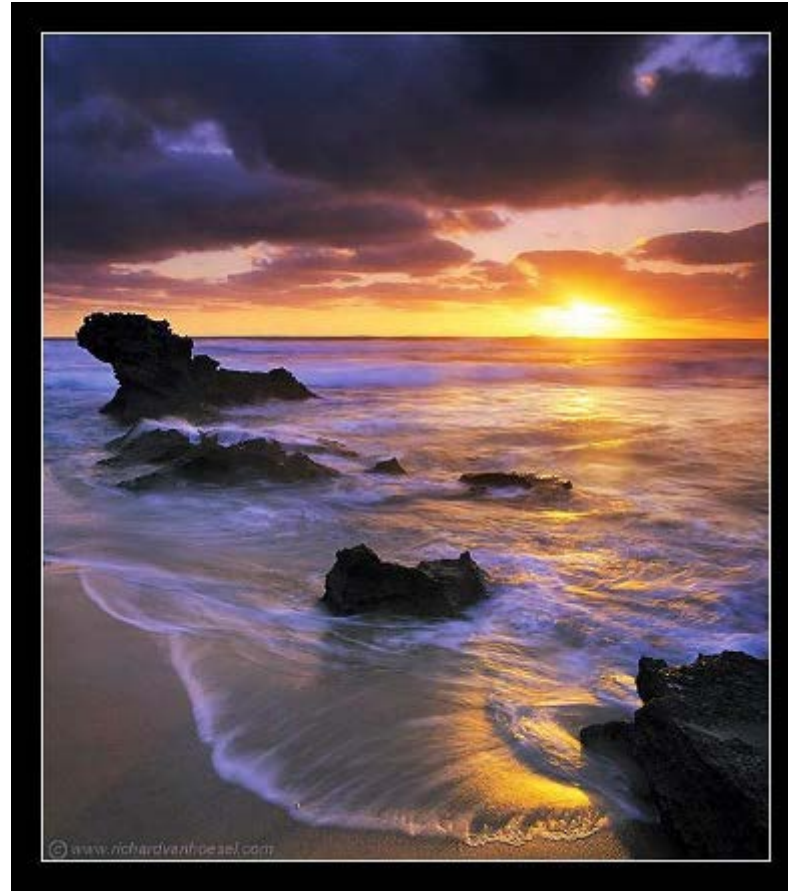


# Capturing Light... in man and machine

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CS194: Image Manipulation & Computational Photography  
Alexei Efros, UC Berkeley, Fall 2014

# Etymology

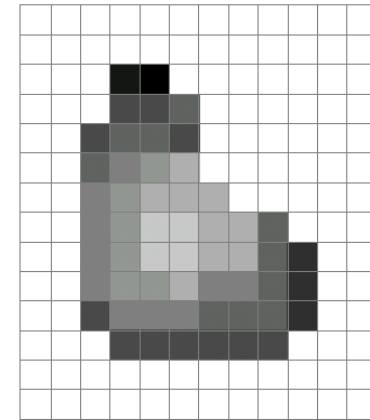
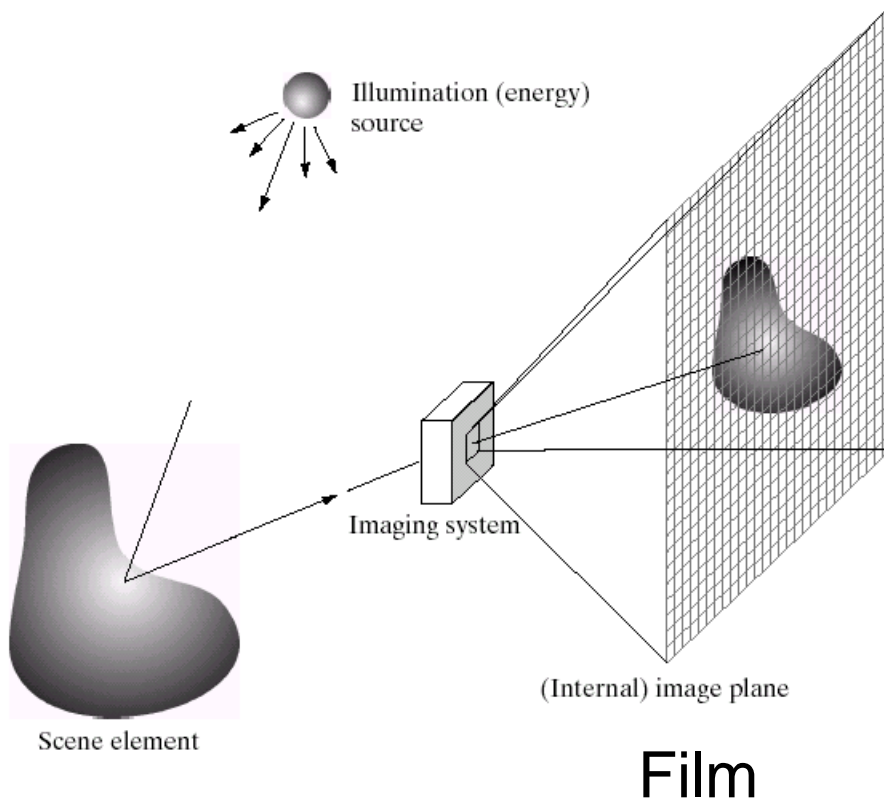
---

PHOTOGRAPHY

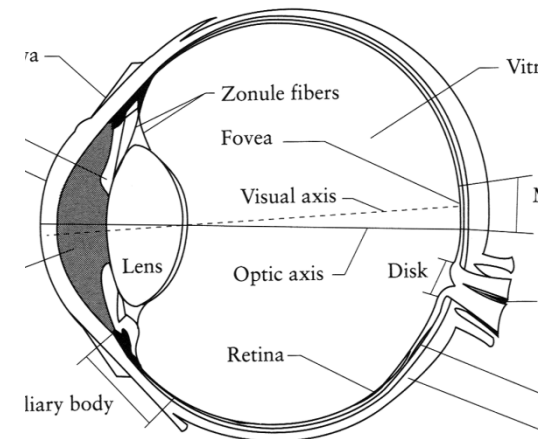
light

drawing  
/ writing

# Image Formation



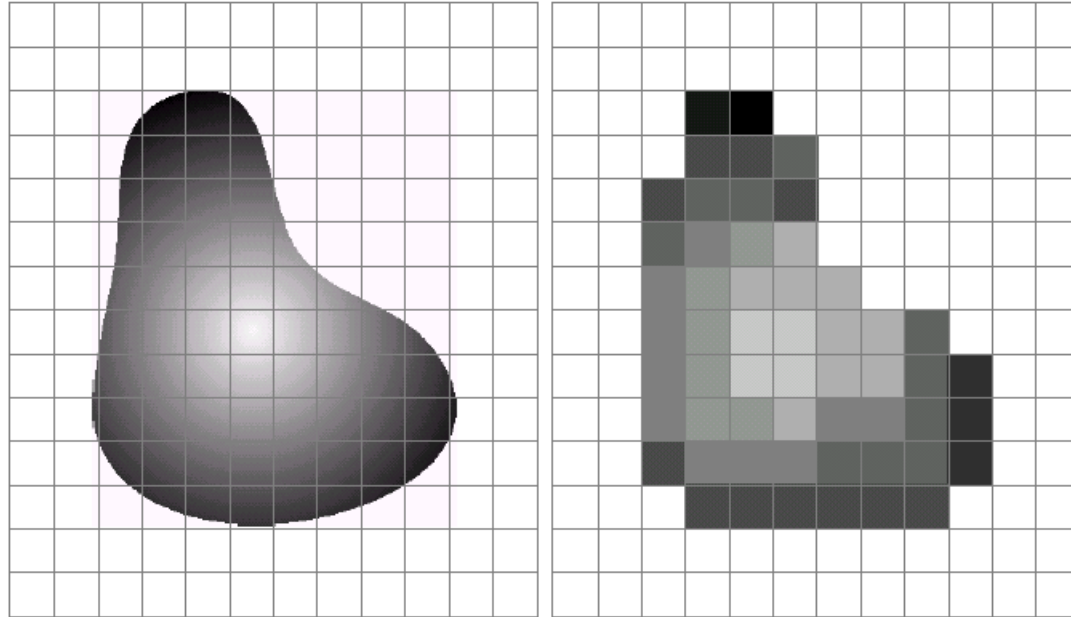
Digital Camera



The Eye

# Sensor Array

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a b

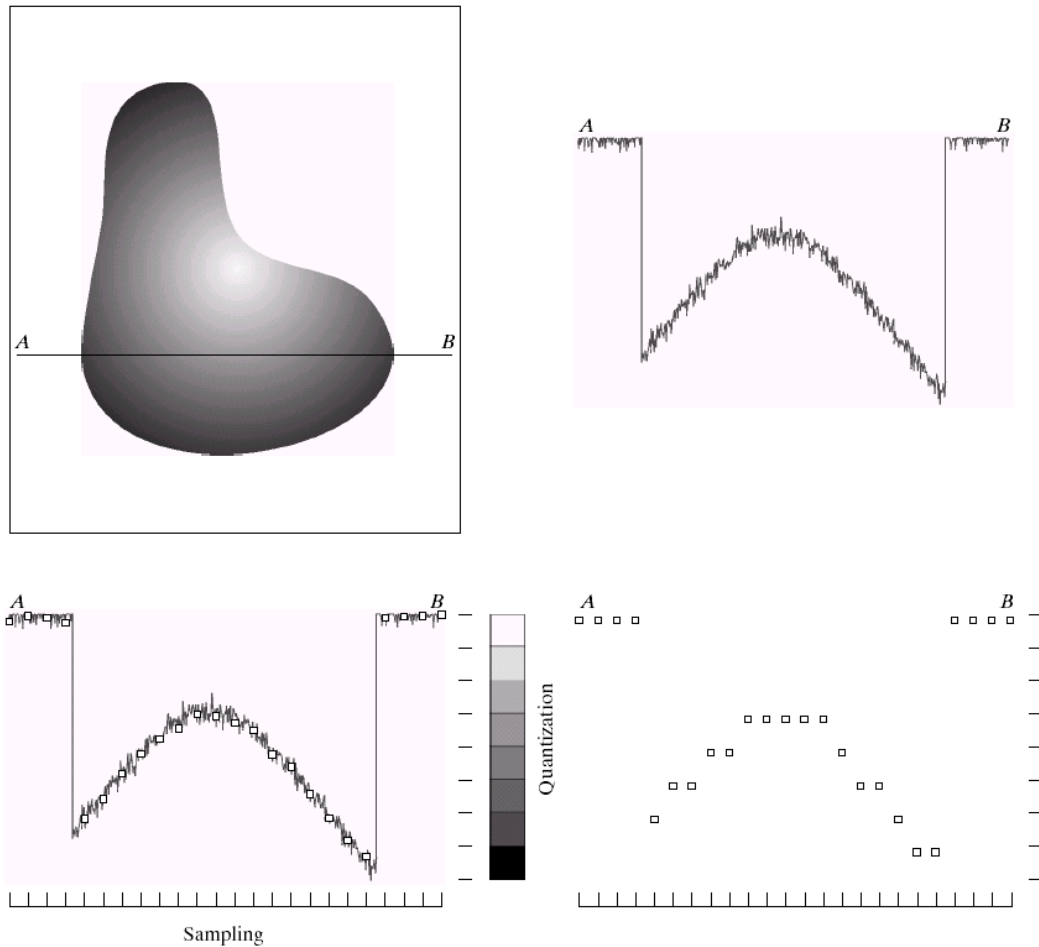
**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.

---



CMOS sensor

# Sampling and Quantization

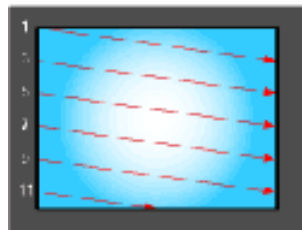


a b  
c d

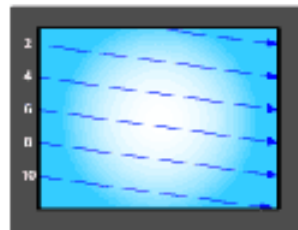
**FIGURE 2.16** Generating a digital image. (a) Continuous image. (b) A scan line from *A* to *B* in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

# Interlace vs. progressive scan

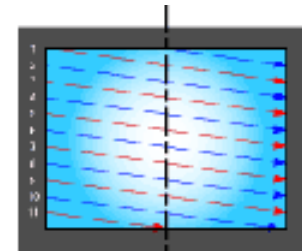
---



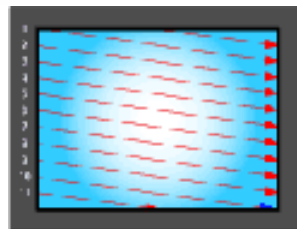
1st field: Odd field



2nd field: Even field



One complete frame  
using interlaced scanning



One complete frame  
using progressive scanning

# Progressive scan

---



# Interlace

---





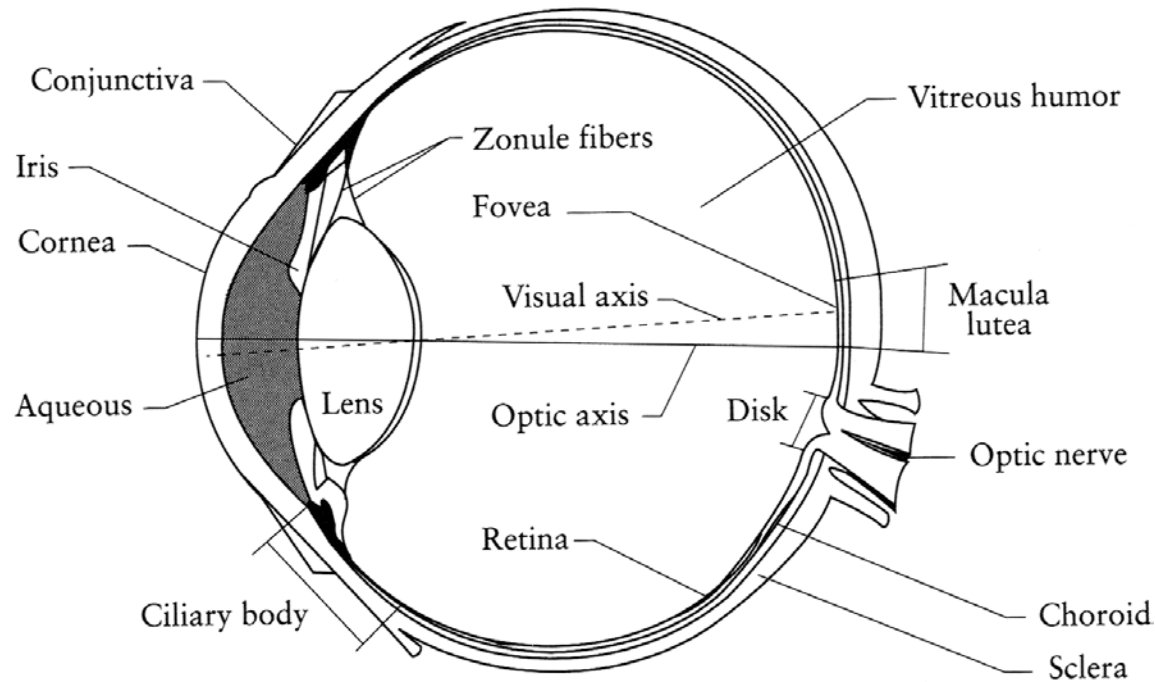
# Rolling Shutter

---



# The Eye

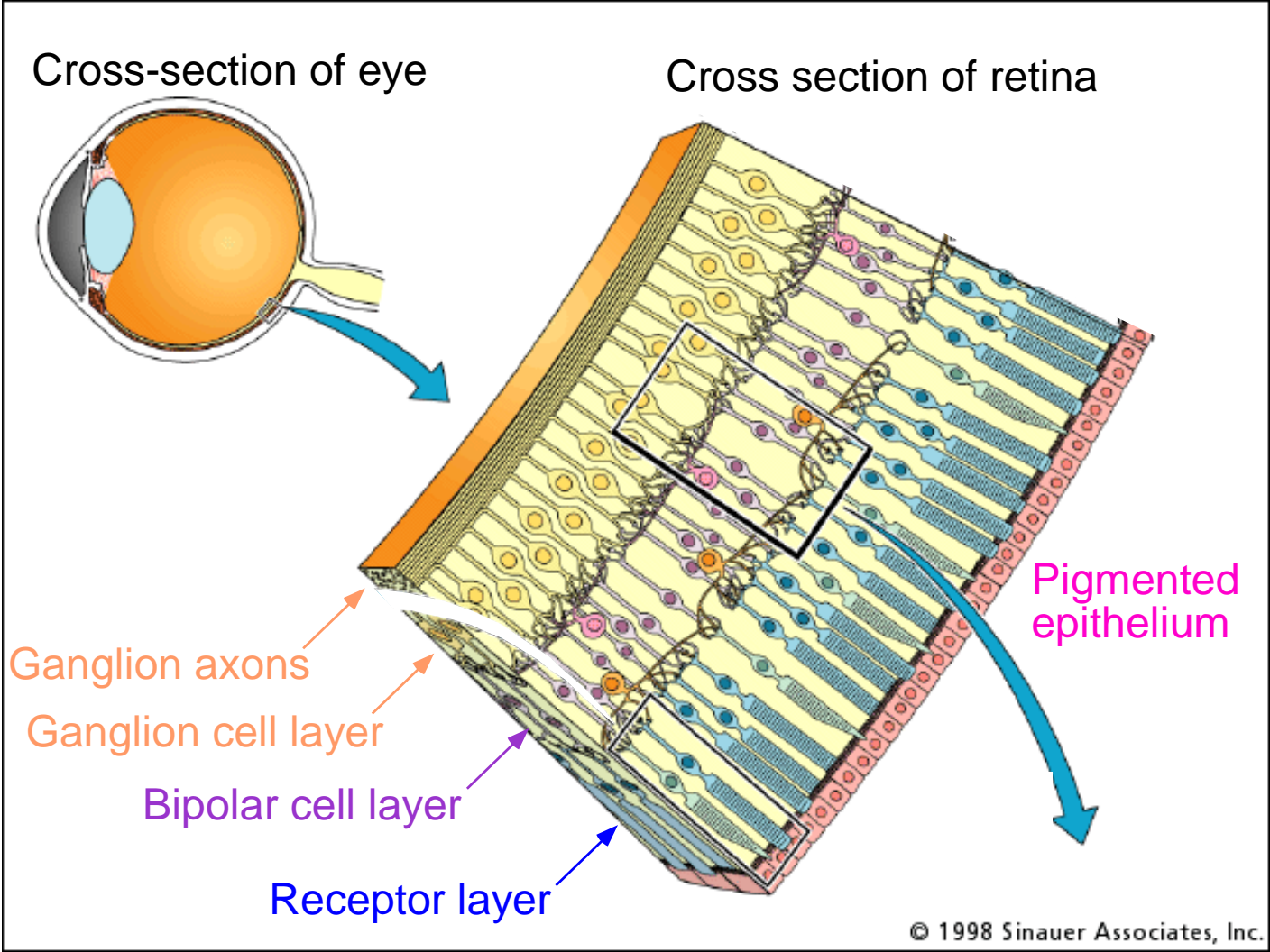
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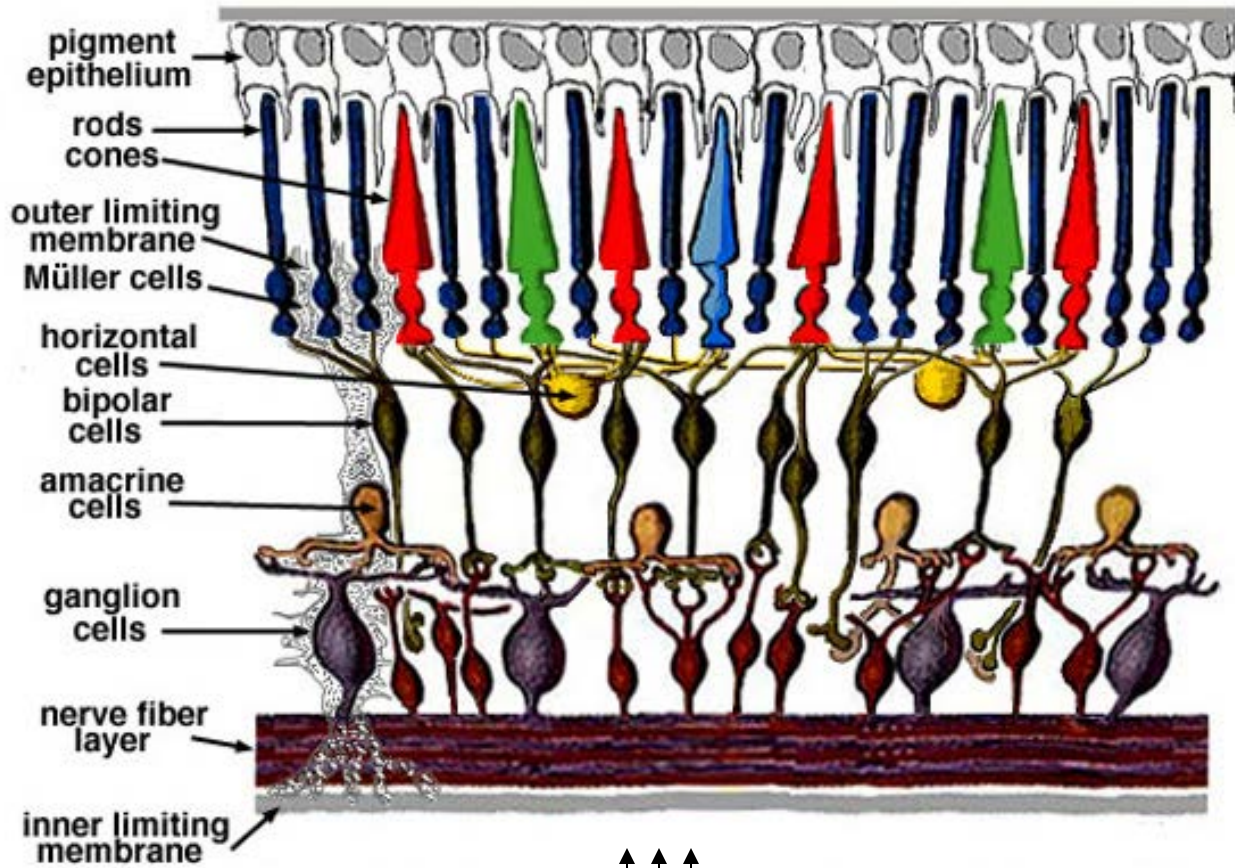
## The human eye is a camera!

- **Iris** - colored annulus with radial muscles
- **Pupil** - the hole (aperture) whose size is controlled by the iris
- What's the "film"?
  - photoreceptor cells (rods and cones) in the **retina**

# The Retina



# Retina up-close



Light

# Two types of light-sensitive receptors

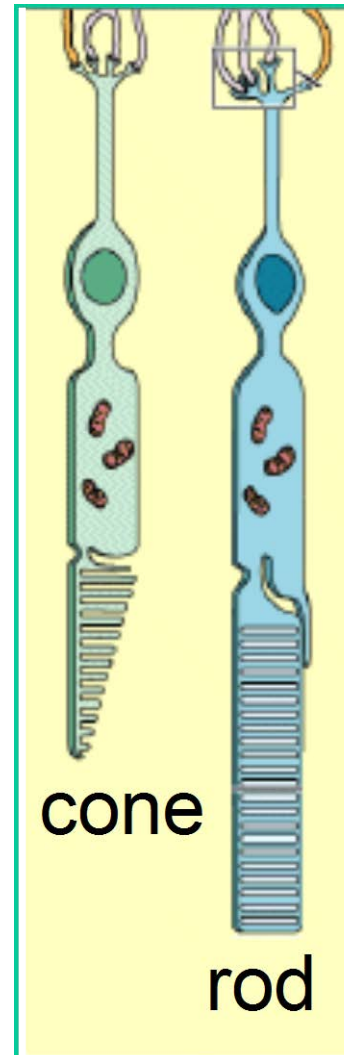
---

## **C**ones

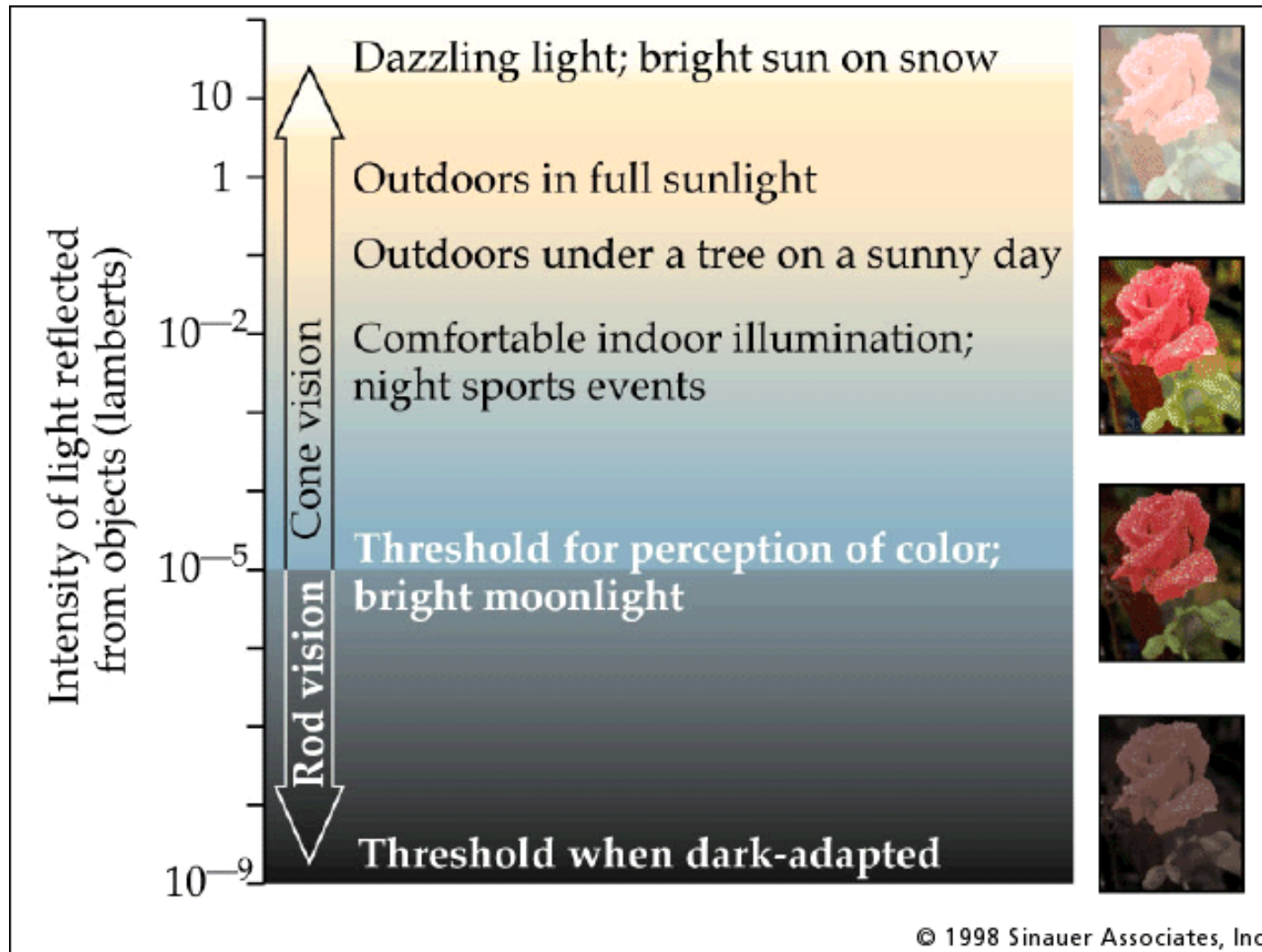
cone-shaped  
less sensitive  
operate in high light  
color vision

## **R**ods

rod-shaped  
highly sensitive  
operate at night  
gray-scale vision



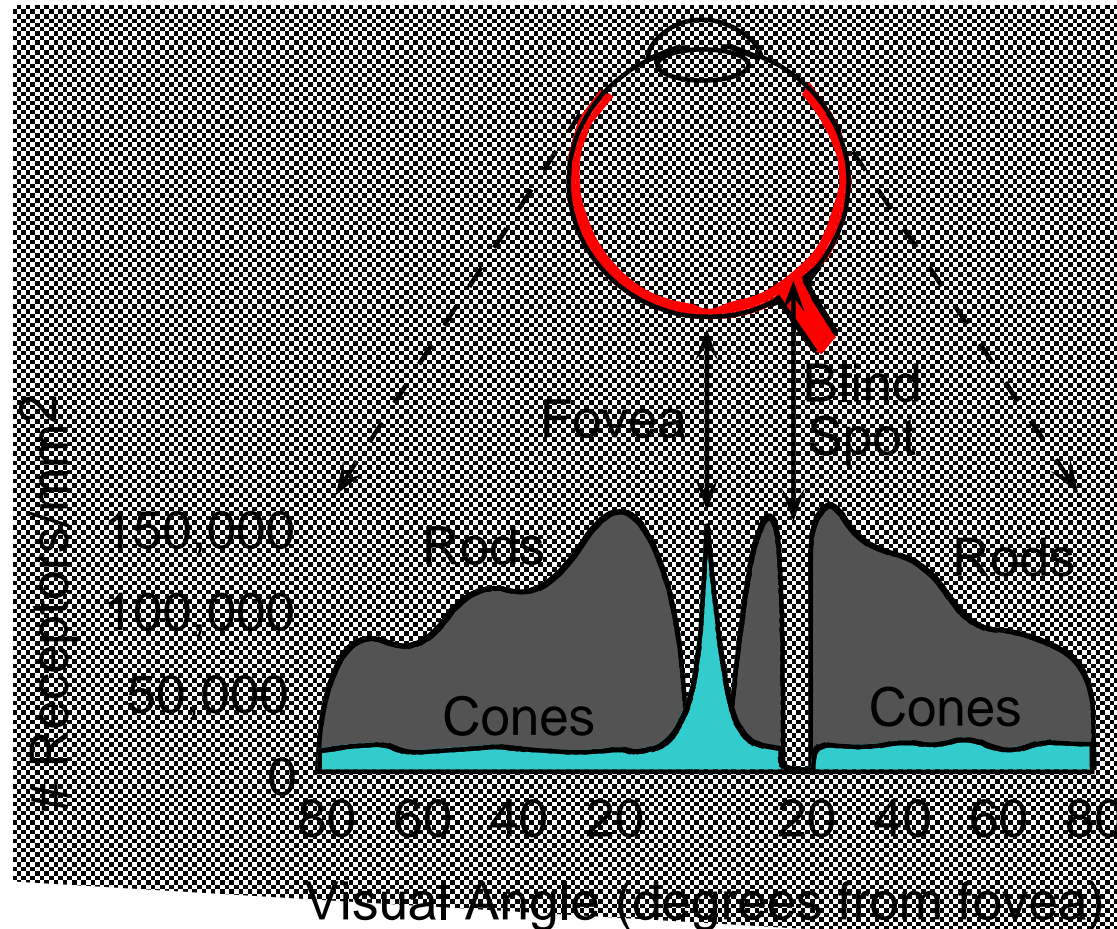
# Rod / Cone sensitivity



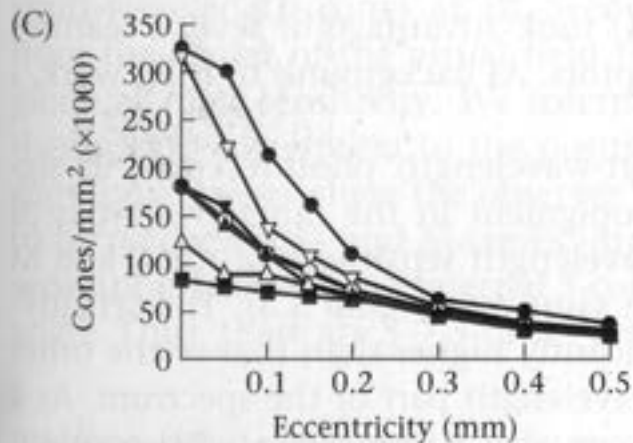
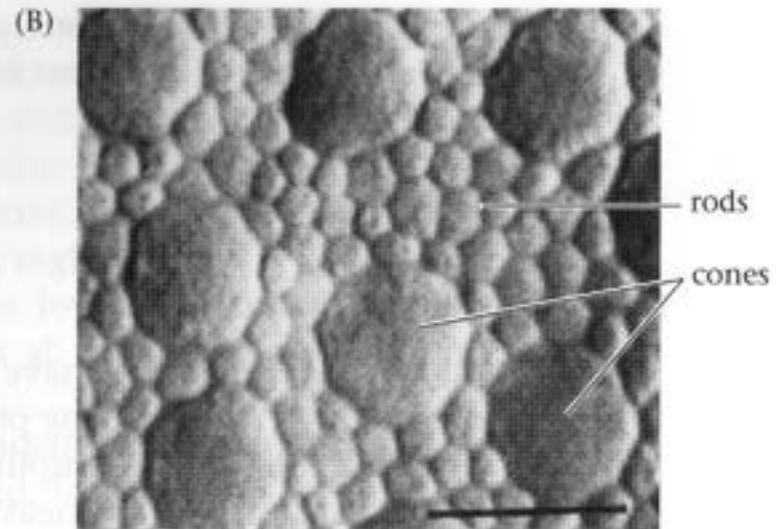
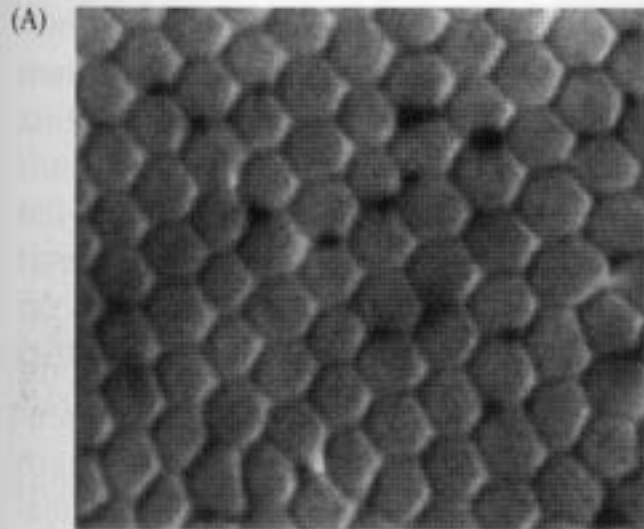
The famous sock-matching problem...

# Distribution of Rods and Cones

---



Night Sky: why are there more stars off-center?

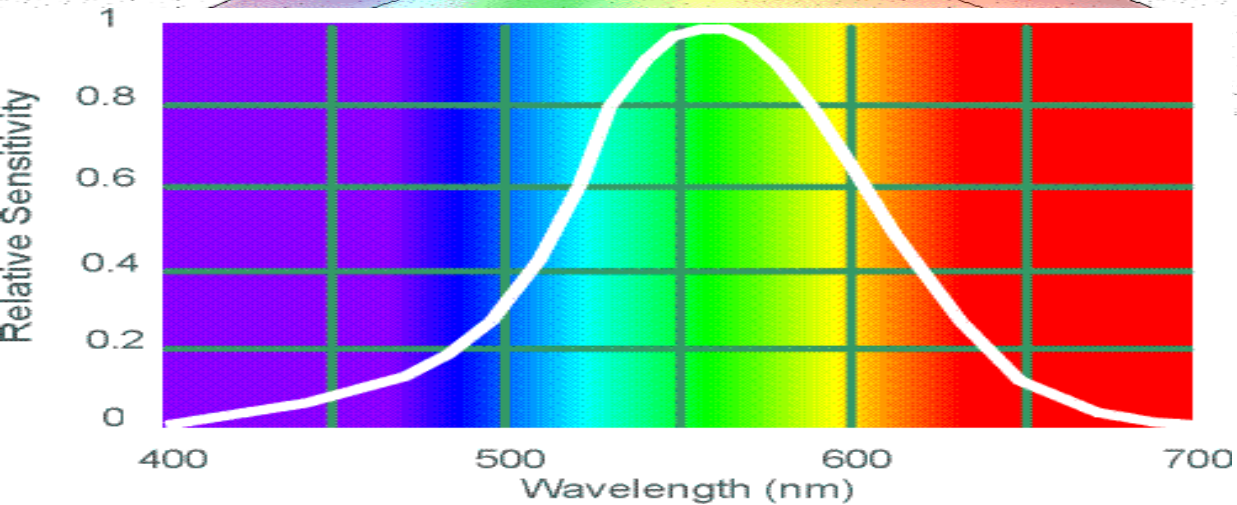
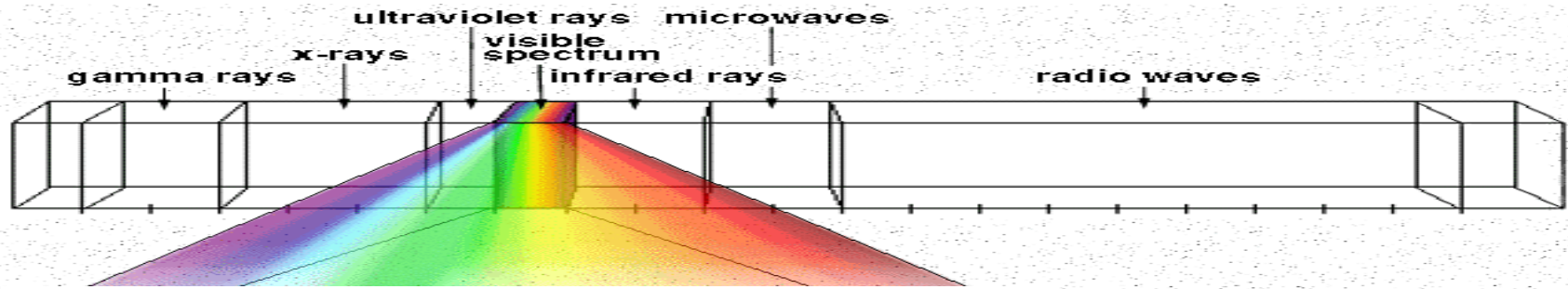


**3.4 THE SPATIAL MOSAIC OF THE HUMAN CONES.** Cross sections of the human retina at the level of the inner segments showing (A) cones in the fovea, and (B) cones in the periphery. Note the size difference (scale bar = 10  $\mu\text{m}$ ), and that, as the separation between cones grows, the rod receptors fill in the spaces. (C) Cone density plotted as a function of distance from the center of the fovea for seven human retinas; cone density decreases with distance from the fovea. Source: Curcio et al., 1990.



# Electromagnetic Spectrum

---

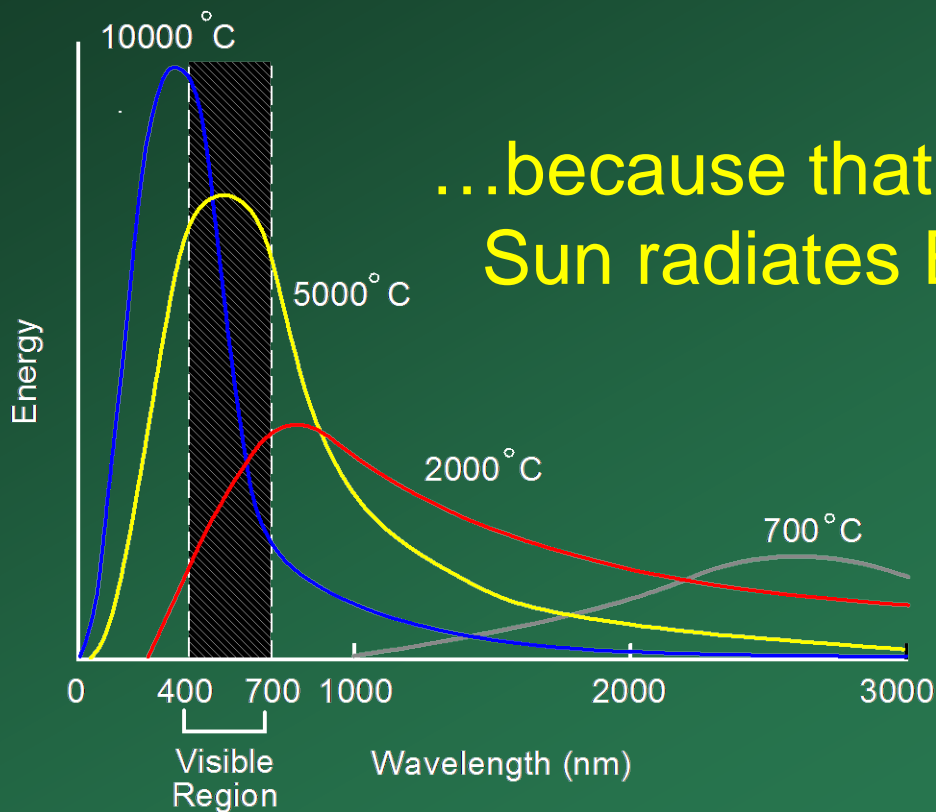


Human Luminance Sensitivity Function

# Visible Light

---

Why do we see light of these wavelengths?

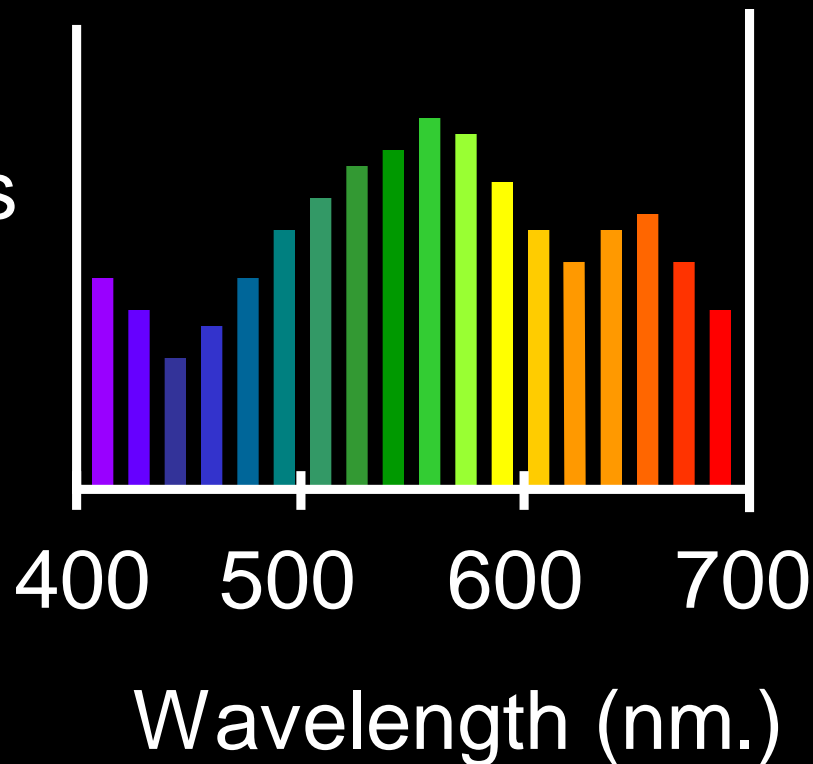


...because that's where the Sun radiates EM energy

# The Physics of Light

Any patch of light can be completely described physically by its spectrum: the number of photons (per time unit) at each wavelength 400 - 700 nm.

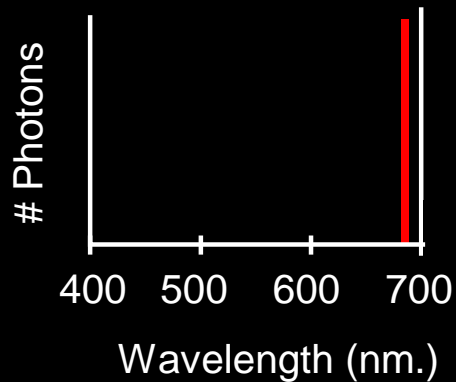
# Photons  
(per ms.)



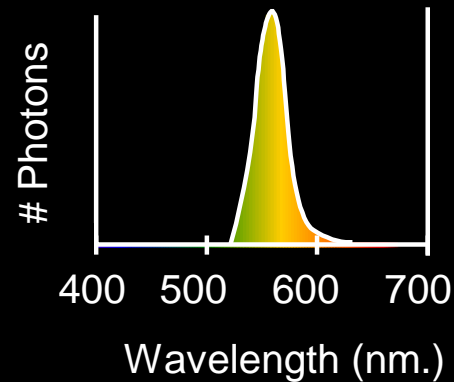
# The Physics of Light

## Some examples of the spectra of light sources

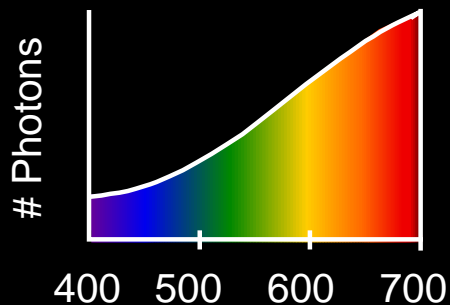
A. Ruby Laser



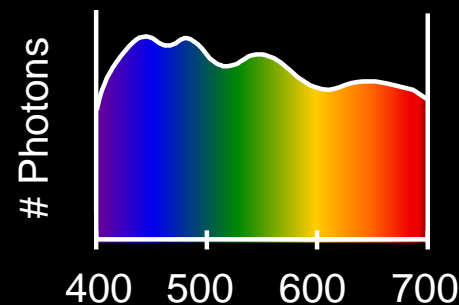
B. Gallium Phosphide Crystal



C. Tungsten Lightbulb



D. Normal Daylight

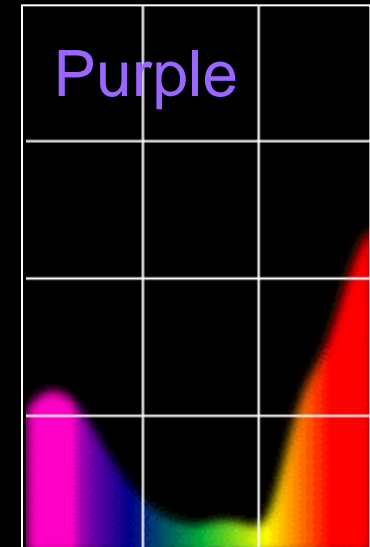
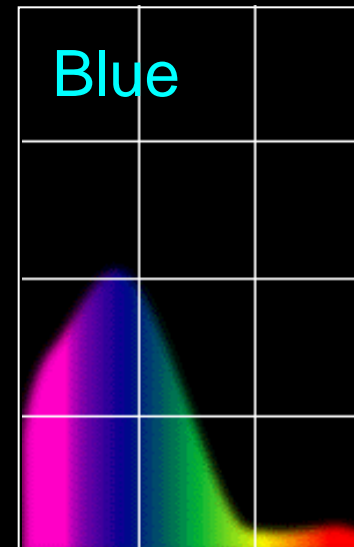
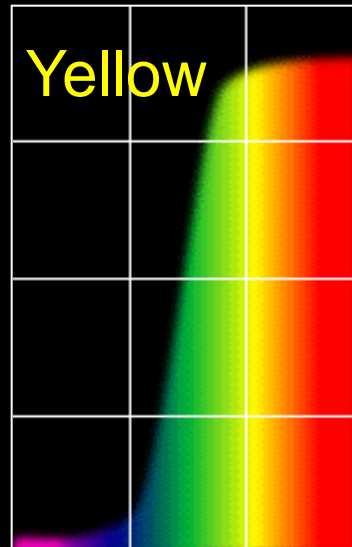
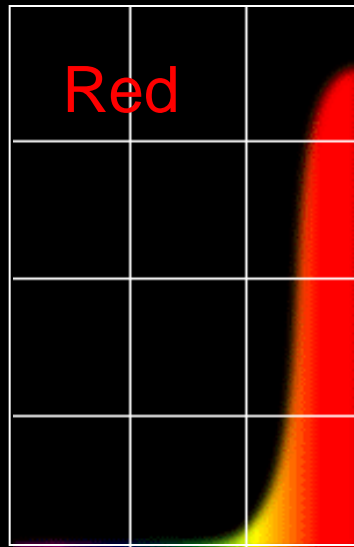


# The Physics of Light

Some examples of the reflectance spectra of surfaces



% Photons Reflected



400

700

400

700

400

700

400

700

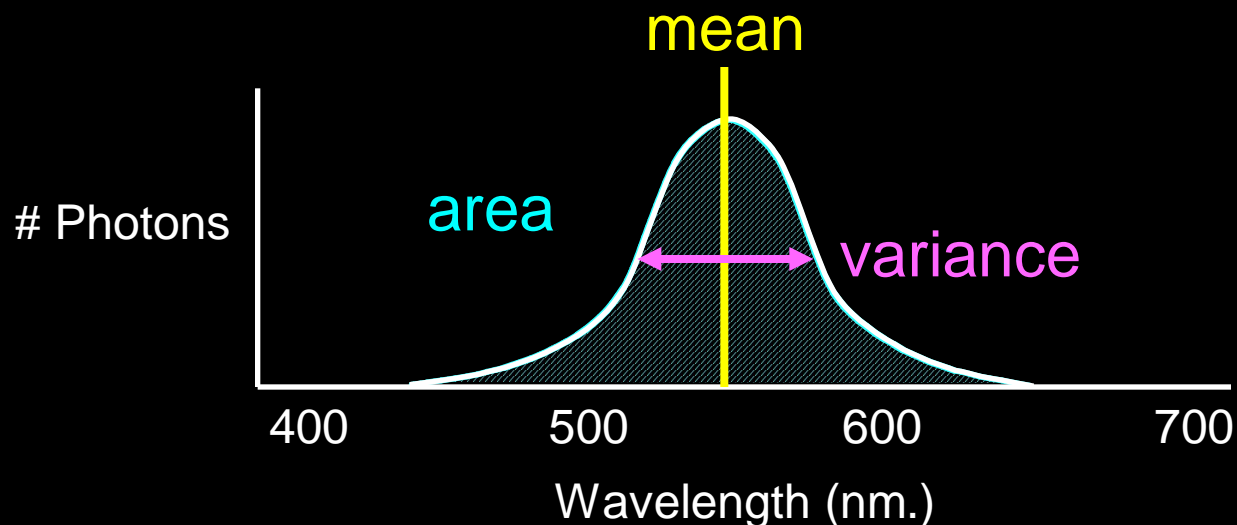
Wavelength (nm)

# The Psychophysical Correspondence

There is no simple functional description for the perceived color of all lights under all viewing conditions, but .....

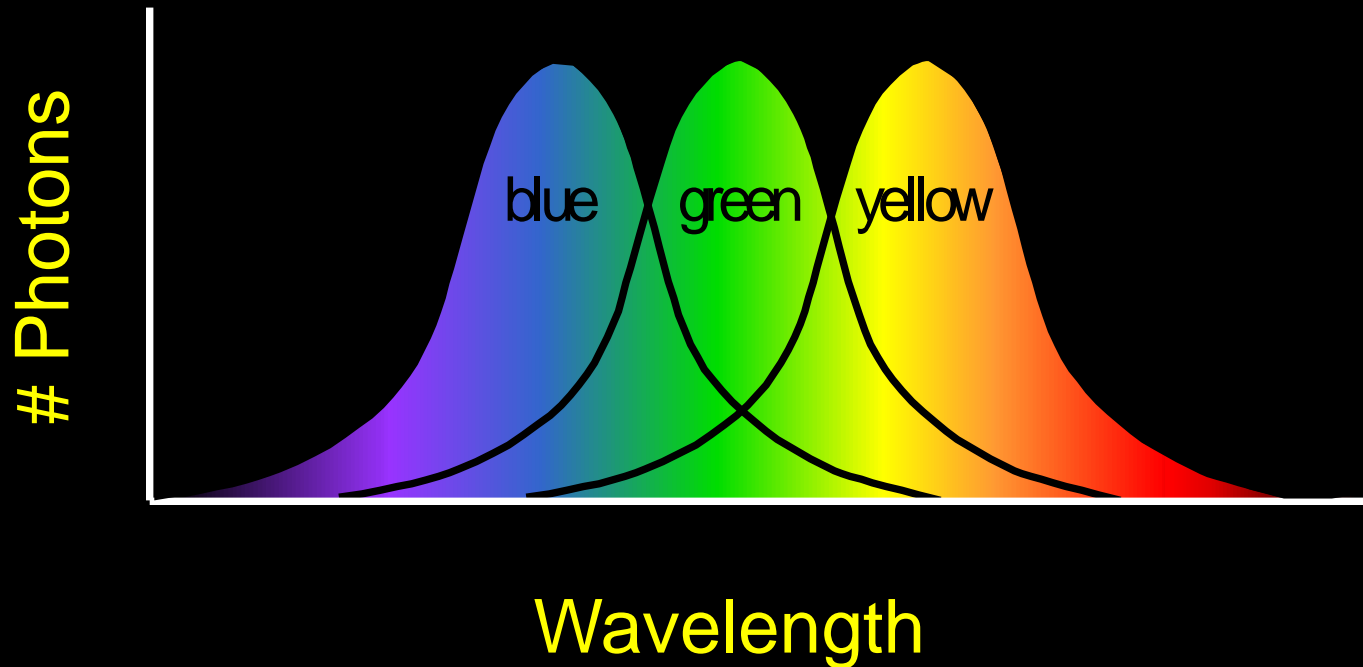
A helpful constraint:

Consider only physical spectra with normal distributions



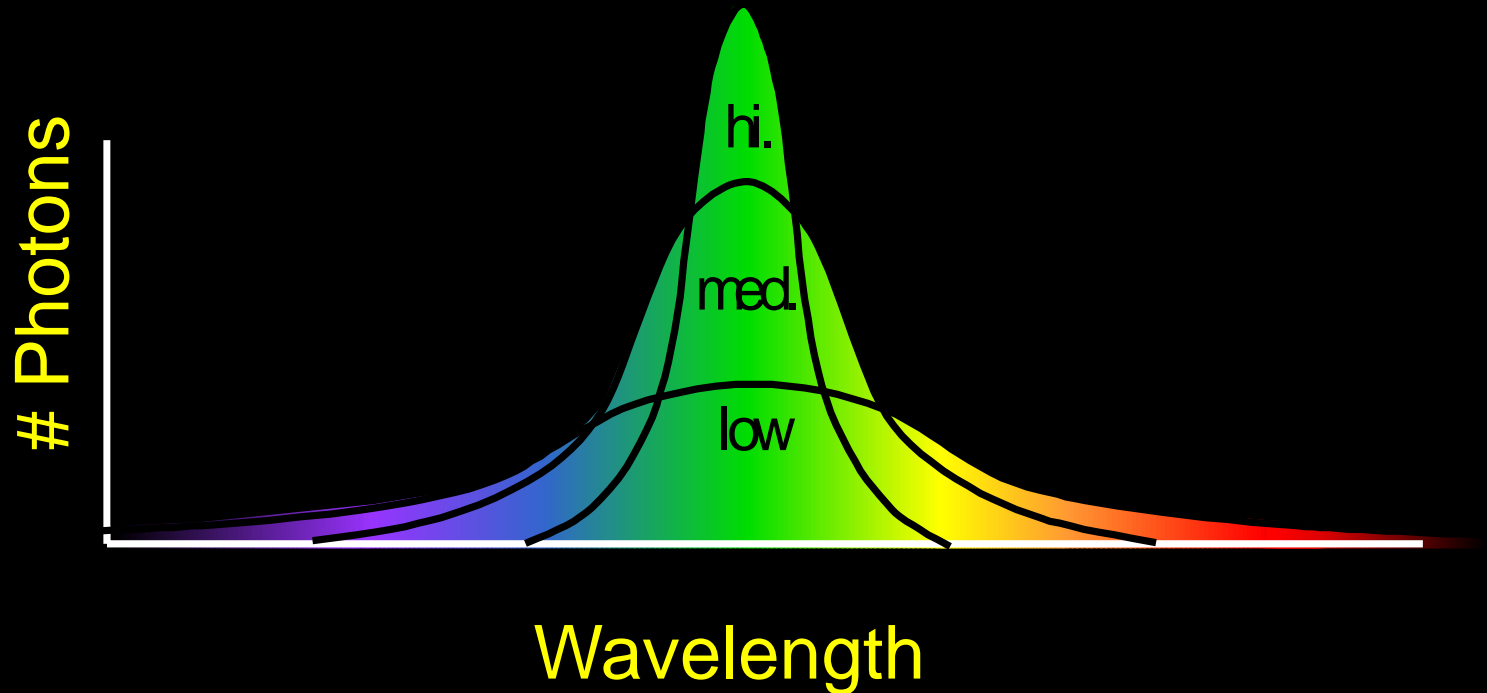
# The Psychophysical Correspondence

Mean ↔ Hue



# The Psychophysical Correspondence

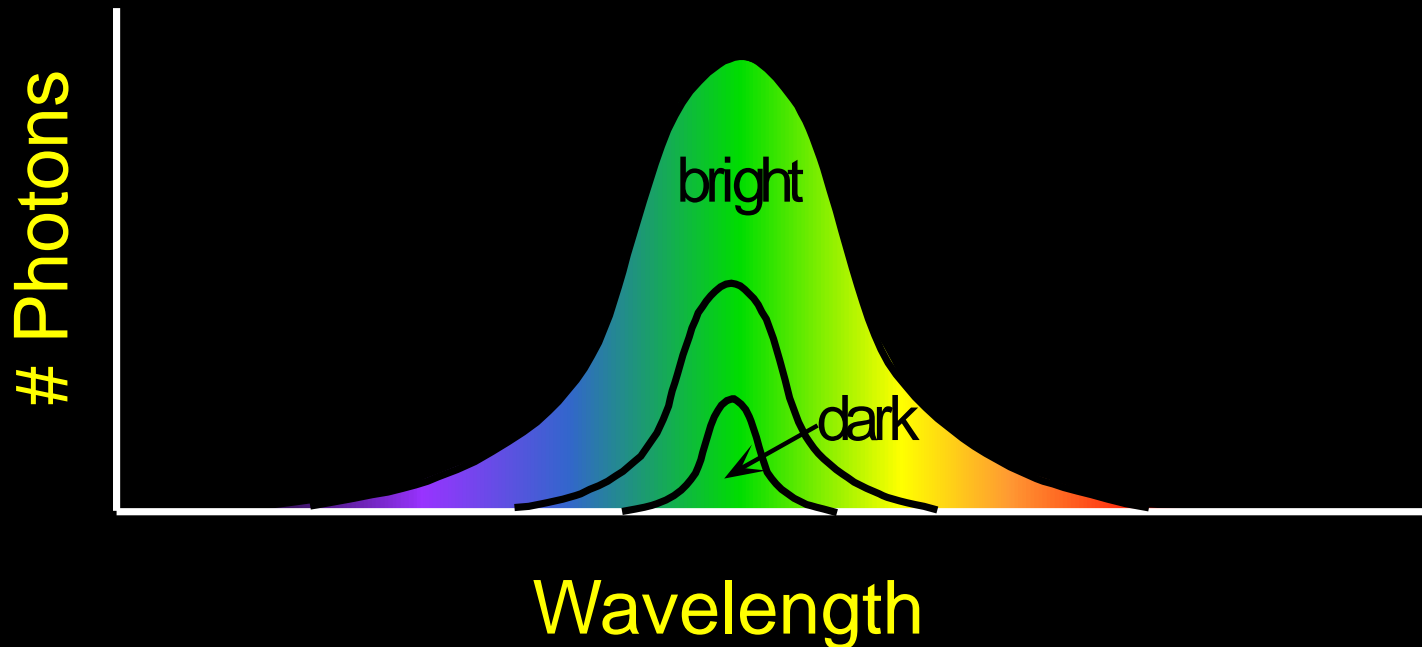
Variance  $\longleftrightarrow$  Saturation





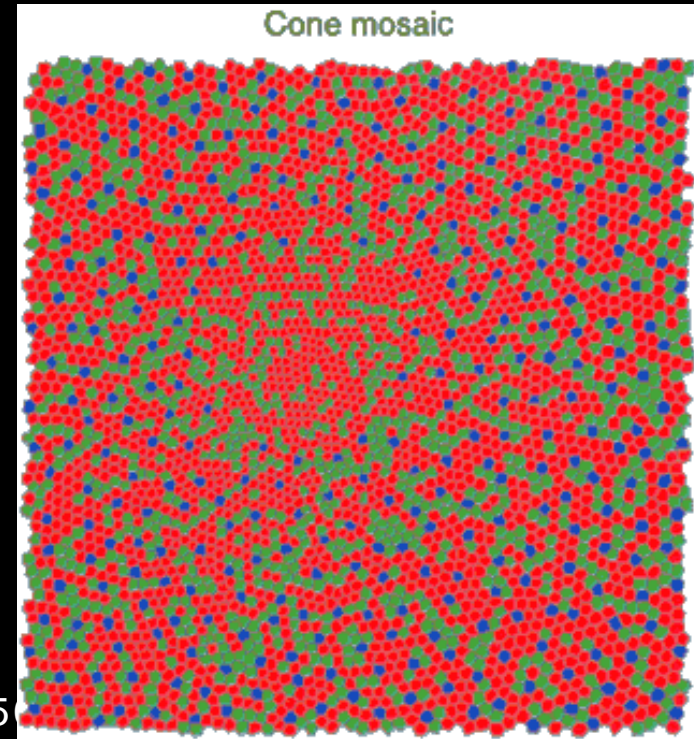
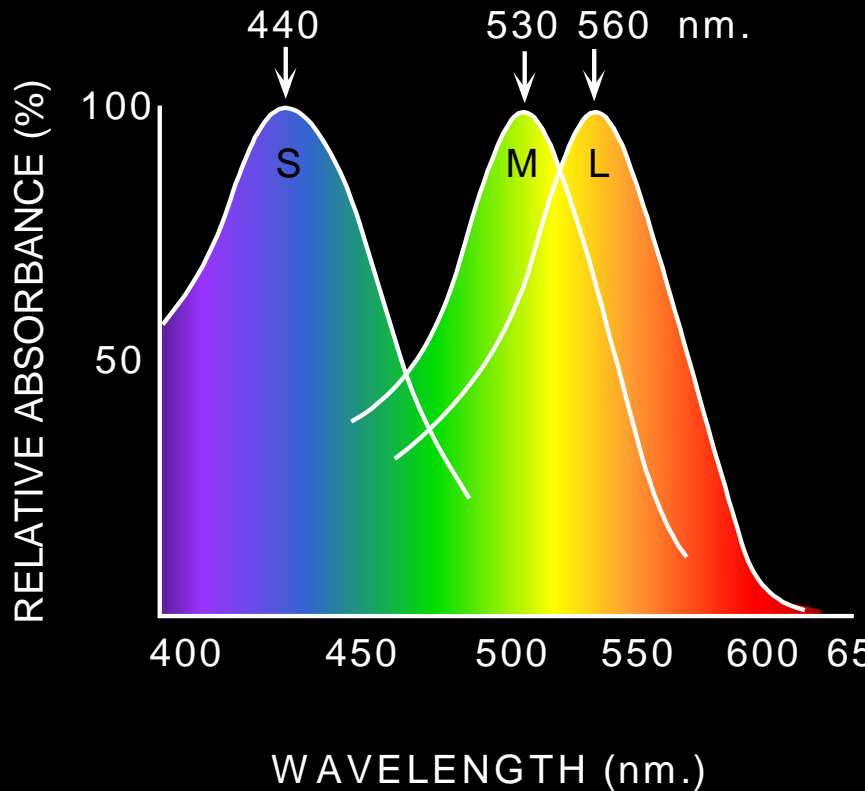
# The Psychophysical Correspondence

Area  $\longleftrightarrow$  Brightness



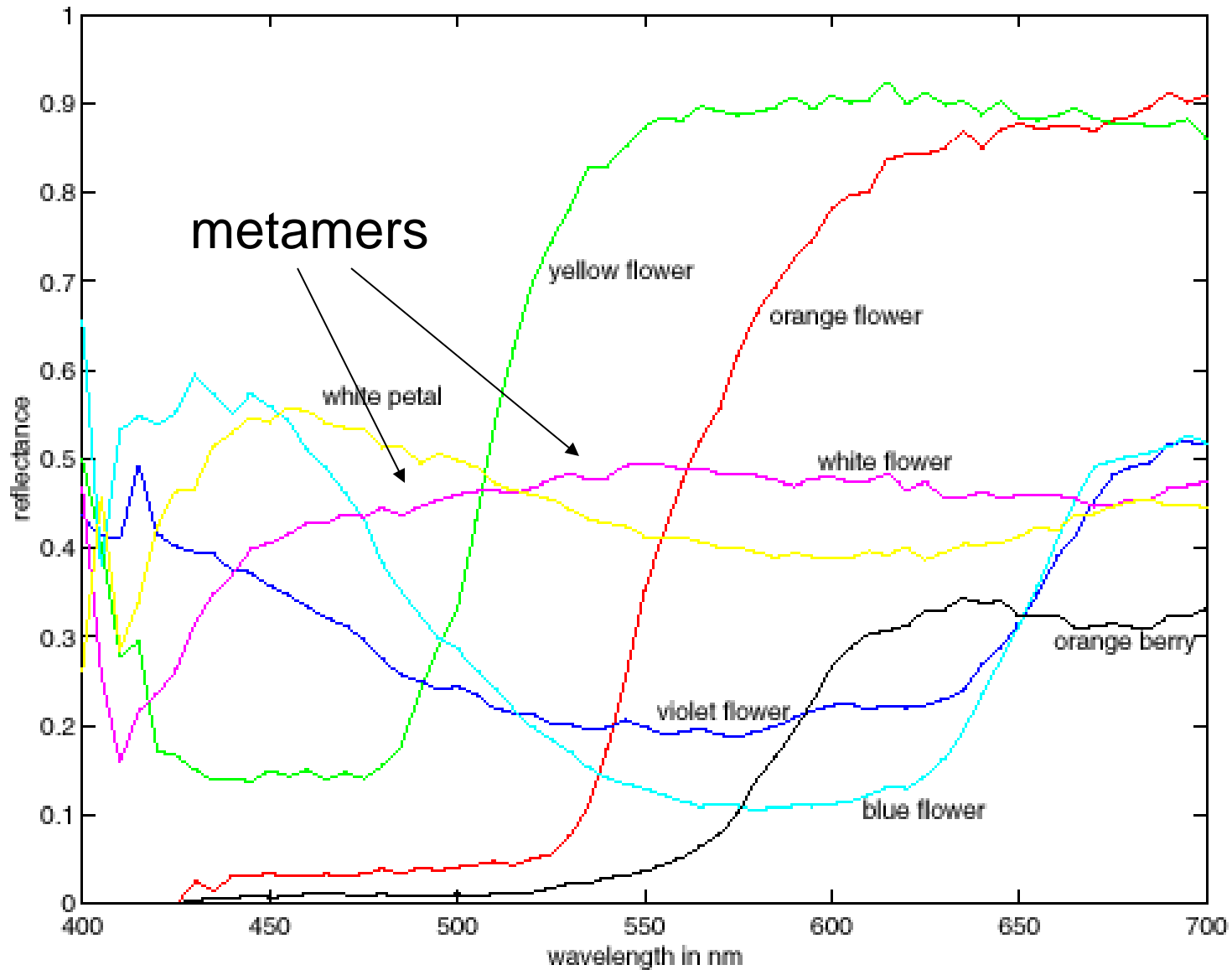
# Physiology of Color Vision

Three kinds of cones:



- Why are M and L cones so close?
- Why are there 3?

# More Spectra



# Color Constancy

The “photometer metaphor” of color perception:  
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

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Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

The “photometer metaphor” of color perception:  
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

~~Do we have constancy over  
all global color transformations?~~



60% blue filter



Complete inversion

# Color Constancy

Color Constancy: the ability to perceive the invariant color of a surface despite ecological Variations in the conditions of observation.

Another of these hard inverse problems:  
Physics of light emission and surface reflection  
underdetermine perception of surface color



# Camera White Balancing

---

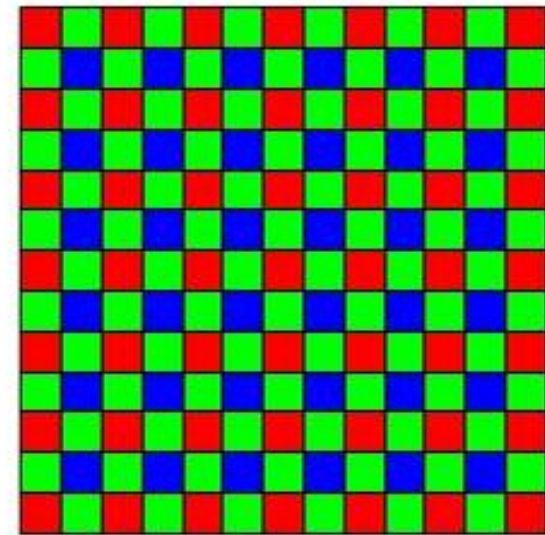
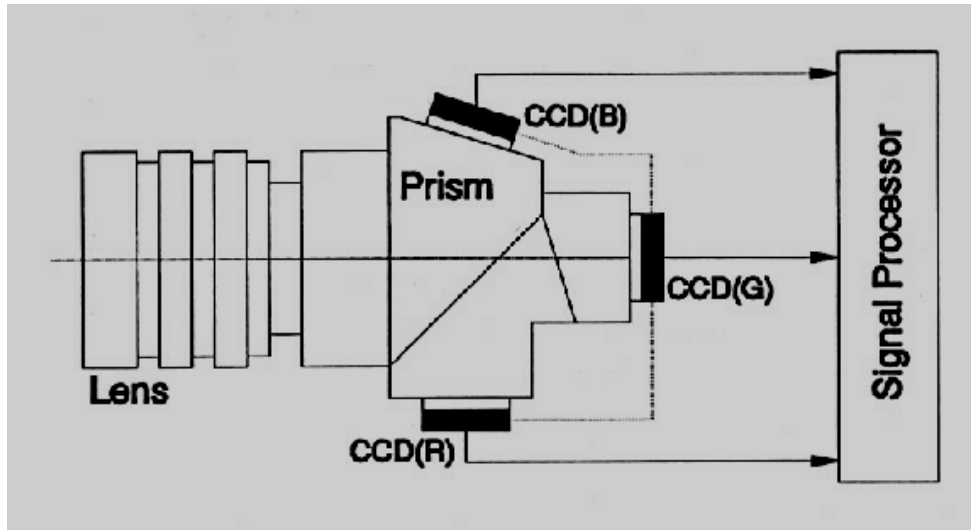
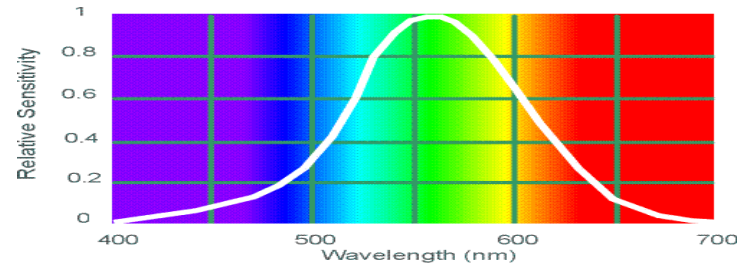


- **Manual**
  - Choose color-neutral object in the photos and normalize
- **Automatic (AWB)**
  - Grey World: force average color of scene to grey
  - White World: force brightest object to white

# Color Sensing in Camera (RGB)

3-chip vs. 1-chip: quality vs. cost

Why more green?



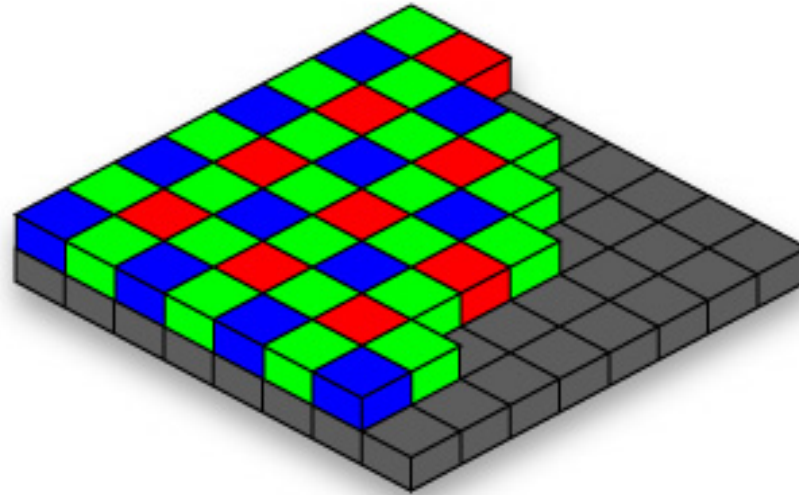
**Bayer filter**

Ruff Works

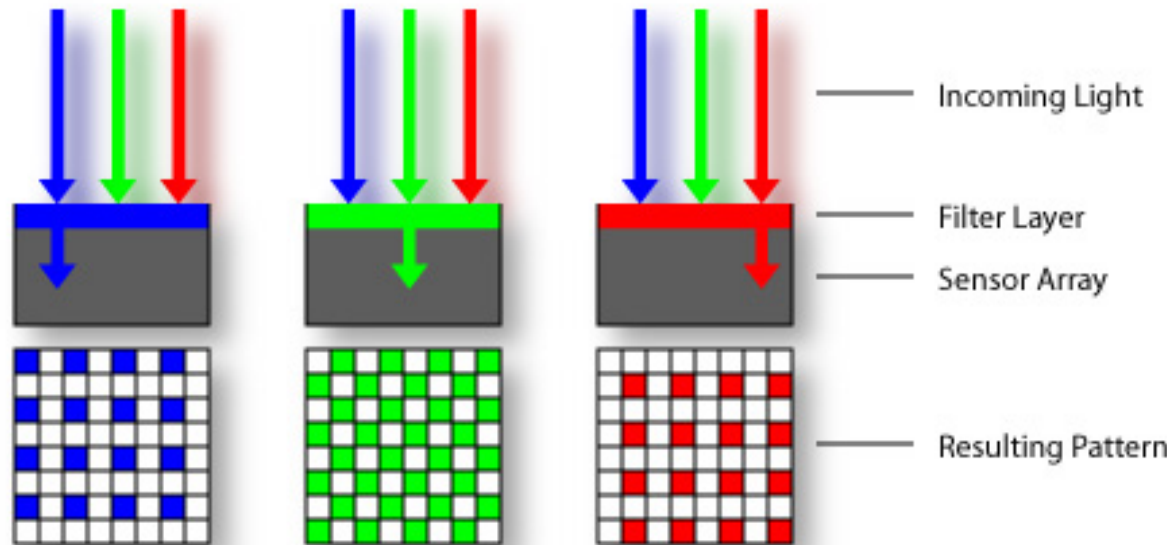
Why 3 colors?

<http://www.cooldictionary.com/words/Bayer-filter.wikipedia>

# Practical Color Sensing: Bayer Grid



Estimate RGB  
at 'G' cels from  
neighboring  
values



[http://www.cooldictionary.com/  
words/Bayer-filter.wikipedia](http://www.cooldictionary.com/words/Bayer-filter.wikipedia)

# Color Image

---

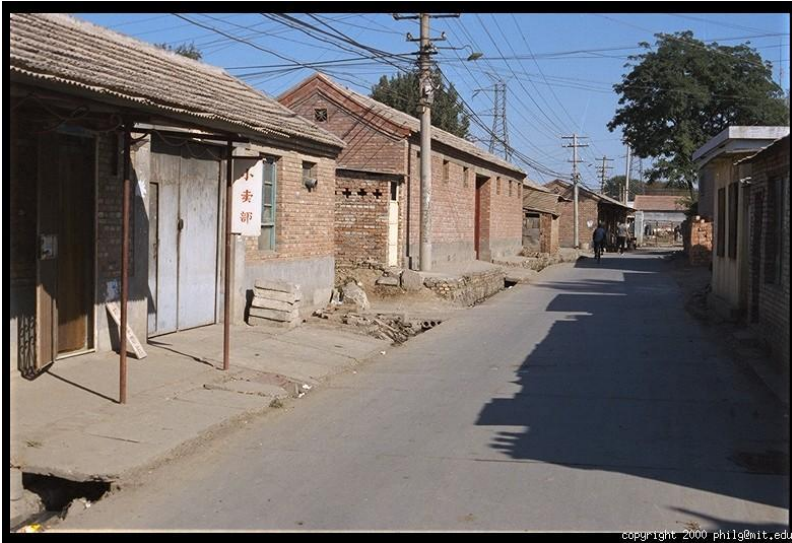
R



G



B



# Images in Matlab

- Images represented as a matrix
- Suppose we have a NxM RGB image called “im”
  - $im(1,1,1)$  = top-left pixel value in R-channel
  - $im(y, x, b)$  = y pixels down, x pixels to right in the b<sup>th</sup> channel
  - $im(N, M, 3)$  = bottom-right pixel in B-channel
- `imread(filename)` returns a uint8 image (values 0 to 255)
  - Convert to double format (values 0 to 1) with `im2double`

The diagram illustrates an RGB image matrix. A large 10x10 grid of numerical values represents the image. A green arrow labeled 'row' points downwards on the left side, and another green arrow labeled 'column' points to the right at the top. To the right of the main grid, three smaller 10x2 grids are shown, labeled 'R', 'G', and 'B', representing the individual color channels. The 'R' channel is the first two columns of the main grid, the 'G' channel is the next two columns, and the 'B' channel is the final two columns. The numerical values in the main grid are as follows:

0.92	0.93	0.94	0.97	0.62	0.37	0.85	0.97	0.93	0.92	0.99
0.95	0.89	0.82	0.89	0.56	0.31	0.75	0.92	0.81	0.95	0.91
0.89	0.72	0.51	0.55	0.51	0.42	0.57	0.41	0.49	0.91	0.92
0.96	0.95	0.88	0.94	0.56	0.46	0.91	0.87	0.90	0.97	0.95
0.71	0.81	0.81	0.87	0.57	0.37	0.80	0.88	0.89	0.79	0.85
0.49	0.62	0.60	0.58	0.50	0.60	0.58	0.50	0.61	0.45	0.33
0.86	0.84	0.74	0.58	0.51	0.39	0.73	0.92	0.91	0.49	0.74
0.96	0.67	0.54	0.85	0.48	0.37	0.88	0.90	0.94	0.82	0.93
0.69	0.49	0.56	0.66	0.43	0.42	0.77	0.73	0.71	0.90	0.99
0.79	0.73	0.90	0.67	0.33	0.61	0.69	0.79	0.73	0.93	0.97
0.91	0.94	0.89	0.49	0.41	0.78	0.78	0.77	0.89	0.99	0.93

The 'R' channel matrix (first two columns) is:

0.92	0.99
0.95	0.91
0.91	0.92
0.97	0.95
0.79	0.85
0.45	0.33
0.49	0.74
0.82	0.93
0.90	0.99
0.93	0.97
0.99	0.93

The 'G' channel matrix (next two columns) is:

0.92	0.99
0.95	0.91
0.51	0.55
0.88	0.94
0.81	0.87
0.60	0.58
0.74	0.58
0.54	0.85
0.56	0.66
0.67	0.67
0.49	0.67
0.89	0.49

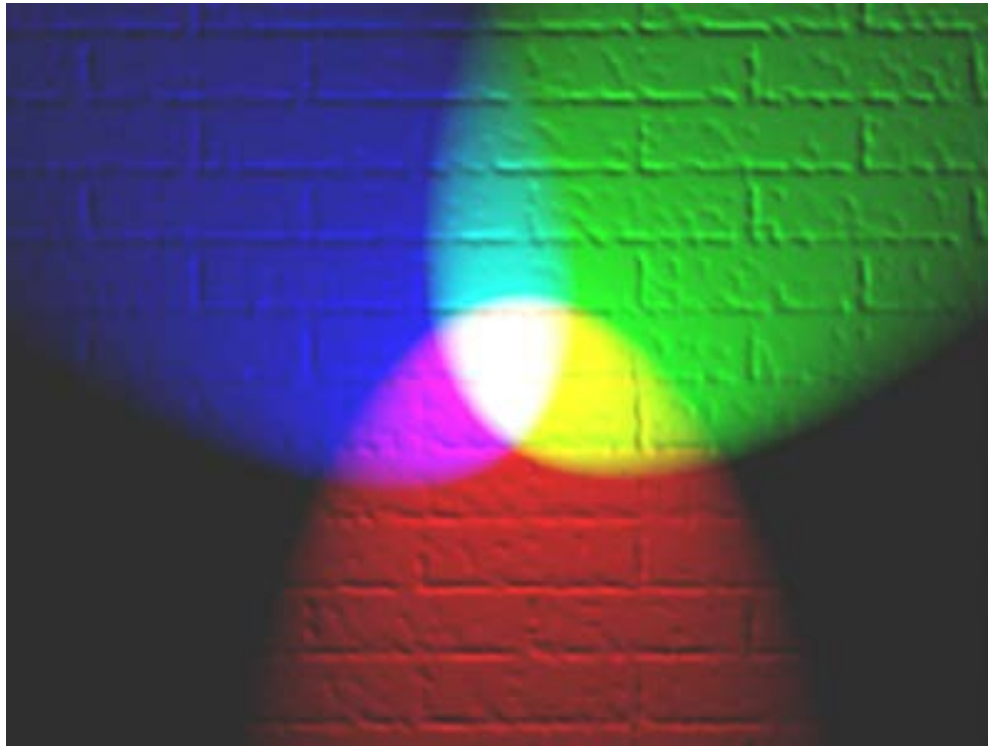
The 'B' channel matrix (final two columns) is:

0.92	0.99
0.95	0.91
0.91	0.92
0.97	0.95
0.79	0.85
0.45	0.33
0.97	0.95
0.49	0.74
0.82	0.93
0.90	0.99
0.93	0.97
0.99	0.93

# Color spaces

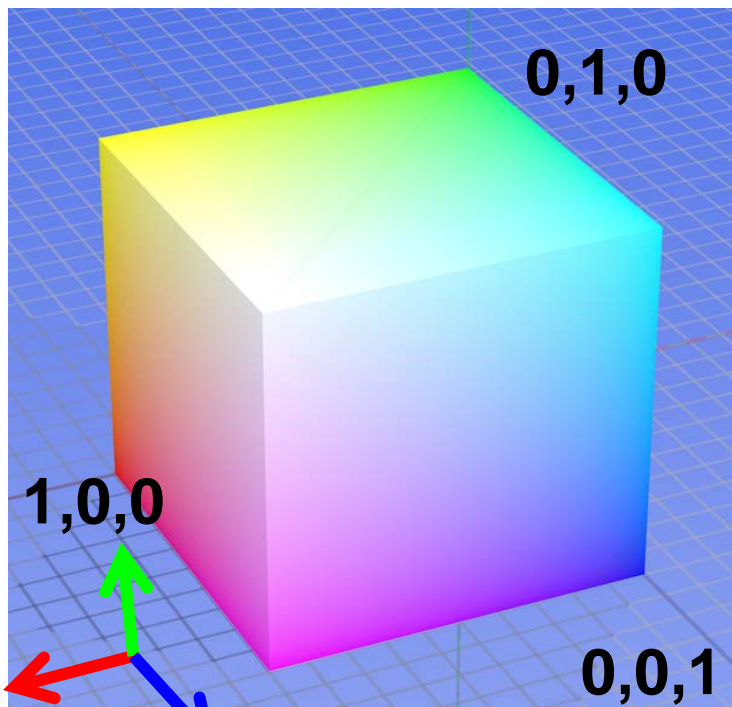
---

How can we represent color?



# Color spaces: RGB

Default color space



RGB cube

- Easy for devices
- But not perceptual
- Where do the grays live?
- Where is hue and saturation?



**R**  
(G=0,B=0)

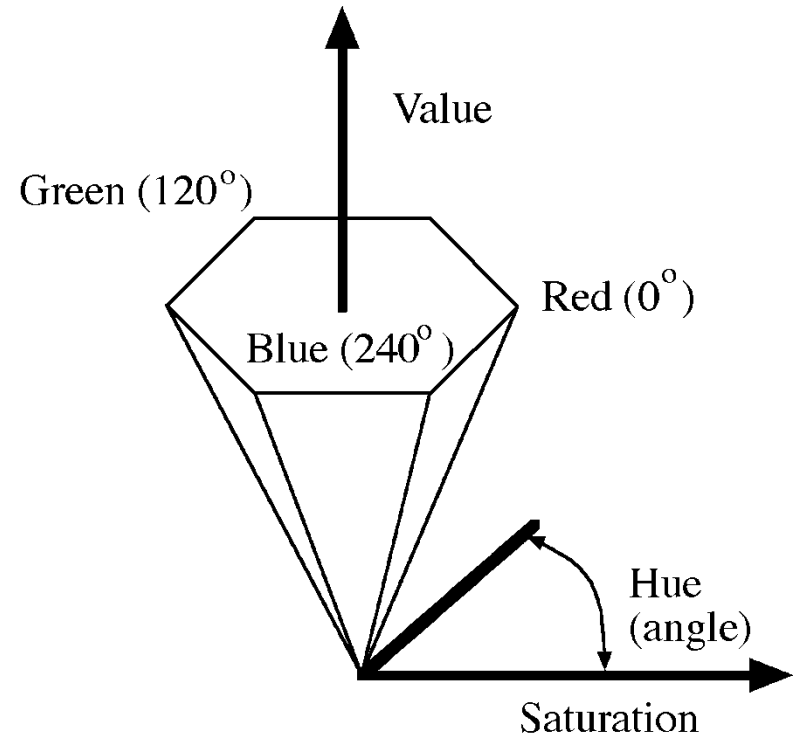
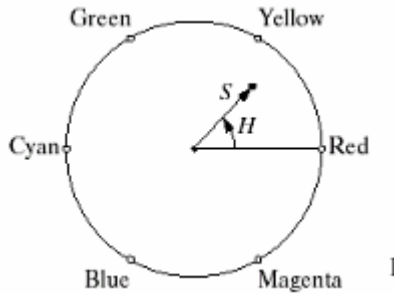
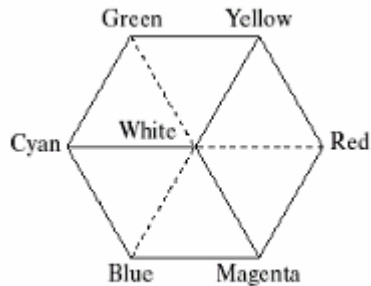


**G**  
(R=0,B=0)



**B**  
(R=0,G=0)

# HSV



## Hue, Saturation, Value (Intensity)

- RGB cube on its vertex

Decouples the three components (a bit)

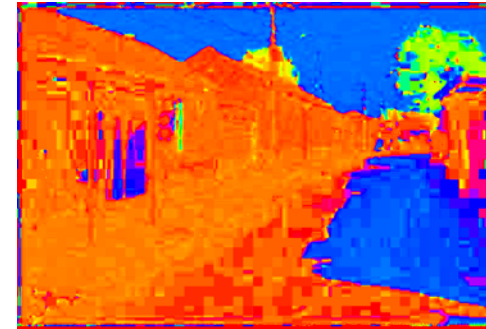
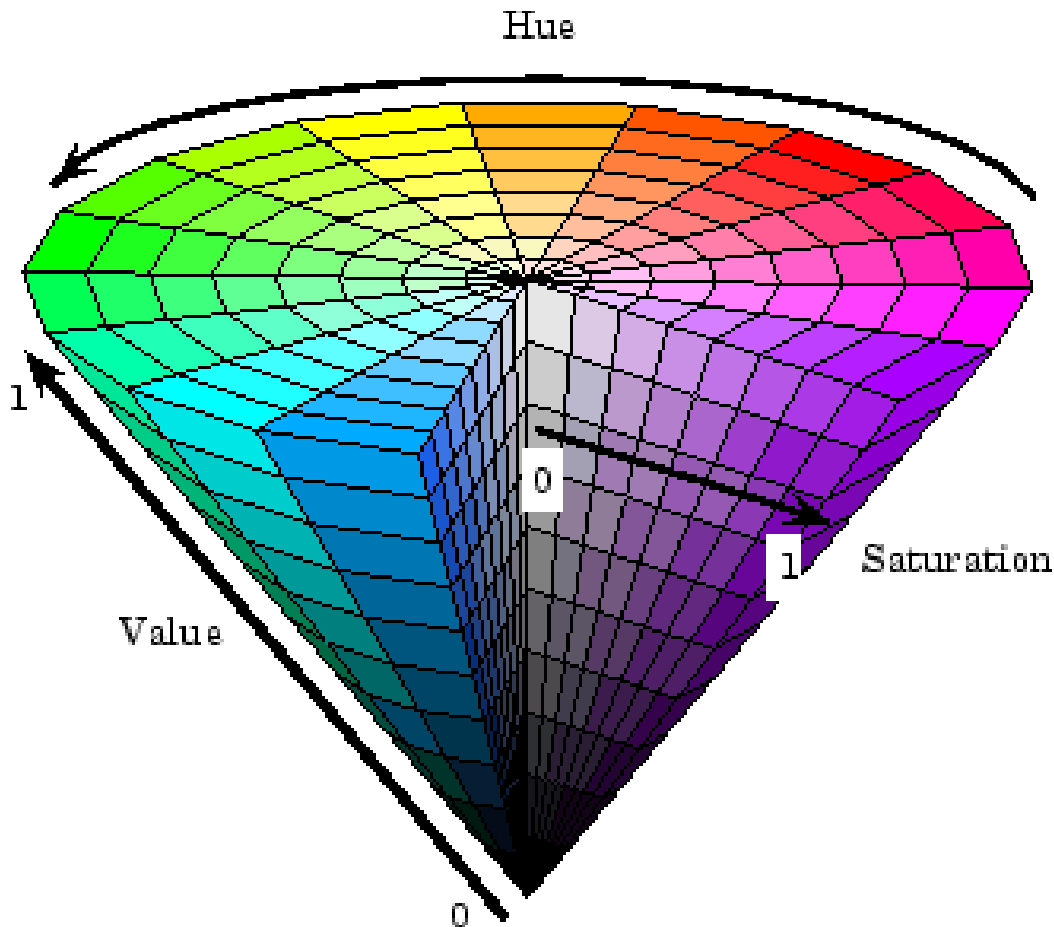
Use `rgb2hsv()` and `hsv2rgb()` in Matlab



# Color spaces: HSV



## Intuitive color space



**H**  
(S=1,V=1)



**S**  
(H=1,V=1)

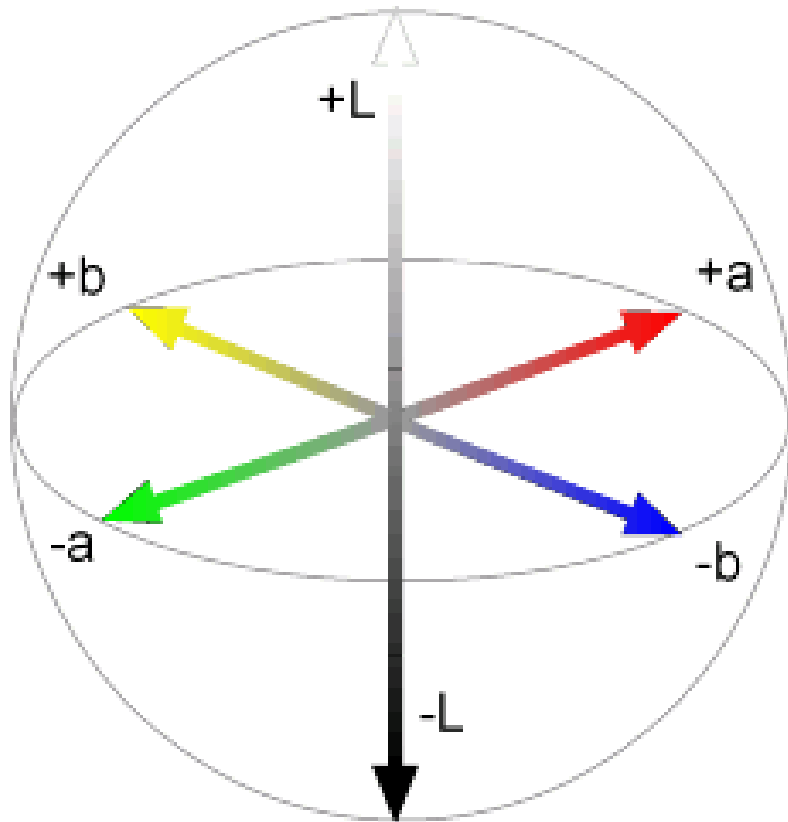


**V**  
(H=1,S=0)

# Color spaces: $L^*a^*b^*$



“Perceptually uniform”\* color space



**L**  
( $a=0, b=0$ )



**a**  
( $L=65, b=0$ )



**b**  
( $L=65, a=0$ )