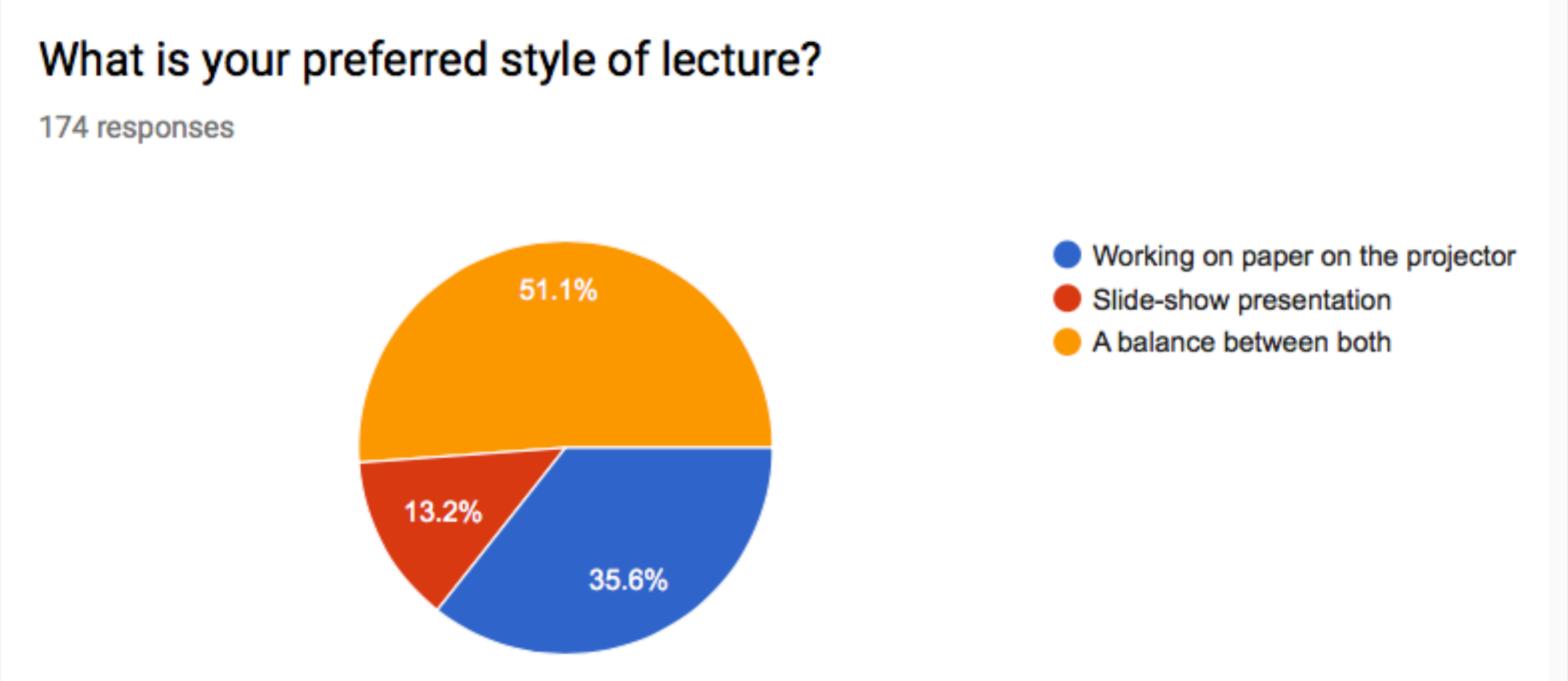
EE16B
Designing Information Devices and Systems II

Lecture 8B
Singular Value Decomposition (SVD)

Mid Semester Survey

- Slides – working on paper –
  I'll do my best.
- Folks, there's a READER– slides are not the only reference
- $ game seems distracting – TA will take note and update $ amont after



- HW too hard too long – we will try to balance that better

Rank 1 Matrix

Consider the following matrix:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 2 & 2 & 2 \\ 3 & 3 & 3 & 3 & 3 & 3 \end{bmatrix}$$ Rank = 1

We can decompose a rank-1 matrix as an outer product:

$$\vec{u}\vec{v}^T \in \mathrm{R}^{m \times n}$$

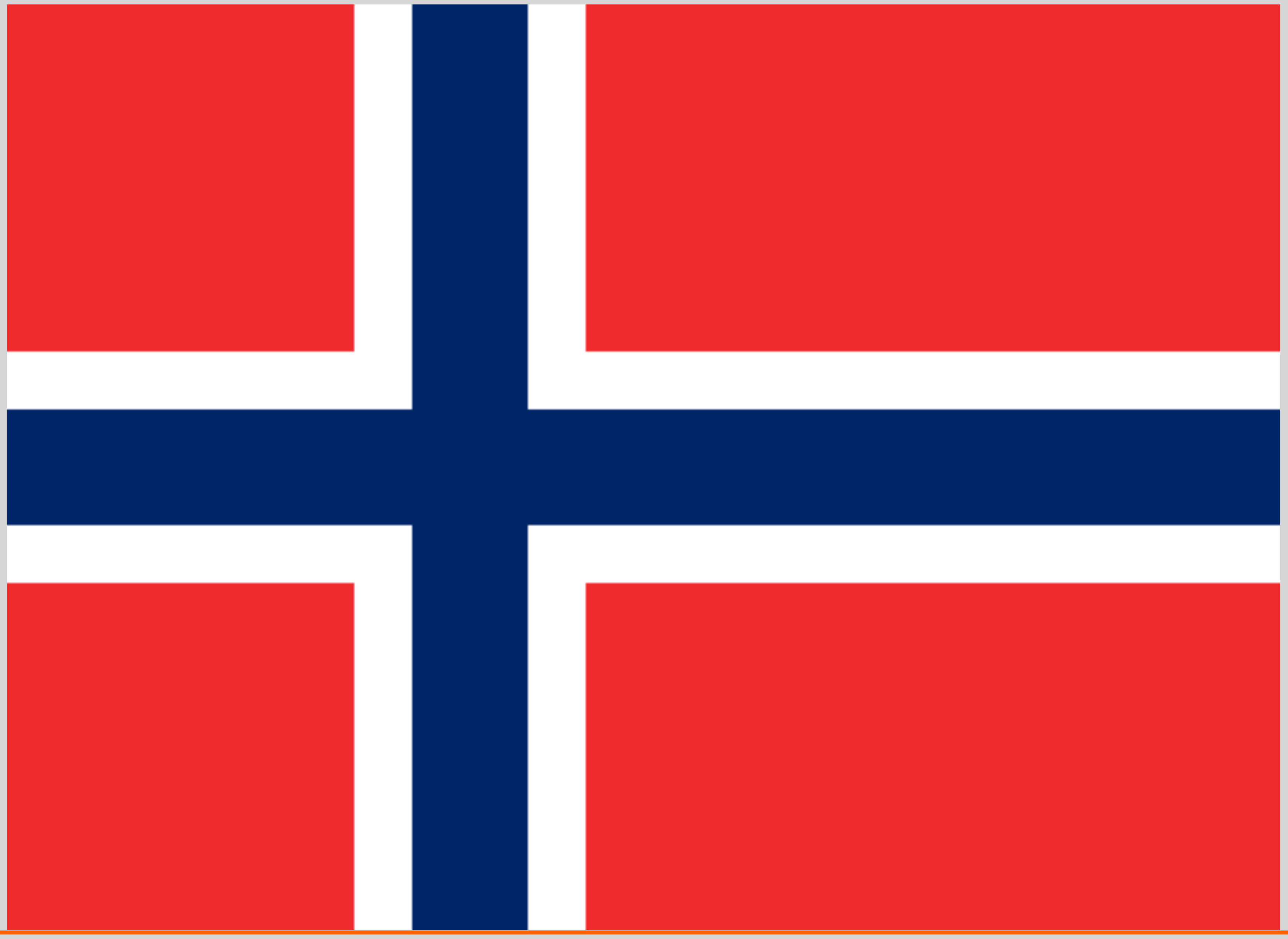
$$\underset{m \times 1}{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}} \underset{1 \times n}{\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}}$$

$\vec{u} \in \mathrm{R}^m$

$\vec{v} \in \mathrm{R}^n$

Flags as low-rank matrices






Quiz

SVD

SVD decomposes a rank r matrix $A \in \mathrm{R}^{m \times n}$
into a sum of r rank-1 matrices:

$$A = \sigma_1 \vec{u}_1 \vec{v}_1^T + \sigma_2 \vec{u}_2 \vec{v}_2^T + \cdots + \sigma_r \vec{u}_r \vec{v}_r^T$$

1) $\vec{u}_i^T \vec{u}_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases} \quad \Rightarrow ||\vec{u}_i|| = 1 \quad \vec{u}_i \perp \vec{u}_j$

2) $\vec{v}_i^T \vec{v}_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases} \quad \Rightarrow ||\vec{v}_i|| = 1 \quad \vec{v}_i \perp \vec{v}_j$

3) $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r > 0$

SVD

$$A = \sigma_1 \vec{u}_1 \vec{v}_1^T + \sigma_2 \vec{u}_2 \vec{v}_2^T + \cdots + \sigma_r \vec{u}_r \vec{v}_r^T$$

$m \times n$ $\quad m+n \quad m+n \quad m+n$

$r(m+n) \leq mn$ If m,n are large and r is small

Typically, $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_{\hat{r}} >> \sigma_{\hat{r}+1} \geq \cdots \geq \sigma_r$

$10 \quad 8 \quad 5 \quad 0.1 \quad 0.001$

$$\begin{bmatrix} 1.02 & 0.99 & 0.98 & 1.03 & 1.01 & 1 \\ 2 & 1.98 & 2.01 & 2.03 & 1.99 & 1.97 \\ 3.01 & 2.98 & 3 & 2.99 & 3.03 & 3.02 \end{bmatrix}$$

$$A \approx \sigma_1 \vec{u}_1 \vec{v}_1^T + \sigma_2 \vec{u}_1 \vec{v}_1^T + \cdots + \sigma_{\hat{r}} \vec{u}_{\hat{r}} \vec{v}_{\hat{r}}^T$$

History

Known for a long time – but not considered important

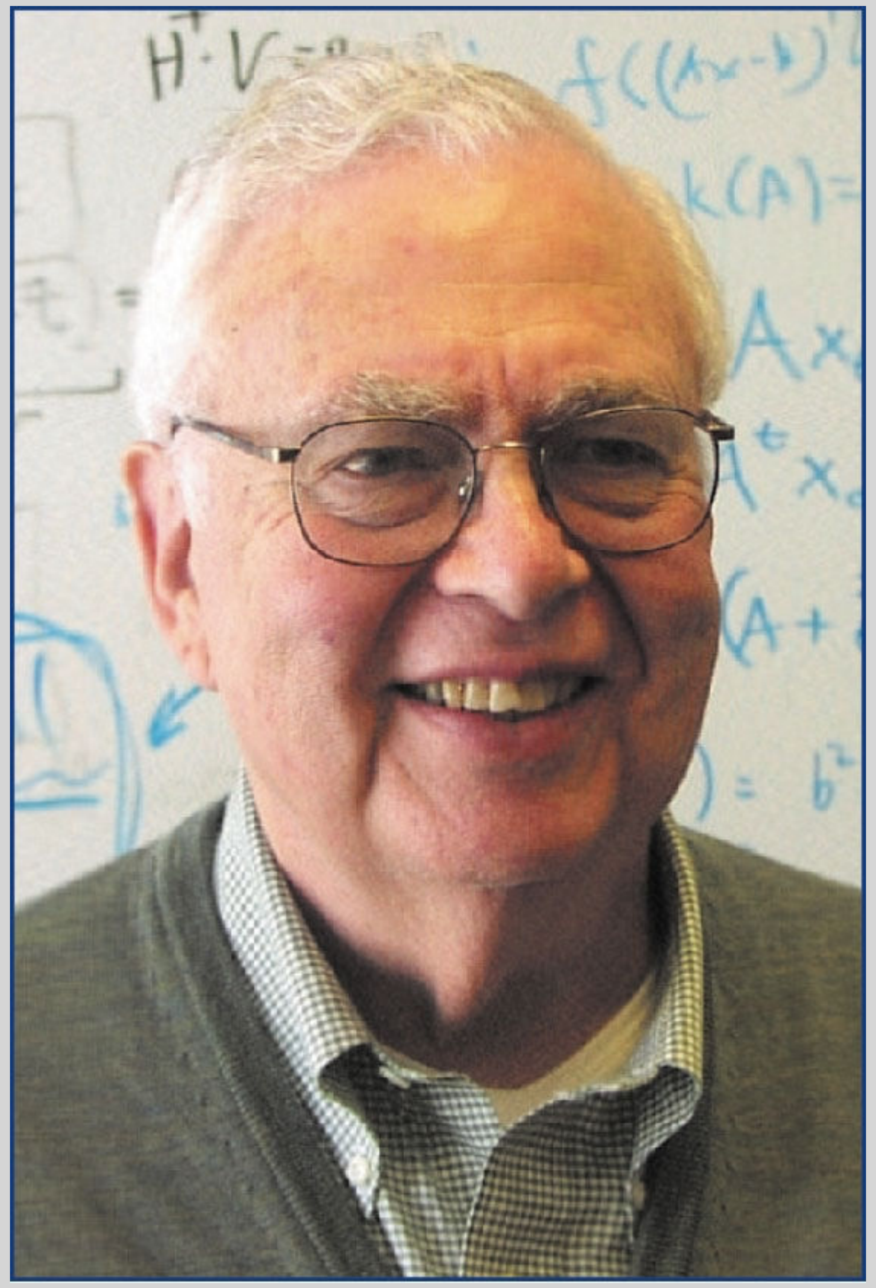
1965 – G. Golub and W. Kahan – practical way of computing the SVD – numerically stable

Today, used everywhere!

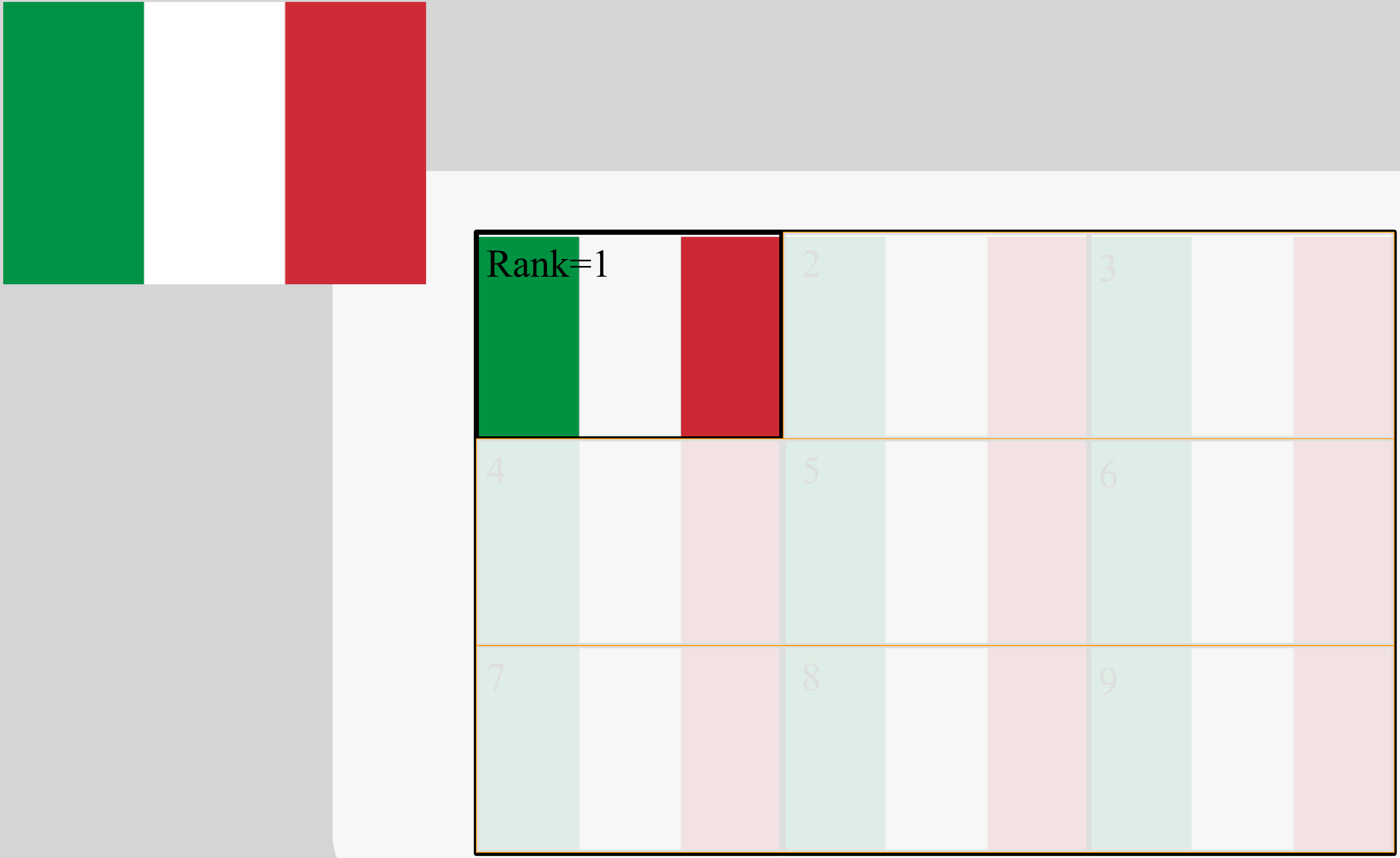
LAPack implementation –Demmel & Kahan 1990

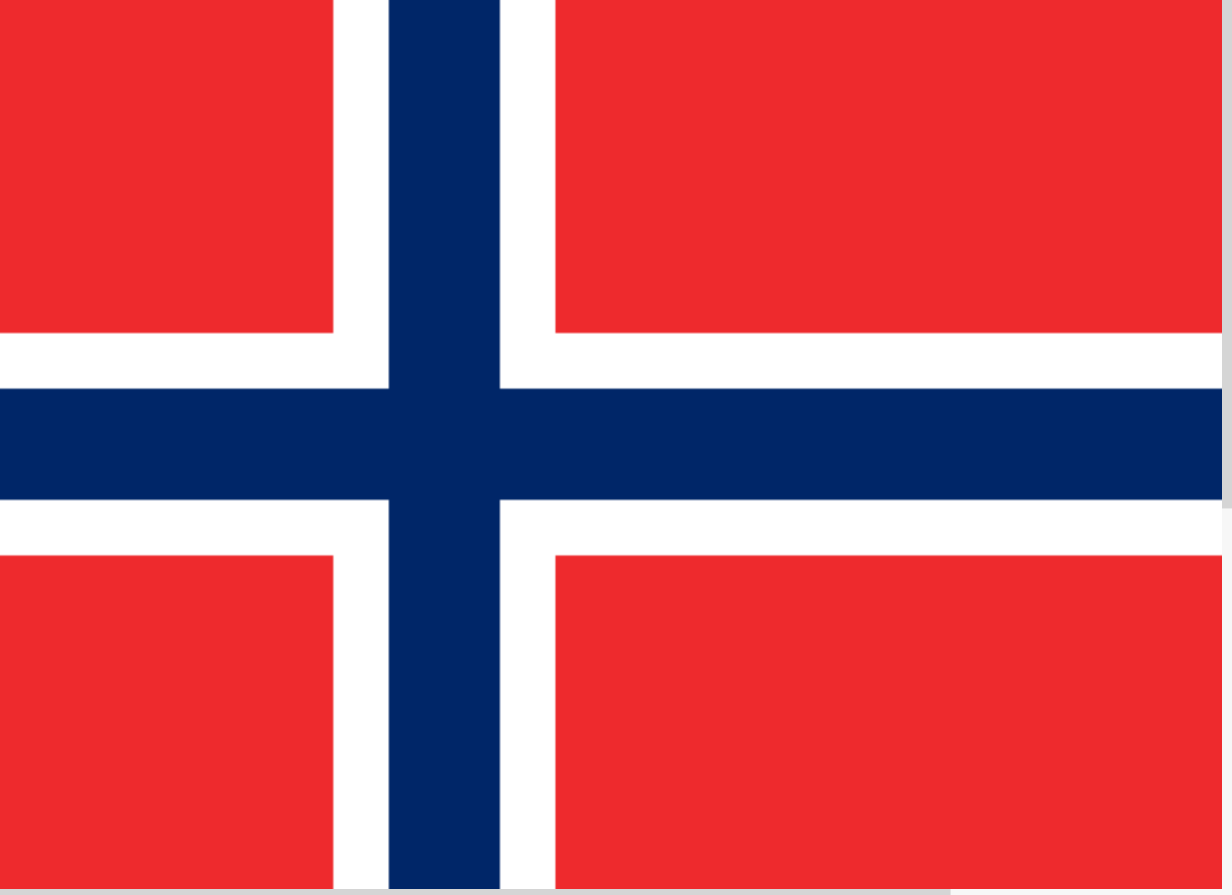
(numpy and matlab use LAPack)

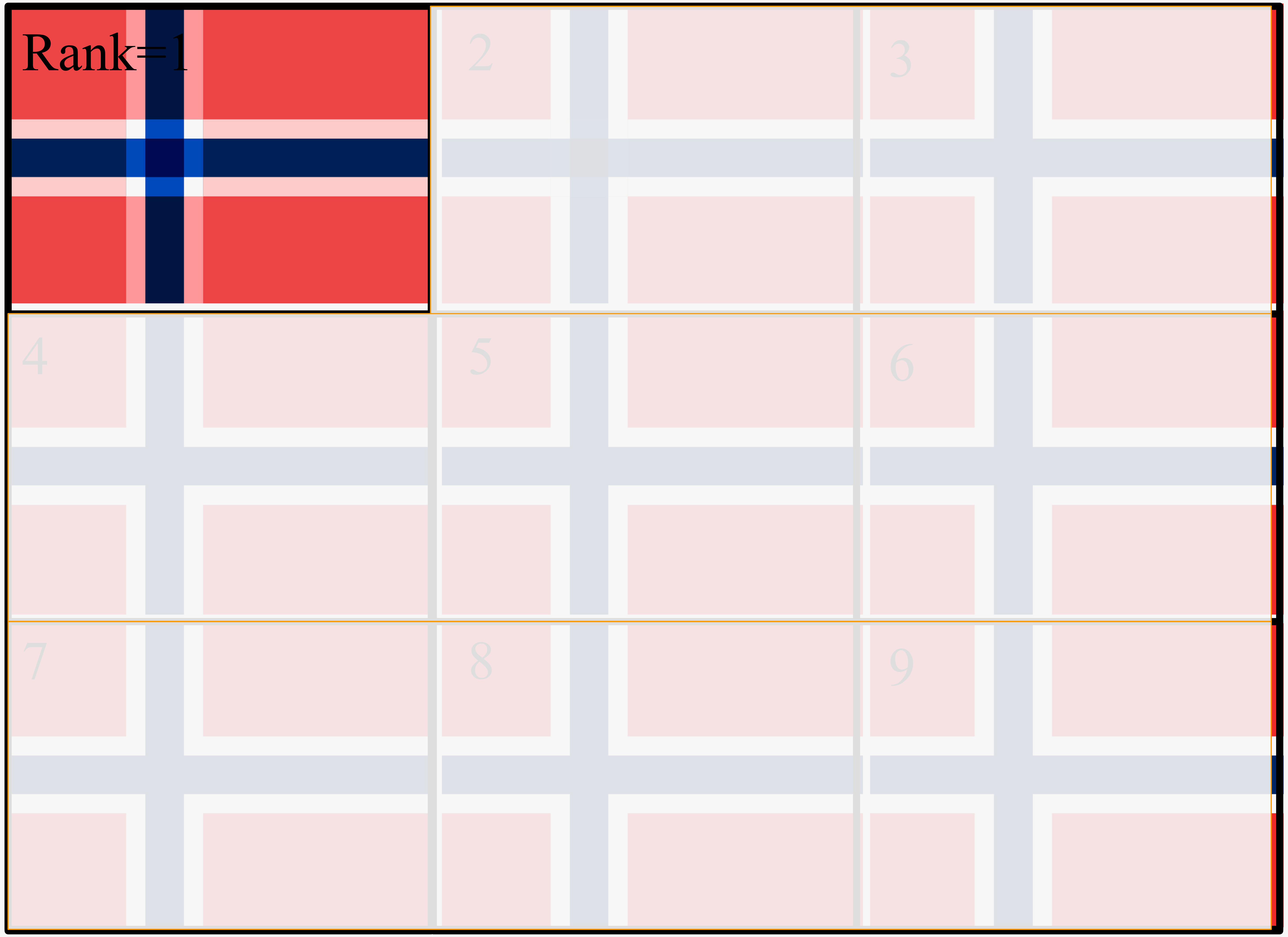
Gene Golub's license plate, photographed by Professor P. M. Kroonenberg of Leiden University.

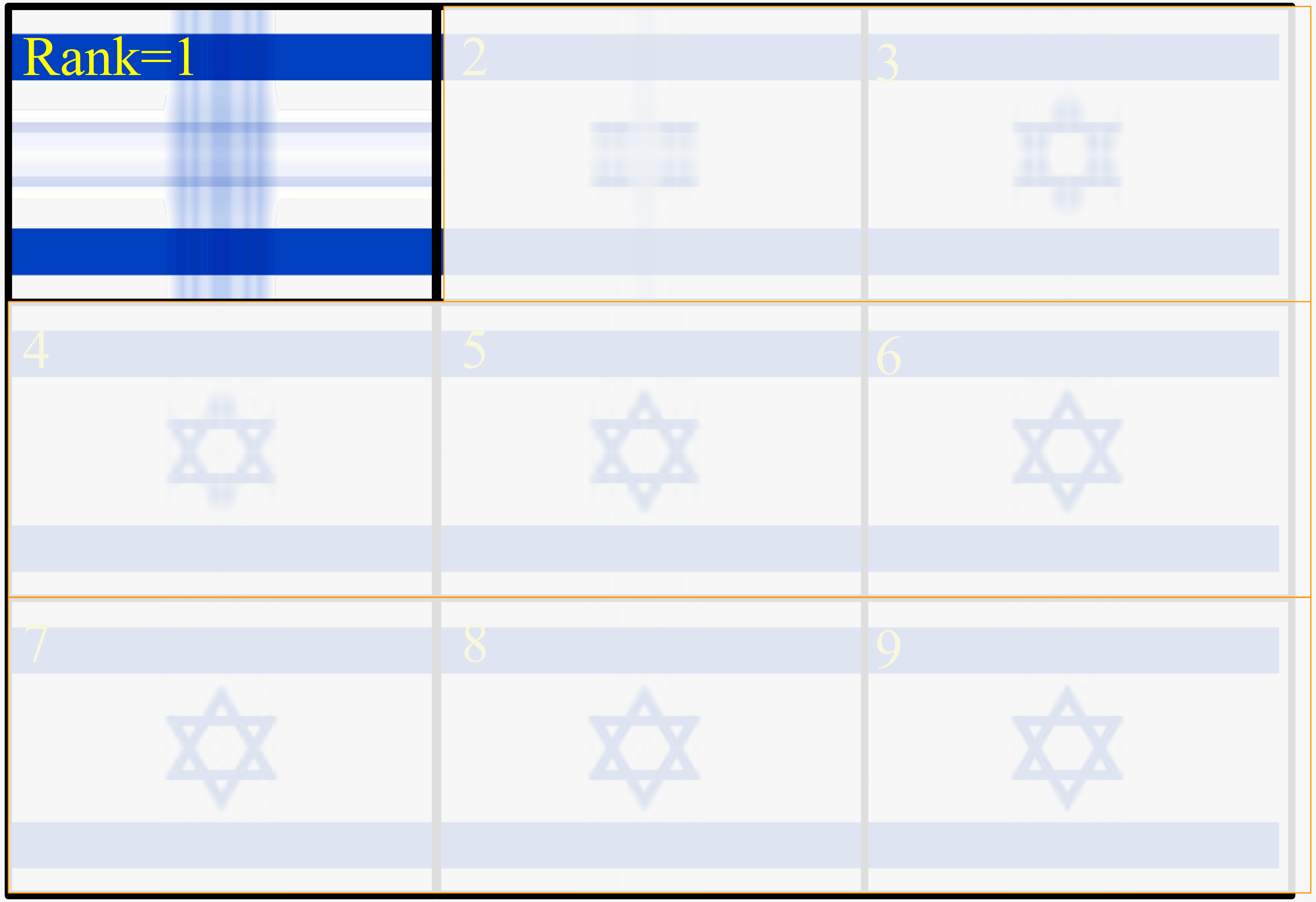


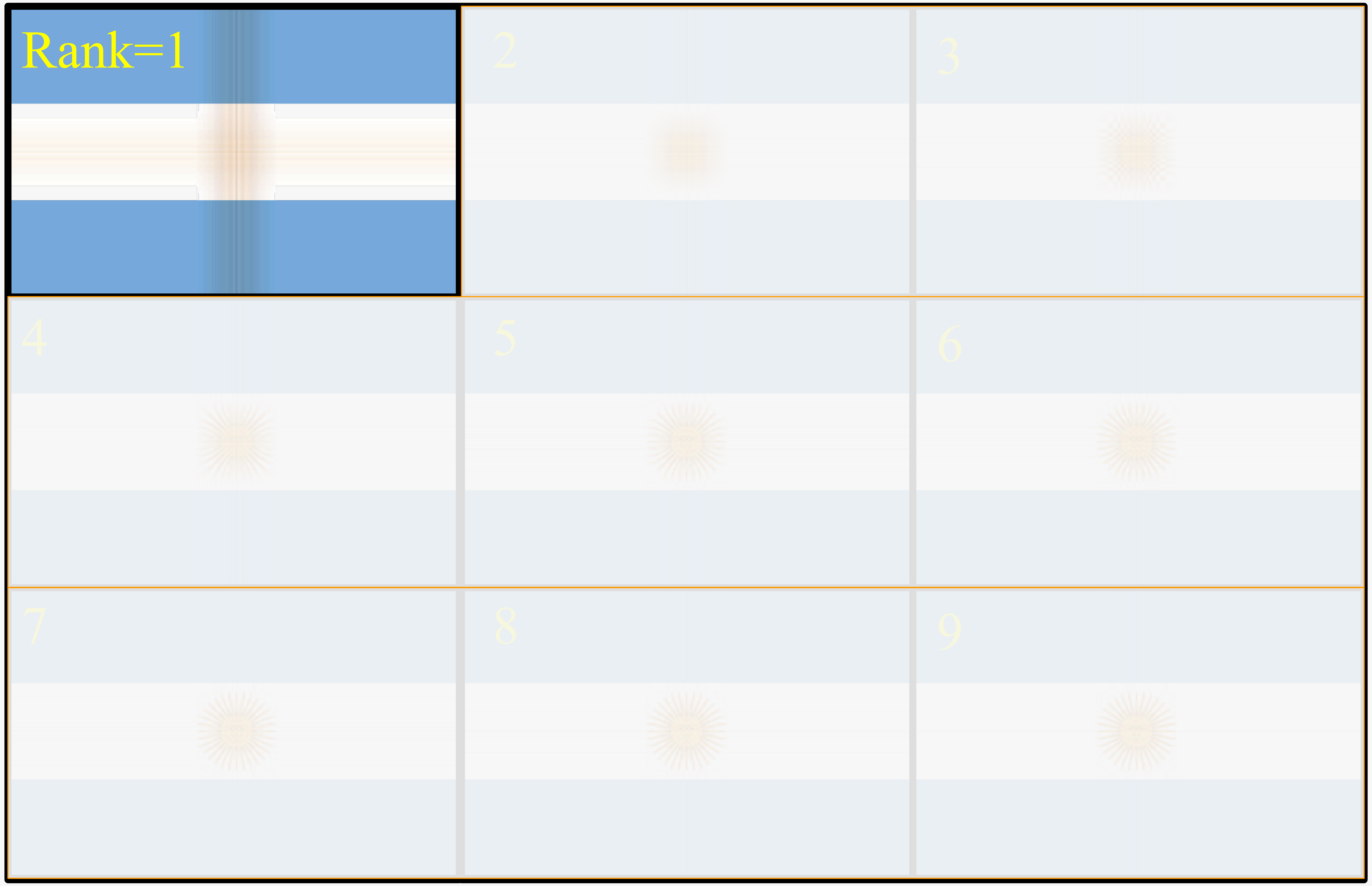
- Los Alamos video 1976 on the SVD. Then Relatively unknow, but today used everywhere. 3D computer graphics by Cleve Moler (Matlab)
- Lecture be Moler: “SVD Saves the Universe” https://www.mathworks.com/videos/the-singular-value-decomposition-saves-the-universe-1481294462044.html

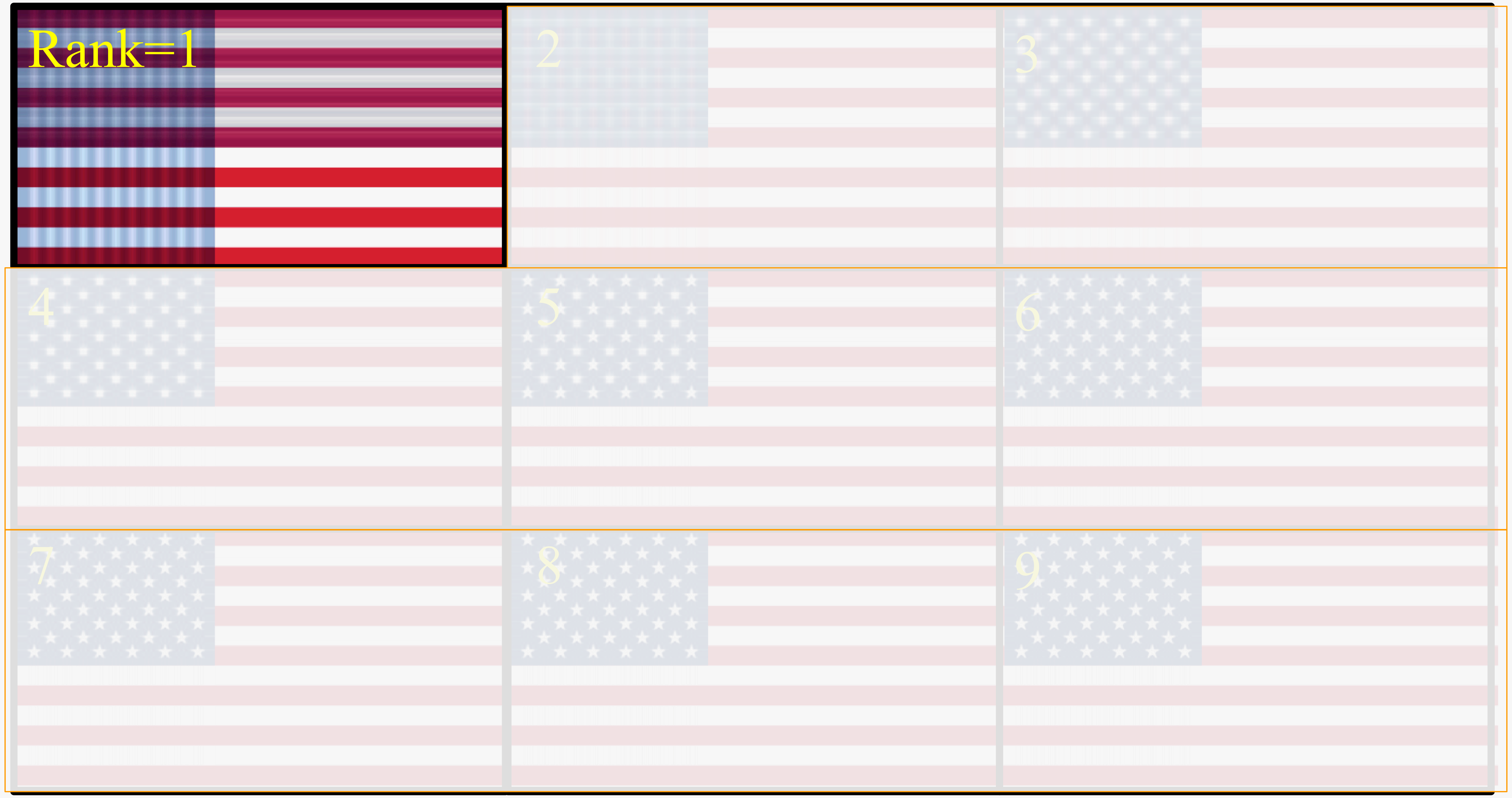

Rank=1
2
3
4
5
6
7
8
9

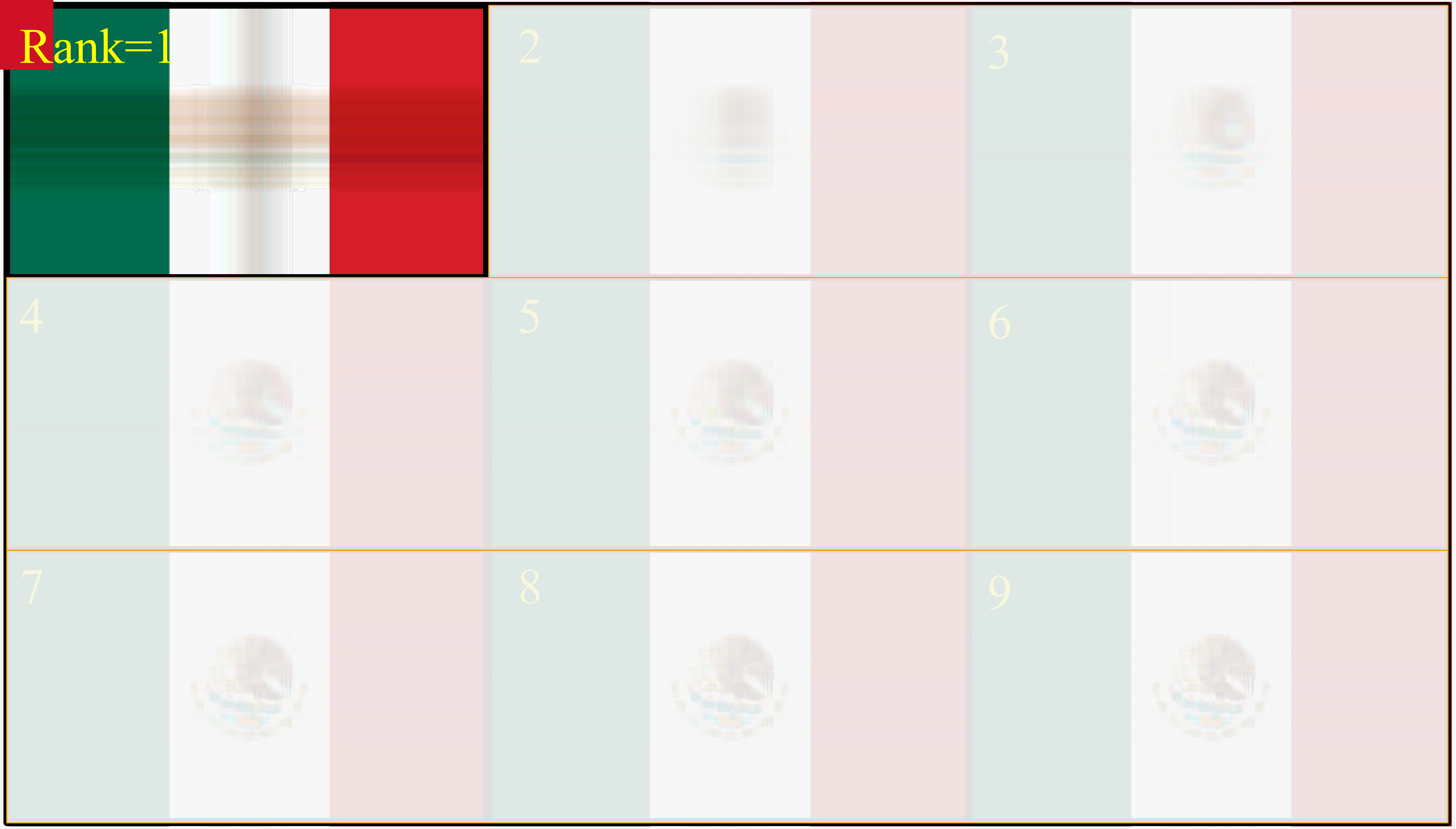


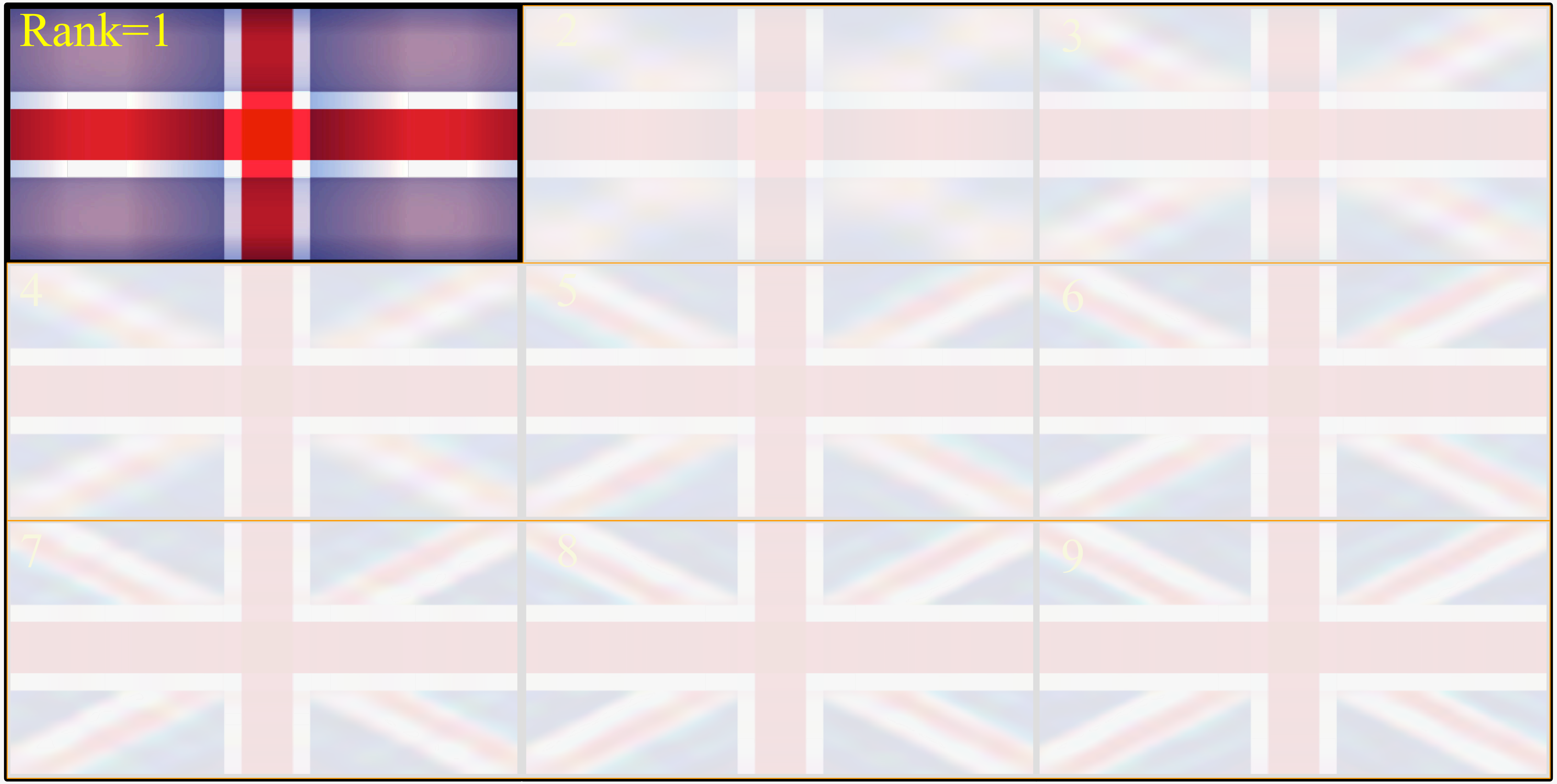

Rank=1
2
3
4
5
6
7
8
9


Rank=1
2
3
4
5
6
7
8
9


Rank=1
2
3
4
5
6
7
8
9


Rank=1
2
3
4
5
6
7
8
9

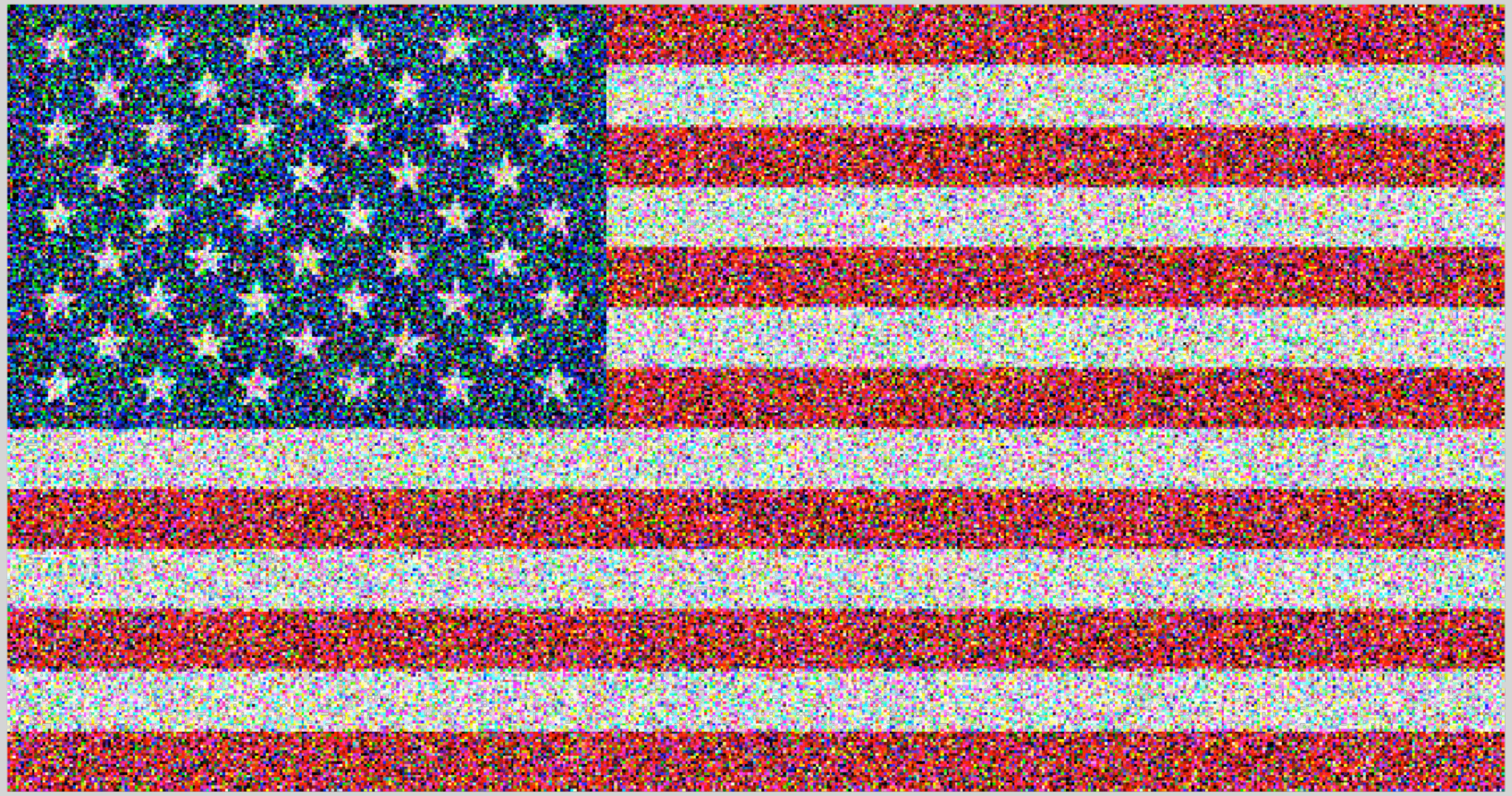

Rank=1
2
3
4
5
6
7
8
9

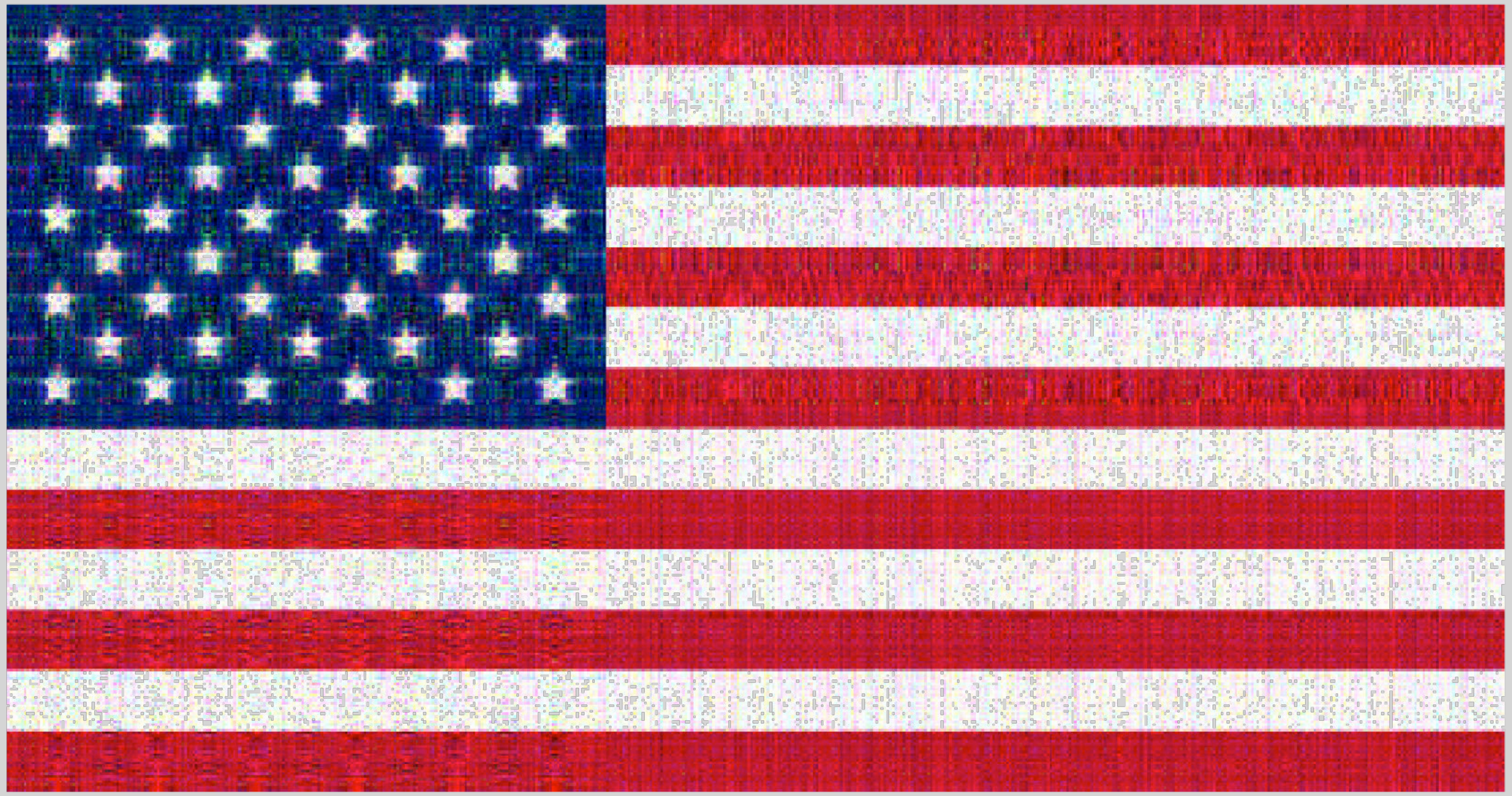

Rank=1
2
3
4
5
6
7
8
9

Noisy Flag

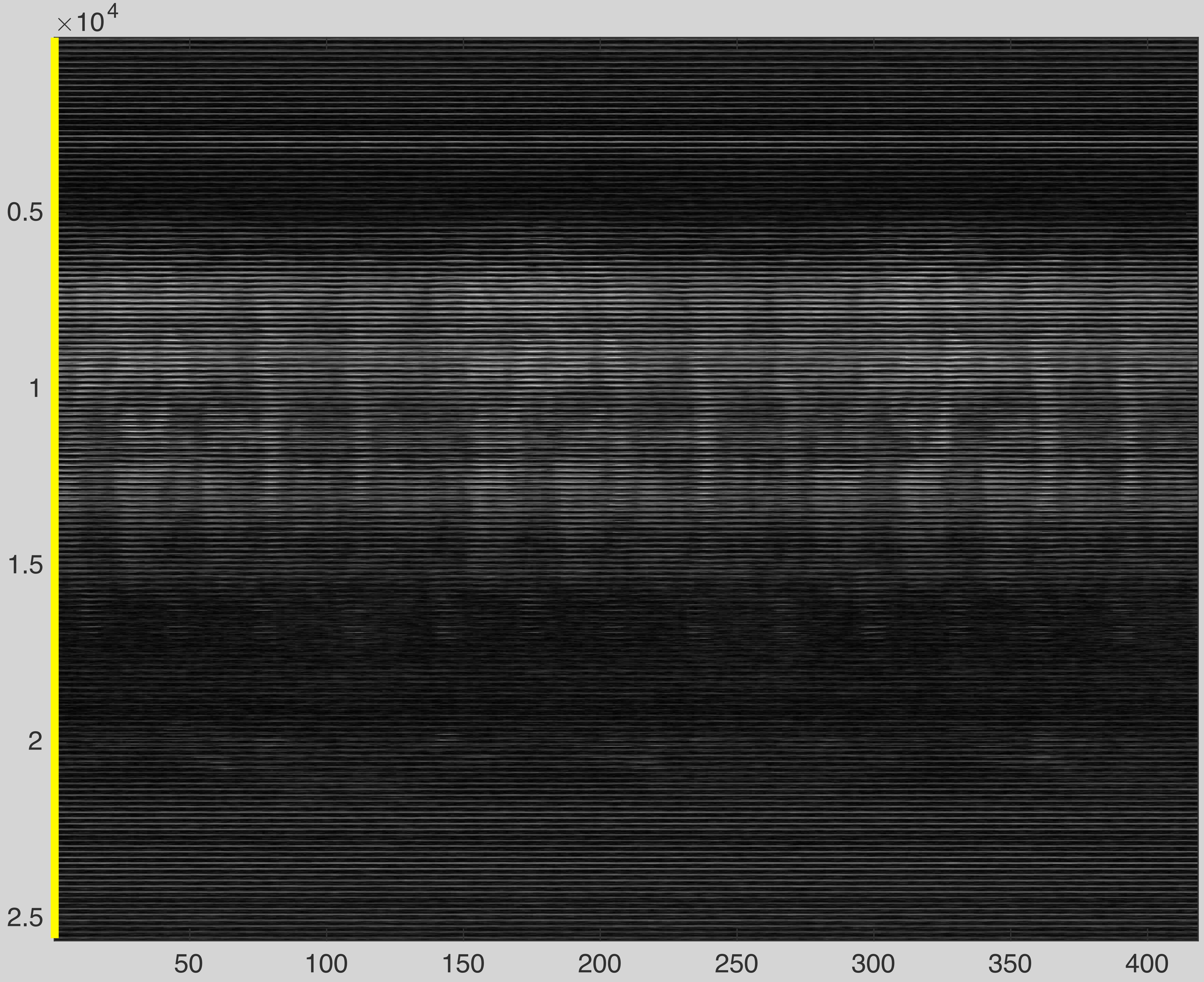
$$\begin{bmatrix} 1.02 & 0.99 & 0.98 & 1.03 & 1.01 & 1 \\ 2 & 1.98 & 2.01 & 2.03 & 1.99 & 1.97 \\ 3.01 & 2.98 & 3 & 2.99 & 3.03 & 3.02 \end{bmatrix}$$

$$\sum_{i=0}^{5} \sigma_i \vec{u}_i \vec{v}_i^T$$



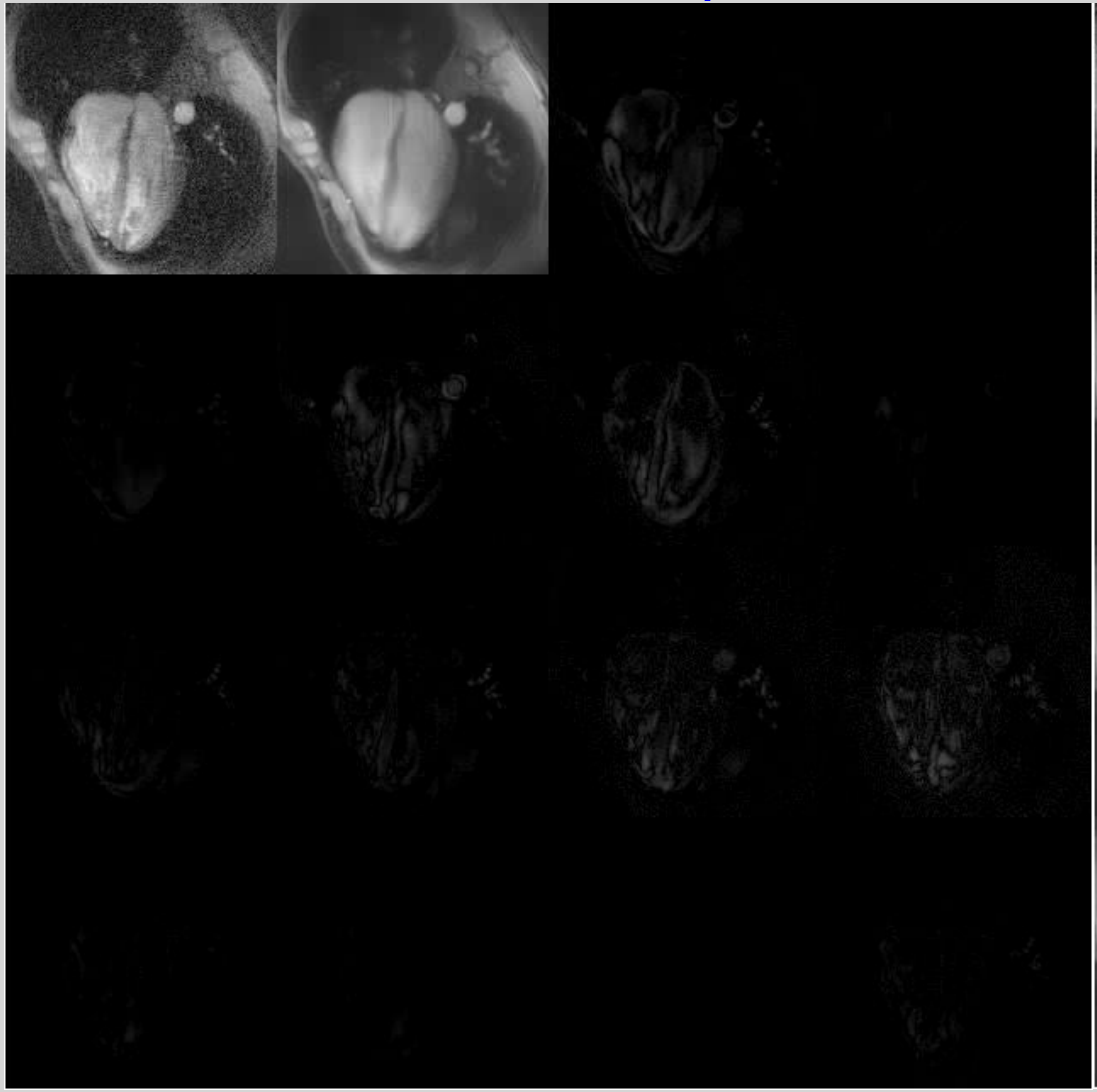


Video of a Heart

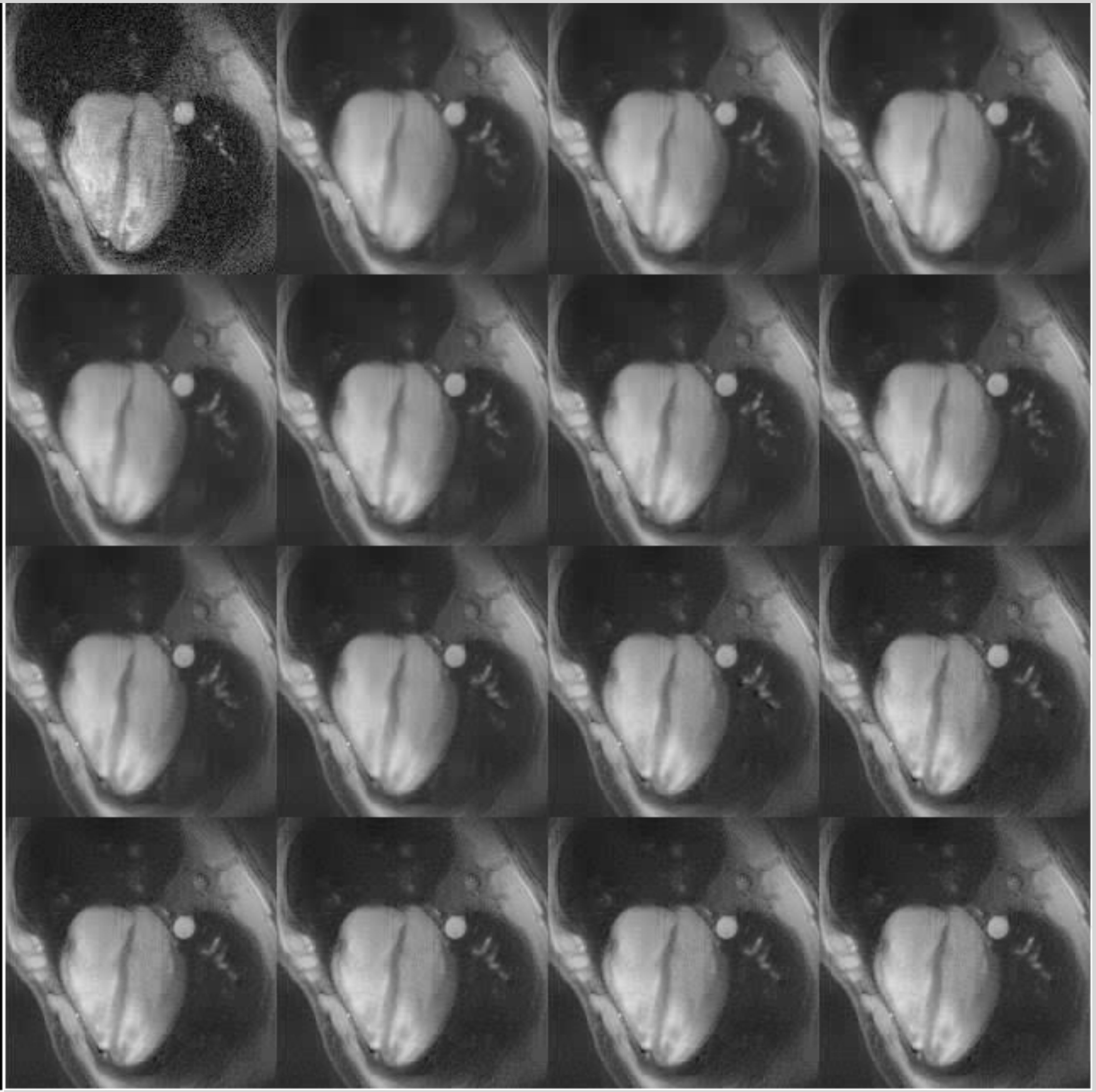


Heart Example

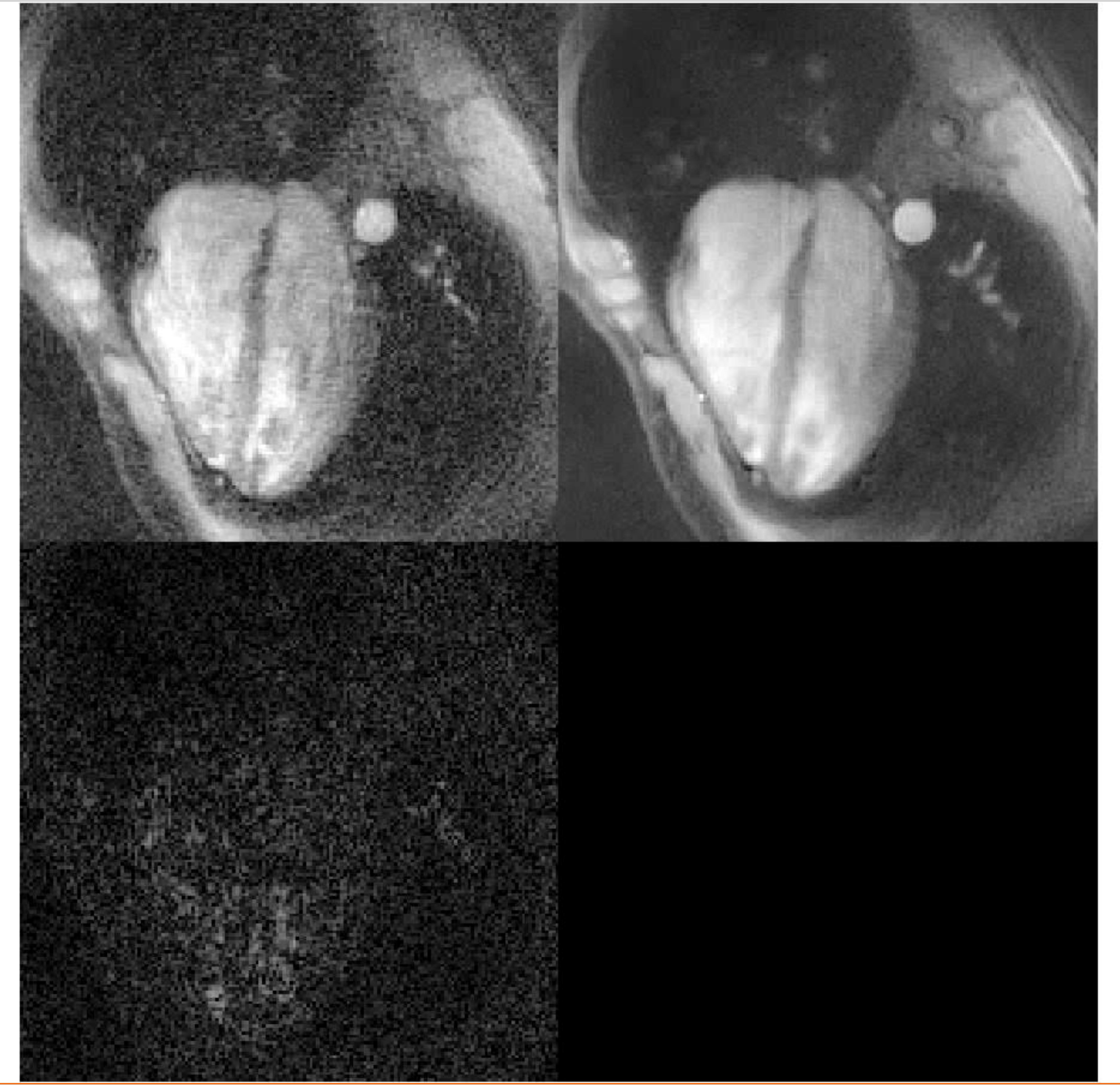
$$\sigma_i \vec{u}_i \vec{v}_i^T$$



$$\sum_{i=0}^{r} \sigma_i \vec{u}_i \vec{v}_i^T$$



Heart Example



$$\sum_{i=0}^{15} \sigma_i \vec{u}_i \vec{v}_i^T$$

$$\sum_{i=16}^{417} \sigma_i \vec{u}_i \vec{v}_i^T$$

Data Analysis with SVD

$$A \approx \sigma_1 \vec{u}_1 \vec{v}_1^T + \sigma_2 \vec{u}_1 \vec{v}_1^T + \cdots + \sigma_{\hat{r}} \vec{u}_{\hat{r}} \vec{v}_{\hat{r}}^T$$

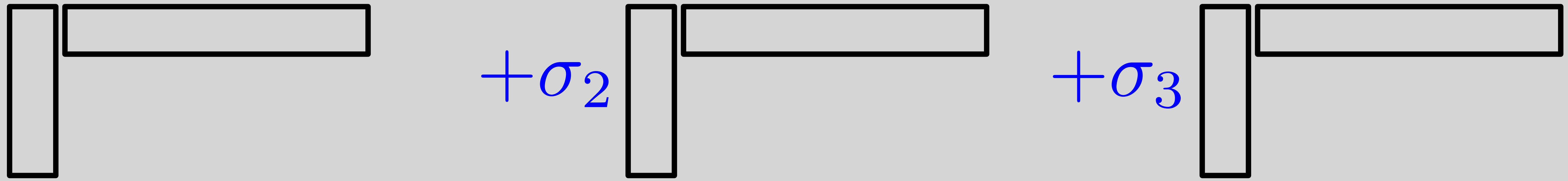
effective

n movies

m views

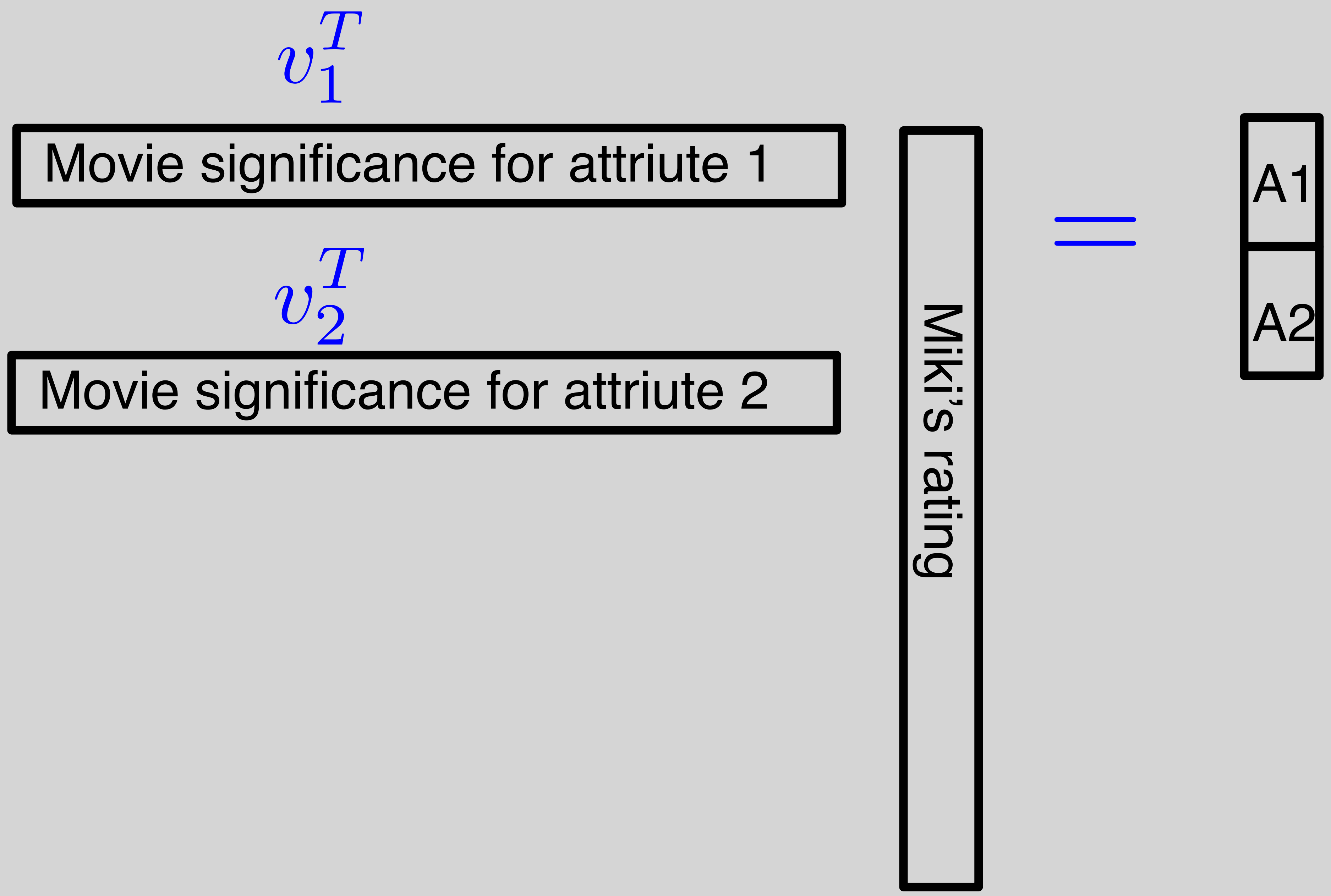
1	2	5	5	1	3	3	3	2	5	5	4	4	3	2	2	5	1	1
5	3	2	1	1	3	3	3	1	1	2	4	5	5	4	4	1	3	2
5	1	2	1	1	2	3	3	1	1	2	1	5	5	3	5	1	1	2
5	3	2	1	1	3	2	3	1	1	2	4	1	1	4	4	5	1	5
1	2	3	2	1	3	2	3	2	1	2	1	1	1	4	4	5	1	5
1	1	1	1	5	3	3	3	1	5	2	4	4	4	2	5	5	1	1

$\approx \sigma_1$ $+\sigma_2$ $+\sigma_3$



Attribute 1 Attribute 2 Attribute 3

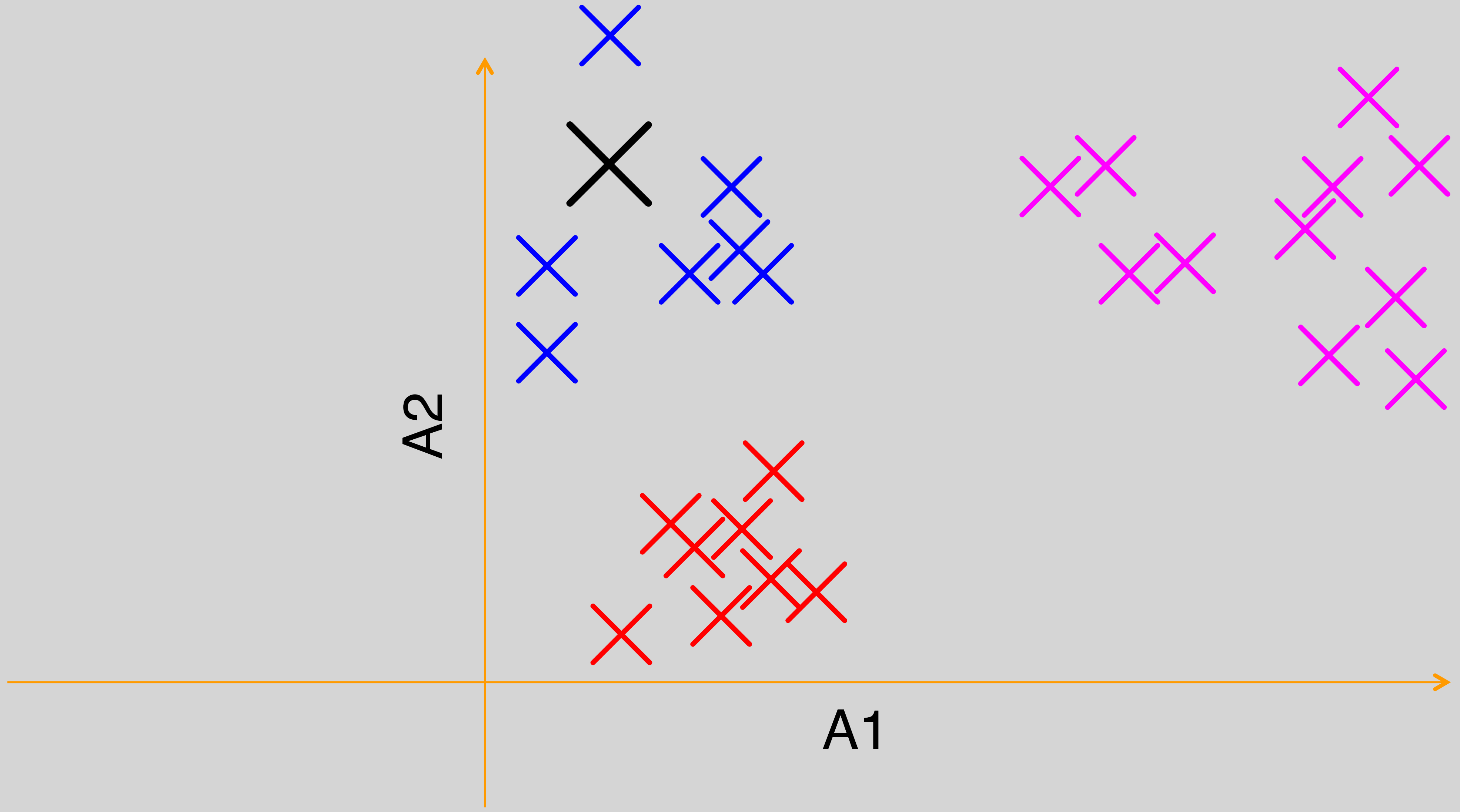
Classification with SVD



n movies

m views

1	2	5	5	1	3	3	3	2	5	5	4	4	3	2	2	5	1	1
5	3	2	1	1	3	3	3	1	1	2	4	5	5	4	4	1	3	2
5	1	2	1	1	2	3	3	1	1	2	1	5	5	3	5	1	1	2
5	3	2	1	1	3	2	3	1	1	2	4	1	1	4	4	5	1	5
1	2	3	2	1	3	2	3	2	1	2	1	1	1	4	4	5	1	5
1	1	1	1	5	3	3	3	1	5	2	4	4	4	2	5	5	1	1



Miki belongs to class: like A2 don't like A1

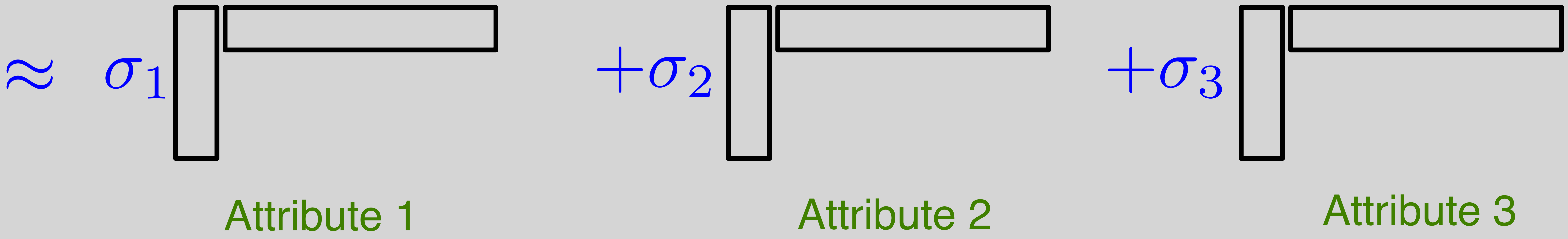
Prediction with SVD

Can try to predict preferences of a new customer with few ratings

See homework!

n movies (columns); m views (rows)

1	2	5	5	1	3	3	3	2	5	5	4	4	3	2	2	5	1	1
5	3	2	1	1	3	3	3	1	1	2	4	5	5	4	4	1	3	2
5	1	2	1	1	2	3	3	1	1	2	1	5	5	3	5	1	1	2
5	3	2	1	1	3	2	3	1	1	2	4	1	1	4	4	5	1	5
1	2	3	2	1	3	2	3	2	1	2	1	1	1	4	4	5	1	5
1	1	1	1	5	3	3	3	1	5	2	4	4	4	2	5	5	1	1
1	?	?	2	?	?	?	?	3	5	1	?	?	?	?	5	2	?	3



Low-rank Completion

What if my database is full of “holes”?

Should be still low-rank!

n movies

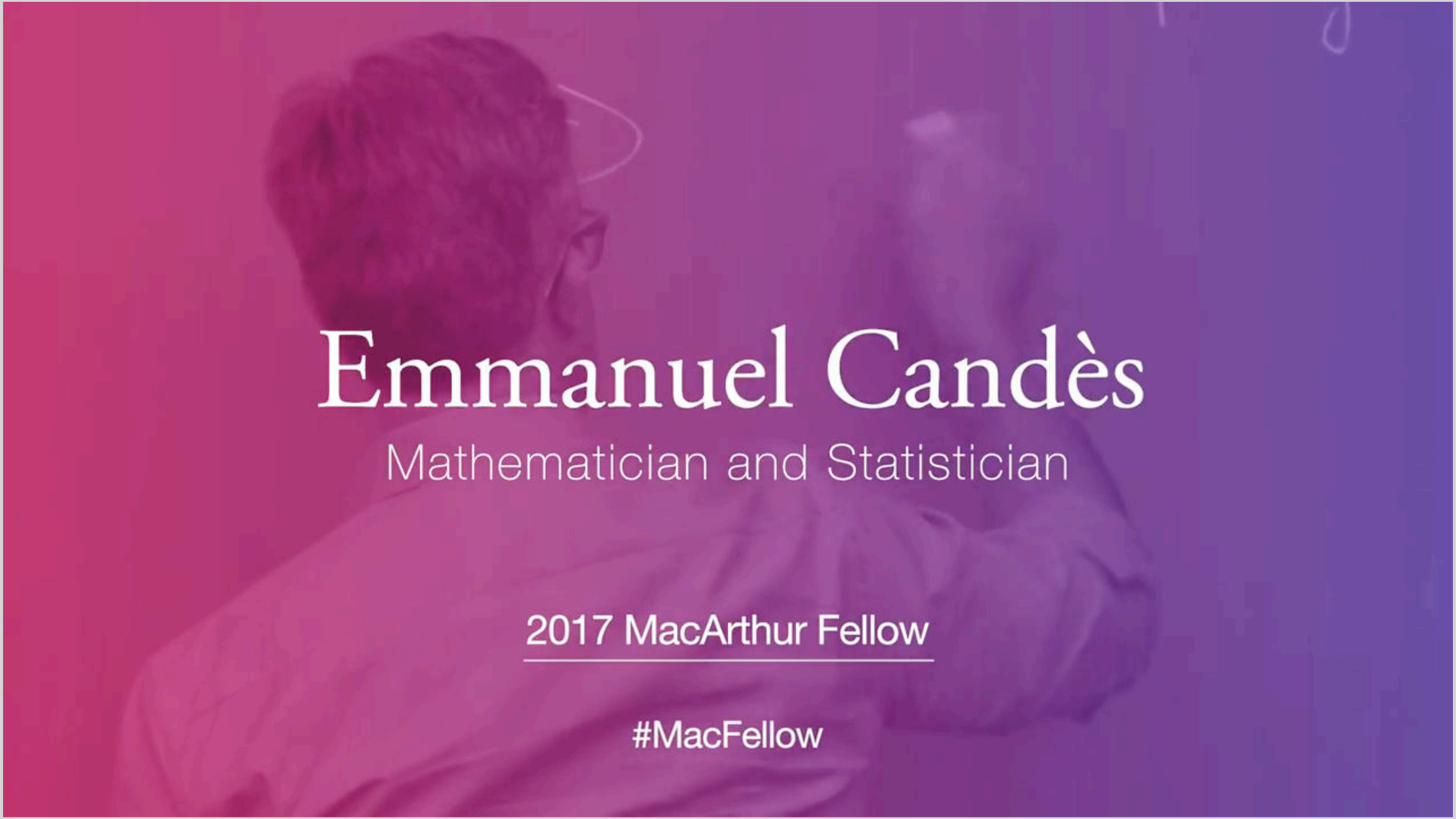
m views

1		5	5	1	3		3	2	5	5	4		3	2	2	5		1	
5	3		1	1	3	3		1	1	2		5		4	4	1	3	2	
	1	2	1	1		3	3		1	2	1	5	5	3	5		1	2	
5	3		1		3	2		1		2	4	1		4		5		5	
1		3	2	1	3	2	3	2	1		1		1	4		5	1	5	
1	1			5	3	3		5	2	4			2	5	5	1	1		

Q) Can we complete missing data?

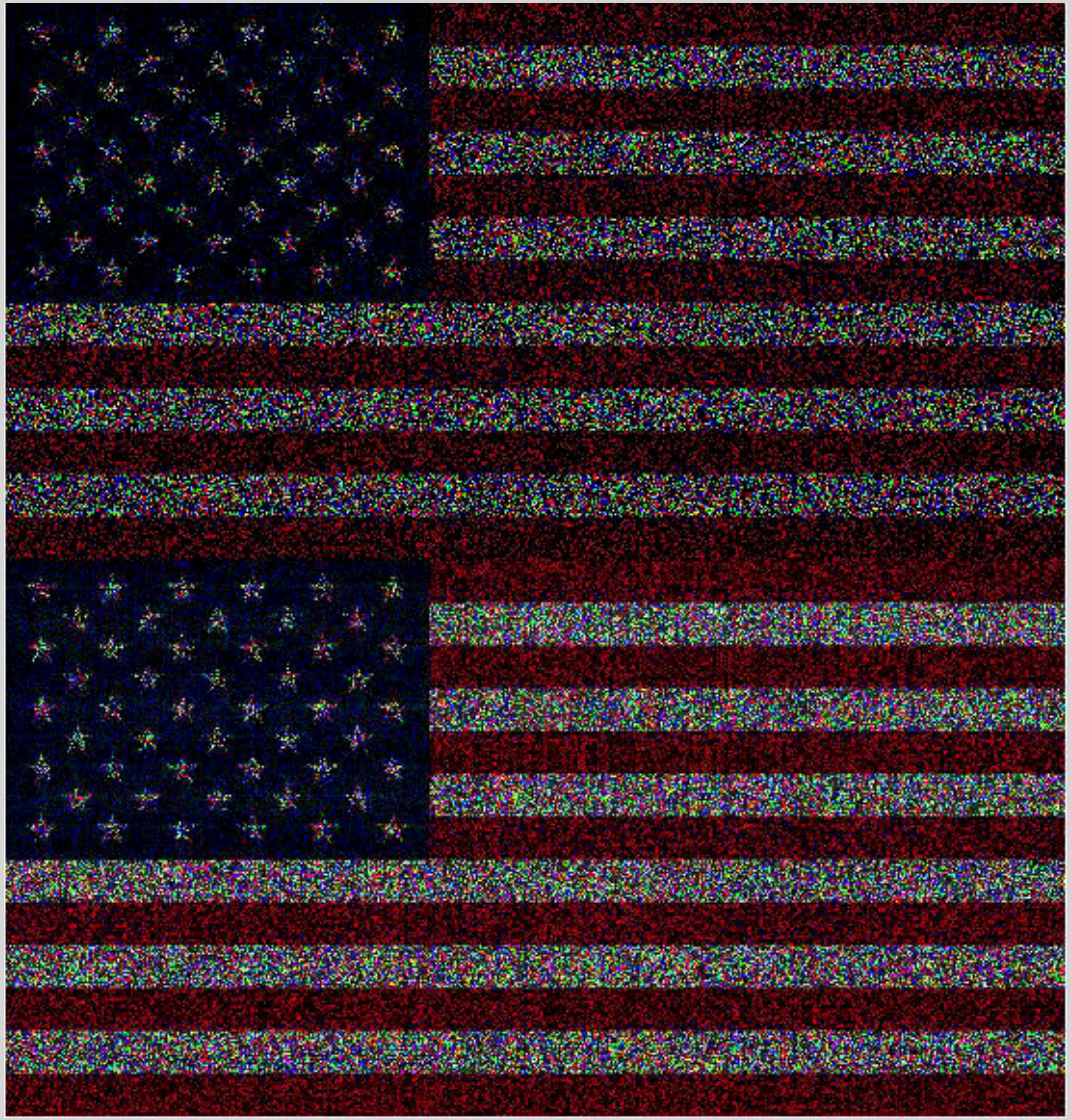
A) Sometimes! Very recent mathematical and practical results show you can.
Keywords: Compressed Sensing, Low-rank completion, robust PCA

E. Candes and B. Recht, Foundation of Computational Mathematics, 2009;9:717


Emmanuel Candès
Mathematician and Statistician
2017 MacArthur Fellow
#MacFellow

Low-Rank Recovery from 20% pixels

- Algorithm for low-rank completion:
  - flag_hat = flag
  - Compute [U,S,V] = svd(flag_hat)
  - $\text{flag}_{\text{hat}} = \sum_{i=0}^{6} \sigma_i \vec{u}_i \vec{v}_i^T$
  - update missing pixels in flag from flag_hat
  - repeat (250 times here)



T. Zhang et. al, Pediatric Radiology 2015;45(11):1635-43

Input

1x1 (Sparse) 4x4 16x16

64x64 144x176 (Low Rank)

Multi-scale Low Rank

F. Ong et. al, IEEE Selected Topics on Signal Processing, 2016