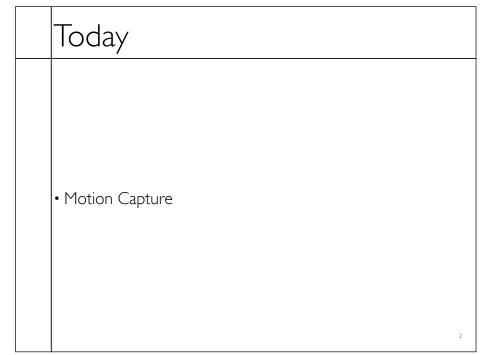
CS-184: Computer Graphics

Lecture #19: Motion Capture

Prof. James O'Brien University of California, Berkeley

V2009-S-19-1.0

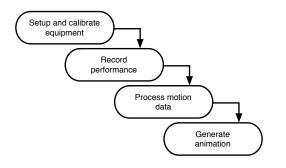


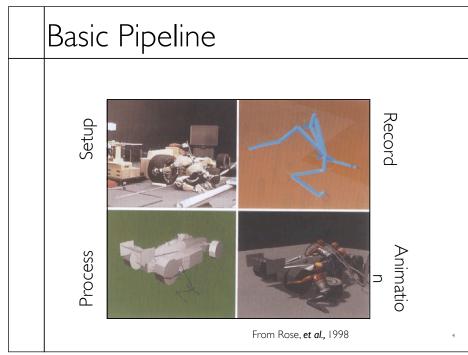
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Motion Capture

- Record motion from physical objects
- Use motion to animate virtual objects

Simplified Pipeline:





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What types of objects?

- Human, whole body
- Portions of body
- Facial animation
- Animals
- Puppets
- Other objects

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Capture Equipment

- Passive Optical
- Reflective markers
- IR (typically) illumination
- Special cameras
 - Fast, high res., filters
- Triangulate for positions







Images from Motion Analysis

Capture Equipment

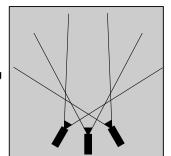
Passive Optical Advantages

Accurate

- Passive Optical Managementers
 - Accurate No cables
- May use many rhigh frequency
- No cables

Disadvantages

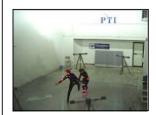
- High frequency
 Requires lots of processing
- Disadvantages Expensive (>\$100K)
- Requires lots of occursions
- Expensive systemarker Swap
- Occlusions Lighting/camera limitations
- Marker swap
- Lighting / camera limitations



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Capture Equipment

- Active Optical
 - Similar to passive but uses LEDs
 - Blink IDs, no marker swap
 - Number of markers trades off w/ frame rate



Phoenix Technology



Phase Space

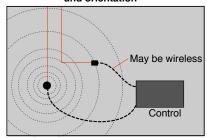
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Capture Equipment

- Magnetic Capture Equipment
 - Transmitter emits field
 - Trackers selviaginetic Trackers
 - Trackers reportansmittien emits milentation

Trackers sense field

Trackers report location and orientation





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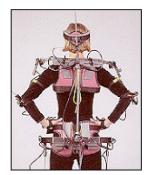
Capture Equipment

- Electromagnetic Advantages
- 6 DOF data
- No occlusions
- · Less post processing
- Cheaper than optical
- Disadvantages
- Cables
- Problems with metal objects
- Low(er) frequency
- Limited range
- Limited number of trackers

Capture Equipment

• Electromechanical





Analogus

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Capture Equipment

Puppets



Digital Image Design

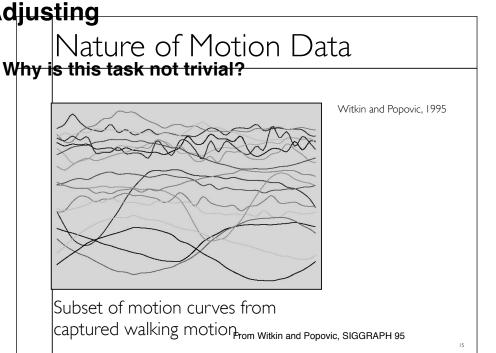
Performance Capture

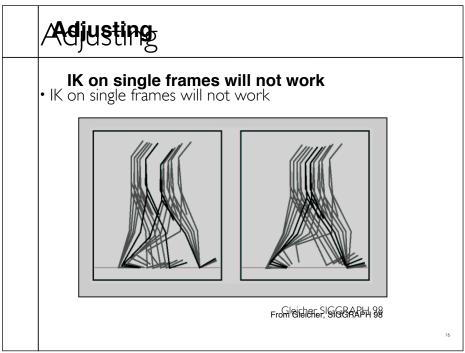
- Many studios regard *Motion* Capture as evil
 - Synonymous with low quality motion
 - No directive / creative control
 - Cheap
- · Performance Capture is different
- Use mocap device as an expressive input device
- Similar to digital music and MIDI keyboards

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Manipulating Motion Data

- Basic tasks
 - Adjusting
 - Blending
 - Transitioning
 - Retargeting
- Building graphs





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Adjusting

• Rajusting a motion function in parts

Define desired function with

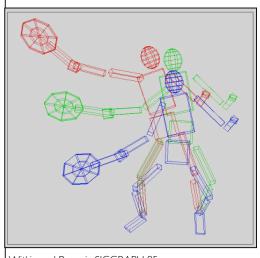
$$oldsymbol{m}(t) = oldsymbol{m}_0(t) + oldsymbol{d}(t)$$
 Adjustment Inital sampled data Result after adjustment

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Adjusting

- Select adjustment function from "some nice space"
 - Example C2 B-splines
- Spread modification over reasonable period of time
- User selects support radius

Adjusting



IK uses control points of the B-spline now

Example:
position racket
fix right foot
fix left toes
balance

Witkin and Popovic SIGGRAPH 95

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Adjusting Witkin and Popovic SIGGRAPH 95 What if adjustment periods overlap?

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Blending,

• Given two motions, can we blend them qualities of both of find a motion 1/2 between them?

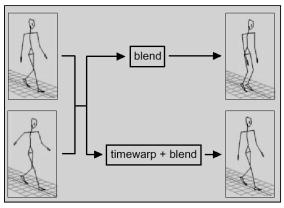
$$\boldsymbol{m}_{\alpha}(t) = \alpha \boldsymbol{m}_{a}(t) + (1 - \alpha) \boldsymbol{m}_{b}(t)$$

- Assumassume same DOFs
- · Assumassume parameter mappings

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Blending

• Consider blending slow-walk and fast-walk

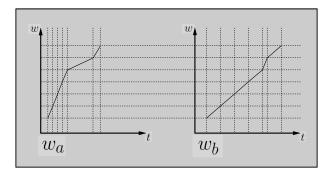


Bruderlin and Williams, SIGGRAPH 95

Blending

• Defin**Blending** functions to align features in motion

Define timewarp functions



Normalized time is w

Blenging Blending

Blend in normalized time
 Blend in normalized time
 Blend in normalized time

$$\boldsymbol{m}_{\alpha}(w) = \alpha \boldsymbol{m}_{a}(w_{a}) + (1-\alpha)\boldsymbol{m}_{b}(w_{b})$$

Blend playback rate

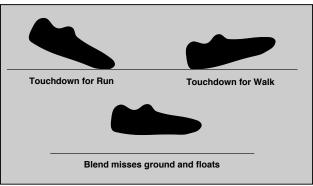
• Blend Blend playback rate

$$\frac{\mathrm{d}t}{\mathrm{d}w} = \alpha \frac{\mathrm{d}t}{\mathrm{d}w_a} + (1 - \alpha)\alpha \frac{\mathrm{d}t}{\mathrm{d}w_b}$$

Blending

• Blending may still break features in original motions

Blending may still break "features" in original motions

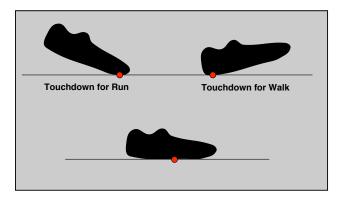


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Blending

- Add **Biending**
- Enforce with IK over time

Add explicit constraints to key points



Blending / Adjustment

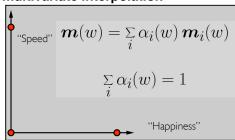
- Short edits will tend to look acceptable
- Longer ones will often exhibit problems
- Optimize to improve blends / adjustments
- · Add quality metric on adjustment
- Minimize accelerations / torques
- Explicit smoothness constraints
- Other criteria...

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Multivariate Blending

Blending

• Extend blending to multivariate interpolation **Extend to multivariate interpolation**



Weights are now barycentric coordiantes

Multivariate Blending

Blending

• Extend blending to multivariate interpolation **Extend to multivariate interpolation**



Becomes standard interpolation problem...Use standard scattered-data

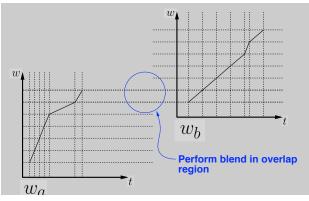
Use standard scattered-data interpolation methods

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Transitions

• Transition from one motion to another

Transition from motion A to motion B



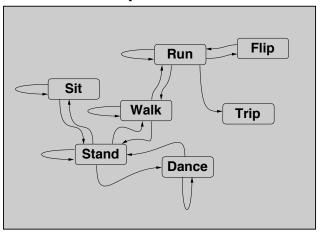
Cyclification

- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

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Transition Graphs

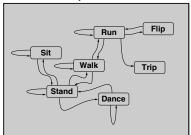
Transition Graphs



Motion Graphs

- Hand build motion graphs often used in games
 - Significant amount of work required
 - Limited transitions by design
- Motion graphs can also be built automatically

Transition Graphs

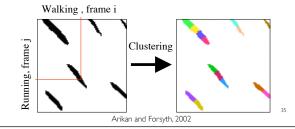


Motion Graphs

- Similarity metric
 - Measurement of how similar two frames of motion are
 - Based on joint angles or point positions
 - Must include some measure of velocity
 - Ideally independent of capture setup and skeleton
- Capture a "large" database of motions

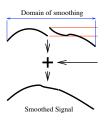
Motion Graphs

- Compute similarity metric between all pairs of frames
 - Maybe expensive
 - Preprocessing step
- There may be too many good edges



Motion Graphs

- Random walks
 - Start in some part of the graph and randomly make transitions
 - Avoid dead ends
 - Useful for "idling" behaviors
- Transitions
- Use blending algorithm we discussed



Motion graphs

- Match imposed requirements
 - Start at a particular location
 - End at a particular location
 - Pass through particular pose
 - Can be solved using dynamic programing
 - Efficiency issues may require approximate solution
 - Notion of "goodness" of a solution

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Suggested Reading

- Fourier principles for emotion-based human figure animation, Unuma, Anjyo, and Takeuchi, SIGGRAPH 95
- Motion signal processing, Bruderlin and Williams, SIGGRAPH 95
- Motion warping, Witkin and Popovic, SIGGRAPH 95
- Efficient generation of motion transitions using spacetime constrains, Rose et al., SIGGRAPH 96
- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Verbs and adverbs: Multidimensional motion interpolation, Rose, Cohen, and Bodenheimer, IEEE: Computer Graphics and Applications, v. 18, no. 5, 1998

Suggested Reading

- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Footskate Cleanup for Motion Capture Editing, Kovar, Schreiner, and Gleicher, SCA 2002.
- Interactive Motion Generation from Examples, Arikan and Forsyth, SIGGRAPH 2002.
- Motion Synthesis from Annotations, Arikan, Forsyth, and O'Brien, SIGGRAPH 2003.
- Pushing People Around, Arikan, Forsyth, and O'Brien, unpublished.
- Automatic Joint Parameter Estimation from Magnetic Motion Capture Data, O'Brien, Bodenheimer, Brostow, and Hodgins, GI 2000.
- Skeletal Parameter Estimation from Optical Motion Capture Data, Kirk, O'Brien, and Forsyth, CVPR 2005.
- Perception of Human Motion with Different Geometric Models, Hodgins, O'Brien, and Tumblin, IEEE:TVCG 1998.