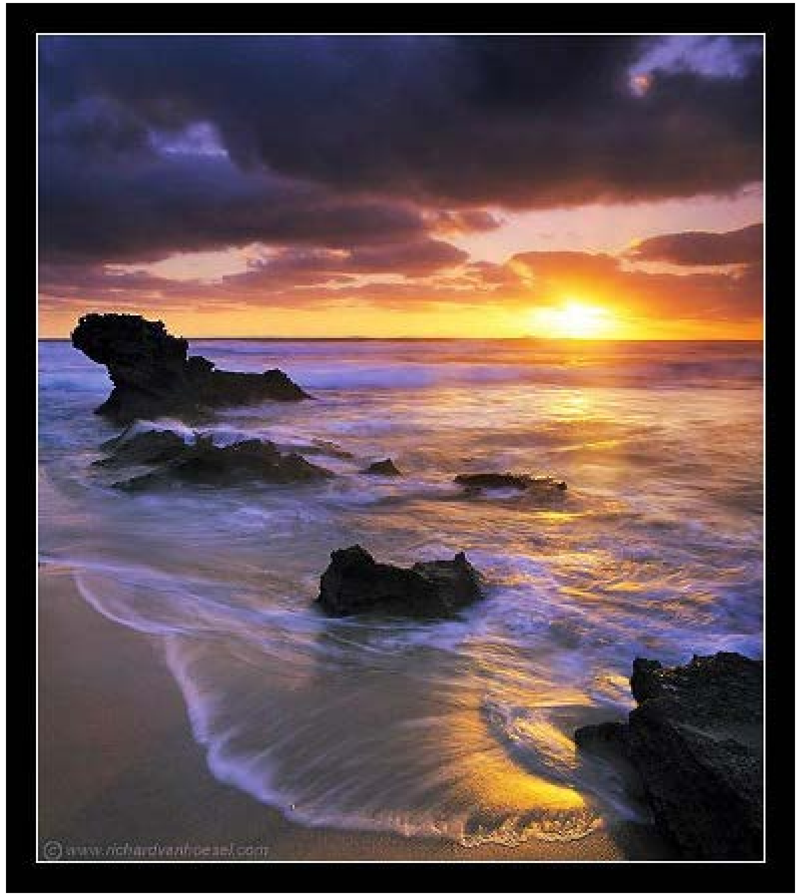
Capturing Light… in man and machine



CS194: Image Manipulation & Computational Photography
Alexei Efros, UC Berkeley, Fall 2015

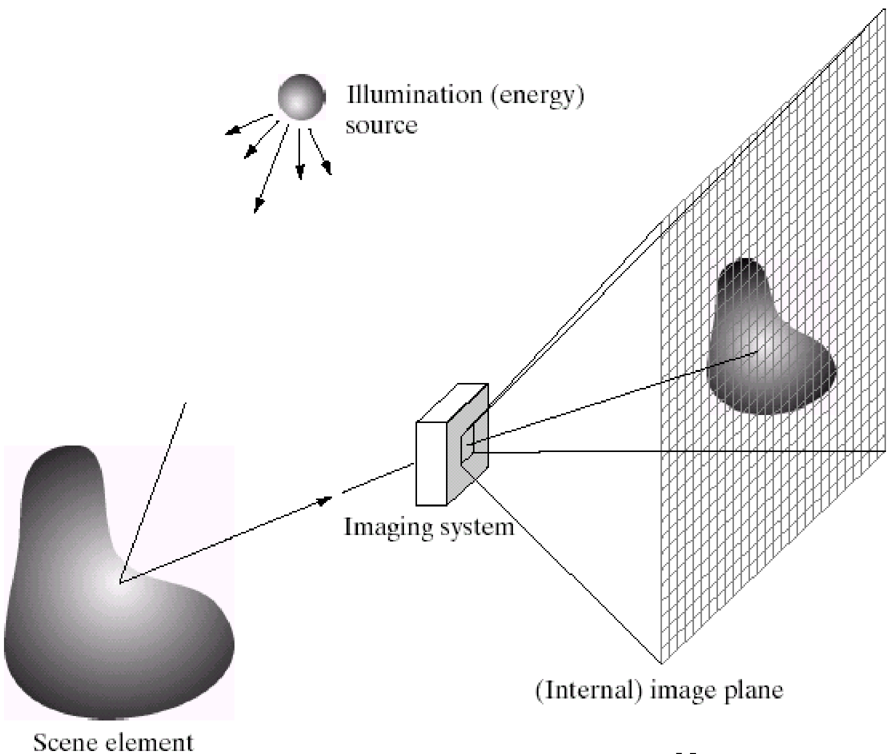
Etymology

PHOTOGRAPHY

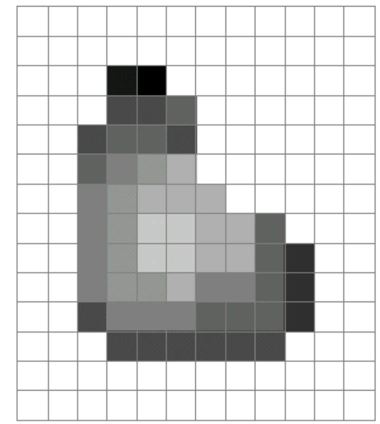
light

drawing / writing

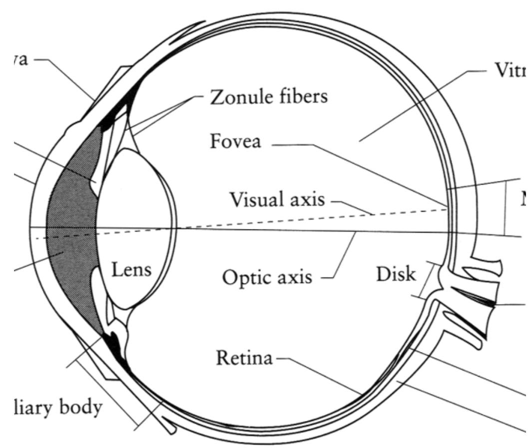
Image Formation



Film

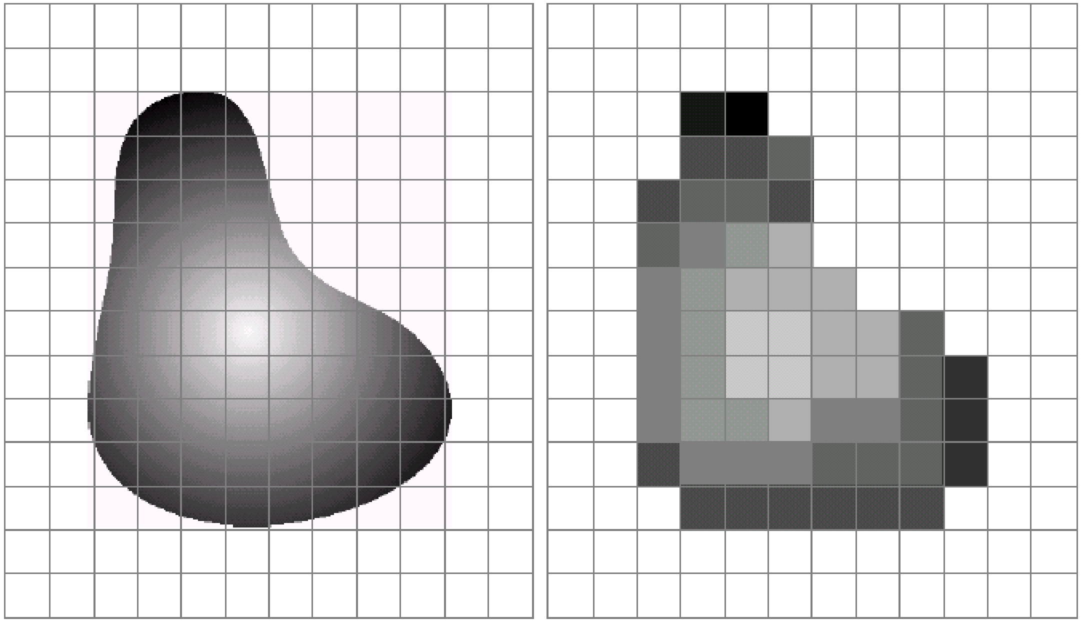


Digital Camera



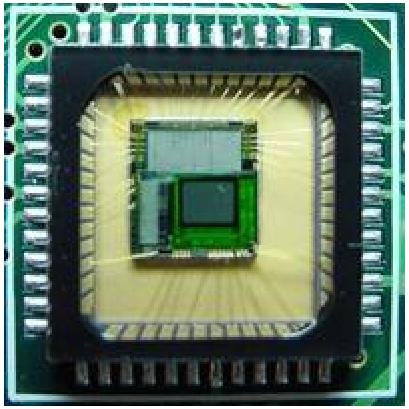
The Eye

Sensor Array



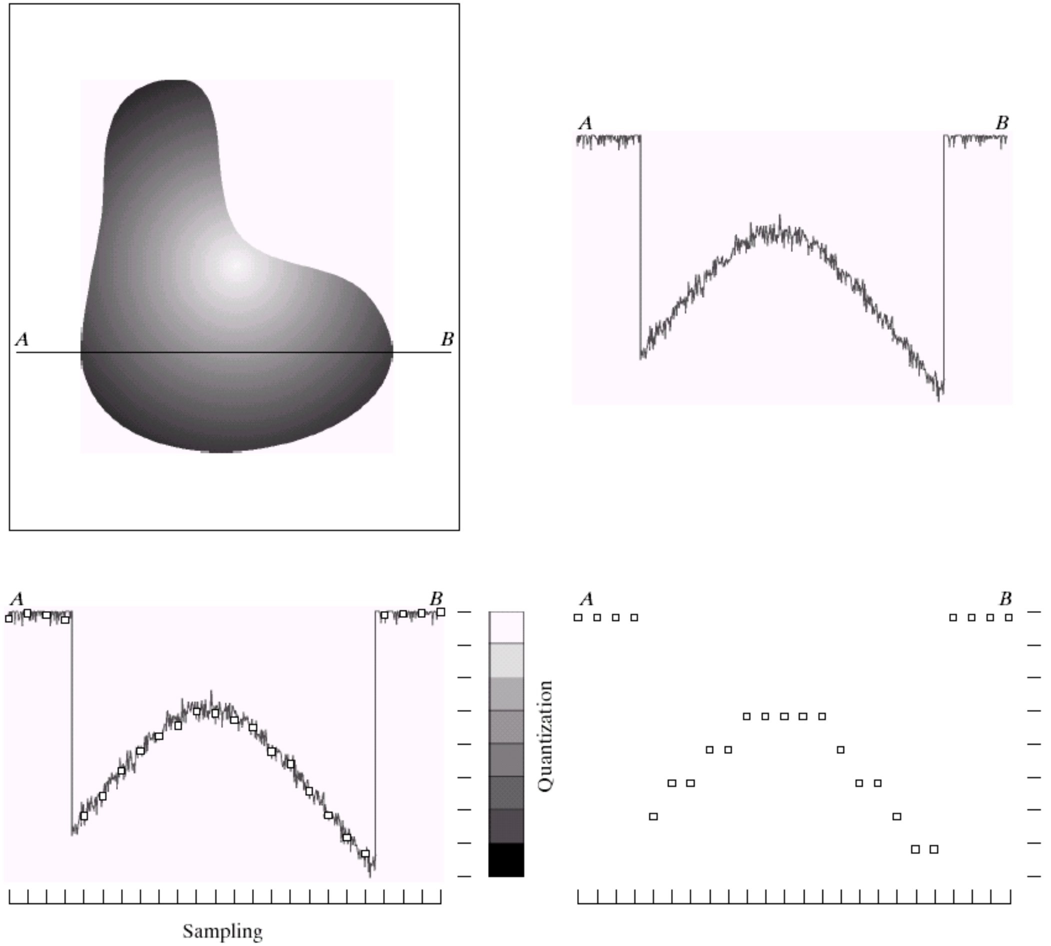
a b

FIGURE 2.17 (a) Continuos image projected onto a sensor array. (b) Result of image sampling and quantization.



CMOS sensor

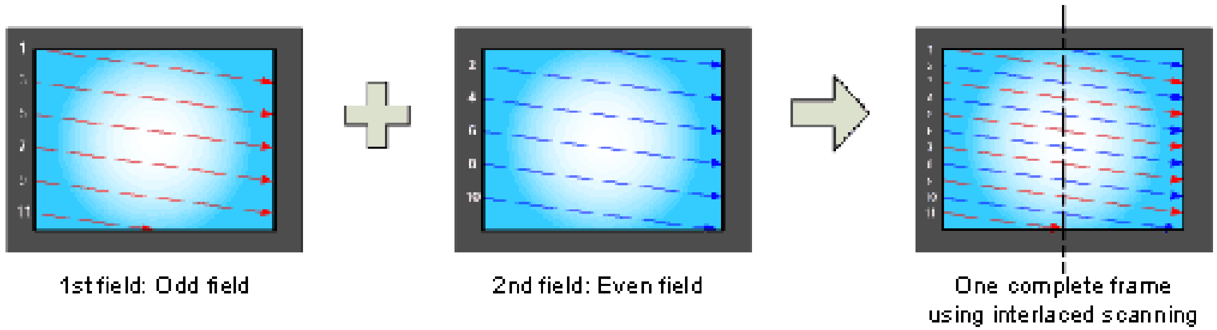
Sampling and Quantization

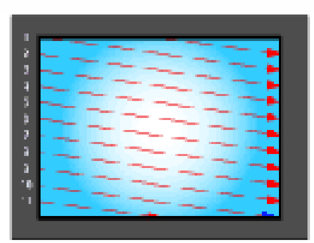


a b
c d

FIGURE 2.16 Generating a digital image. (a) Continuous image. (b) A scan line from A to B in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

Interlace vs. progressive scan





One complete frame
using progressive scanning

http://www.axis.com/products/video/camera/progressive_scan.htm

Slide by Steve Seitz

Progressive scan

http://www.axis.com/products/video/camera/progressive_scan.htm

Slide by Steve Seitz

Interlace

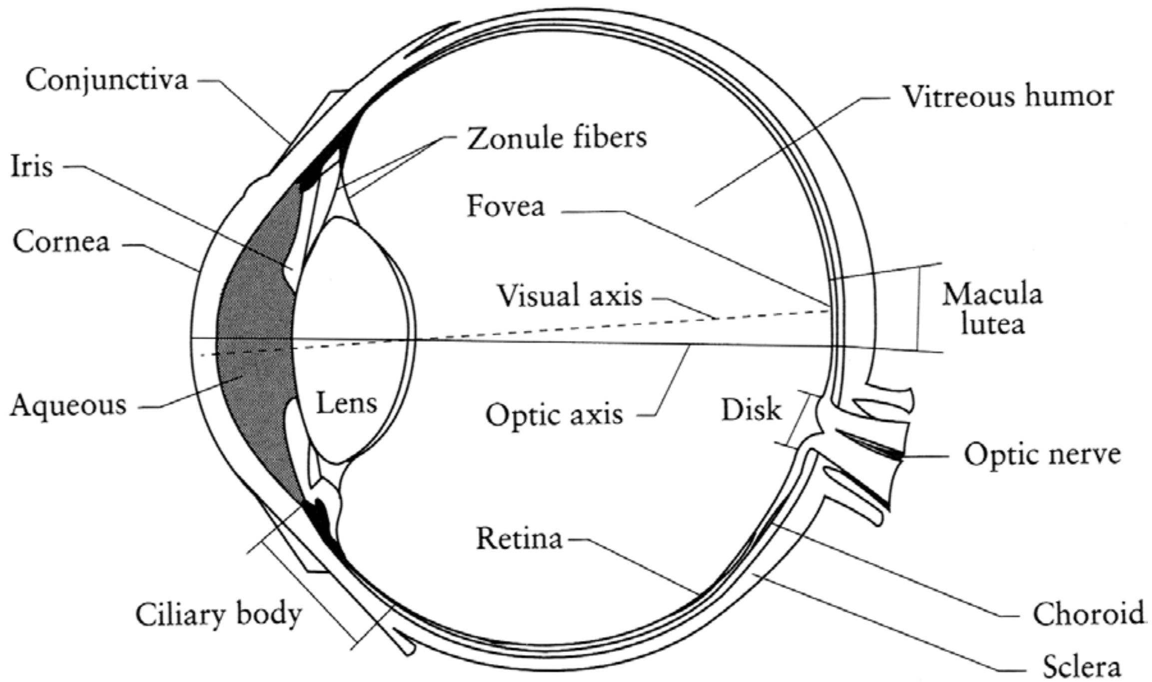
http://www.axis.com/products/video/camera/progressive_scan.htm

Slide by Steve Seitz

Rolling Shutter

http://en.wikipedia.org/wiki/Rolling_shutter

The Eye

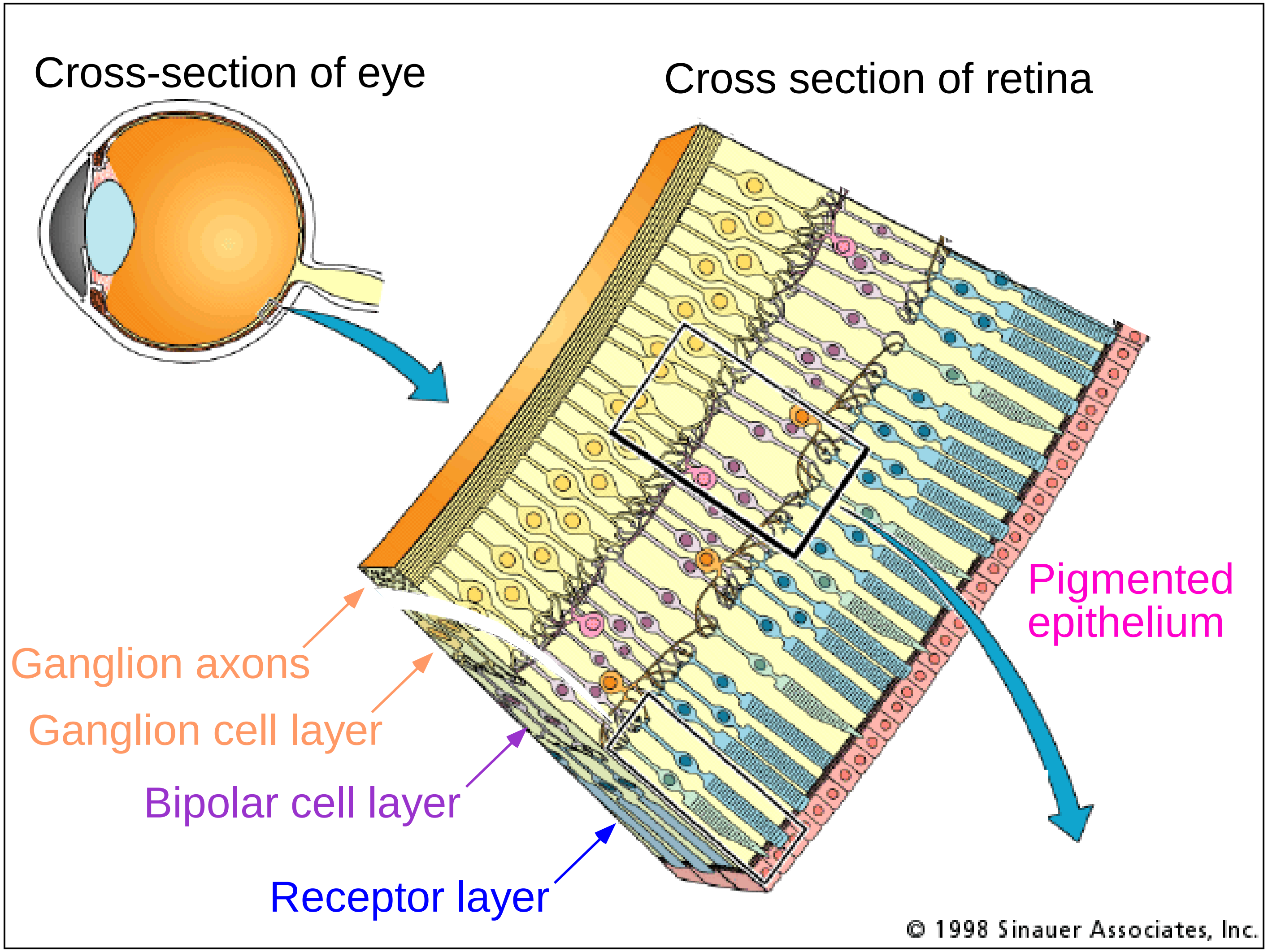


The human eye is a camera!

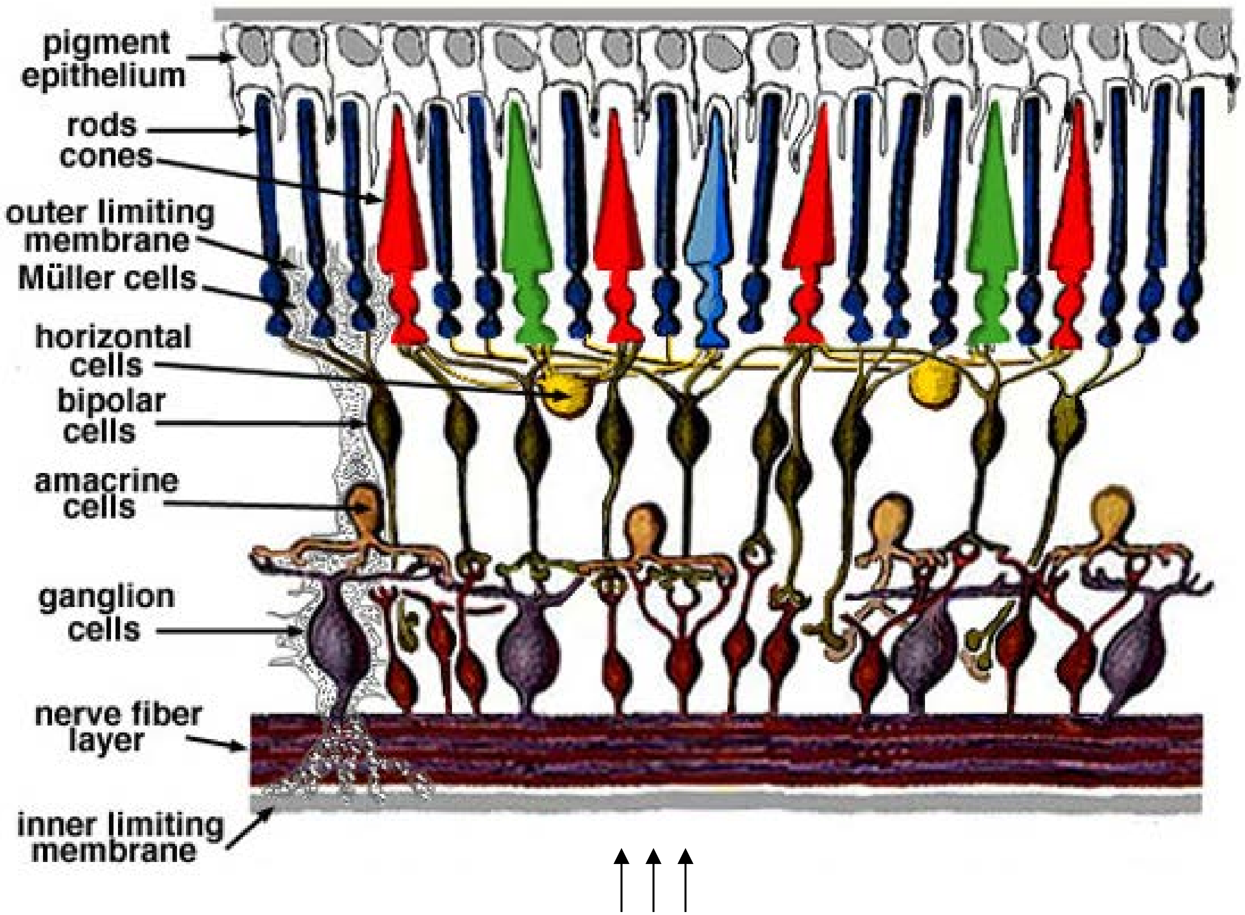
- **Iris** - colored annulus with radial muscles
- **Pupil** - the hole (aperture) whose size is controlled by the iris
- What’s the “film”?
  - photoreceptor cells (rods and cones) in the **retina**

Slide by Steve Seitz

The Retina


Cross-section of eye
Cross section of retina
Pigmented epithelium
Ganglion axons
Ganglion cell layer
Bipolar cell layer
Receptor layer
© 1998 Sinauer Associates, Inc.

Retina up-close



Light

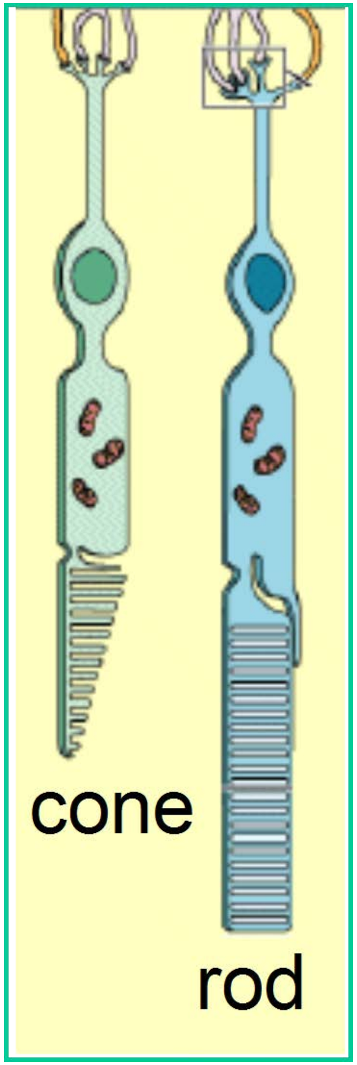
Two types of light-sensitive receptors

Cones

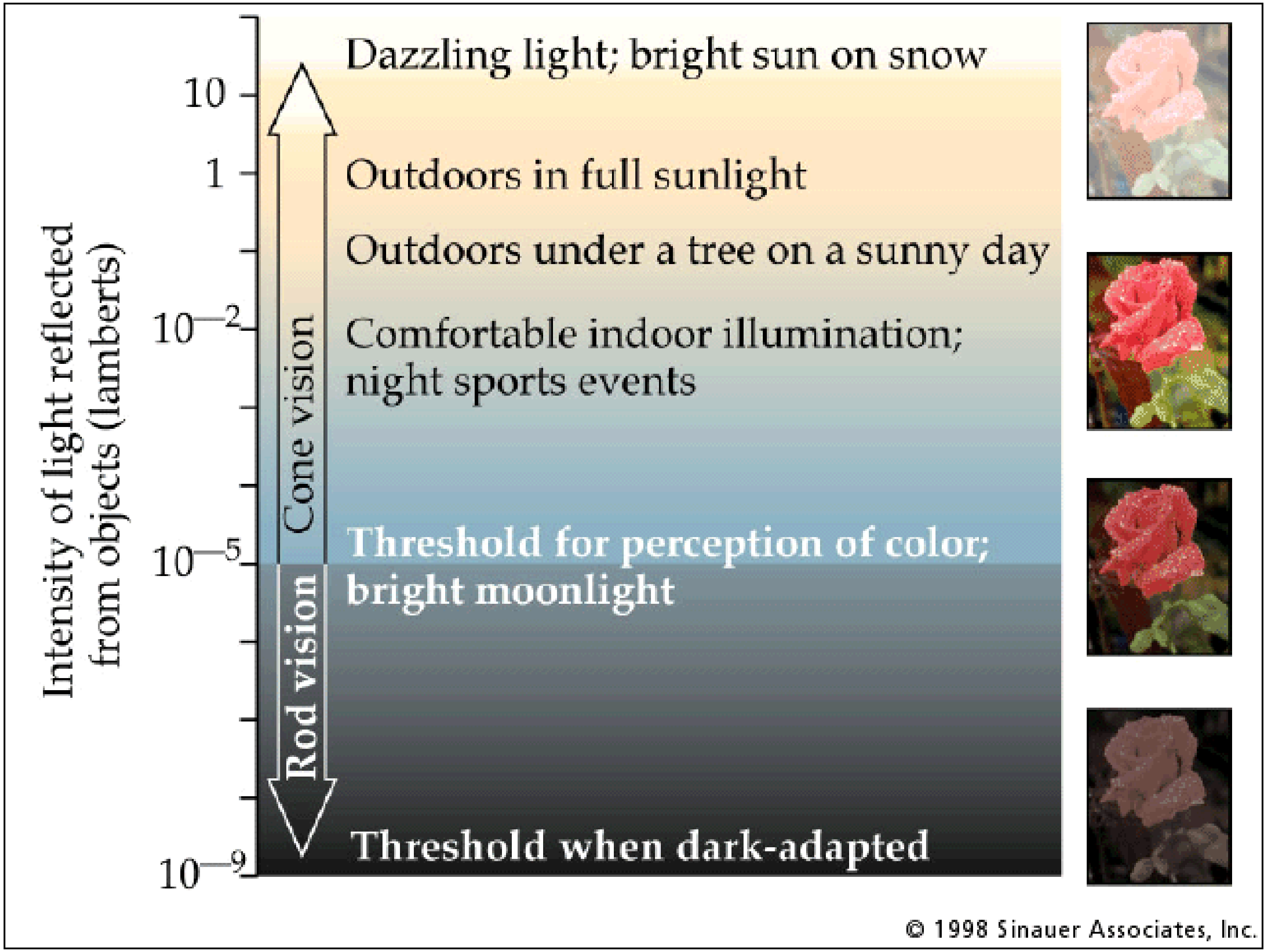
cone-shaped
less sensitive
operate in high light
color vision

Rods

rod-shaped
highly sensitive
operate at night
gray-scale vision

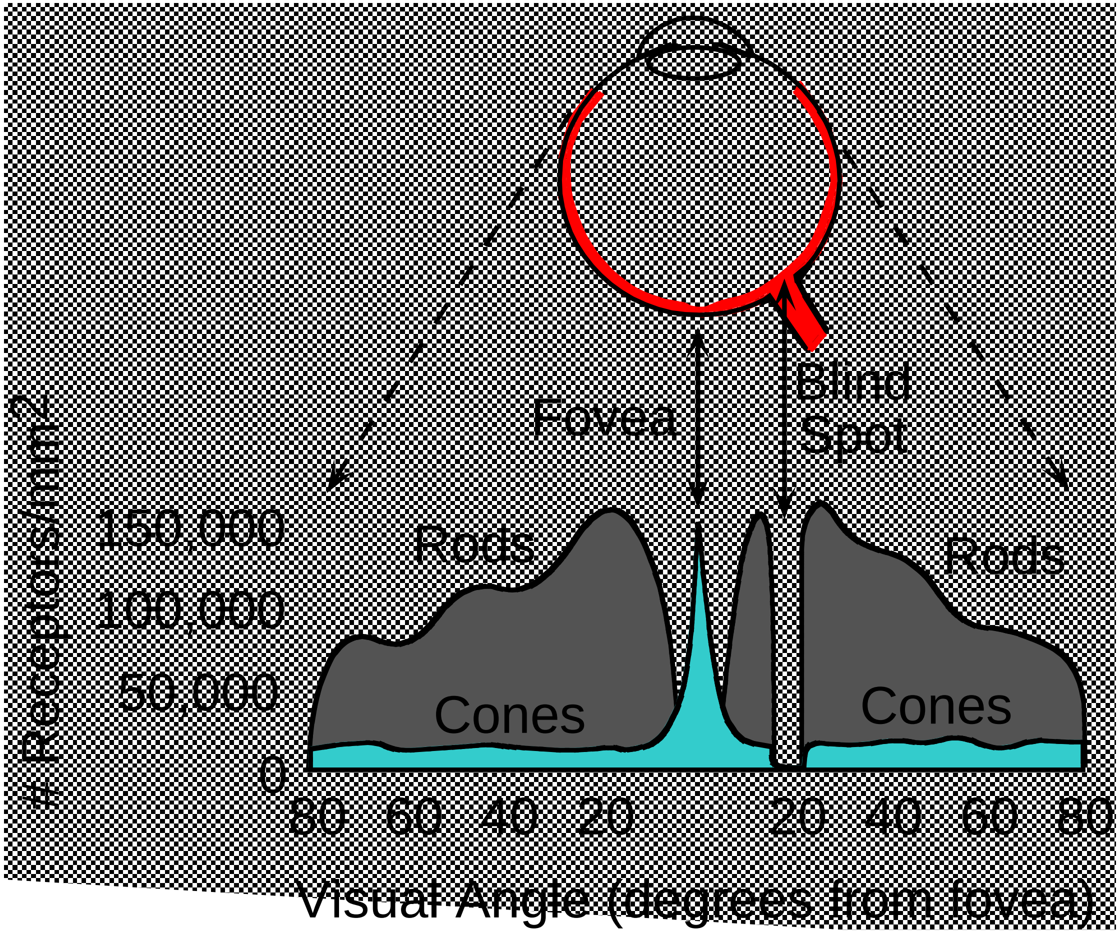


Rod / Cone sensitivity

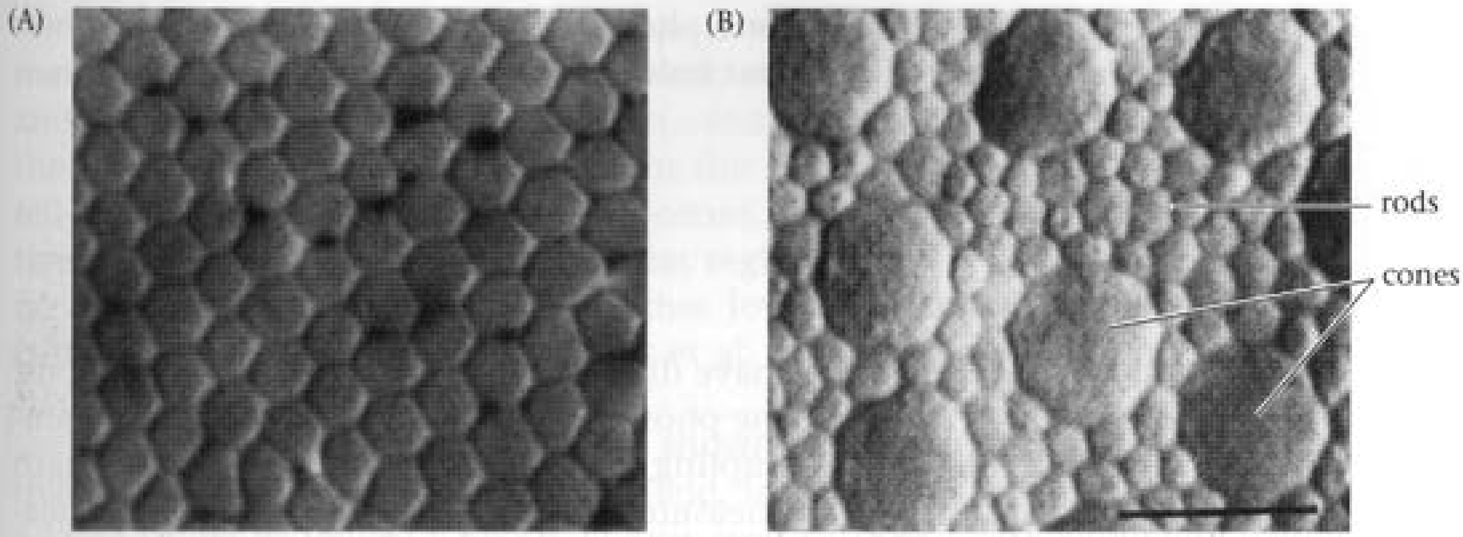


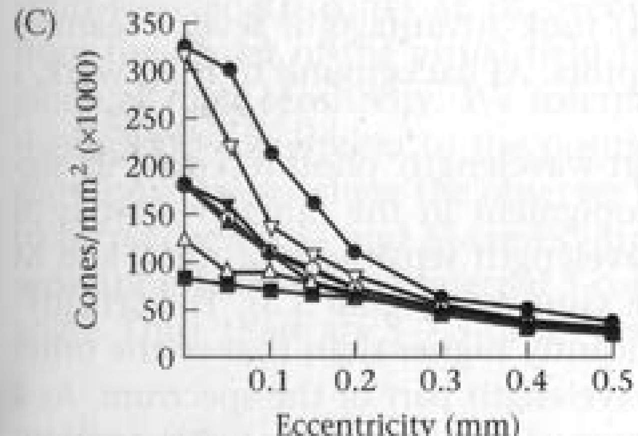
The famous sock-matching problem…

Distribution of Rods and Cones



Night Sky: why are there more stars off-center?

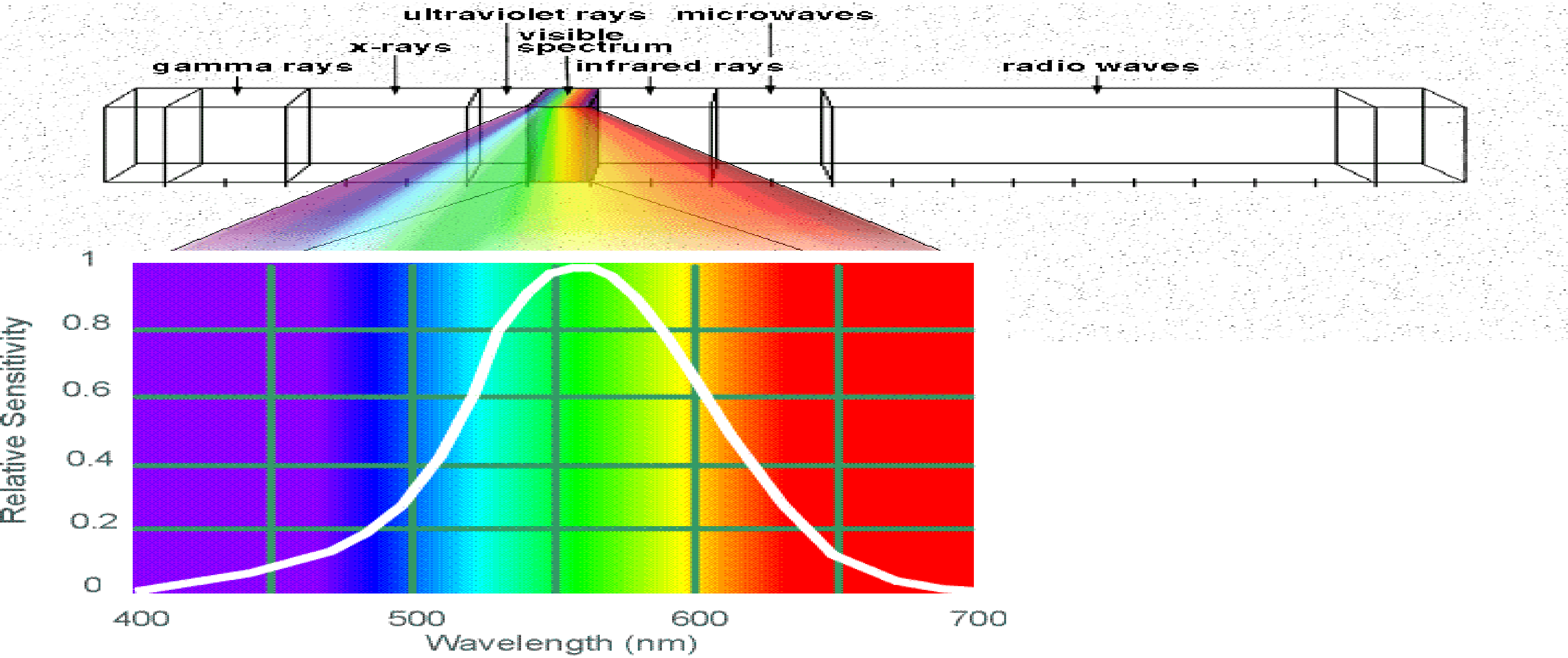




3.4 THE SPATIAL MOSAIC OF THE HUMAN CONES. Cross sections of the human retina at the level of the inner segments showing (A) cones in the fovea, and (B) cones in the periphery. Note the size difference (scale bar = 10 μm), and that, as the separation between cones grows, the rod receptors fill in the spaces. (C) Cone density plotted as a function of distance from the center of the fovea for seven human retinas; cone density decreases with distance from the fovea. Source: Curcio et al., 1990.

Foundations of Vision, by Brian Wandell, Sinauer Assoc., 1995

Electromagnetic Spectrum



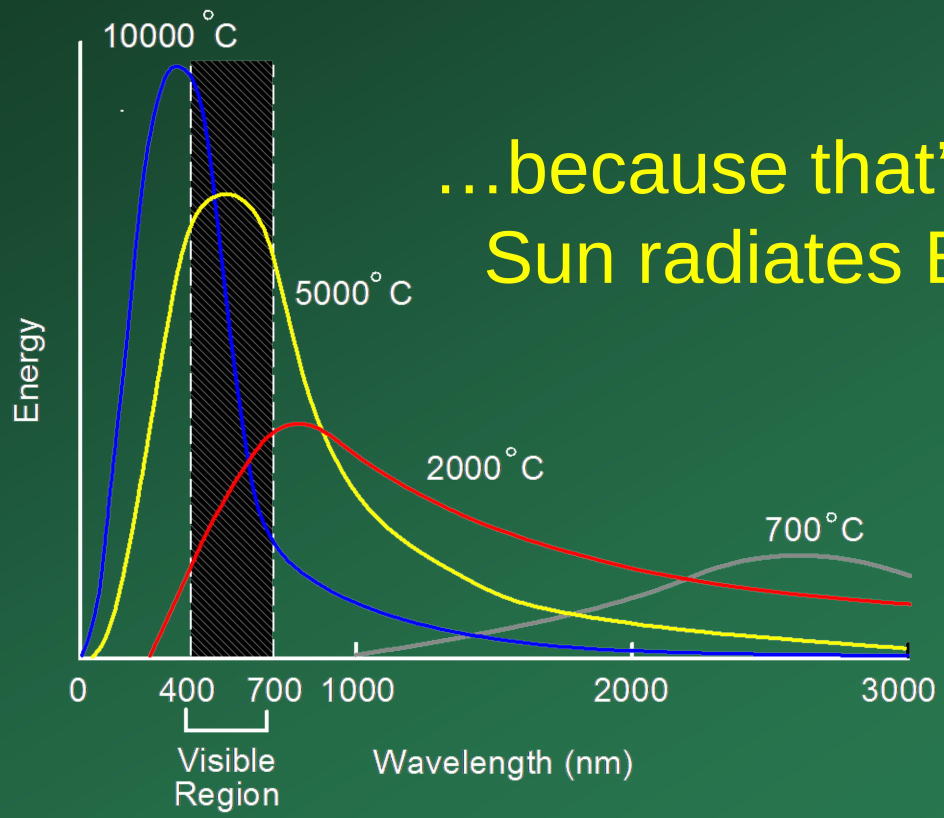
Human Luminance Sensitivity Function

http://www.yorku.ca/eye/photopik.htm

Visible Light

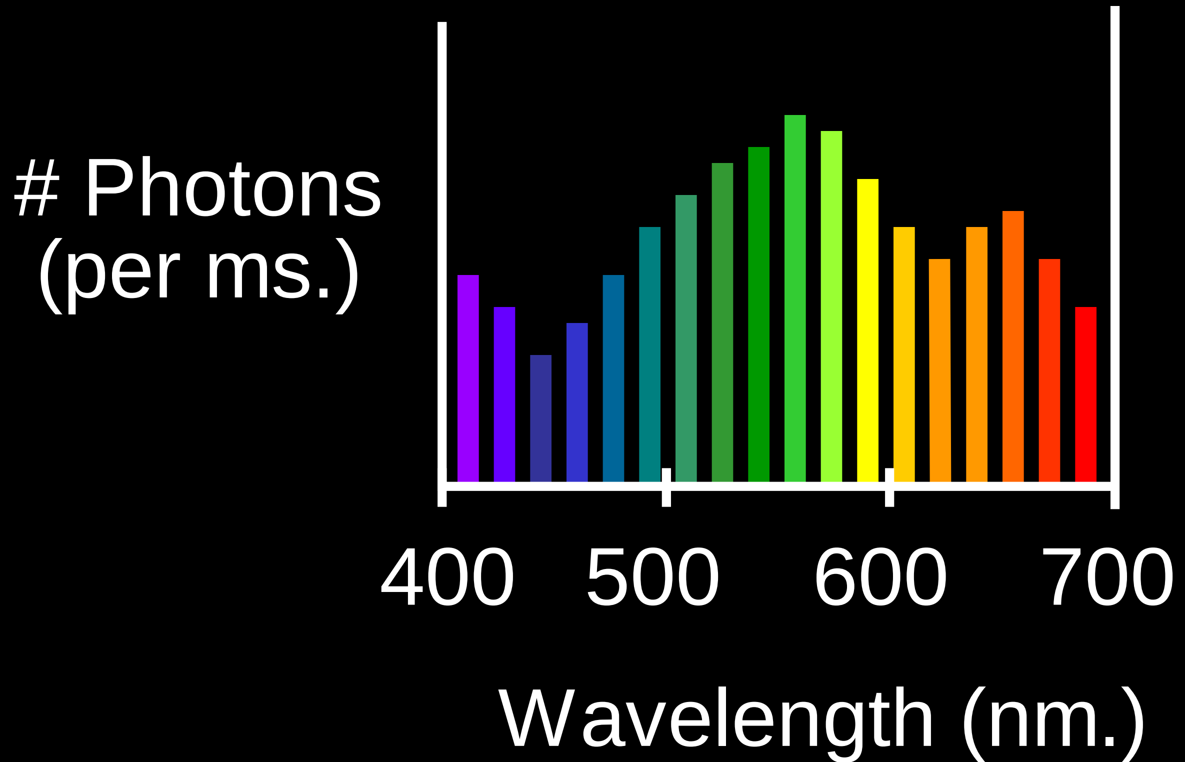
Why do we see light of these wavelengths?

…because that's where the Sun radiates EM energy



The Physics of Light

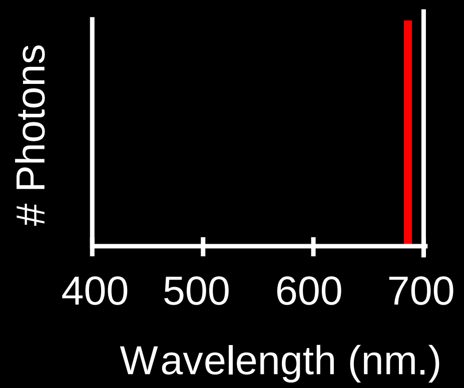
Any patch of light can be completely described physically by its spectrum: the number of photons (per time unit) at each wavelength 400 - 700 nm.



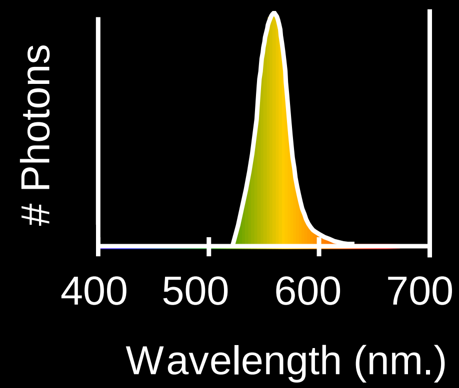
The Physics of Light

Some examples of the spectra of light sources

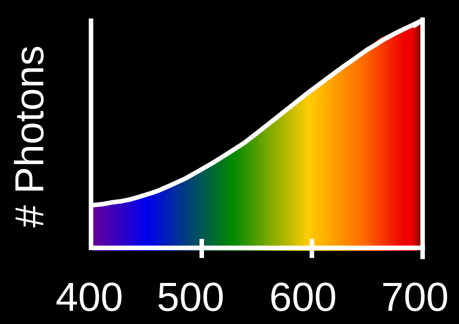
A. Ruby Laser



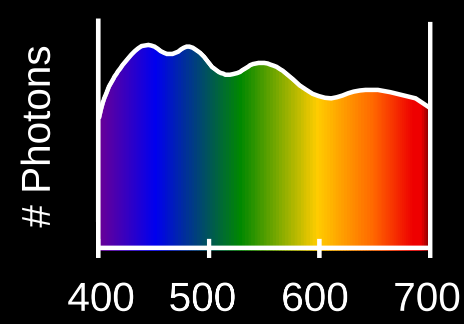
B. Gallium Phosphide Crystal



C. Tungsten Lightbulb

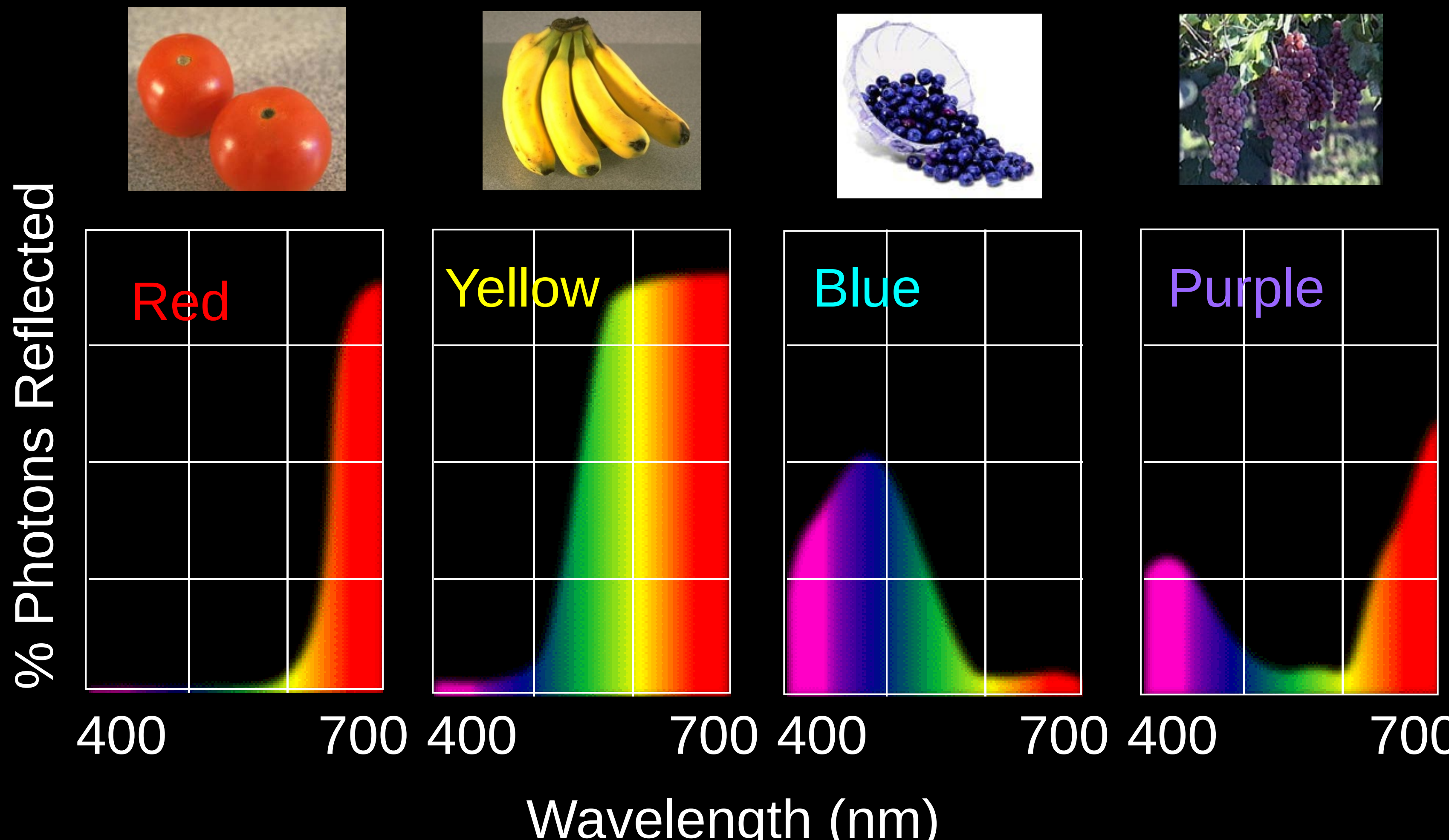


D. Normal Daylight



The Physics of Light

Some examples of the reflectance spectra of surfaces

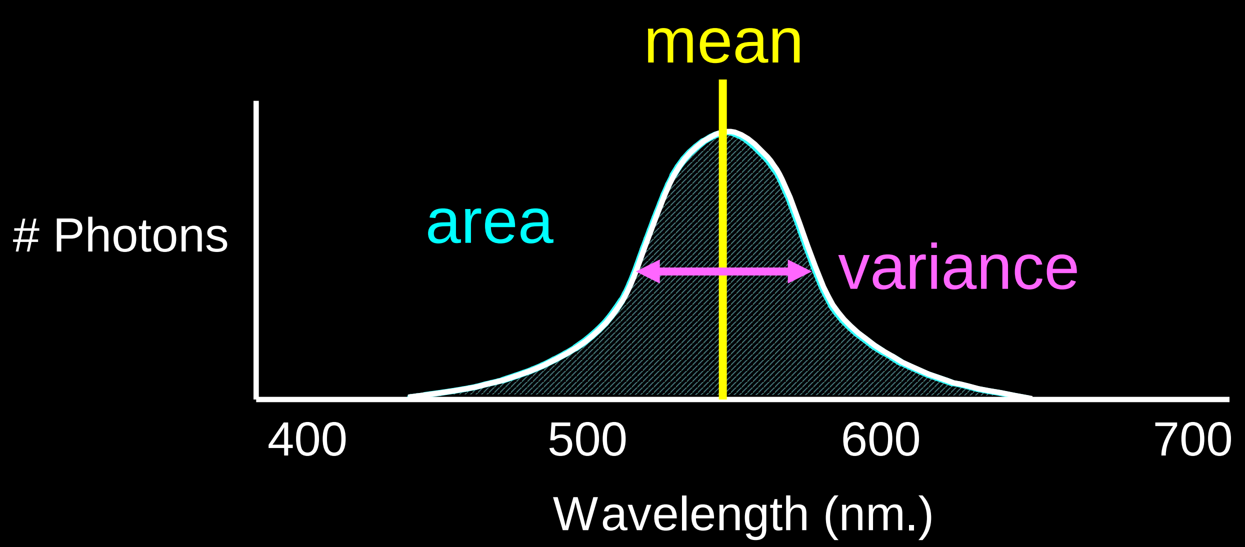


The Psychophysical Correspondence

There is no simple functional description for the perceived color of all lights under all viewing conditions, but ......

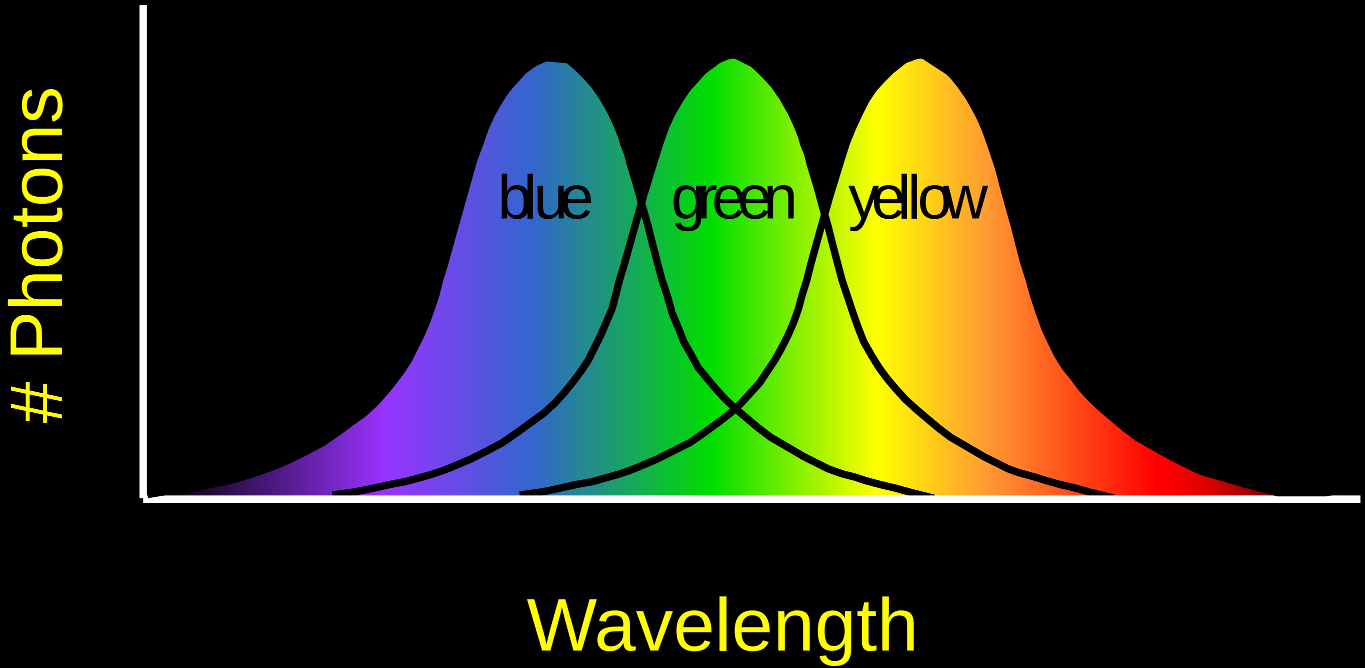
A helpful constraint:

Consider only physical spectra with normal distributions



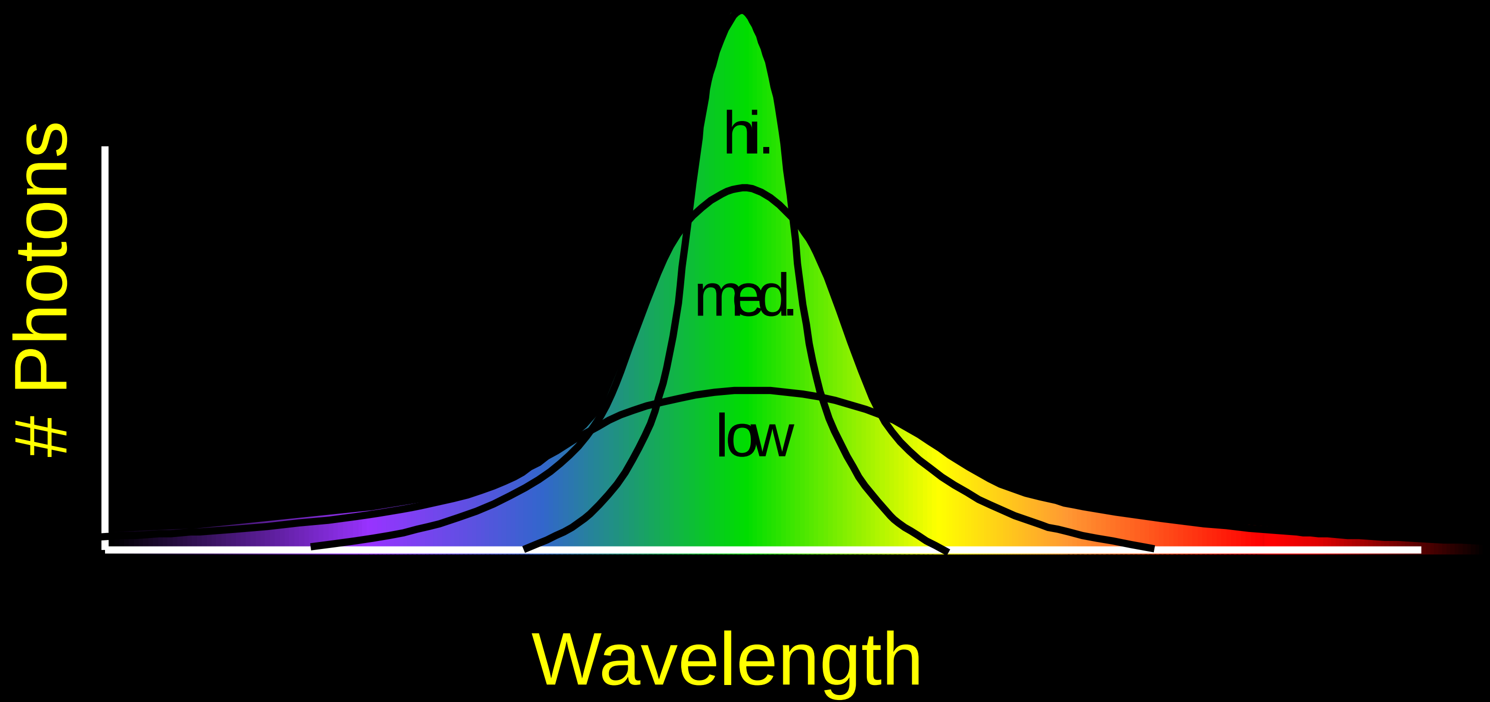
The Psychophysical Correspondence

Mean ⟷ Hue



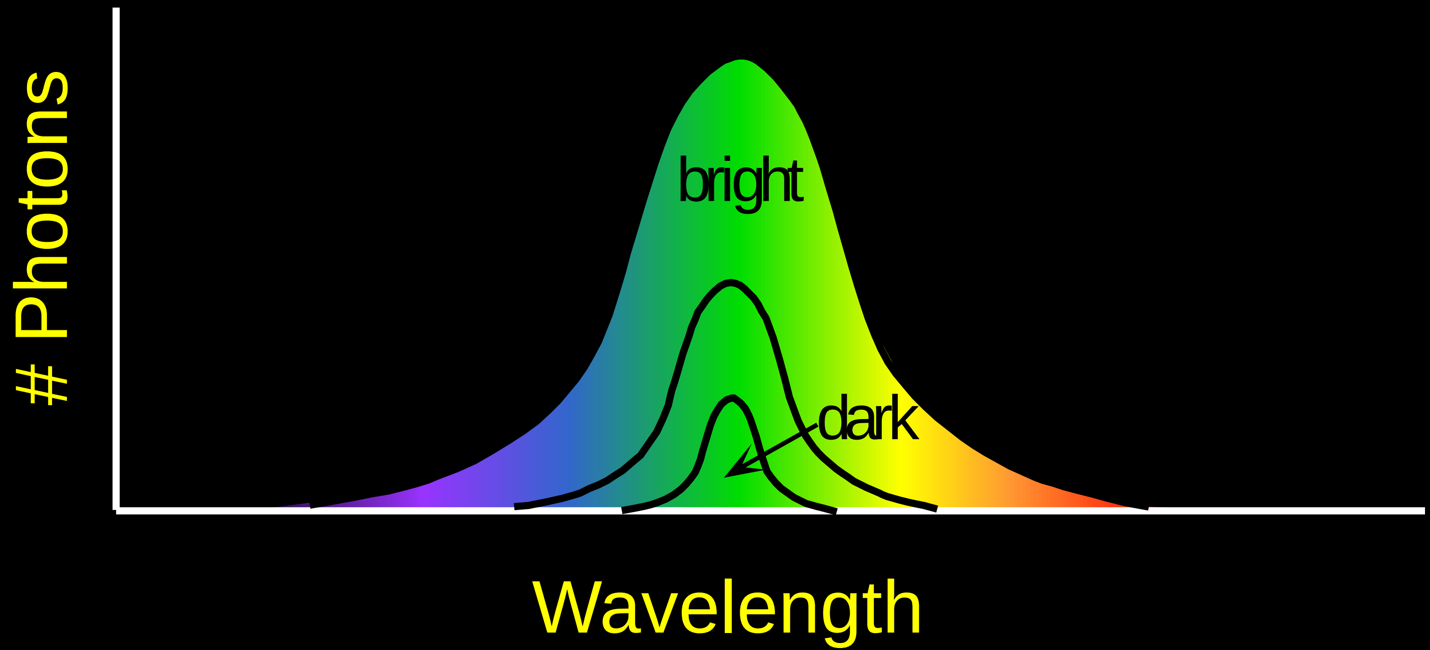
The Psychophysical Correspondence

Variance ⟷ Saturation



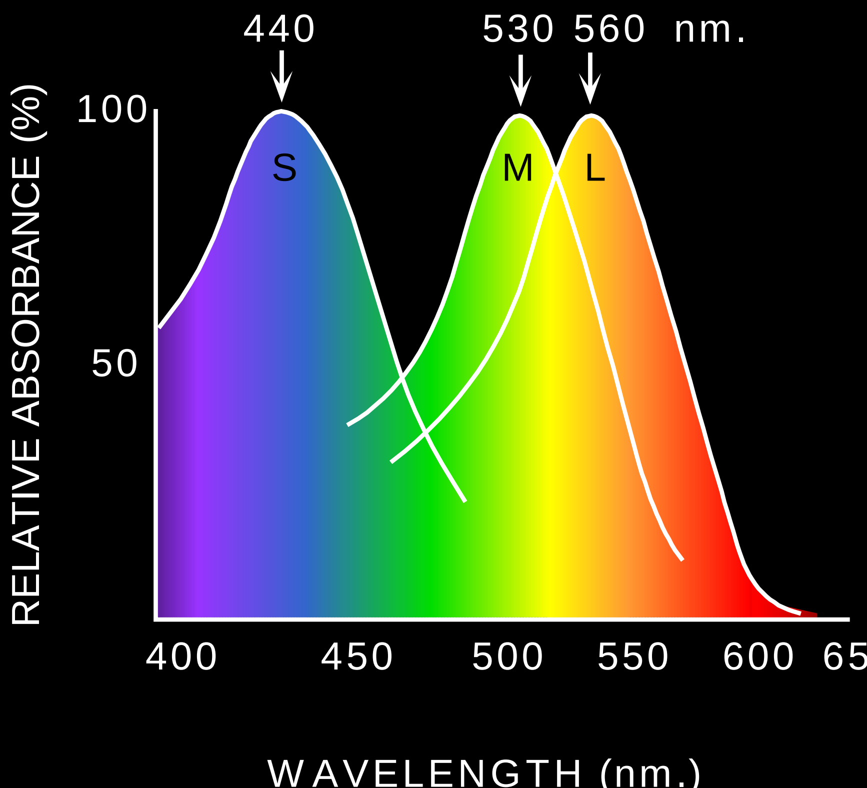
The Psychophysical Correspondence

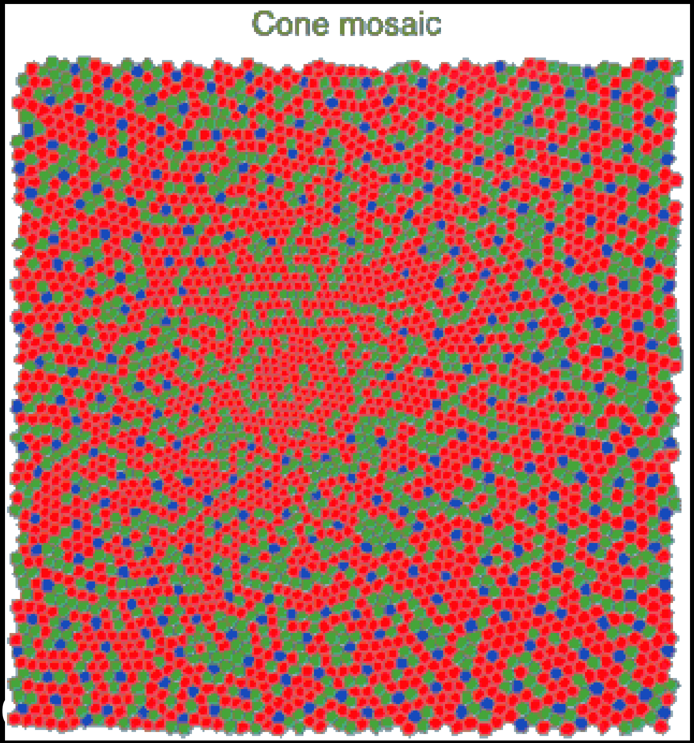
Area ⟷ Brightness



Physiology of Color Vision

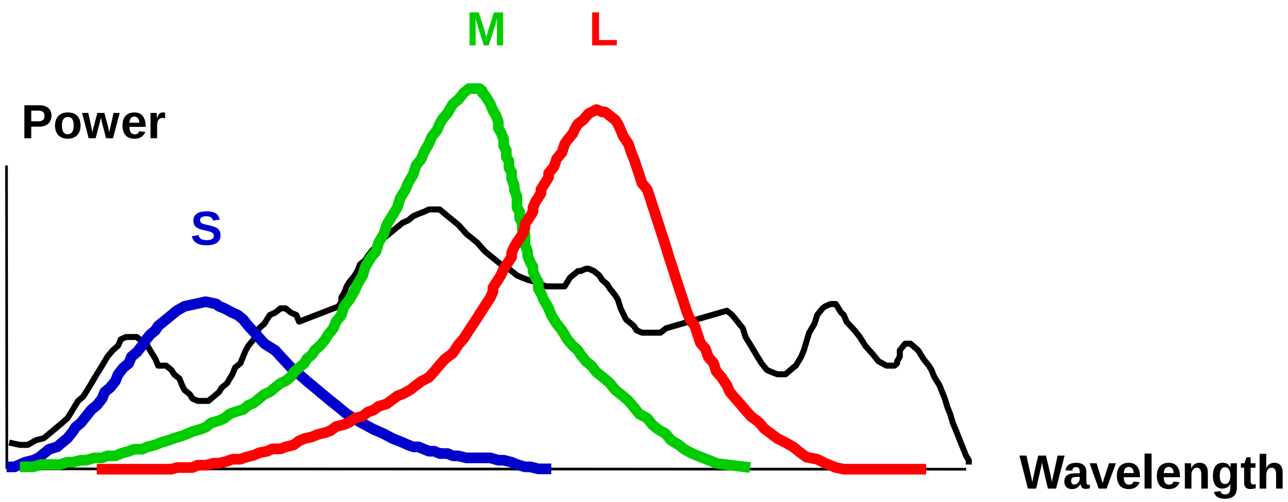
Three kinds of cones:





- Why are M and L cones so close?
- Why are there 3?

Trichromacy



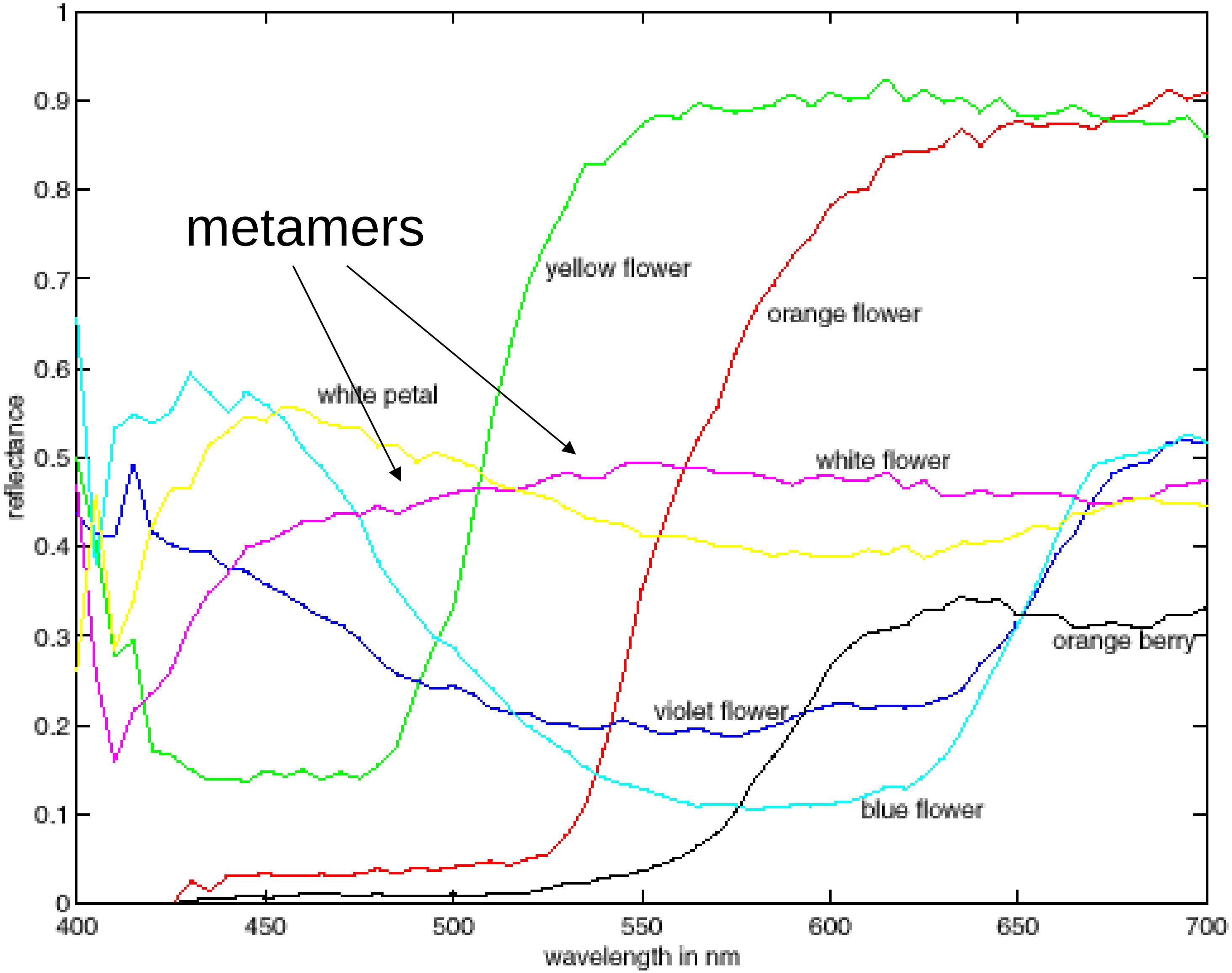
Rods and cones act as *filters* on the spectrum

- To get the output of a filter, multiply its response curve by the spectrum, integrate over all wavelengths
  - Each cone yields one number

- How can we represent an entire spectrum with 3 numbers?
- We can't! Most of the information is lost
  - As a result, two different spectra may appear indistinguishable
    - » such spectra are known as **metamers**

Slide by Steve Seitz

More Spectra



Color Constancy

The "photometer metaphor" of color perception:
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).

Color Constancy

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Color Constancy

<u>The "photometer metaphor" of color perception</u>:
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).

Color Constancy

~~Do we have constancy over all global color transformations?~~

60% blue filter

Complete inversion

Color Constancy

Color Constancy: the ability to perceive the invariant color of a surface despite ecological Variations in the conditions of observation.

Another of these hard inverse problems:
Physics of light emission and surface reflection underdetermine perception of surface color

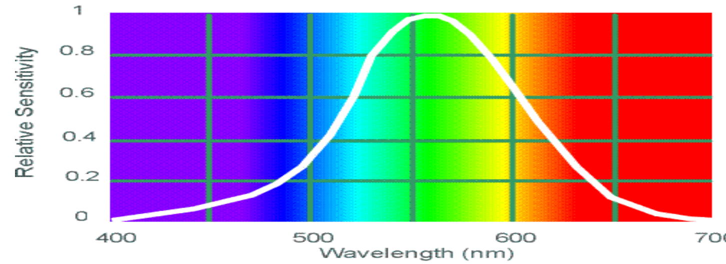
Camera White Balancing

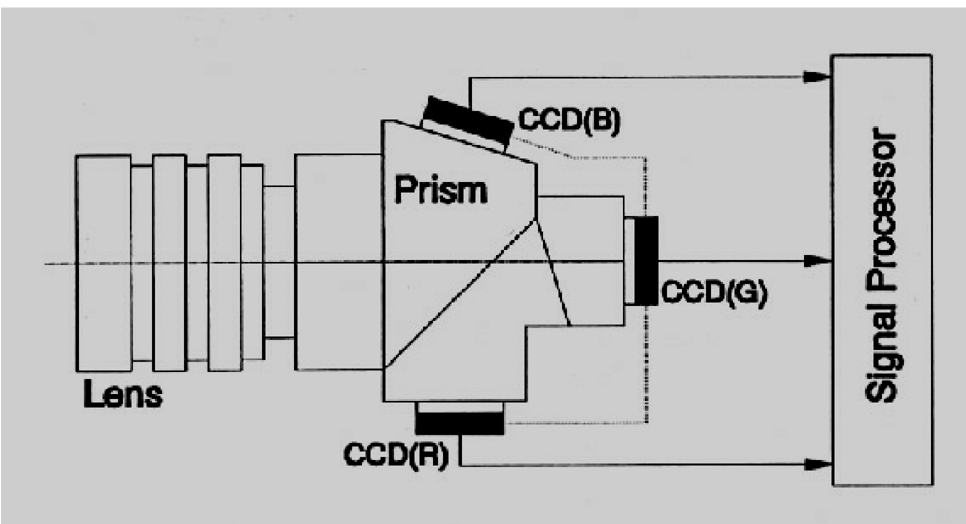
- Manual
  - Choose color-neutral object in the photos and normalize
- Automatic (AWB)
  - Grey World: force average color of scene to grey
  - White World: force brightest object to white

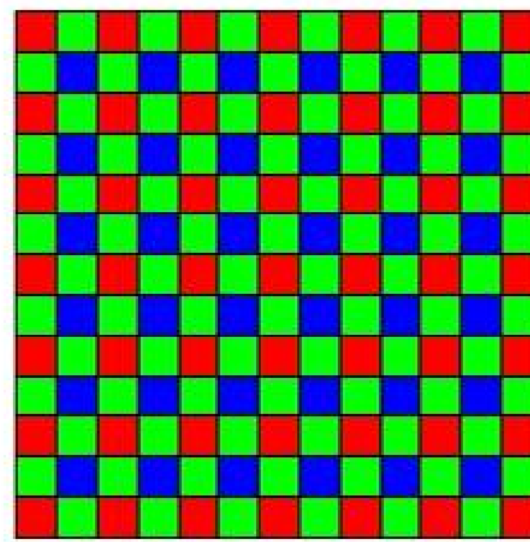
Color Sensing in Camera (RGB)

3-chip vs. 1-chip: quality vs. cost

Why more green?







Bayer filter

tuff Works

Why 3 colors?

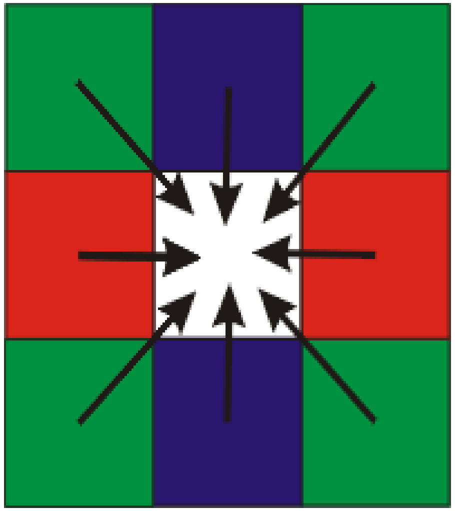
http://www.cooldictionary.com/words/Bayer-filter.wikipedia

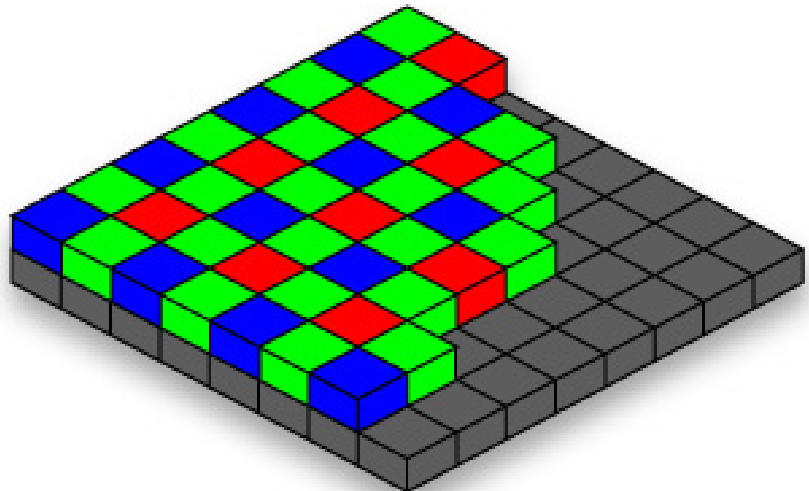
Slide by Steve Seitz

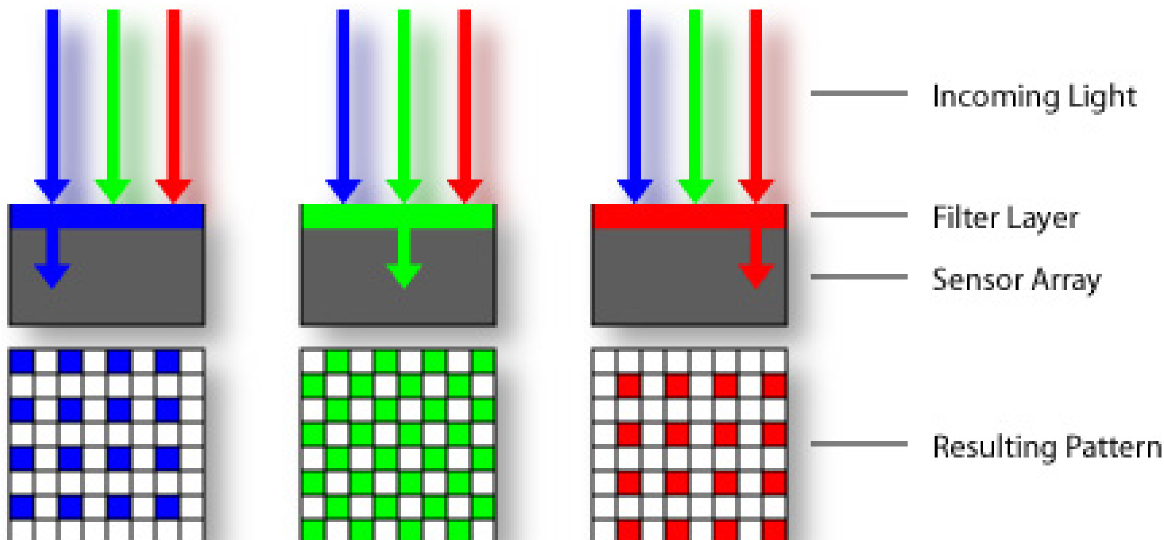
Green is in!

R G B

Practical Color Sensing: Bayer Grid







Estimate RGB at ‘G’ cels from neighboring values

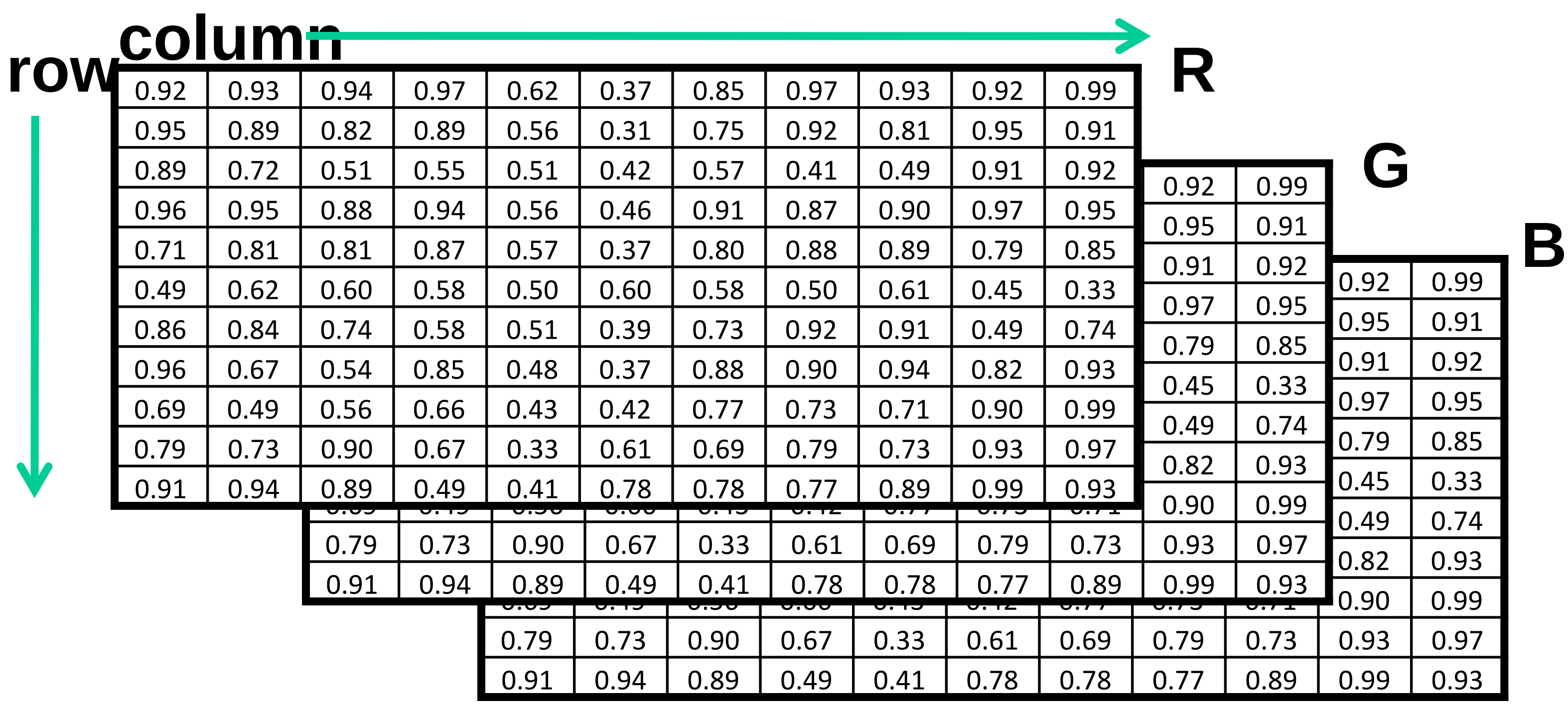
http://www.cooldictionary.com/words/Bayer-filter.wikipedia

Slide by Steve Seitz

Color Image

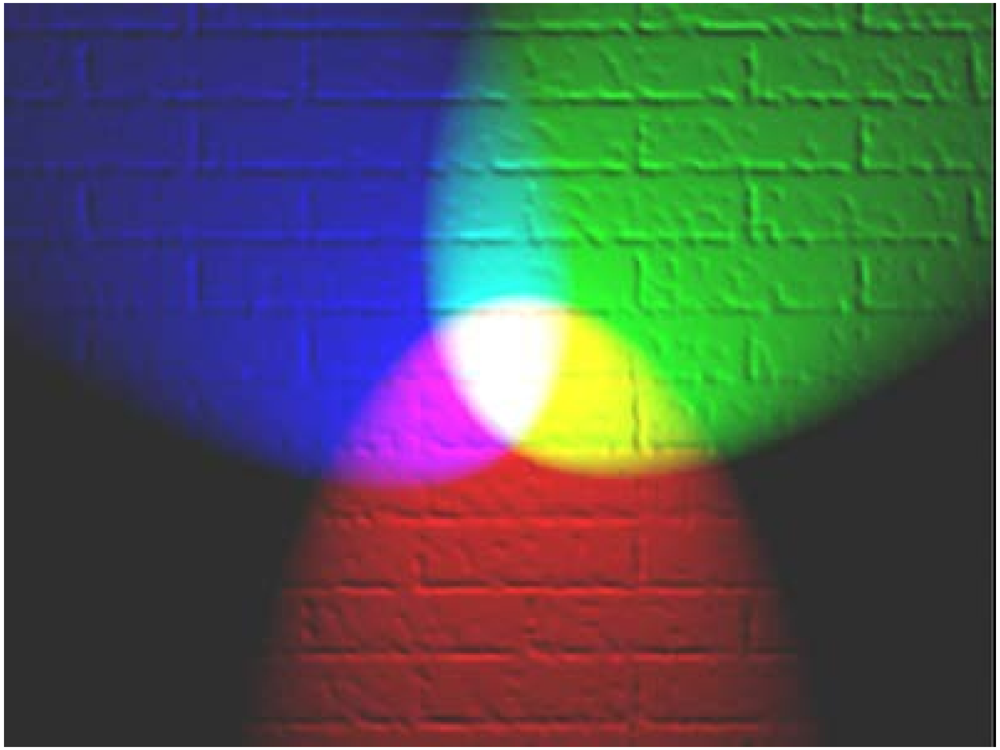
Images in Matlab

- Images represented as a matrix
- Suppose we have a NxM RGB image called “im”
  - im(1,1,1) = top-left pixel value in R-channel
  - im(y, x, b) = y pixels down, x pixels to right in the b^{th} channel
  - im(N, M, 3) = bottom-right pixel in B-channel
- imread(filename) returns a uint8 image (values 0 to 255)
  - Convert to double format (values 0 to 1) with im2double



Color spaces

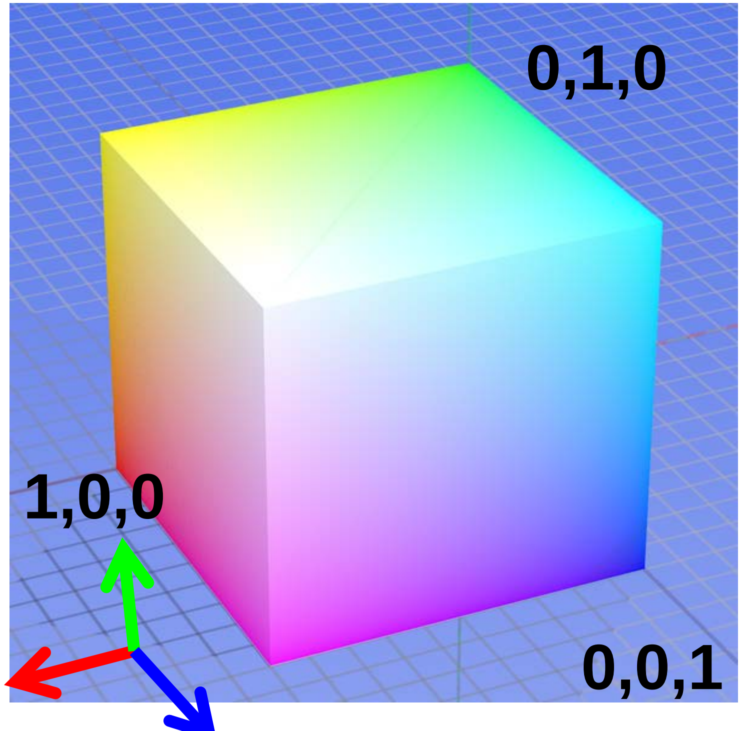
How can we represent color?



http://en.wikipedia.org/wiki/File:RGB_illumination.jpg

Color spaces: RGB

Default color space



RGB cube

- Easy for devices
- But not perceptual
- Where do the grays live?
- Where is hue and saturation?

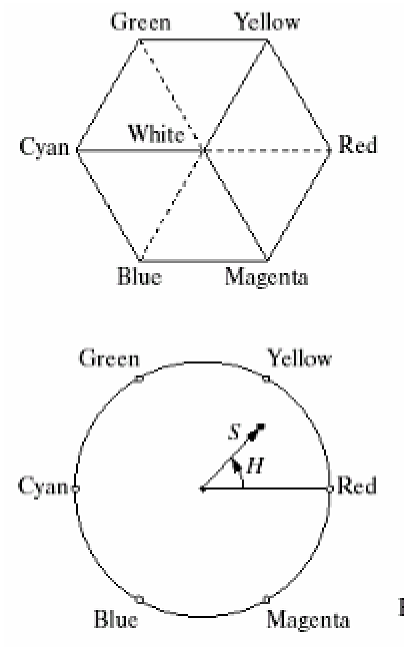
R
(G=0,B=0)

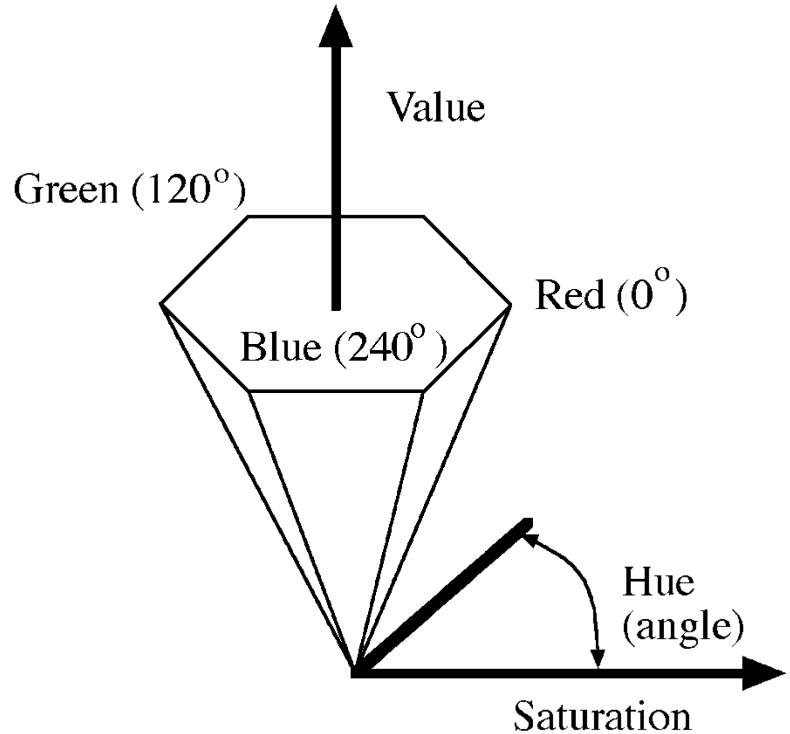
G
(R=0,B=0)

B
(R=0,G=0)

Image from: http://en.wikipedia.org/wiki/File:RGB_color_solid_cube.png

HSV





Hue, Saturation, Value (Intensity)

- RGB cube on its vertex

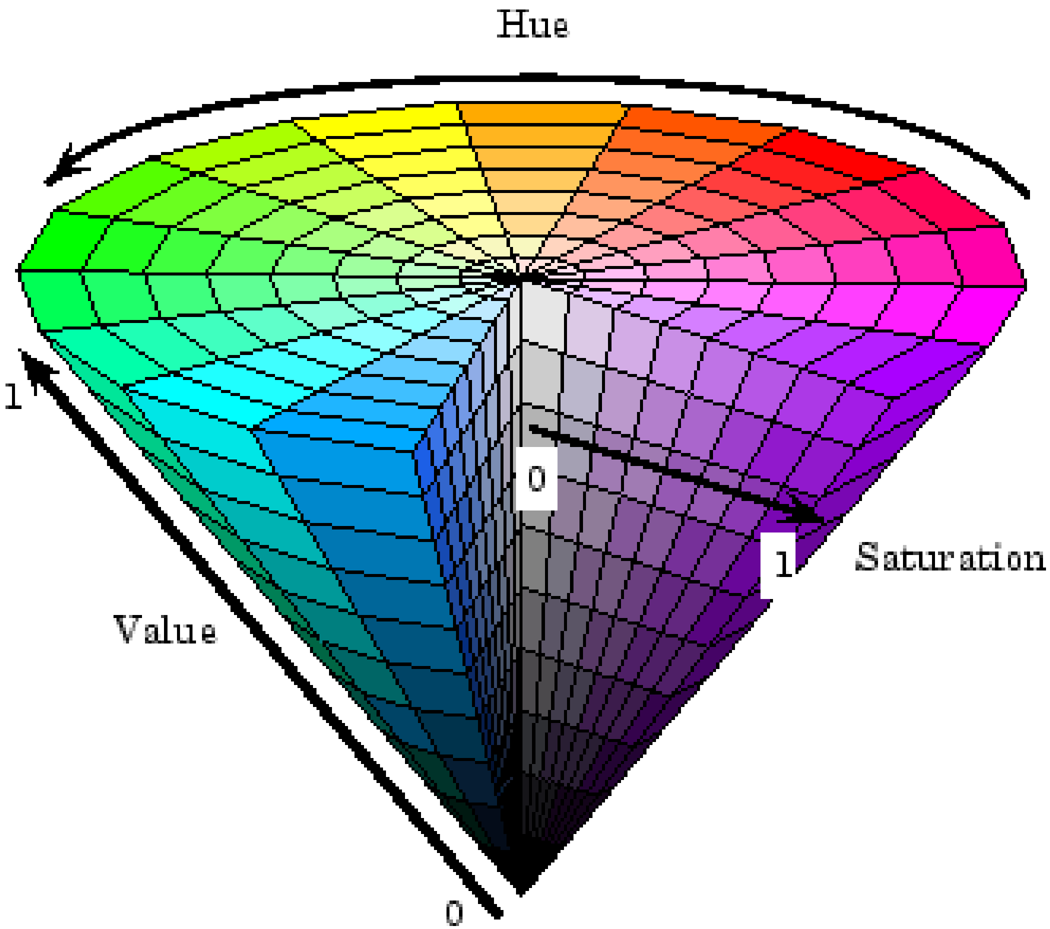
Decouples the three components (a bit)

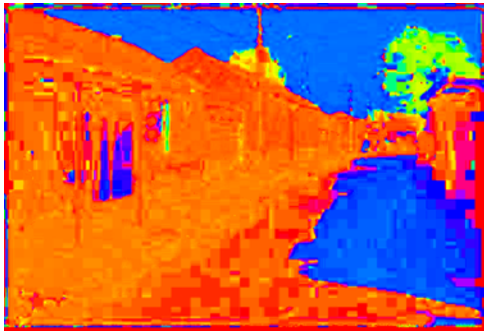
Use rgb2hsv() and hsv2rgb() in Matlab

Slide by Steve Seitz

Color spaces: HSV

Intuitive color space





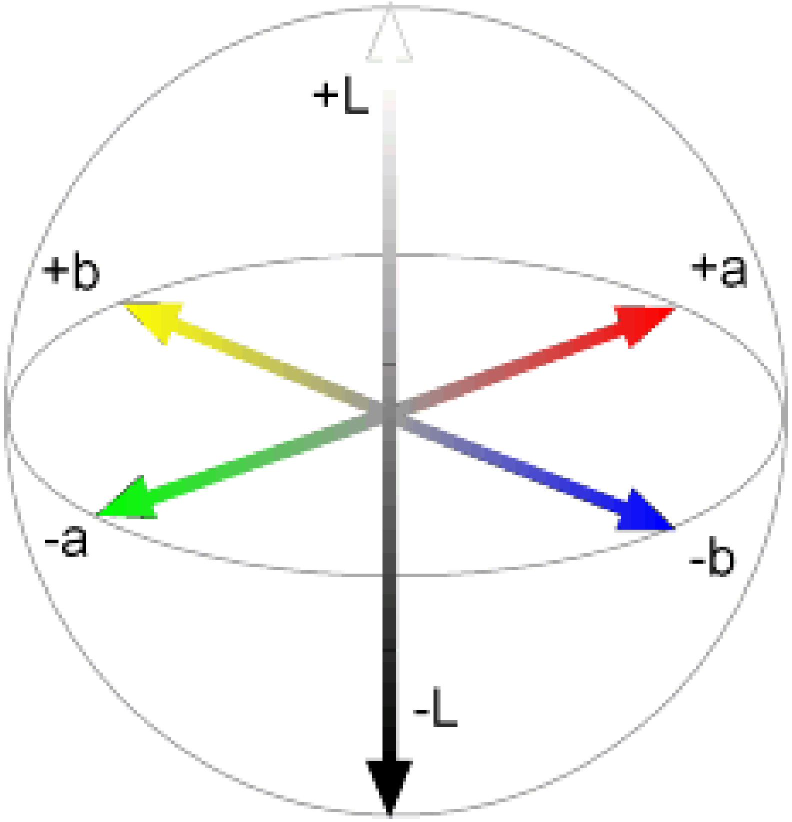
H
(S=1,V=1)

S
(H=1,V=1)

V
(H=1,S=0)

Color spaces: L*a*b*

"Perceptually uniform"* color space



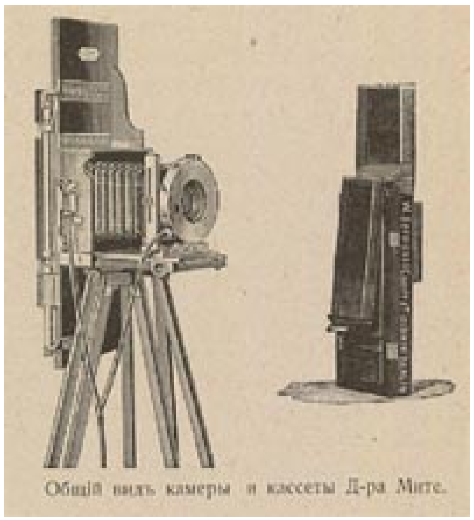
L
(a=0,b=0)

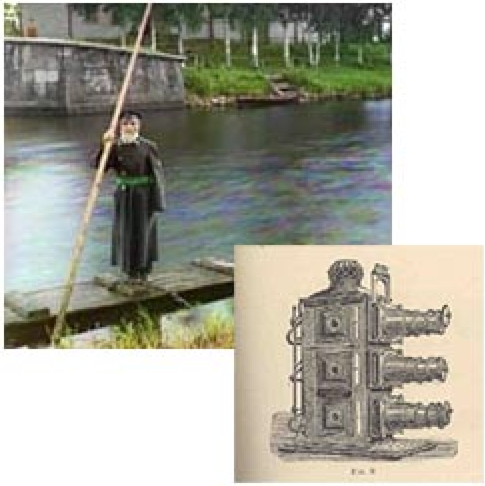
a
(L=65,b=0)

b
(L=65,a=0)

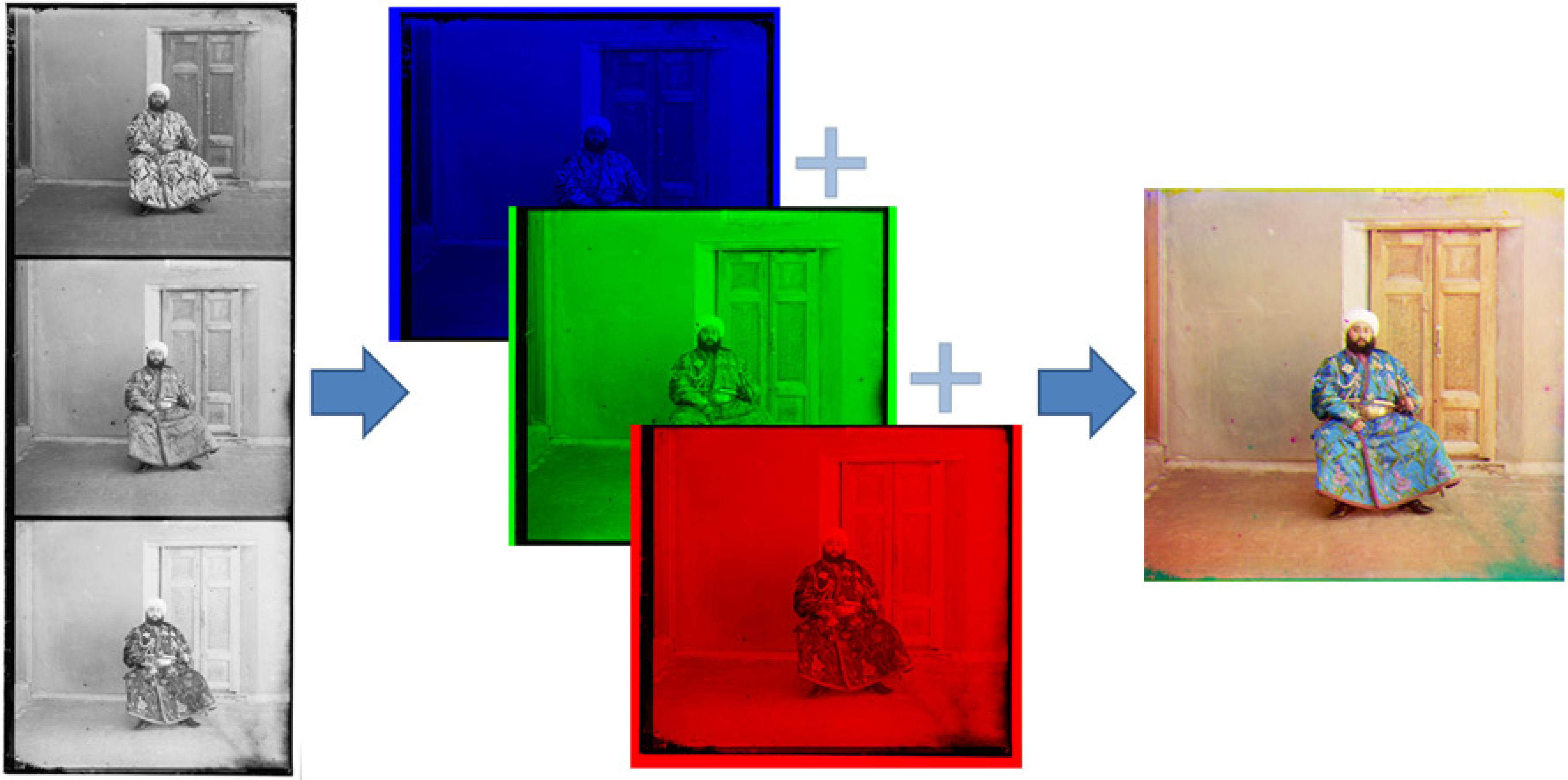
Programming Project #1

Prokudin-Gorskii’s Color Photography (1907)





Programming Project #1



Programming Project #1

- How to compare R,G,B channels?
- No right answer
  - Sum of Squared Differences (SSD):

$$ssd(u,v) = \sum_{(x,y)\in N} \left[I(u+x, v+y) - P(x,y)\right]^2$$

  - Normalized Correlation (NCC):

$$ncc(u,v) = \frac{\sum_{(x,y)\in N} \left[I(u+x, v+y) - \bar{I}\right]\left[P(x,y) - \overline{P}\right]}{\sqrt{\sum_{(x,y)\in N} \left[I(u+x, v+y) - \bar{I}\right]^2 \sum_{(x,y)\in N} \left[P(x,y) - \overline{P}\right]^2}}$$