## EECS 16A Designing Information Devices and Systems I Fall 2017 Official Lecture Notes

### 28.1 Speeding up 0MP

In the last lecture note, we introduced orthogonal matching pursuit, an algorithm that can extract information from sparse signals. Recall that in each iteration of the algorithm, we need to compute the projection of the measurement vector $\vec{y}$ onto the subspace spanned by the signatures computed so far. If we let $A_{j}$ be a matrix whose columns are the 'songs' found so far in iteration $j$ and let $\vec{r}$ be the received signal, we compute $A_{j}\left(A_{j}^{T} A_{j}\right)^{-1} A_{j}^{T} \vec{r}$ to get the projection of $\vec{r}$ onto span $\left(A_{j}\right)$. Matrix inversion and matrix multiplication can be computationally expensive - inversion is $\mathrm{O}\left(n^{3}\right)$ and multiplication is $\mathrm{O}\left(n^{2}\right)$. Is there a way to avoid doing such computations? Yes! It turns out that if the columns of $A_{j}$ are mutually orthogonal to each other, the projection of $\vec{r}$ onto span $\left(A_{j}\right)$ is the sum of the projection of $\vec{r}$ onto each of the columns of $A_{j}$. Recall that the projection of a vector $\vec{r}$ on any other nonzero vector $\vec{b}$ of the same size is

$$
\begin{equation*}
\vec{r}_{b}=\frac{\vec{r}^{T} \vec{b}}{\|\vec{b}\|^{2}} \vec{b} \tag{1}
\end{equation*}
$$

This is fast to compute as computing the dot product of two vectors and the norm of a vector takes linear in time in the number of components in the vectors.

Let's take a look at the case where $j=2$ and the signatures are mutually orthogonal. Suppose the songs found so far are $\vec{S}_{1}$ and $\vec{S}_{2}$, i.e., $A_{2}=\left[\begin{array}{cc}\mid & \mid \\ \vec{S}_{1} & \vec{S}_{2} \\ \mid & \mid\end{array}\right]$. Since $\vec{S}_{1}$ and $\vec{S}_{2}$ are orthogonal to each other, we have $\vec{S}_{1}^{T} \vec{S}_{2}=0$. The least squares solution of $A_{2} \vec{x}=\vec{r}$ is given by:

$$
\begin{equation*}
\vec{x}=\left(A_{2}^{T} A_{2}\right)^{-1} A_{2}^{T} \vec{r} \tag{2}
\end{equation*}
$$

and we now multiply by $A_{2}$ to obtain the projection of the least sqaures solution onto the subspace spanned by $A_{2}$ :

$$
\begin{equation*}
\vec{r}_{A_{2}}=A_{2}\left(A_{2}^{T} A_{2}\right)^{-1} A_{2}^{T} \vec{r} \tag{3}
\end{equation*}
$$

Let's first compute the term $\left(A_{2}^{T} A_{2}\right)^{-1}$ :

$$
\begin{align*}
A_{2}^{T} A_{2} & =\left[\begin{array}{ccc}
- & \vec{S}_{1}^{T} & - \\
- & \vec{S}_{2}^{T} & -
\end{array}\right]\left[\begin{array}{cc}
\mid & \mid \\
\vec{S}_{1} & \vec{S}_{2} \\
\mid & \mid
\end{array}\right]  \tag{4}\\
& =\left[\begin{array}{ll}
\vec{S}_{1}^{T} & \vec{S}_{1} \\
\vec{S}_{1}^{T} & \vec{S}_{2} \\
\vec{S}_{2} & \vec{S}_{1} \\
\vec{S}_{2}^{T} & \vec{S}_{2}
\end{array}\right]  \tag{5}\\
& =\left[\begin{array}{cc}
\left\|\vec{S}_{1}\right\|^{2} & 0 \\
0 & \left\|\vec{S}_{2}\right\|^{2}
\end{array}\right] \tag{6}
\end{align*}
$$

Thus, we have

$$
\left(A_{2}^{T} A_{2}\right)^{-1}=\left[\begin{array}{cc}
\frac{1}{\left\|\vec{S}_{1}\right\|^{2}} & 0  \tag{8}\\
0 & \frac{1}{\left\|\vec{S}_{2}\right\|^{2}}
\end{array}\right] .
$$

Then the projection of $\vec{r}$ onto $\operatorname{span}\left(A_{2}\right)$ is

$$
\begin{align*}
\vec{r}_{A_{2}} & =A_{2}\left(A_{2}^{T} A_{2}\right)^{-1} A_{2}^{T} \vec{r}  \tag{9}\\
& =\left[\begin{array}{cc}
\mid & \mid \\
\vec{S}_{1} & \vec{S}_{2} \\
\mid & \mid
\end{array}\right]\left[\begin{array}{cc}
\frac{1}{\left\|\vec{S}_{1}\right\|^{2}} & 0 \\
0 & \frac{1}{\left\|\vec{S}_{2}\right\|^{2}}
\end{array}\right]\left[\begin{array}{lll}
- & \vec{S}_{1}^{T} & - \\
- & \vec{S}_{2}^{T} & -
\end{array}\right] \vec{r}  \tag{10}\\
& =\left[\begin{array}{cc}
\mid & \mid \\
\vec{S}_{1} & \vec{S}_{2} \\
\mid & \mid
\end{array}\right]\left[\begin{array}{cc}
\frac{1}{\left\|\vec{S}_{1}\right\|^{2}} & 0 \\
0 & \frac{1}{\left\|\vec{S}_{2}\right\|^{2}}
\end{array}\right]\left[\begin{array}{l}
\vec{S}_{1}^{T} \vec{r} \\
\vec{S}_{2}^{T} \vec{r}
\end{array}\right]  \tag{11}\\
& =\left[\begin{array}{cc}
\mid & \mid \\
\vec{S}_{1} & \vec{S}_{2} \\
\mid & \mid
\end{array}\right]\left[\begin{array}{l}
\vec{S}_{1}^{T} \vec{r} \\
\left\|\vec{S}_{1}\right\|^{2} \\
\frac{\vec{S}_{2}^{T} \vec{r}}{\left\|\vec{S}_{2}\right\|^{2}}
\end{array}\right]  \tag{12}\\
& =\binom{\vec{S}_{1}^{T} \vec{r}}{\left\|\vec{S}_{1}\right\|^{2}} \vec{S}_{1}+\left(\frac{\vec{S}_{2}^{T} \vec{r}}{\left\|\vec{S}_{2}\right\|^{2}}\right) \vec{S}_{2} . \tag{13}
\end{align*}
$$

Observe that the first term in the sum above is the projection of $\vec{r}$ onto $\vec{S}_{1}$ and the second term is the projection of $\vec{r}$ onto $\vec{S}_{2}$. Generalizing, the projection of $\vec{r}$ onto $\operatorname{span}\left(A_{n}\right)$ where $A_{n}$ has mutually orthogonal columns is

$$
\begin{equation*}
\vec{r}_{A_{n}}=\left(\frac{\vec{S}_{1}^{T} \vec{r}}{\left\|\vec{S}_{1}\right\|^{2}}\right) \vec{S}_{1}+\left(\frac{\vec{S}_{2}^{T} \vec{r}}{\left\|\vec{S}_{2}\right\|^{2}}\right) \vec{S}_{2}+\cdots+\left(\frac{\vec{S}_{n}^{T} \vec{r}}{\left\|\vec{S}_{n}\right\|^{2}}\right) \vec{S}_{n} . \tag{14}
\end{equation*}
$$

Furthermore, observe that if $\vec{S}_{1}, \ldots, \vec{S}_{n}$ are unit vectors, i.e., they all have length 1 , the above further reduces to

$$
\begin{equation*}
\vec{r}_{A_{n}}=\left(\vec{S}_{1}^{T} \vec{r}\right) \vec{S}_{1}+\left(\vec{S}_{2}^{T} \vec{r}\right) \vec{S}_{2}+\cdots+\left(\vec{S}_{n}^{T} \vec{r}\right) \vec{S}_{n} \tag{15}
\end{equation*}
$$

which further reduces our computation.
We see that we can speed up OMP considerably if the songs $\vec{S}_{1}, \ldots, \vec{S}_{n}$ are mutually orthogonal to each other and are of unit length. Now the question is how do we convert any set of linearly independent vectors to a set of mutually orthogonal unit vectors that span the same vector space? We will answer this in the next section.

### 28.2 Gram Schmidt Process

Before we begin, let's remind ourselves that the following subspaces are equivalent for any pairs of linearly independent vectors $\vec{v}_{1}, \vec{v}_{2}$ :

- $\operatorname{span}\left(\vec{v}_{1}, \vec{v}_{2}\right)$
- $\operatorname{span}\left(\vec{v}_{1}, \alpha \vec{v}_{2}\right)$
- $\operatorname{span}\left(\vec{v}_{1}, \vec{v}_{1}+\vec{v}_{2}\right)$
- $\operatorname{span}\left(\vec{v}_{1}, \vec{v}_{1}-\vec{v}_{2}\right)$
- $\operatorname{span}\left(\vec{v}_{1}, \vec{v}_{2}-\alpha \vec{v}_{1}\right)$

Now what should $\alpha$ be if we would like $\vec{v}_{1}$ and $\vec{v}_{2}-\alpha \vec{v}_{1}$ to be orthogonal to each other? We want $\alpha \vec{v}_{1}$ to be the projection of $\vec{v}_{2}$ onto $\vec{v}_{1}$. Let's solve this algebraically using the definition of orthogonality:

$$
\begin{align*}
& \vec{v}_{1} \text { and } \vec{v}_{2}-\alpha \vec{v}_{1} \text { are orthogonal }  \tag{16}\\
\Leftrightarrow & \vec{v}_{1}^{T}\left(\vec{v}_{2}-\alpha \vec{v}_{1}\right)=0  \tag{17}\\
\Leftrightarrow & \vec{v}_{1}^{T} \vec{v}_{2}-\alpha\left\|\vec{v}_{1}\right\|^{2}=0  \tag{18}\\
\Leftrightarrow & \alpha=\frac{\vec{v}_{1}^{T} \vec{v}_{2}}{\left\|\vec{v}_{1}\right\|^{2}} \tag{19}
\end{align*}
$$

Definition 28.1 (Orthonormal): A set of vectors $\left\{\vec{S}_{1}, \ldots, \vec{S}_{n}\right\}$ is orthonormal if all the vectors are mutually orthogonal to each other and all are of unit length.

Gram Schmidt is an algorithm that takes a set of linearly independent vectors $\left\{\vec{S}_{1}, \ldots, \vec{S}_{n}\right\}$ and generates an orthonormal set of vectors $\left\{q_{1}, \ldots, q_{n}\right\}$ that span the same vector space as the original set. Concretely, $\left\{q_{1}, \ldots, q_{n}\right\}$ needs to satisfy the following:

- $\operatorname{span}\left(\left\{S_{1}, \ldots, S_{n}\right\}\right)=\operatorname{span}\left(\left\{q_{1}, \ldots, q_{n}\right\}\right)$
- $\left\{q_{1}, \ldots, q_{n}\right\}$ is an orthonormal set of vectors

Now let's see how we can do this with a set of three vectors $\left\{\vec{S}_{1}, \vec{S}_{2}, \vec{S}_{3}\right\}$ that is linearly independent of each other.

- Step 1: Find unit vector $\vec{q}_{1}$ such that $\operatorname{span}\left(\left\{\vec{q}_{1}\right\}\right)=\operatorname{span}\left(\left\{\vec{S}_{1}\right\}\right)$.

Since $\operatorname{span}\left(\left\{\vec{S}_{1}\right\}\right)$ is a one dimensional vector space, the unit vector that span the same vector space would just be the normalized vector point at the same direction as $\vec{S}_{1}$. We have

$$
\begin{equation*}
\vec{q}_{1}=\frac{\vec{S}_{1}}{\left\|\vec{S}_{1}\right\|} \tag{20}
\end{equation*}
$$

- Step 2: Given $\vec{q}_{1}$ from the previous step, find $\vec{q}_{2}$ such that $\operatorname{span}\left(\left\{\vec{q}_{1}, \vec{q}_{2}\right\}\right)=\operatorname{span}\left(\left\{\vec{S}_{1}, \vec{S}_{2}\right\}\right)$ and orthogonal to $\vec{q}_{1}$. We know that $\vec{S}_{2}$ (the projection of $\vec{S}_{2}$ on $\vec{q}_{1}$ ) would be orthogonal to $\vec{q}_{1}$ as seen earlier. Hence, a vector $\vec{e}_{2}$ orthogonal to $\vec{q}_{1}$ where $\operatorname{span}\left(\left\{\vec{q}_{1}, \vec{e}_{2}\right\}\right)=\operatorname{span}\left(\left\{\vec{S}_{1}, \vec{S}_{2}\right\}\right)$ is

$$
\begin{equation*}
\vec{e}_{2}=\vec{S}_{2}-\left(\vec{S}_{2}^{T} \vec{q}_{1}\right) \vec{q}_{1} \tag{21}
\end{equation*}
$$

Normalizing, we have $\vec{q}_{2}=\frac{\vec{e}_{2}}{\left\|\vec{e}_{2}\right\|}$.

- Step 3: Now given $\vec{q}_{1}$ and $\vec{q}_{2}$ in the previous steps, we would like to find $\vec{q}_{3}$ such that $\operatorname{span}\left(\left\{\vec{q}_{1}, \vec{q}_{2}, \vec{q}_{3}\right\}\right)=$ $\operatorname{span}\left(\left\{\vec{S}_{1}, \vec{S}_{2}, \vec{S}_{3}\right\}\right)$. We know that the projection of $\vec{S}_{3}$ onto the subspace spanned by $\vec{q}_{1}, \vec{q}_{2}$ is

$$
\begin{equation*}
\left(\vec{S}_{3}^{T} \vec{q}_{2}\right) \vec{q}_{2}+\left(\vec{S}_{3}^{T} \vec{q}_{1}\right) \vec{q}_{1} \tag{22}
\end{equation*}
$$

We know that

$$
\begin{equation*}
\vec{e}_{3}=\vec{S}_{3}-\left(\vec{S}_{3}^{T} \vec{q}_{2}\right) \vec{q}_{2}-\left(\vec{S}_{3}^{T} \vec{q}_{1}\right) \vec{q}_{1} \tag{23}
\end{equation*}
$$

is orthogonal to $\vec{q}_{1}$ and $\vec{q}_{2}$. Normalizing, we have $\vec{q}_{3}=\frac{\vec{e}_{3}}{\left\|\vec{e}_{3}\right\|}$.

We can generalize the above procedure for any number of linearly independent vectors as follows:

## Inputs

- A set of linearly independent vectors $\left\{\vec{S}_{1}, \ldots, \vec{S}_{n}\right\}$.


## Outputs

- An orthonormal set of vectors $\left\{\vec{q}_{1}, \ldots, \vec{q}_{n}\right\}$ where $\operatorname{span}\left(\left\{\vec{S}_{1}, \ldots, \vec{S}_{n}\right\}\right)=\operatorname{span}\left(\left\{\vec{q}_{1}, \ldots, \vec{q}_{n}\right\}\right)$.


## Gram Schmidt Procedure

- compute $\vec{q}_{1}: \vec{q}_{1}=\frac{\vec{S}_{1}}{\left\|\bar{S}_{1}\right\|}$
- for $(i=2 \ldots n)$ :

1. Compute the vector $\vec{e}_{i}$, such that $\operatorname{span}\left(\left\{\vec{q}_{1}, \ldots, \vec{e}_{i}\right\}\right)=\operatorname{span}\left(\left\{\vec{S}_{1}, \ldots, \vec{S}_{i}\right\}\right)$ :

$$
\vec{e}_{i}=\vec{S}_{i}-\sum_{j=1}^{i-1}\left(\vec{S}_{i}^{T} \vec{q}_{j}\right) \vec{q}_{j}
$$

2. compute $\vec{q}_{i}: \vec{q}_{i}=\frac{\vec{e}_{i}}{\left\|\vec{e}_{i}\right\|}$

### 28.3 Implementing Gram Schmidt for 0MP

Now we would like to use Gram Schmidt to speed up OMP. Recall the step in OMP that augments matrix $A$ with the newest version of the song: $A=\left[A \mid \overrightarrow{S_{i}^{(N i)}}\right]$ and then uses least squares to obtain the message value: $\vec{x}=\left(A^{T} A\right)^{-1} A^{T} \vec{r}$. We now know that with each iteration, that computation gets harder and harder.

Therefore, let us now build a matrix $Q$ containing orthonormal vectors to use as a subspace rather than A. We can initialize $Q=[]$ and once we identify a song, we can then perform Gram Schmidt on $Q$ and the song.

## Procedure:

- Initialize the following values: $\vec{y}=\vec{r}, j=1, k=10, F=\{\emptyset\}, Q=[], \overrightarrow{b_{0}}=0$
- while $((j \leq k) \&(\|\vec{y}\| \geq t h))$ :

1. Cross correlate $\vec{y}$ with the shifted versions of all songs. Find the song index, $i$, and the shifted version of the song, $\overrightarrow{S_{i}^{(N i)}}$, with which the received signal has the highest correlation value.
2. Set $\vec{v}_{j}=\overrightarrow{S_{i}^{(N i)}}$
3. Add $i$ to the set of song indices, F .
4. Perform Gram Schmidt on $Q$ and $\vec{v}_{j}$
(a) Find $\vec{e}_{j}$ which is $\vec{v}_{j}-$ projection of $\vec{v}_{j}$ onto $Q: \vec{e}_{j}=\vec{v}_{j}-\left(\vec{v}_{j}^{T} \vec{q}_{1}\right) \vec{q}_{1}-\cdots-\left(\vec{v}_{j}^{T} \vec{q}_{j-1}\right) q_{j-1}$
(b) Find $\vec{q}_{j}: \vec{q}_{j}=\frac{\vec{e}_{j}}{\left\|\vec{e}_{j}\right\|}$
(c) Column concatenate matrix $Q$ with $\vec{q}_{j}: Q=\left[Q \mid \vec{q}_{j}\right]$
5. Now that vectors are orthonormal, can simply project received signal onto newest column and add: $\vec{b}_{j}=\overrightarrow{b_{j-1}}+\left(\vec{r}^{T} \vec{q}_{j}\right) \vec{q}_{j}$
6. Update the residual value $\vec{y}$ by subtracting: $\vec{y}=\vec{r}-\vec{b}_{j}$
7. Update the counter: $j=j+1$
