CS 162 Section 2 Spring 2014

True/False

- 1. Preemptive multithreading requires threads to give up the CPU using the yield() system call
- 2. In some cases, two threads can both be executing a specific critical section at the same time
- 3. Every interrupt results in a transition from user to kernel mode. Hint: think Inception
- 4. A thread needs to own a semaphore, meaning the thread has called semaphore.P(), before it can call semaphore.V()
- 5. A thread needs to own the monitor lock before it can signal() a condition variable.

Short Answer

- 1. With spinlocks, threads spin in a loop (busy waiting) until the lock is freed in general this is a bad idea and wastes many CPU cycles. However, there are certain cases where a spinlock is more efficient than a blocking lock (puts waiting thread to sleep). When?
- 2. What are some similarities and differences between interrupts and system calls?

Locks

Consider the two spinlock implementations below. Are they correct? If not, give an example scenario that would cause the lock to break. Assume a system with two threads, and in #2 this_thread and other_thread correspond to integer thread IDs.

```
1.
struct lock { void acquire(lock) {
                                           void release(lock) {
     int held = 0;
                          while(lock->held);
                                                    lock->held = 0;
                          lock->held = 1;
}
                                               }
                     }
2.
struct lock {
                     void acquire(lock) {
                          while(lock->turn != this thread);
     int turn = 0;
}
                     }
void release(lock) {
     lock->turn = other_thread;
}
```

Semaphores

Implement the P() and V() methods of a Semaphore class backed by monitors (i.e. the Lock and CondVar classes).

Neither of the methods should require more than five lines.

Assume **Mesa**-scheduled monitors.

How would the implementation change for **Hoare**-scheduled monitors?