

1. Orthogonal Matching Pursuit Lecture

Orthogonal Matching Pursuit (OMP) algorithm:

Inputs:

- A set of m songs, each of length n : $\mathbf{S} = \{\vec{S}_0, \vec{S}_1, \dots, \vec{S}_{m-1}\}$
- An n -dimensional received signal vector: \vec{r}
- The sparsity level k of the signal
- Some threshold, th . When the norm of the signal is below this value, the signal contains only noise.

Outputs:

- A set of songs that were identified, F , which will contain at most k elements
- A vector \vec{x} containing song messages (a_1, a_2, \dots) , which will be of length k or less
- An n -dimensional residual \vec{y}

Procedure:

- Initialize the following values: $\vec{y} = \vec{r}$, $j = 1$, k , $\mathbf{A} = []$, $F = \{\emptyset\}$
- while $((j \leq k) \text{ and } (\|\vec{y}\| \geq th))$:
 - (a) Cross-correlate \vec{y} with the shifted versions of all songs. Find the song index i and the shifted version of the song, \vec{S}_i^N , with which the received signal has the highest correlation value.
 - (b) Add i to the set of song indices F .
 - (c) Column concatenate matrix \mathbf{A} with the correctly shifted version of the song: $\mathbf{A} = [\mathbf{A} \mid \vec{S}_i^N]$
 - (d) Use least squares to obtain the message value: $\vec{x} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \vec{r}$
 - (e) Update the residual value \vec{y} by subtracting: $\vec{y} = \vec{r} - \mathbf{A} \vec{x}$
 - (f) Update the counter: $j = j + 1$

2. Orthogonal Matching Pursuit

Let's work through an example of the OMP algorithm. Suppose that we have a vector $\vec{x} \in \mathbb{R}^4$. We take 3 measurements of it, $b_1 = \vec{m}_1^T \vec{x} = 4$, $b_2 = \vec{m}_2^T \vec{x} = 6$, and $b_3 = \vec{m}_3^T \vec{x} = 3$, where \vec{m}_1 , \vec{m}_2 and \vec{m}_3 are some measurement vectors. We are given that \vec{x} is sparse and only has 2 non-zero entries. In particular,

$$\mathbf{M}\vec{x} \approx \vec{b}$$

$$\begin{bmatrix} - & \vec{m}_1^T & - \\ - & \vec{m}_2^T & - \\ - & \vec{m}_3^T & - \end{bmatrix} \vec{x} \approx \vec{b}$$

$$\begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \approx \begin{bmatrix} 5 \\ 1 \\ 1 \end{bmatrix}$$

where exactly 2 of x_1 to x_4 are non-zero. Use Orthogonal Matching Pursuit to estimate x_1 to x_4 .

- Why can we not solve for \vec{x} directly?
- Why can we not apply the least squares process to obtain \vec{x} ?
- Compute the inner product of every column with the \vec{b} vector. Which column has the largest inner product? This will be the first column of the matrix \mathbf{A} . Why are we using the inner product instead of the correlation? Does it make sense to shift the columns of \mathbf{A} ?
- Now find the projection of \vec{b} onto the columns of \mathbf{A} . Use this to update the residual.
- Now compute the inner product of every column with the new residual vector. Which column has the largest inner product? This will be the second column of \mathbf{A} .
- Project \vec{b} onto the columns of \mathbf{A} to find \vec{x} .

3. One Magical Procedure (Fall 2015 Final)

Suppose that we have a vector $\vec{x} \in \mathbb{R}^5$ and an $N \times 5$ measurement matrix \mathbf{M} defined by column vectors $\vec{c}_1, \dots, \vec{c}_5$, such that:

$$\mathbf{M}\vec{x} = \begin{bmatrix} | & & | \\ \vec{c}_1 & \cdots & \vec{c}_5 \\ | & & | \end{bmatrix} \vec{x} \approx \vec{b}$$

We can treat the vector $\vec{b} \in \mathbb{R}^N$ as a noisy measurement of the vector \vec{x} , with measurement matrix \mathbf{M} and some additional noise in it as well.

You also know that the true \vec{x} is sparse – it only has two non-zero entries and all the rest of the entries are zero in reality. Our goal is to recover this original \vec{x} as best we can.

However, your intern has managed to lose not only the measurements \vec{b} but the entire measurement matrix \mathbf{M} as well!

Fortunately, you have found a backup in which you have all the pairwise inner products $\langle \vec{c}_i, \vec{c}_j \rangle$ between the columns of \mathbf{M} and each other as well as all the inner products $\langle \vec{c}_i, \vec{b} \rangle$ between the columns of \mathbf{M} and the vector \vec{b} . Finally, you also know the inner product $\langle \vec{b}, \vec{b} \rangle$ of \vec{b} with itself.

All the information you have is captured in the following table of inner products. (These are not the vectors themselves.)

| $\langle \cdot, \cdot \rangle$ | \vec{c}_1 | \vec{c}_2 | \vec{c}_3 | \vec{c}_4 | \vec{c}_5 | \vec{b} |
|--------------------------------|-------------|-------------|-------------|-------------|-------------|-----------|
| \vec{c}_1 | 2 | 0 | 1 | -1 | 1 | 1 |
| \vec{c}_2 | | 2 | 1 | -1 | -1 | -5 |
| \vec{c}_3 | | | 2 | 0 | -1 | 2 |
| \vec{c}_4 | | | | 2 | -1 | 6 |
| \vec{c}_5 | | | | | 2 | -1 |
| \vec{b} | | | | | | 29 |

(So, for example, if you read this table, you will see that the inner product $\langle \vec{c}_2, \vec{c}_3 \rangle = 1$, that the inner product $\langle \vec{c}_3, \vec{b} \rangle = 2$, and that the inner product $\langle \vec{b}, \vec{b} \rangle = 29$. By symmetry of the real inner product, $\langle \vec{c}_3, \vec{c}_2 \rangle = 1$ as well.)

Your goal is to find which entries of \vec{x} are non-zero and what their values are.

- (a) Use the information in the table above to answer which of the $\vec{c}_1, \dots, \vec{c}_5$ has the largest magnitude inner product with \vec{b} .
- (b) Let the vector with the largest magnitude inner product with \vec{b} be \vec{c}_a . Let \vec{b}_p be the projection of \vec{b} onto \vec{c}_a . Write \vec{b}_p symbolically as an expression only involving \vec{c}_a, \vec{b} , and their inner products with themselves and each other.
- (c) Use the information in the table above to find which of the column vectors $\vec{c}_1, \dots, \vec{c}_5$ has the largest magnitude inner product with the residue $\vec{b} - \vec{b}_p$.
Hint: The linearity of inner products might prove useful.
- (d) Suppose that the vectors we found in parts (a) and (c) are \vec{c}_a and \vec{c}_c . These correspond to the components of \vec{x} that are non-zero, that is, $\vec{b} \approx x_a \vec{c}_a + x_c \vec{c}_c$. However, there might be noise in the measurements \vec{b} , so we want to find the linear least squares estimates \hat{x}_a and \hat{x}_c . Write a matrix expression for $\begin{bmatrix} \hat{x}_a \\ \hat{x}_c \end{bmatrix}$ in terms of appropriate matrices filled with the inner products of $\vec{c}_a, \vec{c}_c, \vec{b}$.

(e) Compute the numerical values of \hat{x}_a and \hat{x}_c using the information in the table.