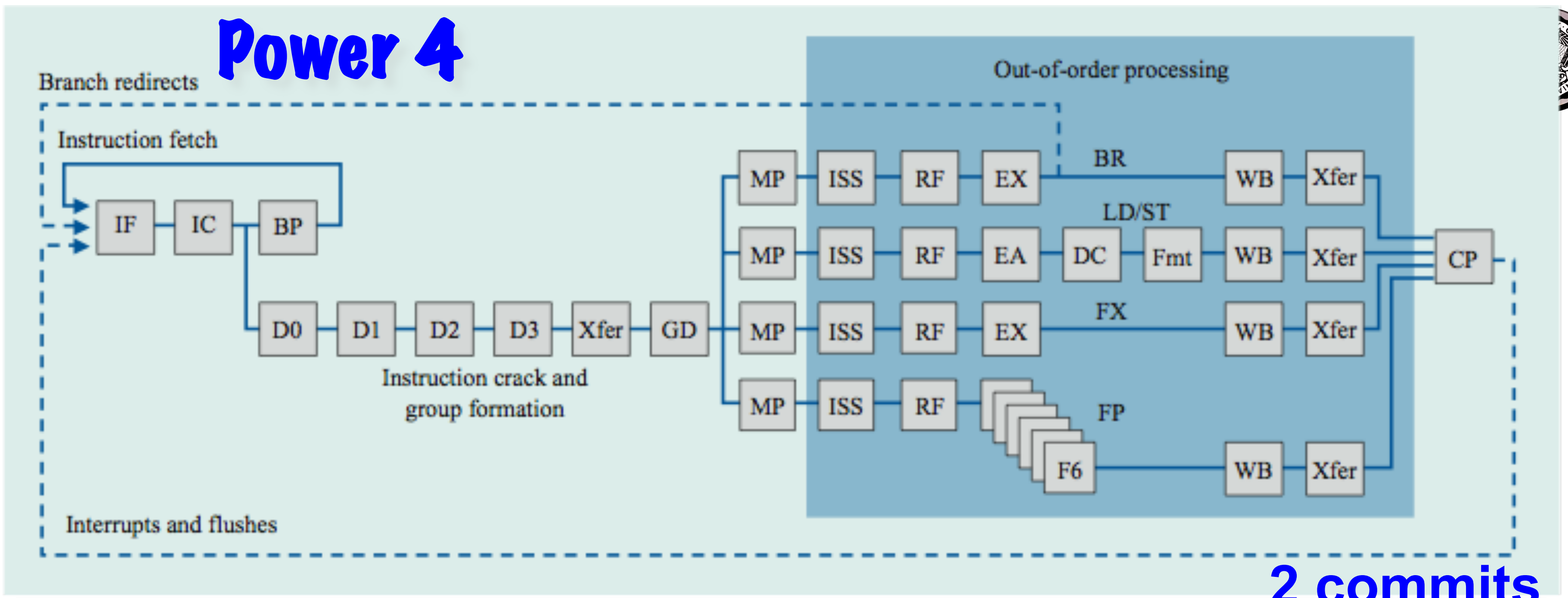
IBM Power 4

Single-threaded predecessor to Power 5. 8 execution units in out-of-order engine, each may issue an instruction each cycle.

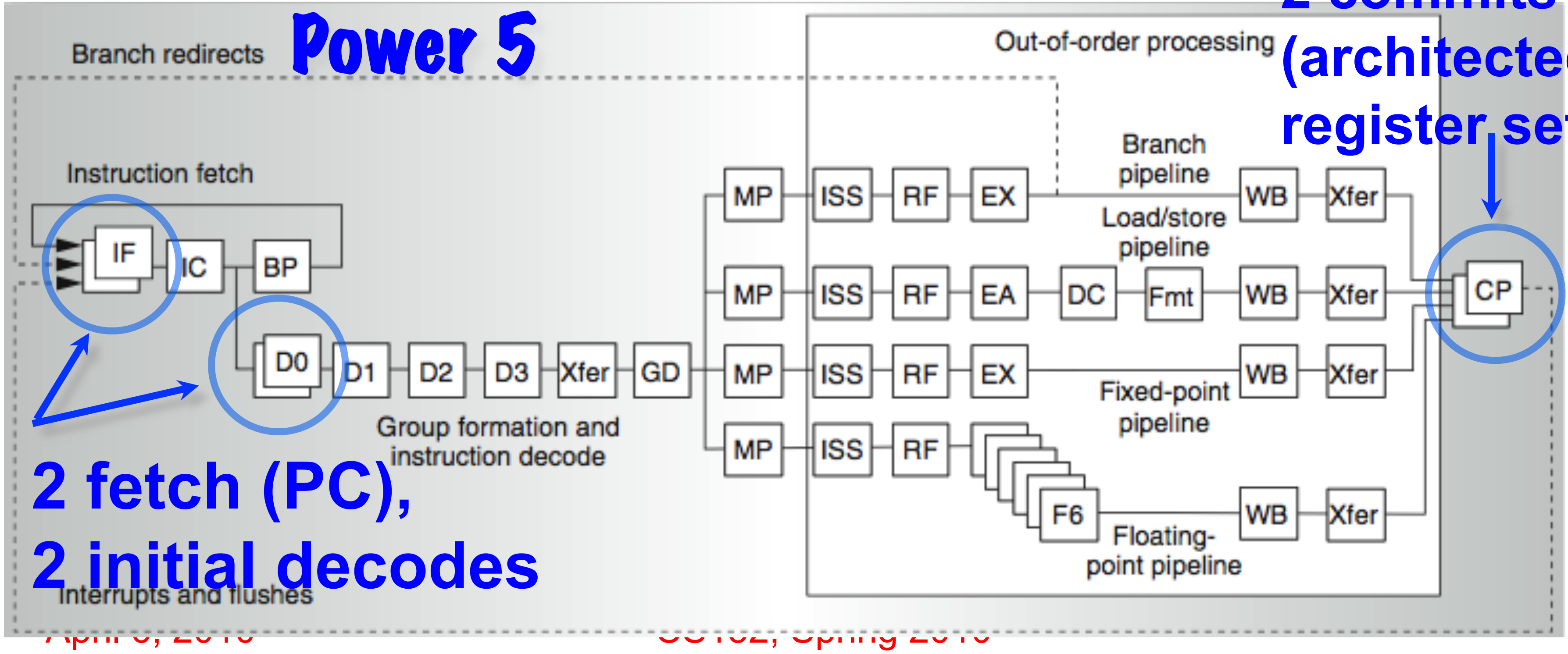




Power 4



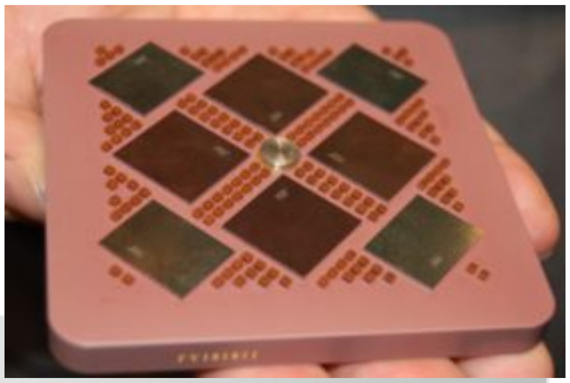
Power 5

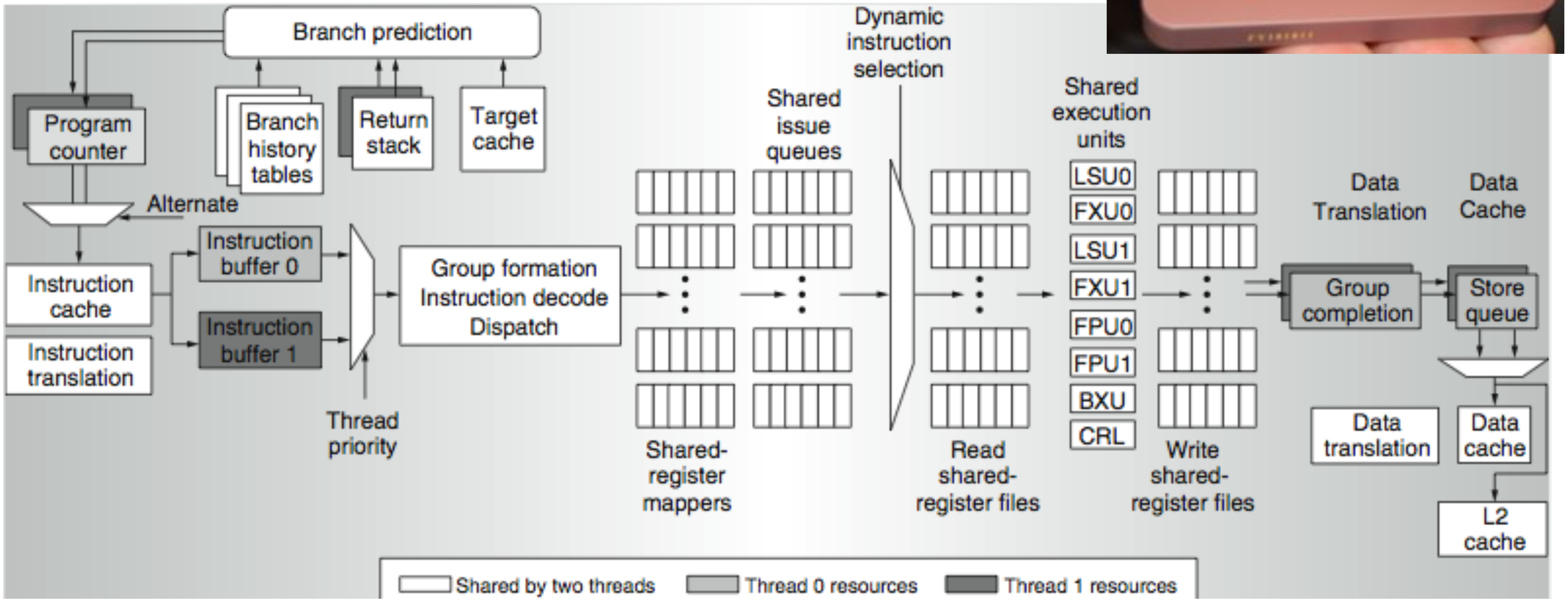


2 commits (architected register sets)

2 fetch (PC), 2 initial decodes

Power 5 data flow ...





Why only 2 threads? With 4, one of the shared resources (physical registers, cache, memory bandwidth) would be prone to bottleneck

Changes in Power 5 to support SMT

- Increased associativity of L1 instruction cache and the instruction address translation buffers
- Added per thread load and store queues
- Increased size of the L2 (1.92 vs. 1.44 MB) and L3 caches
- Added separate instruction prefetch and buffering per thread
- Increased the number of virtual registers from 152 to 240
- Increased the size of several issue queues
- The Power5 core is about 24% larger than the Power4 core because of the addition of SMT support

Pentium-4 Hyperthreading (2002)

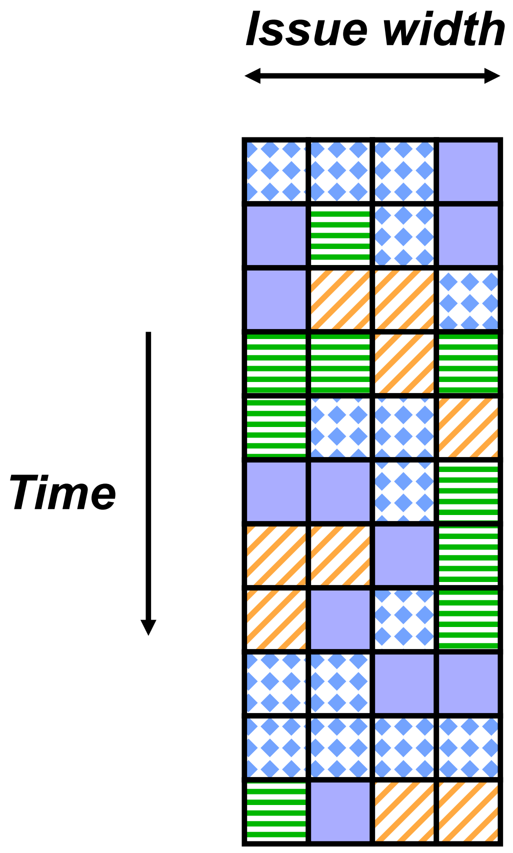
- First commercial SMT design (2-way SMT)
  - Hyperthreading == SMT
- Logical processors share nearly all resources of the physical processor
  - Caches, execution units, branch predictors
- Die area overhead of hyperthreading ~ 5%
- When one logical processor is stalled, the other can make progress
  - No logical processor can use all entries in queues when two threads are active
- Processor running only one active software thread runs at approximately same speed with or without hyperthreading
- Hyperthreading dropped on OoO P6 based followons to Pentium-4 (Pentium-M, Core Duo, Core 2 Duo), until revived with Nehalem generation machines in 2008.
- Intel Atom (in-order x86 core) has two-way vertical multithreading

Initial Performance of SMT

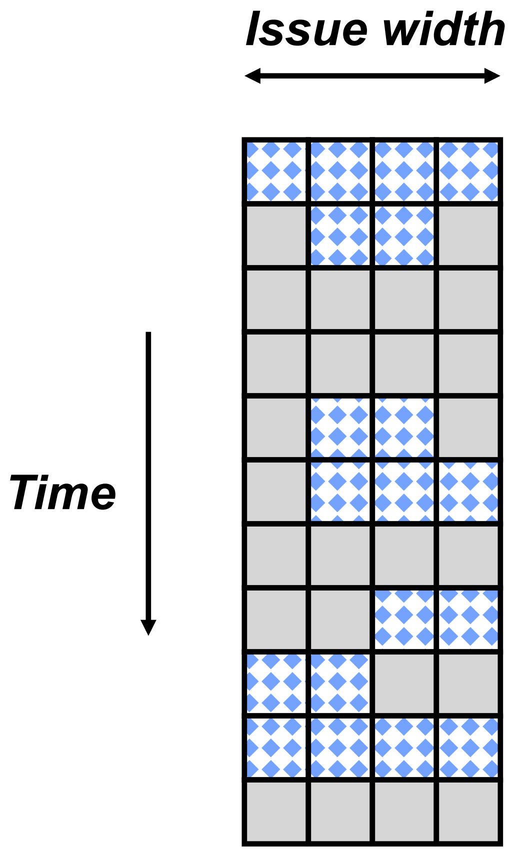
- Pentium 4 Extreme SMT yields 1.01 speedup for SPECint_rate benchmark and 1.07 for SPECfp_rate
  - Pentium 4 is dual threaded SMT
  - SPECRate requires that each SPEC benchmark be run against a vendor-selected number of copies of the same benchmark
- Running on Pentium 4 each of 26 SPEC benchmarks paired with every other (26^2 runs) speed-ups from 0.90 to 1.58; average was 1.20
- Power 5, 8-processor server 1.23 faster for SPECint_rate with SMT, 1.16 faster for SPECfp_rate
- Power 5 running 2 copies of each app speedup between 0.89 and 1.41
  - Most gained some
  - Fl.Pt. apps had most cache conflicts and least gains

SMT adaptation to parallelism type

For regions with high thread level parallelism (TLP) entire machine width is shared by all threads

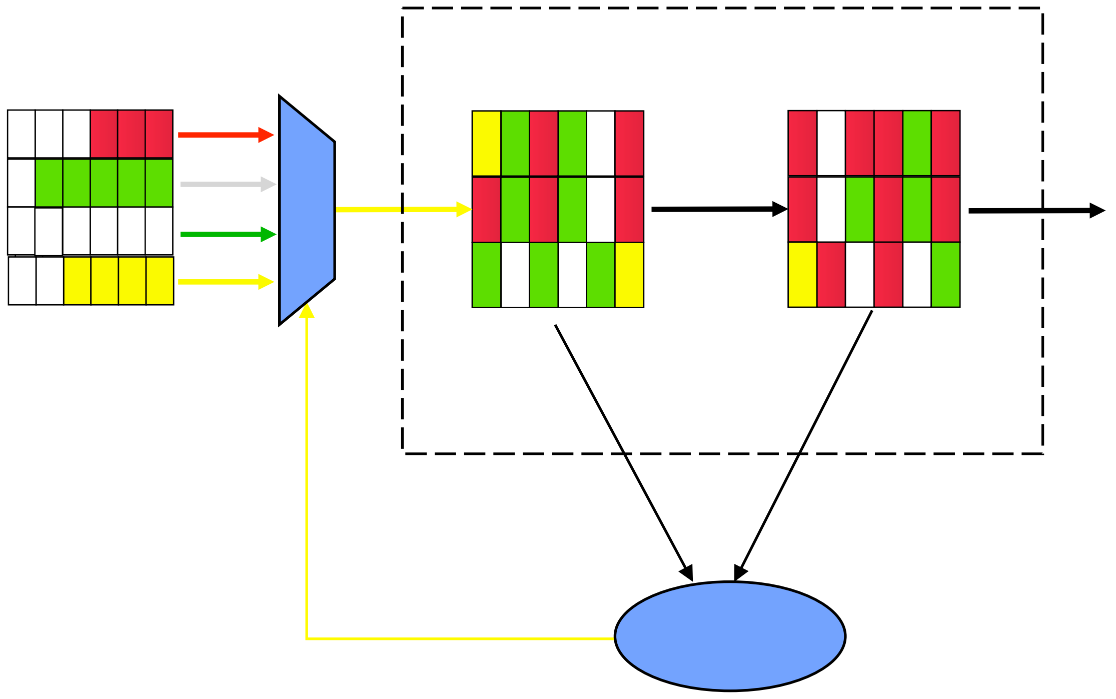


For regions with low thread level parallelism (TLP) entire machine width is available for instruction level parallelism (ILP)



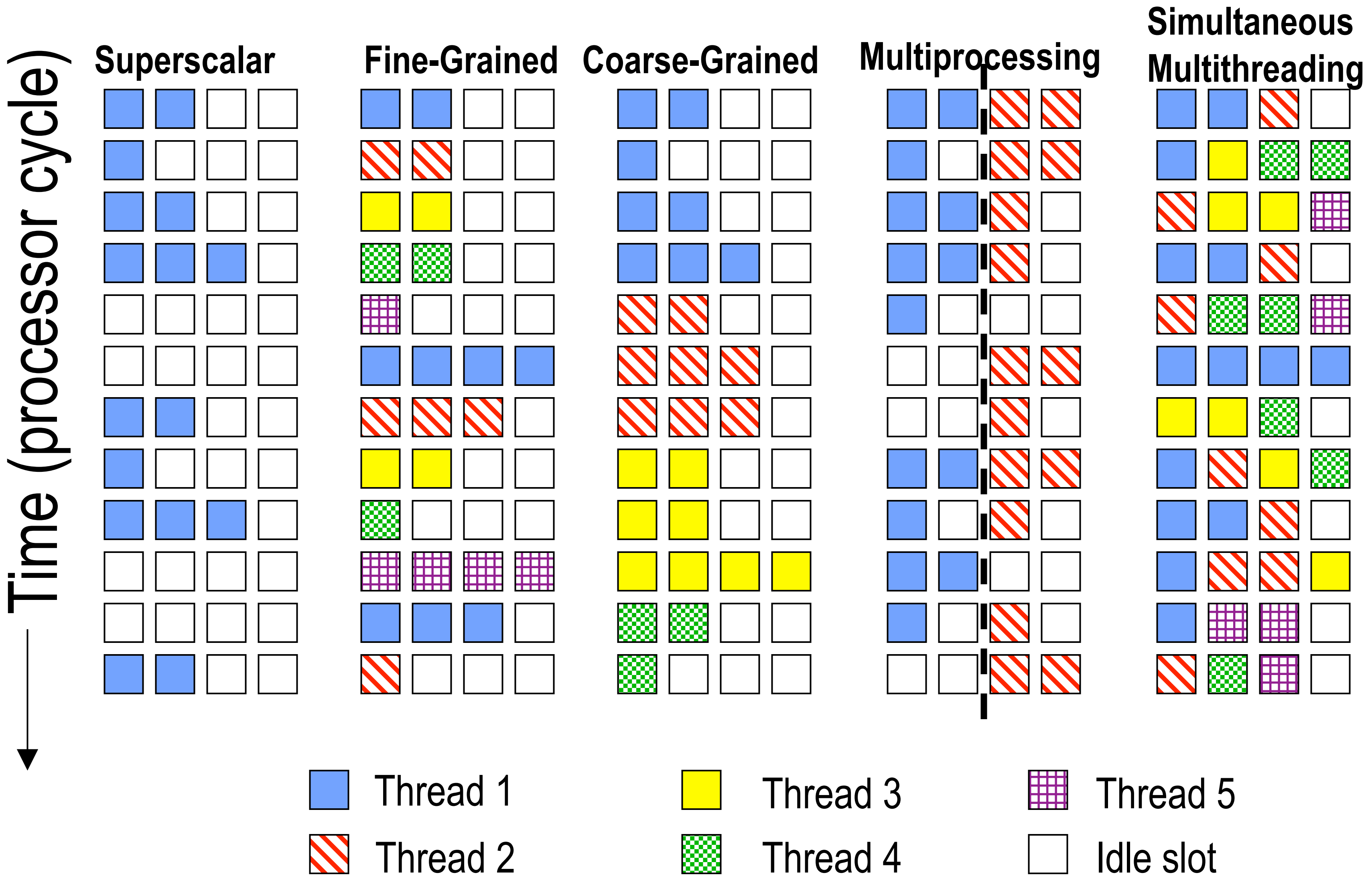
Icount Choosing Policy

Fetch from thread with the least instructions in flight.



Why does this enhance throughput?

Summary: Multithreaded Categories



Acknowledgements

- These slides contain material developed and copyright by:
  - Arvind (MIT)
  - Krste Asanovic (MIT/UCB)
  - Joel Emer (Intel/MIT)
  - James Hoe (CMU)
  - John Kubiatowicz (UCB)
  - David Patterson (UCB)
- MIT material derived from course 6.823
- UCB material derived from course CS252