## **Foundations of Computer Graphics** (Fall 2012)

CS 184, Lecture 10: Curves 2 http://inst.eecs.berkeley.edu/~cs184

## **Outline of Unit**

- Bezier curves (last time)
- deCasteljau algorithm, explicit, matrix (last time)
- Polar form labeling (blossoms)
- B-spline curves
- Not well covered in textbooks (especially as taught here). Main reference will be lecture notes. If you do want a printed ref, handouts from CAGD, Seidel

### Idea of Blossoms/Polar Forms

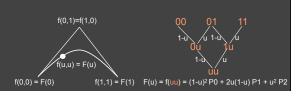
- (Optional) Labeling trick for control points and intermediate deCasteljau points that makes thing intuitive
- E.g. quadratic Bezier curve F(u)
  - Define auxiliary function  $f(u_1, u_2)$  [number of args = degree]

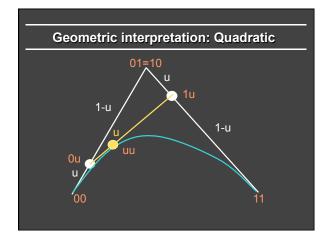
  - Points on curve simply have  $u_1=u_2$  so that F(u)=f(u,u)And we can label control points and deCasteljau points not on curve with appropriate values of (u<sub>1</sub>,u<sub>2</sub>)

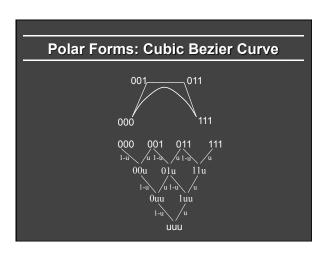


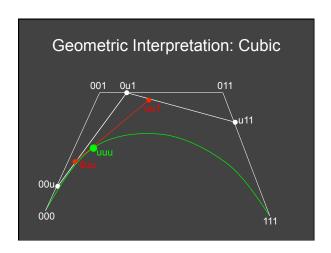
## Idea of Blossoms/Polar Forms

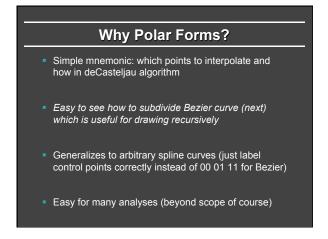
- Points on curve simply have  $u_1=u_2$  so that F(u)=f(u,u)
- f is symmetric f(0,1) = f(1,0)
- Only interpolate linearly between points with one arg different
   f(0,u) = (1-u) f(0,0) + u f(0,1) Here, interpolate f(0,0) and f(0,1)=f(1,0)

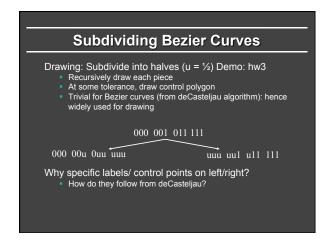


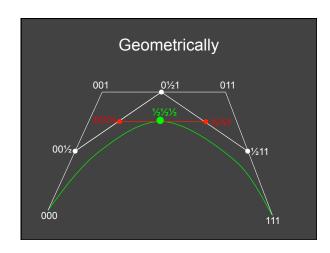


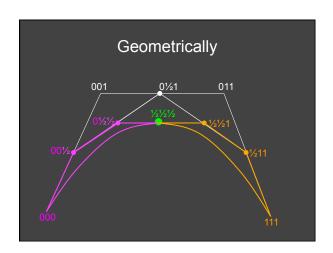


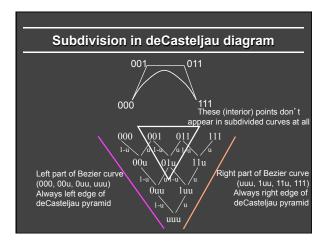












# Summary for HW 3 (with demo)

- Bezier2 (Bezier discussed last time)
- Given arbitrary degree Bezier curve, recursively subdivide for some levels, then draw control polygon
- Generate deCasteljau diagram; recursively call a routine with left edge and right edge of this diagram
- You are given some code structure; you essentially just need to compute appropriate control points for left, right

### DeCasteljau: Recursive Subdivision

Input: Control points  $C_i$  with  $0 \le i \le n$  where n is the degree. Output:  $L_i$ ,  $R_i$  for left and right control points in recursion. 1 for  $(level = n ; level \ge 0 ; level - -)$  {

```
1 for (level = n ; level \ge 0 ; level - -) {
2 if (level = n) \{ // lnitial control points \}
3 \forall i : 0 \le i \le n : p_i^{level} = C_i ; continue ; \}
4 for (i = 0 ; i \le level ; i + +)
5 p_i^{level} = \frac{1}{2} * (p_i^{level+1} + p_{i+1}^{level+1}) ;
6 }
7 \forall i : 0 \le i \le n : L_i = r^i : R_i = r^i : R_i
```

- DeCasteljau (from last lecture) for midpoint
- Followed by recursive calls using left, right parts

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## Bezier: Disadvantages

- Single piece, no local control (move a control point, whole curve changes) [Demo of HW 3]
- Complex shapes: can be very high degree, difficult
- In practice, combine many Bezier curve segments
  - But only position continuous at join since Bezier curves interpolate end-points (which match at segment boundaries)
  - Unpleasant derivative (slope) discontinuities at end-points
  - Can you see why this is an issue?

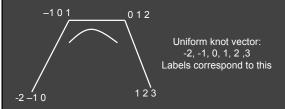
#### **B-Splines**

- Cubic B-splines have C<sup>2</sup> continuity, local control
- 4 segments / control point, 4 control points/ segment
- Knots where two segments join: Knotvector
- Knotvector uniform/non-uniform (we only consider uniform cubic B-splines, not general NURBS)



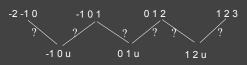
#### **Polar Forms: Cubic Bspline Curve**

- Labeling little different from in Bezier curve
- No interpolation of end-points like in Bezier
- Advantage of polar forms: easy to generalize



# deCasteljau: Cubic B-Splines

- Easy to generalize using −1 0 ½ polar-form labels
- Impossible remember without



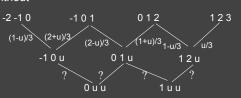
-2 –1 0

123

123

# deCasteljau: Cubic B-Splines

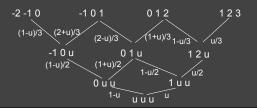
- Easy to generalize using -10 } polar-form labels
- Impossible remember without



123

# deCasteljau: Cubic B-Splines

- Easy to generalize using polar-form labels
- Impossible remember without



-2 –1 0

## **Explicit Formula (derive as exercise)**

$$F(u) = [u^{3} u^{2} u \, 1] M \begin{bmatrix} P0 \\ P1 \\ P2 \\ P3 \end{bmatrix} M = \frac{1}{6} \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{c} P0 \\ -2 - 1 \, 0 \\ -1 \, 0 \, 1 \\ \end{array} \begin{array}{c} P1 \\ P2 \\ -2 - 1 \, 0 \\ \end{array} \begin{array}{c} P3 \\ -1 \, 0 \, 1 \\ \end{array} \begin{array}{c} P2 \\ 0 \, 1 \, 2 \\ \end{array} \begin{array}{c} P3 \\ 1 \, 23 \\ \end{array}$$

$$\begin{array}{c} -1 \, 0 \, u \\ (1 - u)/2 \\ \end{array} \begin{array}{c} (1 + u)/3 \\ (1 - u)/2 \\ \end{array} \begin{array}{c} (1 + u)/2 \\ 1 - u \, u \, u \, u \end{array} \begin{array}{c} 1 \, u \, u \\ u \, u \, u \, u \end{array}$$

# Summary of HW 3

- BSpline Demo hw3
- Arbitrary number of control points / segments
   Do nothing till 4 control points (see demo)
   Number of segments = # cpts 3
- Segment A will have control pts A,A+1,A+2,A+3
- Evaluate Bspline for each segment using 4 control points (at some number of locations, connect lines)
- Use either deCasteljau algorithm (like Bezier) or explicit form [matrix formula on previous slide]
- Questions?