inst.eecs.berkeley.edu/~cs61c/su05 CS61C: Machine Structures

Lecture #11: FP II & Pseudo Instructions



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FP Review

- Floating Point numbers <u>approximate</u> values that we want to use.
- IEEE 754 Floating Point Standard is most widely accepted attempt to standardize interpretation of such numbers
 - Every desktop or server computer sold since
 ~1997 follows these conventions
- Summary (single precision):

31 30 23 22 C S Exponent Significand

1 bit 8 bits 23 bits

- (-1)^S x (1 + Significand) x 2^(Exponent-127)
 - Double precision identical, bias of 1023

Representation for Denorms (1/3)

- Problem: There's a gap among representable FP numbers around 0
 - Smallest representable pos num:

$$a = 1.0..._2 * 2^{-126} = 2^{-126}$$

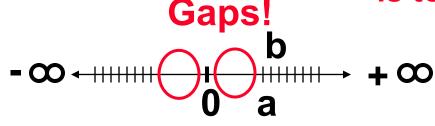
Second smallest representable pos num:

$$b = 1.000....1_{2} * 2^{-126} = 2^{-126} + 2^{-149}$$

$$a - 0 = 2^{-126}$$

$$b - a = 2^{-149}$$

Normalization and implicit 1 is to blame!





Representation for Denorms (2/3)

Solution:

- We still haven't used Exponent = 0,
 Significand nonzero
- Denormalized number: no leading 1, implicit exponent = -126.
- Smallest representable pos num:

$$a = 2^{-149}$$

Second smallest representable pos num:

$$b = 2^{-148}$$

$$-\infty \longleftrightarrow +\infty$$

$$0$$



Representation for Denorms (3/3)

- Normal FP equation:
 - (-1)^S x (1 + Significand) x 2^(Exponent-127)

- If (fp.exp == 0 and fp.signifcant != 0)
 - Denorm
 - (-1)^S x (0 + Significand) x 2⁽⁻¹²⁶⁾



IEEE Four Rounding Modes

- Math on real numbers ⇒ we worry about rounding to fit result in the significant field.
- FP hardware carries 2 extra bits of precision, and rounds for proper value
- Rounding occurs when converting...
 - double to single precision
 - floating point # to an integer



IEEE Four Rounding Modes

- Round towards + ∞
 - ALWAYS round "up": $2.1 \Rightarrow 3$, $-2.1 \Rightarrow -2$
- Round towards ∞
 - ALWAYS round "down": $1.9 \Rightarrow 1$, $-1.9 \Rightarrow -2$
- Truncate
 - Just drop the last bits (round towards 0)
- Round to (nearest) even (default)
 - Normal rounding, almost: $2.5 \Rightarrow 2$, $3.5 \Rightarrow 4$
 - Like you learned in grade school
 - Insures fairness on calculation
 - Half the time we round up, other half down



Clarification - IEEE Four Rounding Modes

- This is just an example in base 10 to show you the 4 modes.
- What really happens is...
- 1) in binary, not decimal!
- 2) at the lowest bit of the mantissa with the guard bit(s) as our extra bit(s), and you need to decide how these extra bit(s) affect the result if the guard bits are "100..."
- 3) If so, you're half-way between the representable numbers.
- E.g., 0.1010 is 5/8, halfway between our representable 4/8 [1/2] and 6/8 [3/4]. Which number do we round to? 4 modes!

Integer Multiplication (1/3)

Paper and pencil example (unsigned):

```
Multiplier x1001 9

Multiplier x1001 9

0000

0000

+1000

01001000
```

• m bits x n bits = m + n bit product



Integer Multiplication (2/3)

- In MIPS, we multiply registers, so:
 - 32-bit value x 32-bit value = 64-bit value
- Syntax of Multiplication (signed):
 - mult register1, register2
 - Multiplies 32-bit values in those registers & puts 64-bit product in special result regs:
 - puts product upper half in hi, lower half in lo
 - hi and lo are 2 registers separate from the 32 general purpose registers
 - Use mfhi register & mflo register to move from hi, lo to another register



Integer Multiplication (3/3)

• Example:

```
• in C: a = b * c;
```

• in MIPS:

- let b be \$s2; let c be \$s3; and let a be \$s0 and \$s1 (since it may be up to 64 bits)

 Note: Often, we only care about the lower half of the product.

Integer Division (1/2)

Paper and pencil example (unsigned):

Dividend = Quotient x Divisor + Remainder



Integer Division (2/2)

- Syntax of Division (signed):
 - div register1, register2
 - Divides 32-bit register 1 by 32-bit register 2:
 - puts remainder of division in hi, quotient in lo
- Implements C division (/) and modulo (%)

```
• Example in C: a = c / d;
b = c % d;
```

• in MIPS: a↔\$s0;b↔\$s1;c↔\$s2;d↔\$s3

```
div $s2,$s3 # lo=c/d, hi=c%d
mflo $s0 # get quotient
mfhi $s1 # get remainder
```



Unsigned Instructions & Overflow

 MIPS also has versions of mult, div for unsigned operands:

multu

divu

- Determines whether or not the product and quotient are changed if the operands are signed or unsigned.
- MIPS does not check overflow on ANY signed/unsigned multiply, divide instr
 - Up to the software to check hi



FP Addition & Subtraction

- Much more difficult than with integers (can't just add significands)
- How do we do it?
 - De-normalize to match larger exponent
 - Add significands to get resulting one
 - Normalize (& check for under/overflow)
 - Round if needed (may need to renormalize)
- If signs ≠, do a subtract. (Subtract similar)
 - If signs ≠ for add (or = for sub), what's ans sign?
- Question: How do we integrate this into the integer arithmetic unit? [Answer: We don't!]



MIPS Floating Point Architecture (1/4)

- Separate floating point instructions:
 - Single Precision:

```
add.s, sub.s, mul.s, div.s
```

Double Precision:

```
add.d, sub.d, mul.d, div.d
```

- These are <u>far more complicated</u> than their integer counterparts
 - Can take much longer to execute



MIPS Floating Point Architecture (2/4)

Problems:

- Inefficient to have different instructions take vastly differing amounts of time.
- Generally, a <u>particular piece of data will</u> not change FP ⇔ int within a program.
 - Only 1 type of instruction will be used on it.
- Some programs do no FP calculations
- It takes lots of hardware relative to integers to do FP fast



MIPS Floating Point Architecture (3/4)

- 1990 Solution: Make a completely separate chip that handles only FP.
- Coprocessor 1: FP chip
 - contains 32 32-bit registers: \$f0, \$f1, ...
 - most of the registers specified in .s and
 d instruction refer to this set
 - separate load and store: 1wc1 and swc1 ("load word coprocessor 1", "store ...")
 - Double Precision: by convention,
 even/odd pair contain one DP FP number:
 \$£0/\$£1, \$£2/\$£3, ..., \$£30/\$£31
 - Even register is the name



MIPS Floating Point Architecture (4/4)

- 1990 Computer actually contains multiple separate chips:
 - Processor: handles all the normal stuff
 - Coprocessor 1: handles FP and only FP;
 - more coprocessors?... Yes, later
 - Today, FP coprocessor integrated with CPU, or cheap chips may leave out FP HW
- Instructions to move data between main processor and coprocessors:
 - •mfc0, mtc0, mfc1, mtc1, etc.
- Appendix pages A-70 to A-74 contain many, many more FP operations.

FP/Math Summary

Reserve exponents, significands:

Exponent	Significand	Object
0	0	0
0	nonzero	Denorm
1-254	anything	+/- fl. pt. #
255	0	+/- ∞
255	nonzero	NaN

- Integer mult, div uses hi, lo regs
 mfhi and mflo copies out.
- Four rounding modes (to even default)

MIPS FL ops complicated, expensive

Administrivia

- Midterm TOMORROW!!!11!one!
 - 11:00 **–** 2:00
 - 277 Cory
 - You may bring with you:
 - The green sheet from COD or a photocopy thereof
 - One 8 ½" x 11" note sheet with handwritten notes on one side
 - No books, calculators, other shenanigans
 - Conflicts, DSP, other issues:
 - let me know ASAP



Review from before: lui

- •So how does lui help us?
 - Example:

```
addi $t0,$t0, 0xABABCDCD
```

becomes:

```
lui $at, 0xABAB
ori $at, $at, 0xCDCD
add $t0,$t0,$at
```

- Now each I-format instruction has only a 16bit immediate.
- Wouldn't it be nice if the assembler would this for us automatically?
 - If number too big, then just automatically replace addi with lui, ori, add



True Assembly Language (1/3)

- Pseudoinstruction: A MIPS instruction that doesn't turn directly into a machine language instruction, but into other MIPS instructions
- What happens with pseudoinstructions?
 - They're broken up by the assembler into several "real" MIPS instructions.
 - But what is a "real" MIPS instruction?
 Answer in a few slides
- First some examples



Example Pseudoinstructions

Register Move

```
move reg2,reg1
Expands to:
add reg2,$zero,reg1
```

Load Immediate

```
li reg, value
If value fits in 16 bits:
addi reg, $zero, value
else:
lui reg, upper 16 bits of value
ori reg, $zero, lower 16 bits
```



True Assembly Language (2/3)

Problem:

- When breaking up a pseudoinstruction, the assembler may need to use an extra reg.
- If it uses any regular register, it'll overwrite whatever the program has put into it.

Solution:

- Reserve a register (\$1, called \$at for "assembler temporary") that assembler will use to break up pseudo-instructions.
- Since the assembler may use this at any time, it's not safe to code with it.



Example Pseudoinstructions

Rotate Right Instruction

```
ror reg, value

Expands to:

srl $at, reg, value

sll reg, reg, 32-value

or reg, reg, $at
```

"No OPeration" instruction

nop

Expands to instruction = 0_{ten} , \$11 \$0, \$0, 0



Example Pseudoinstructions

Wrong operation for operand

```
addu reg, reg, value # should be addiu
```

If value fits in 16 bits, addu is changed to:

```
addiu reg, reg, value
```

else:

lui \$at,upper 16 bits of value

ori \$at,\$at,lower 16 bits

addu reg, reg, \$at

 How do we avoid confusion about whether we are talking about MIPS assembler with or without pseudoinstructions?

True Assembly Language (3/3)

- MAL (MIPS Assembly Language): the set of instructions that a programmer may use to code in MIPS; this includes pseudoinstructions
- TAL (True Assembly Language): set of instructions that can actually get translated into a single machine language instruction (32-bit binary string)
- A program must be converted from MAL into TAL before translation into 1s & 0s.



Questions on Pseudoinstructions

Question:

 How does MIPS recognize pseudoinstructions?

Answer:

- It looks for officially defined pseudoinstructions, such as ror and move
- It looks for special cases where the operand is incorrect for the operation and tries to handle it gracefully



Rewrite TAL as MAL

• TAL:

```
or $v0,$0,$0
Loop: slt $t0,$0,$a1
beq $t0,$0,Exit
add $v0,$v0,$a0
addi $a1,$a1,-1
j Loop
Exit:
```

- This time convert to MAL
- It's OK for this exercise to make up MAL instructions

Rewrite TAL as MAL (Answer)

```
• TAL:

Loop:

slt $t0,$0,$1

beq $t0,$0,Exit

add $v0,$v0,$a0

addi $a1,$a1,-1

j Loop

Exit:
```

• MAL:

```
Loop: bge $zero,$a1,Exit add $v0,$v0,$a0 sub $a1,$a1,1 j Loop

Exit:
```



Peer Instruction

Which of the instructions below are MAL and which are TAL?

```
A.addi $t0, $t1, 40000
```

```
B.beq $s0, 10, Exit
```

C.sub \$t0, \$t1, 1



In conclusion

- Assembler expands real instruction set (TAL) with pseudoinstructions (MAL)
 - Only TAL can be converted to raw binary
 - Assembler's job to do conversion
 - Assembler uses reserved register \$at
 - MAL makes it <u>much</u> easier to write MIPS

