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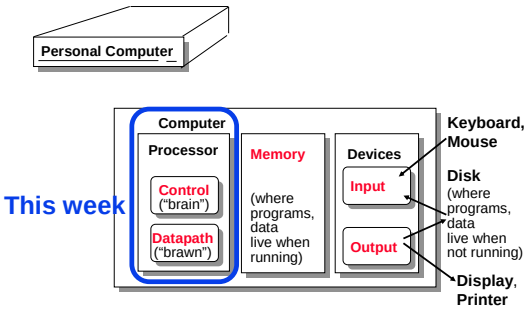
CS61C : Machine Structures

Lecture #17: CPU Design II – Control

2005-07-19

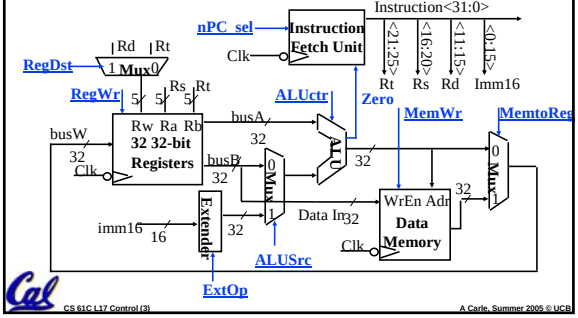
Andy Carle

Anatomy: 5 components of any Computer



Review: A Single Cycle Datapath

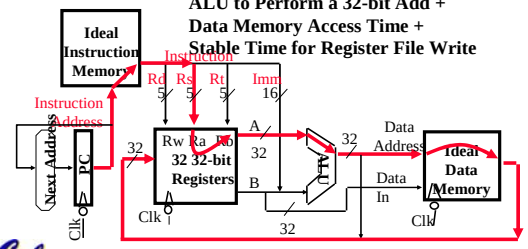
- Rs, Rt, Rd, Imed16 connected to datapath
- We have everything except control signals



An Abstract View of the Critical Path

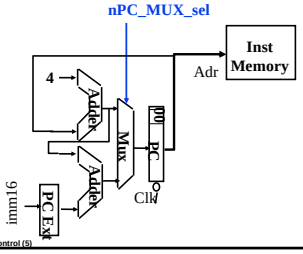
- This affects how much you can overclock your PC!

Critical Path (Load Operation) =
Delay clock through PC (FFs) +
Instruction Memory's Access Time +
Register File's Access Time, +
ALU to Perform a 32-bit Add +
Data Memory Access Time +
Stable Time for Register File Write



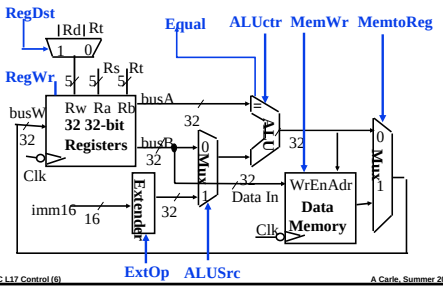
Recap: Meaning of the Control Signals

- nPC_MUX_sel: "n"=next
  - 0 ⇒ PC <– PC + 4
  - 1 ⇒ PC <– PC + 4 + {SignExt(Im16) , 00 }
- Later in lecture: higher-level connection between mux and branch cond

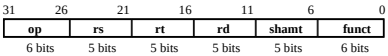


Recap: Meaning of the Control Signals

- ExtOp: "zero", "sign"
- ALUsrc: 0 ⇒ regB; 1 ⇒ immed
- ALUctr: "add", "sub", "or"
- MemWr: 1 ⇒ write memory
- MemtoReg: 0 ⇒ ALU; 1 ⇒ Mem
- RegDst: 0 ⇒ "rt"; 1 ⇒ "rd"
- RegWr: 1 ⇒ write register



RTL: The Add Instruction

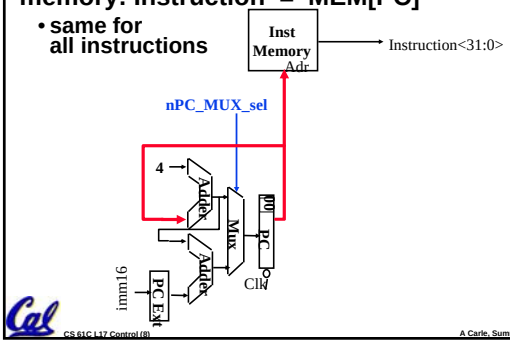


`add rd, rs, rt`

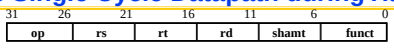
- MEM[PC] Fetch the instruction from memory
- R[rd] = R[rs] + R[rt] The actual operation
- PC = PC + 4 Calculate the next instruction's address

Instruction Fetch Unit at the Beginning of Add

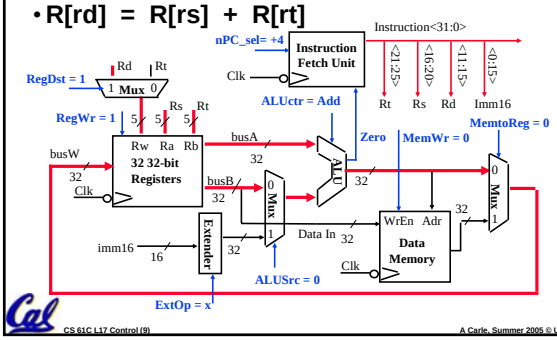
- Fetch the instruction from Instruction memory: Instruction = MEM[PC]
  - same for all instructions



The Single Cycle Datapath during Add

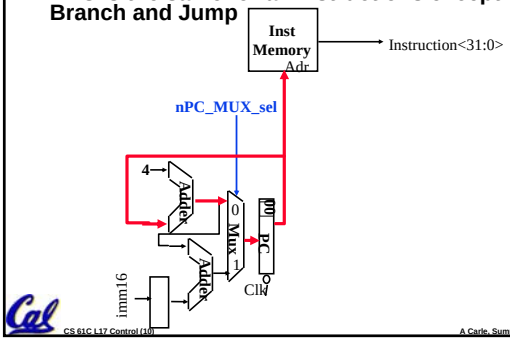


- R[rd] = R[rs] + R[rt]

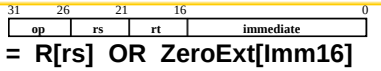


Instruction Fetch Unit at the End of Add

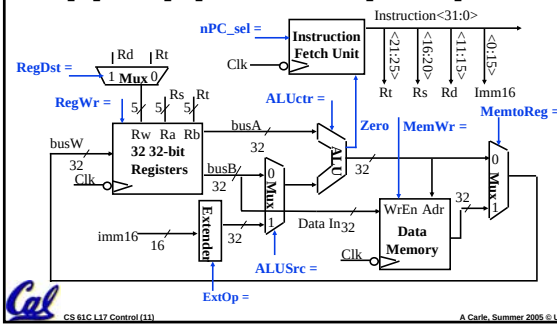
- PC = PC + 4
  - This is the same for all instructions except: Branch and Jump



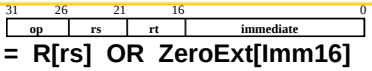
Single Cycle Datapath during Or Immediate?



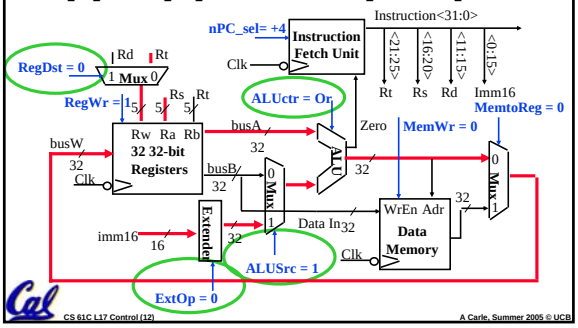
- R[rt] = R[rs] OR ZeroExt[Imm16]



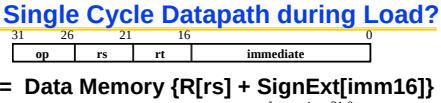
Single Cycle Datapath during Or Immediate?



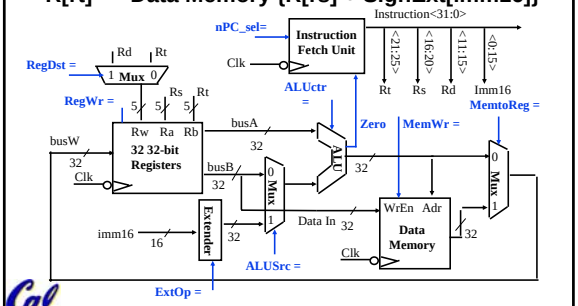
- R[rt] = R[rs] OR ZeroExt[Imm16]



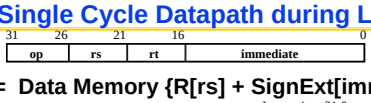
The Single Cycle Datapath during Load?



• R[rt] = Data Memory {R[rs] + SignExt[imm16]}



The Single Cycle Datapath during Load



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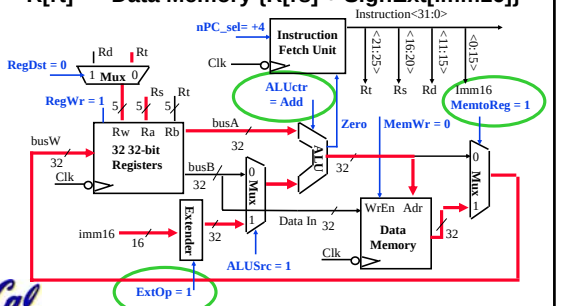
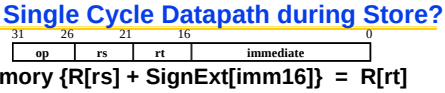
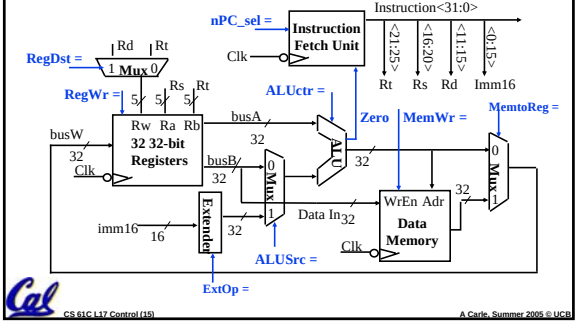


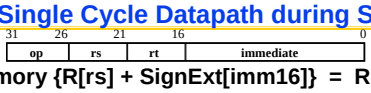
The Single Cycle Datapath during Store?



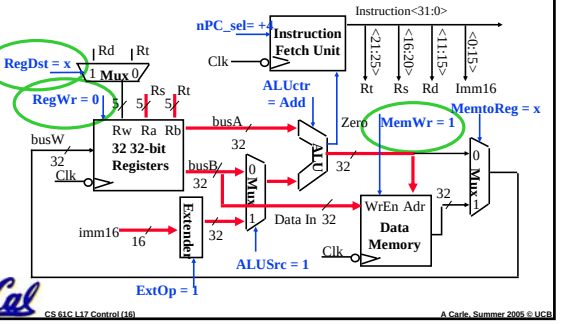
• Data Memory {R[rs] + SignExt[imm16]} = R[rt]



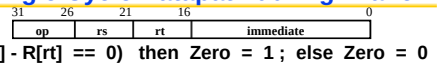
The Single Cycle Datapath during Store



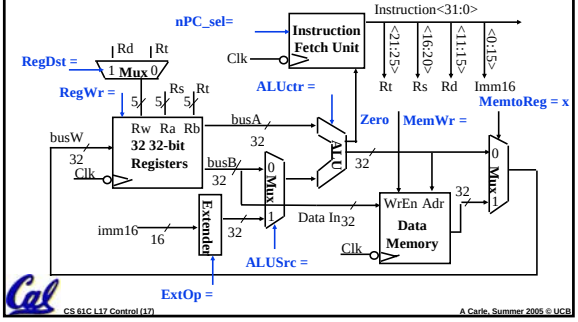
• Data Memory {R[rs] + SignExt[imm16]} = R[rt]



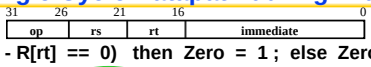
The Single Cycle Datapath during Branch?



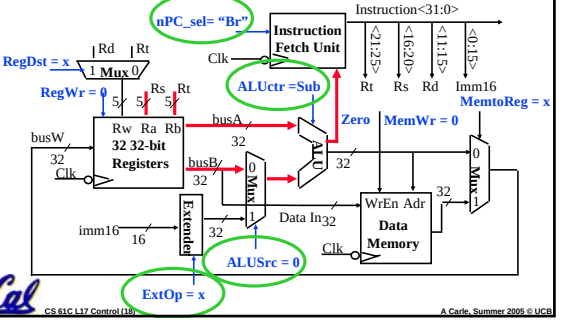
• if (R[rs] - R[rt] == 0) then Zero = 1 ; else Zero = 0



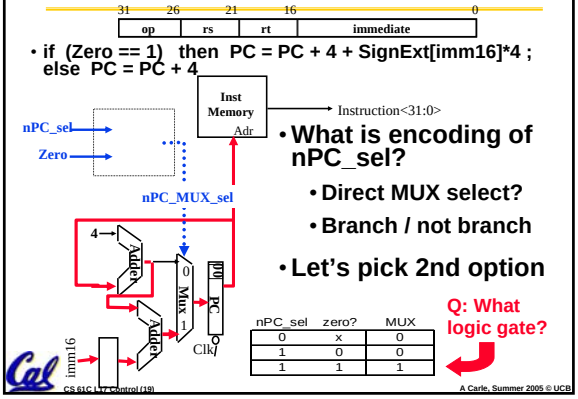
The Single Cycle Datapath during Branch



• if (R[rs] - R[rt] == 0) then Zero = 1 ; else Zero = 0



Instruction Fetch Unit at the End of Branch



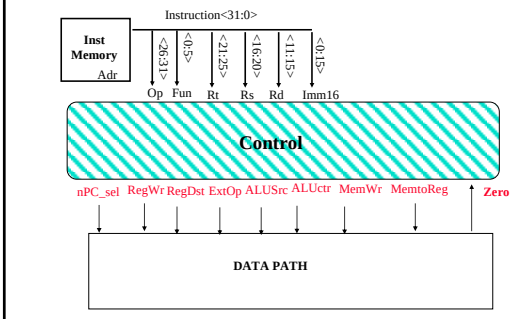
- if (Zero == 1) then PC = PC + 4 + SignExt[imm16]*4 ; else PC = PC + 4

- What is encoding of nPC_sel?
  - Direct MUX select?
  - Branch / not branch
- Let's pick 2nd option

Q: What logic gate?

nPC_sel	zero?	MUX
0	x	0
1	0	0
1	1	1

Step 4: Given Datapath: RTL -> Control



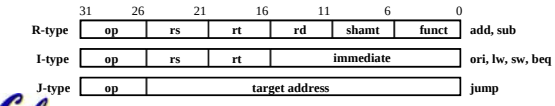
A Summary of the Control Signals (1/2)

inst	Register Transfer	
ADD	R[rd] <– R[rs] + R[rt];	PC <– PC + 4
	ALUsrc = RegB, ALUctr = "add", RegDst = rd, RegWr, nPC_sel = "+4"	
SUB	R[rd] <– R[rs] – R[rt];	PC <– PC + 4
	ALUsrc = RegB, ALUctr = "sub", RegDst = rd, RegWr, nPC_sel = "+4"	
ORi	R[rt] <– R[rs] + zero_ext(Imm16);	PC <– PC + 4
	ALUsrc = Im, Extop = "Z", ALUctr = "or", RegDst = rt, RegWr, nPC_sel ="+4"	
LOAD	R[rt] <– MEM[R[rs] + sign_ext(Imm16)];	PC <– PC + 4
	ALUsrc = Im, Extop = "Sn", ALUctr = "add", MemtoReg, RegDst = rt, RegWr,	nPC_sel = "+4"
STORE	MEM[R[rs] + sign_ext(Imm16)] <– R[rs];	PC <– PC + 4
	ALUsrc = Im, Extop = "Sn", ALUctr = "add", MemWr, nPC_sel = "+4"	
BEQ	if (R[rs] == R[rt]) then PC <– PC + sign_ext(Imm16)] || 00 else PC <– PC + 4	
	nPC_sel = "Br", ALUctr = "sub"	

A Summary of the Control Signals (2/2)

See Appendix A

func	10 0000	10 0010	We Don't Care :-)				
op	00 0000	00 0000	00 1101	10 0011	10 1011	00 0100	00 0010
	add	sub	ori	lw	sw	beq	jump
RegDst	1	1	0	0	x	x	x
ALUSrc	0	0	1	1	1	0	x
MemtoReg	0	0	0	1	x	x	x
RegWrite	1	1	1	1	0	0	0
MemWrite	0	0	0	0	1	0	0
nPCsel	0	0	0	0	0	1	0
Jump	0	0	0	0	0	0	1
ExtOp	x	x	0	1	1	x	x
ALUctr<2:0>	Add	Subtract	Or	Add	Add	Subtract	xxx

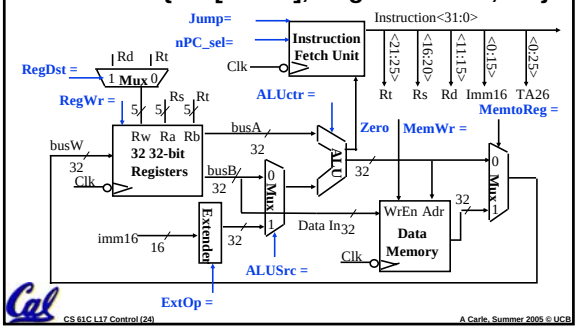


Administrivia

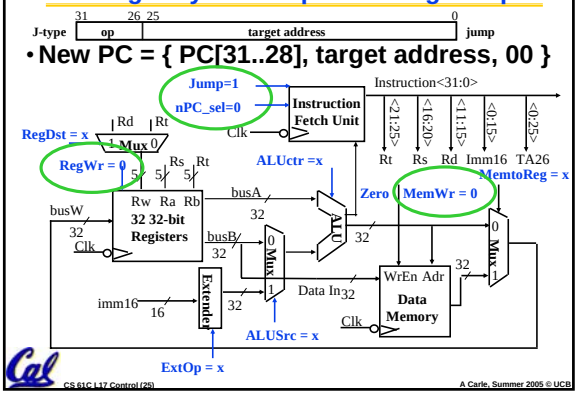
- Project 2 Due Sunday
- HW 6 out tomorrow
- Slight shakeup of the schedule starting tomorrow (we're only doing one Control lecture)
  - This allows us to have the second midterm before the drop deadline, if that would be preferable

The Single Cycle Datapath during Jump

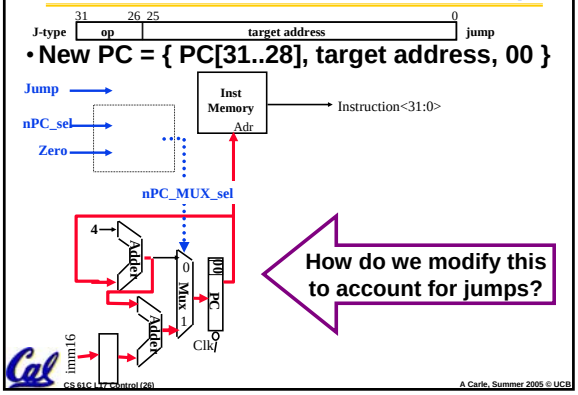
- New PC = { PC[31..28], target address, 00 }



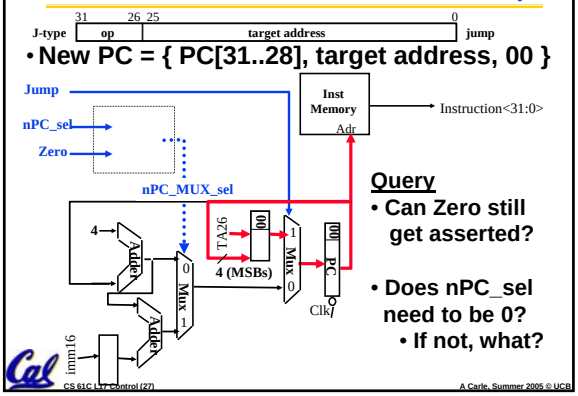
The Single Cycle Datapath during Jump



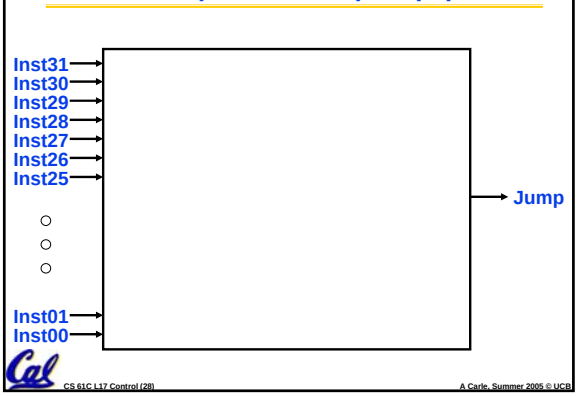
Instruction Fetch Unit at the End of Jump



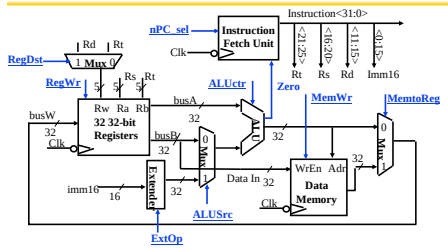
Instruction Fetch Unit at the End of Jump



Build CL to implement Jump on paper now



Peer Instruction



A. MemToReg='x' & ALUctr='sub'. SUB or BEQ?

B. ALUctr='add'. Which 1 signal is different for all 3 of: ADD, LW, & SW? RegDst or ExtOp?

C. "Don't Care" signals are useful because we can simplify our Boolean equations?

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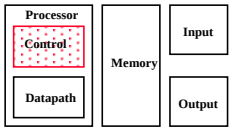
And in Conclusion... Single cycle control

- 5 steps to design a processor
  - 1. Analyze instruction set => datapath requirements
  - 2. Select set of datapath components & establish clock methodology
  - 3. Assemble datapath meeting the requirements
  - 4. Analyze implementation of each instruction to determine setting of control points that effects the register transfer.
  - 5. Assemble the control logic
- Control is the hard part
- MIPS makes that easier
  - Instructions same size
  - Source registers always in same place
  - Immediates same size, location
  - Operations always on registers/immediates



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