

CSI 62
Operating Systems and
Systems Programming
Lecture 22

TCP Flow Control,
Distributed Decision Making,
RPC

November 13th, 2017
Prof. Ion Stoica
<http://cs162.eecs.berkeley.edu>

Goals of Today's Lecture

- TCP flow control
- Two-Phase Commit

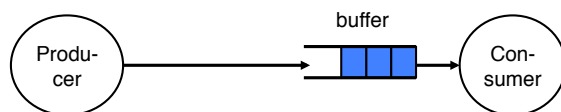
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Flow Control

- Recall: Flow control ensures a fast sender does not overwhelm a slow receiver
- Example: Producer-consumer with bounded buffer (Lecture 5)
 - A buffer between producer and consumer
 - Producer puts items into buffer as long as buffer **not full**
 - Consumer consumes items from buffer



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TCP Flow Control

- TCP: sliding window protocol at byte (not packet) level
- Receiver tells sender how many more bytes it can receive without overflowing its buffer (i.e., AdvertisedWindow)
- The ack(nowledgement) contains sequence number N of **next byte the receiver expects**, i.e., receiver has received all bytes in **sequence** up to and including N-1

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TCP Flow Control

- TCP/IP implemented by OS (Kernel)
 - Cannot do context switching on sending/receiving every packet
 - » At 10Gbps, it takes 1.2 usec to send an 1500 bytes, and 80nsec to send an 100 byte packet
- Need buffers to match ...
 - sending app with sending TCP
 - receiving TCP with receiving app

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TCP Flow Control

- Three pairs of producer-consumer's
 - ① sending process → sending TCP
 - ② Sending TCP → receiving TCP
 - ③ receiving TCP → receiving process

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TCP Flow Control

- Example assumptions:
 - Maximum IP packet size = 100 bytes
 - Size of the receiving buffer (MaxRcvBuf) = 300 bytes
- Recall, ack indicates the next expected byte in-sequence, not the last received byte
- Use circular buffers

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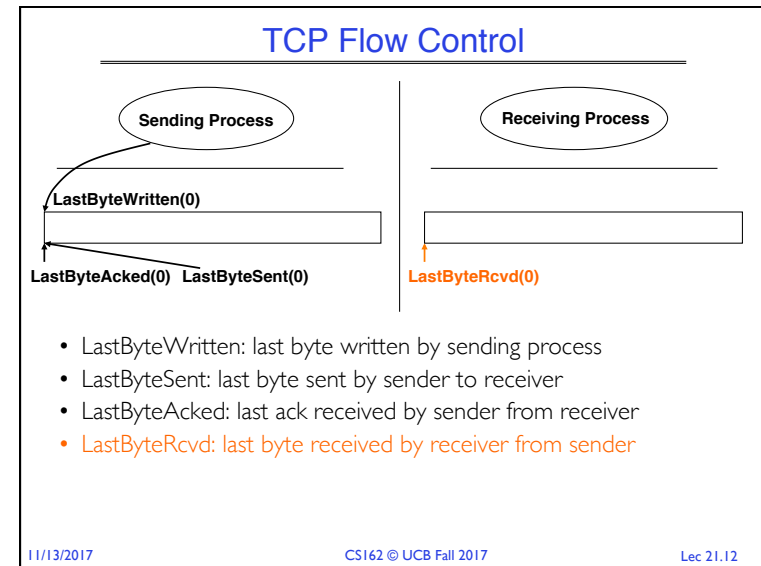
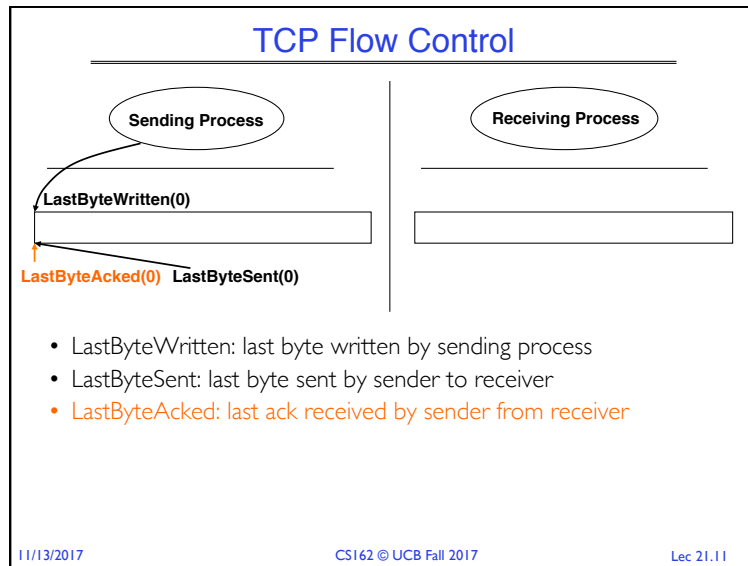
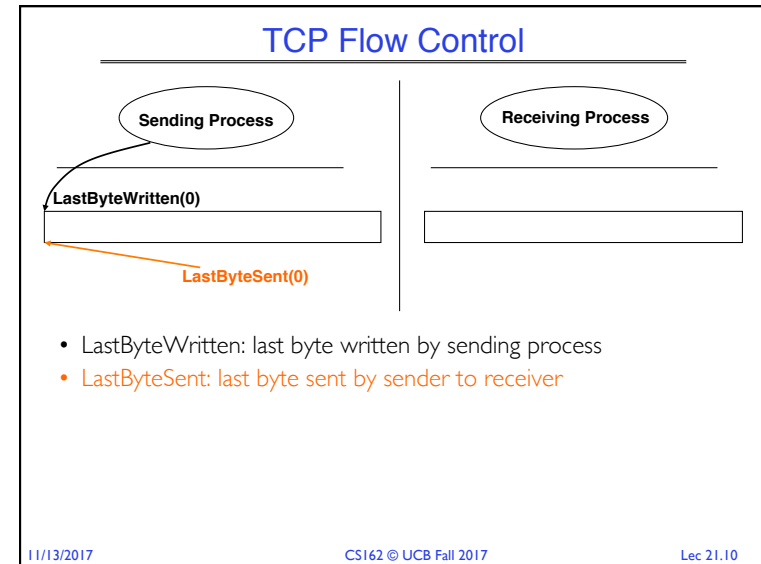
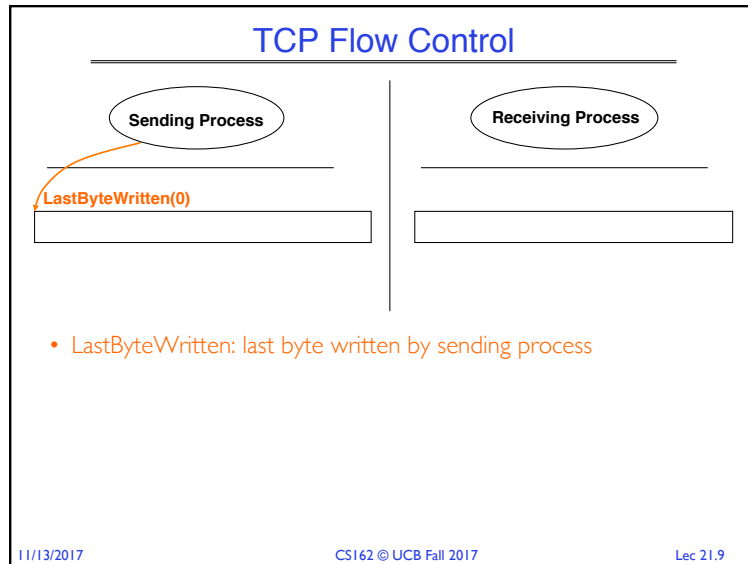
Circular Buffer

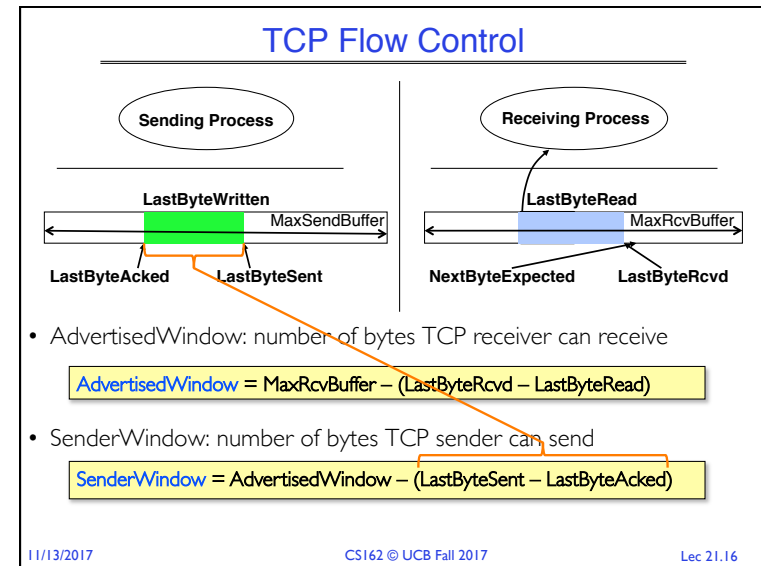
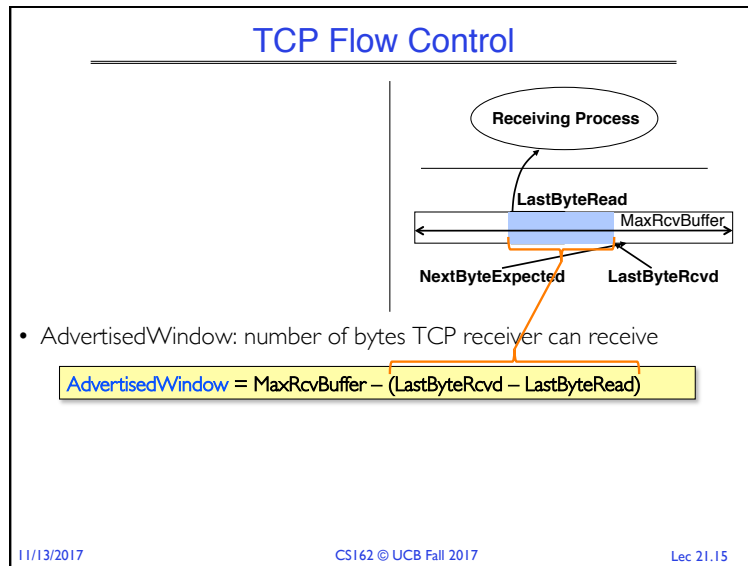
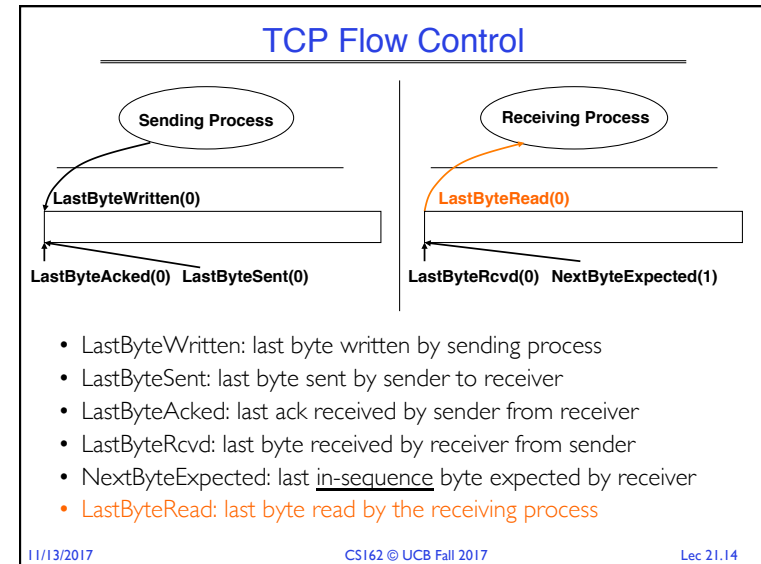
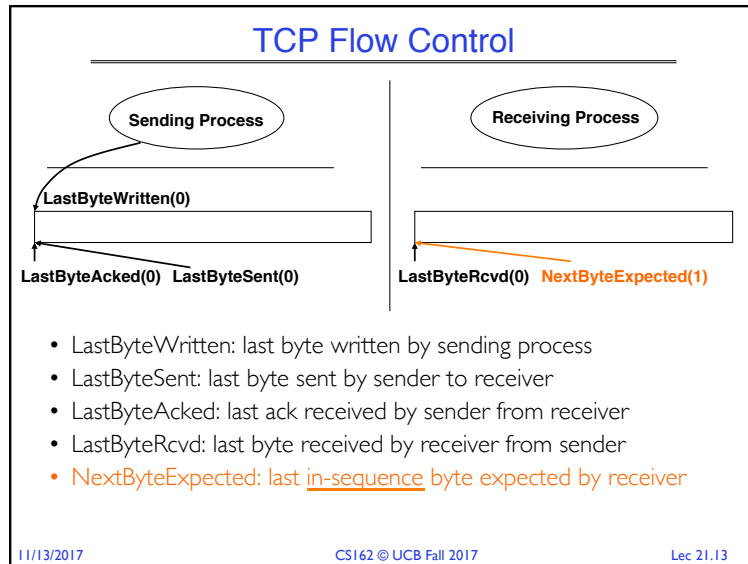
- Assume
 - A buffer of size N
 - A stream of bytes, where bytes have increasing sequence numbers
 - » Think of stream as an unbounded array of bytes and of sequence number as indexes in this array
- Buffer stores at most N consecutive bytes from the stream
- Byte k stored at position $(k \bmod N) + 1$ in the buffer

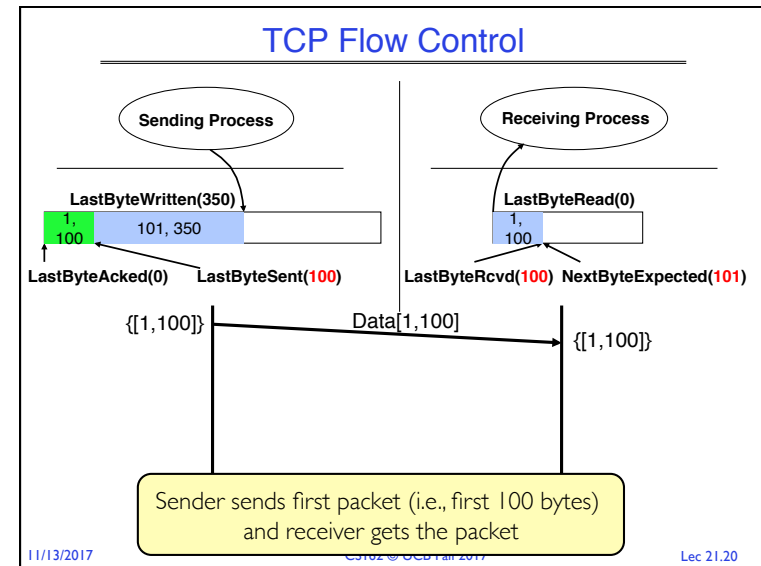
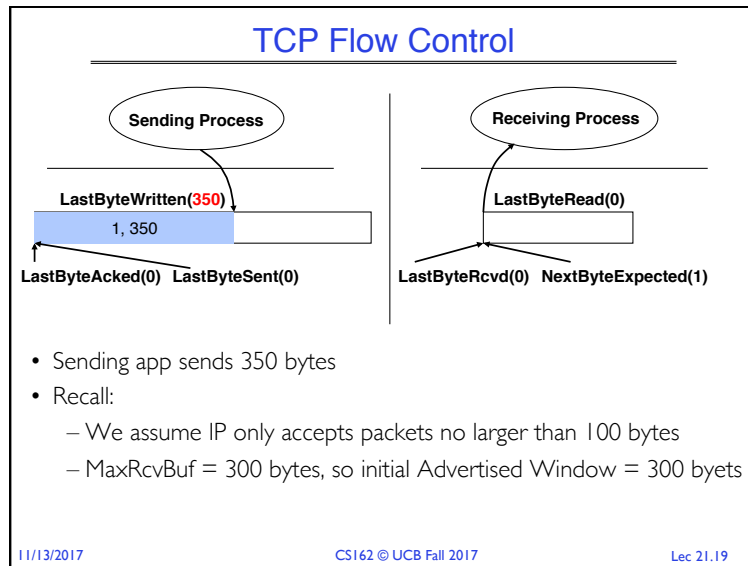
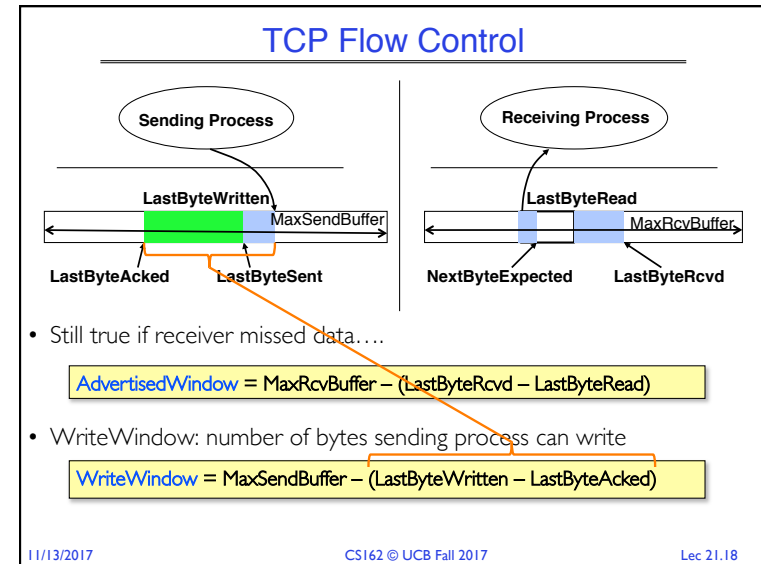
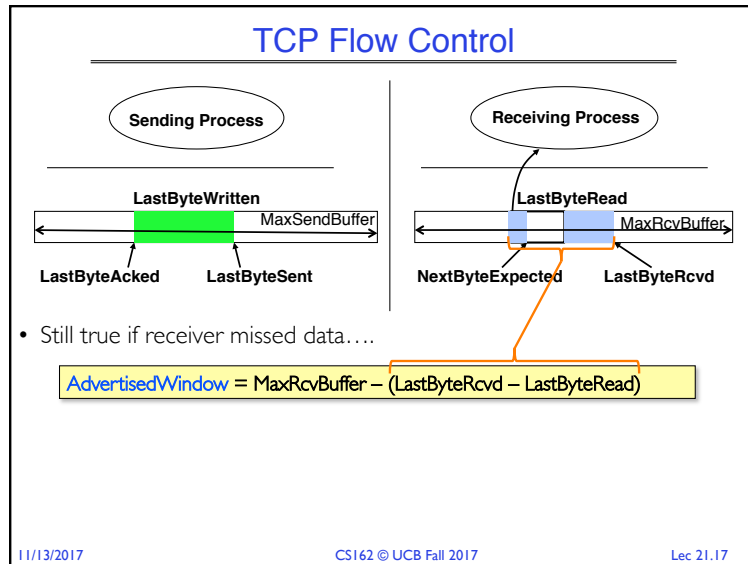
sequence #

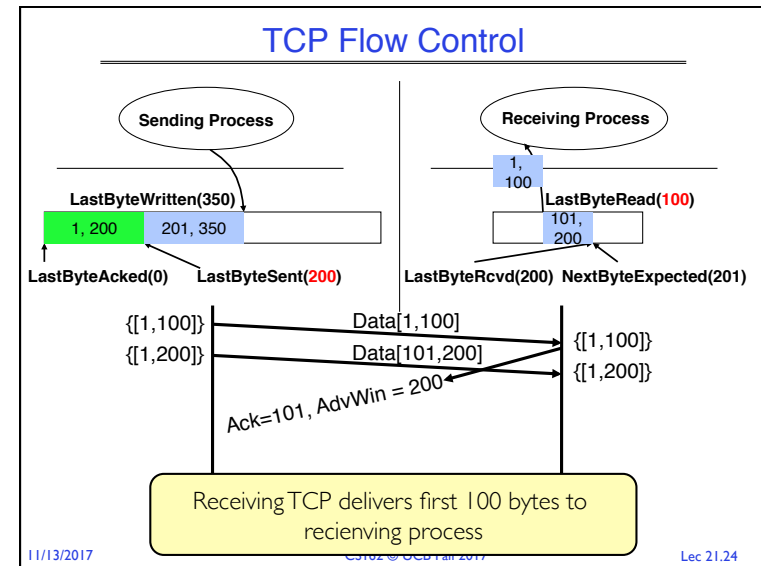
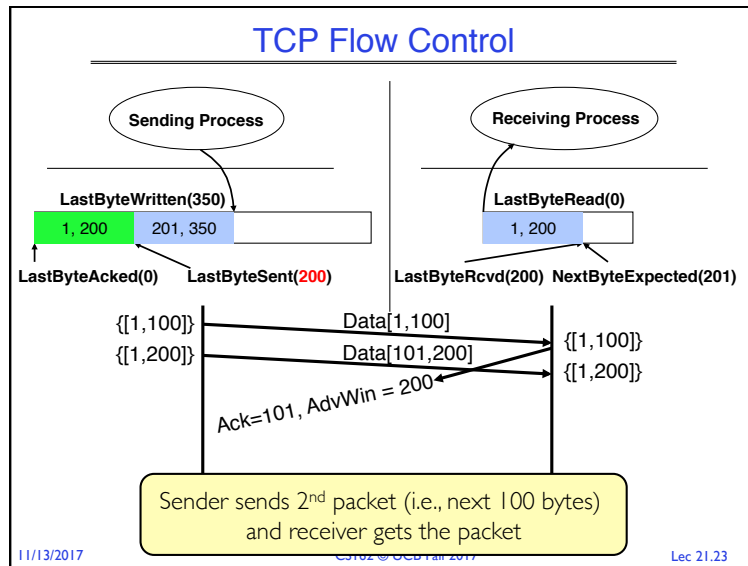
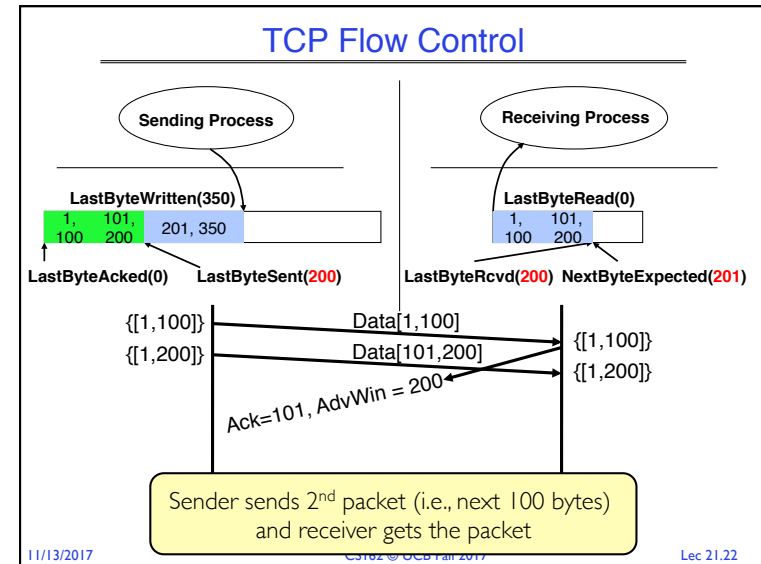
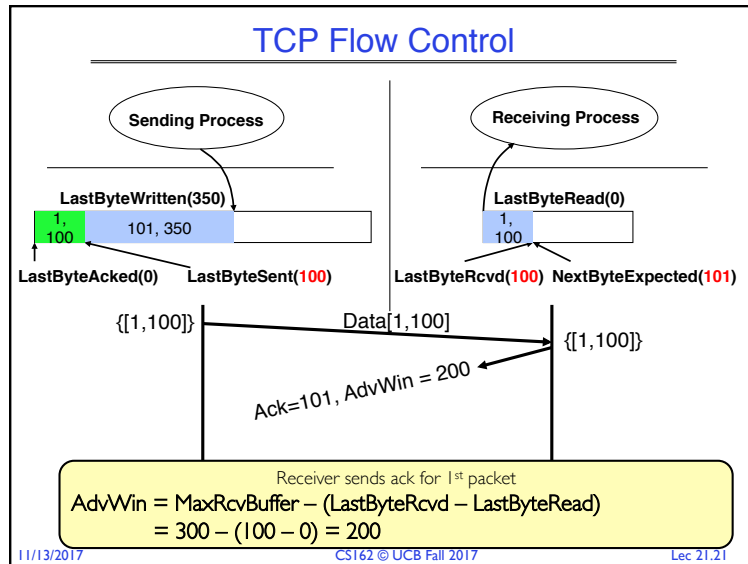
	buffered data									
	27	28	29	30	31	32	33	34	35	36
	H	E	L	L	O	W	O	R	L	D
	$(28 \bmod 10) + 1 = 9$						$(35 \bmod 10) + 1 = 6$			
Circular buffer (N = 10)	L	O	W	O	R			E	L	
	1	2	3	4	5	6	7	8	9	10
						end		start		

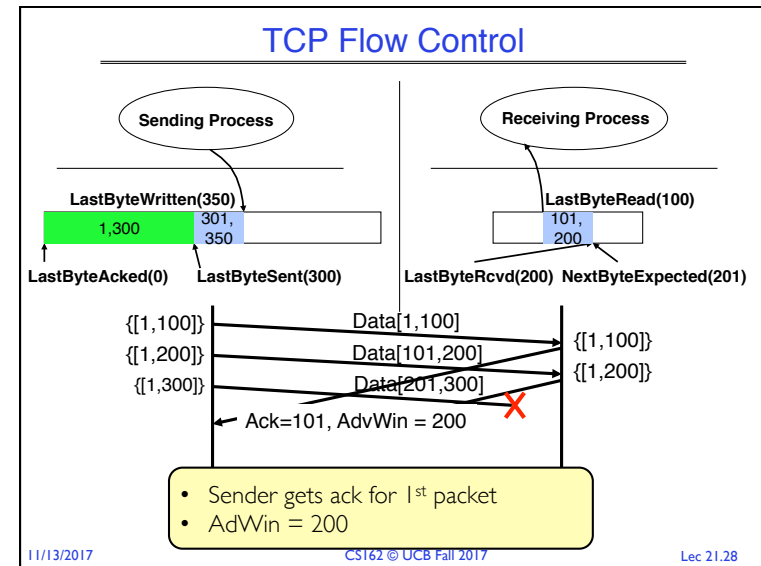
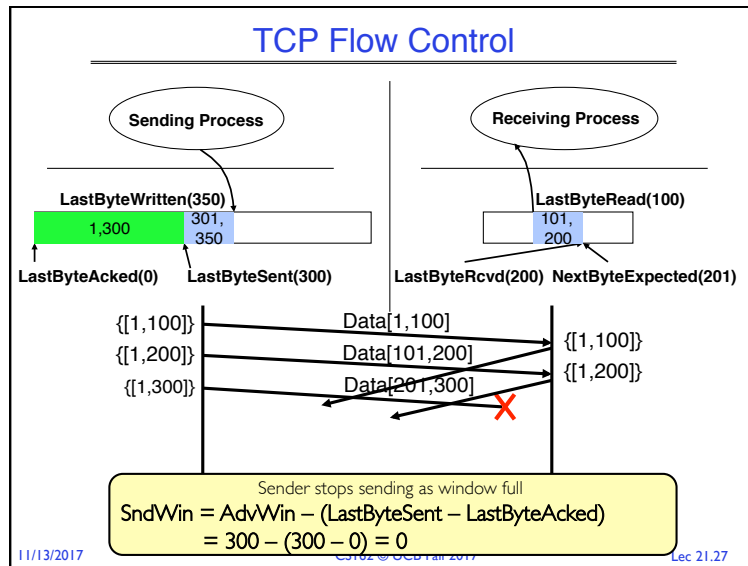
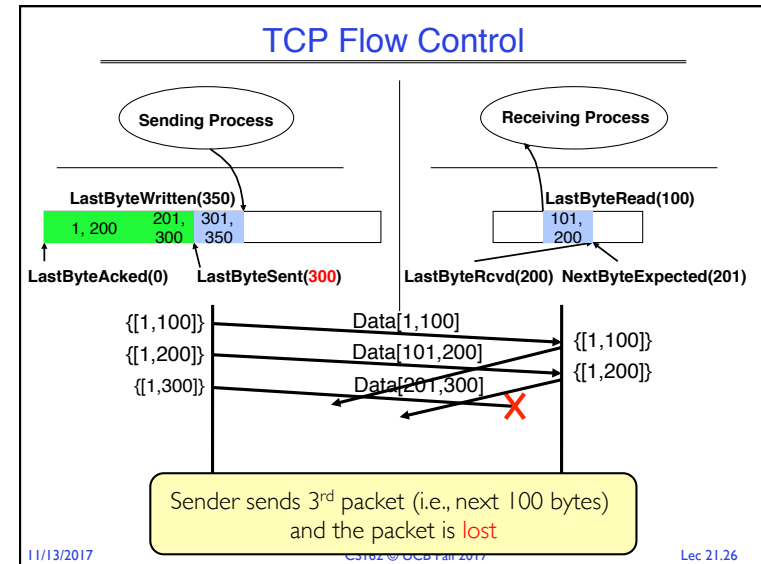
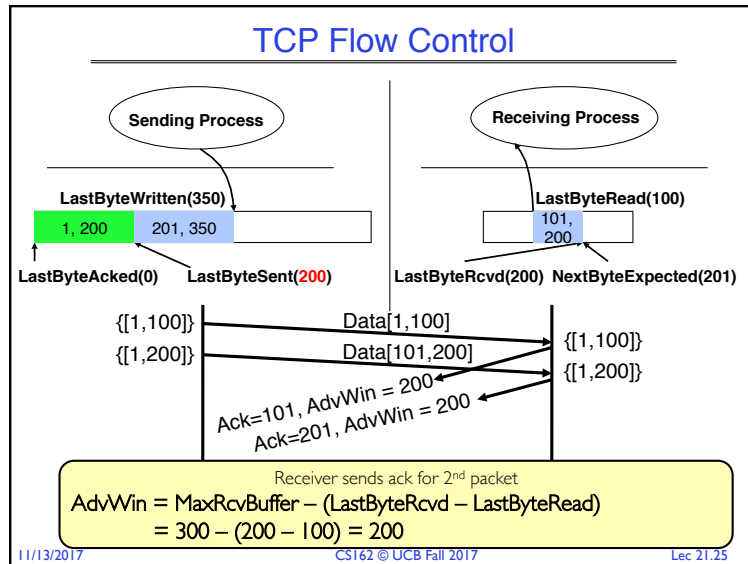
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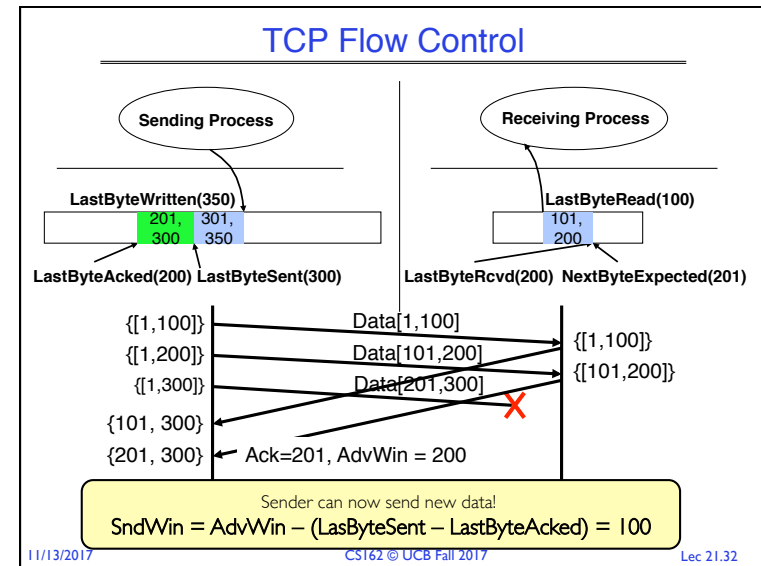
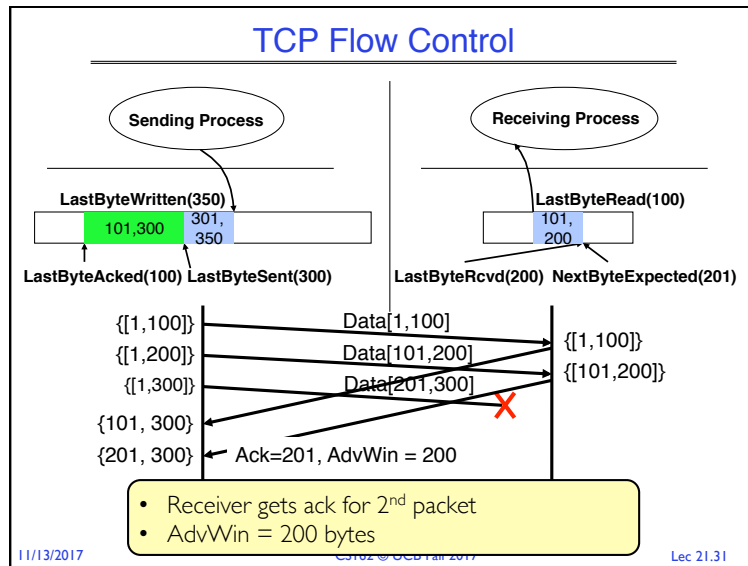
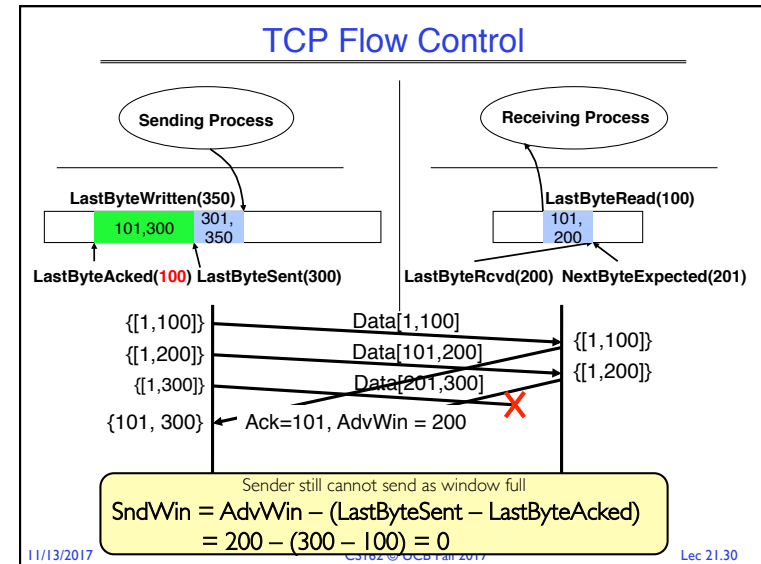
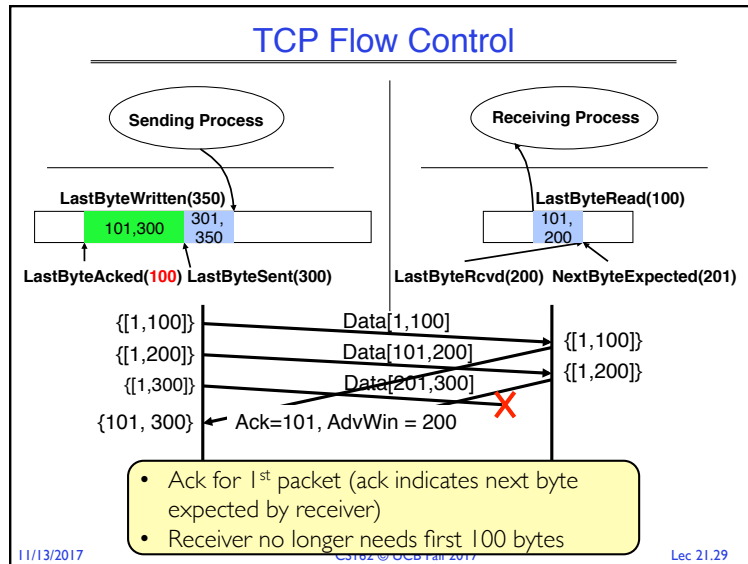


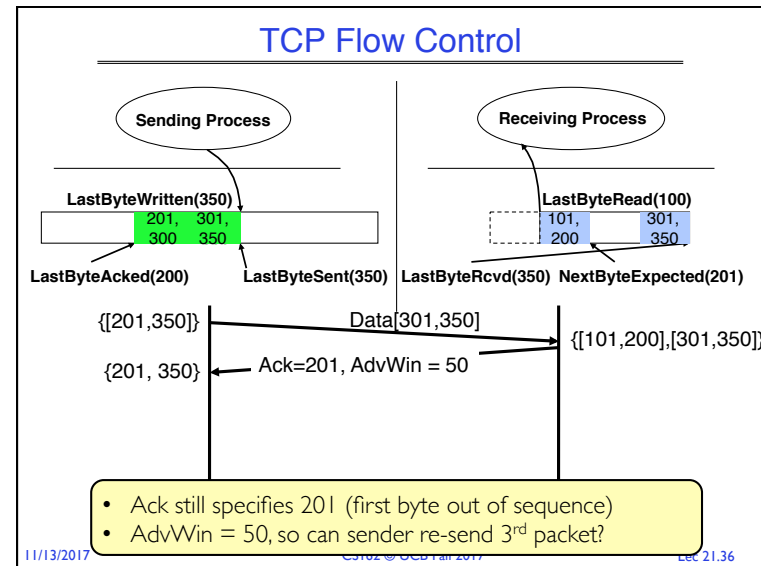
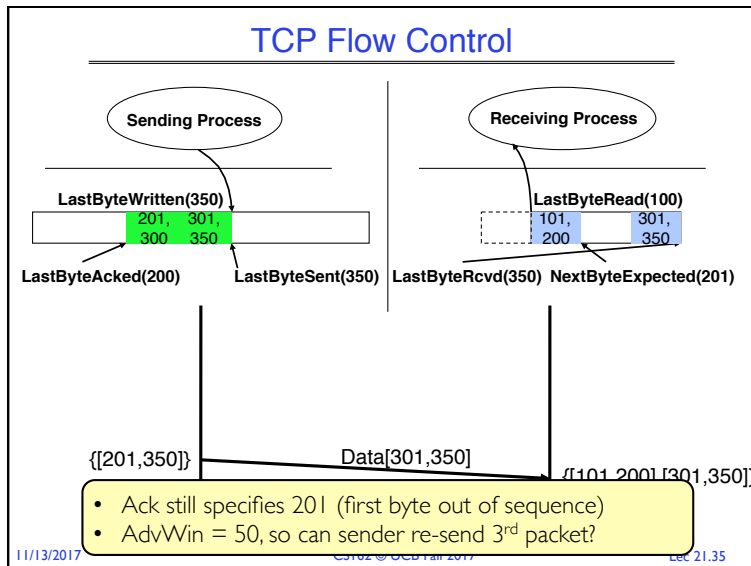
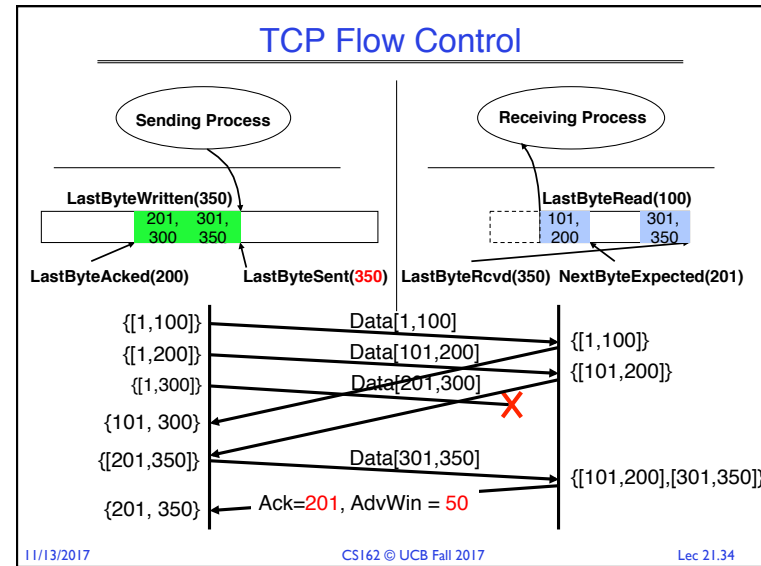
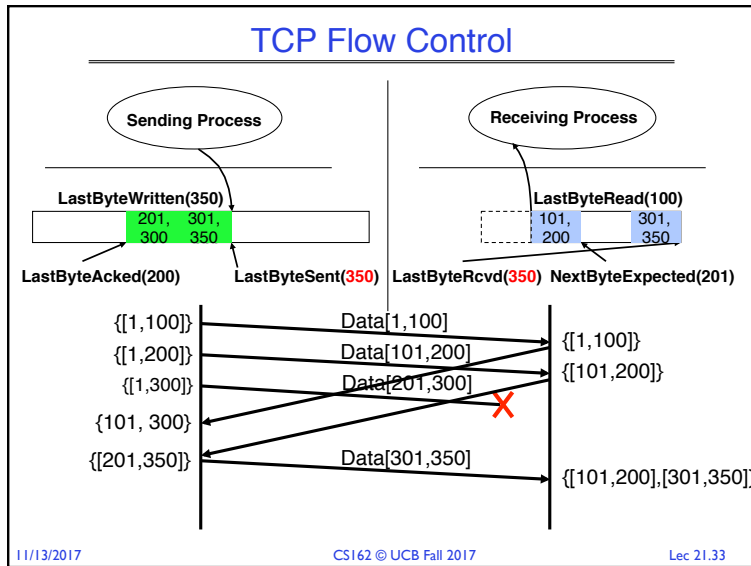


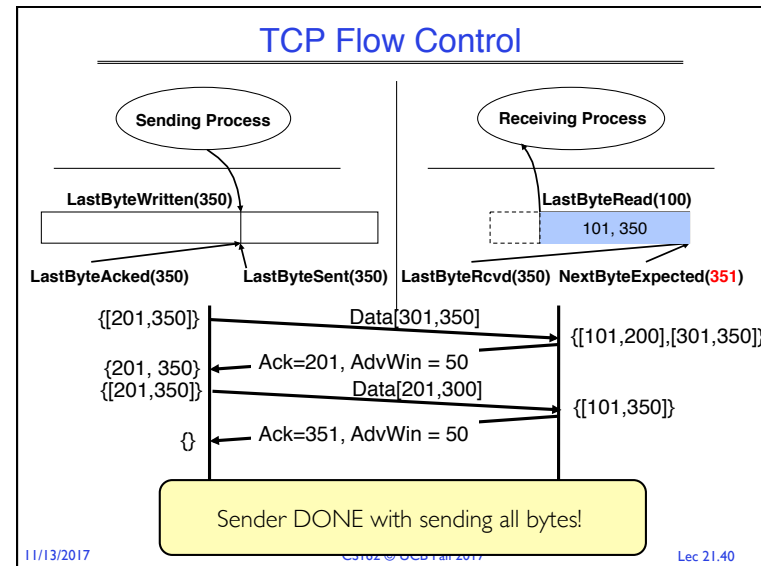
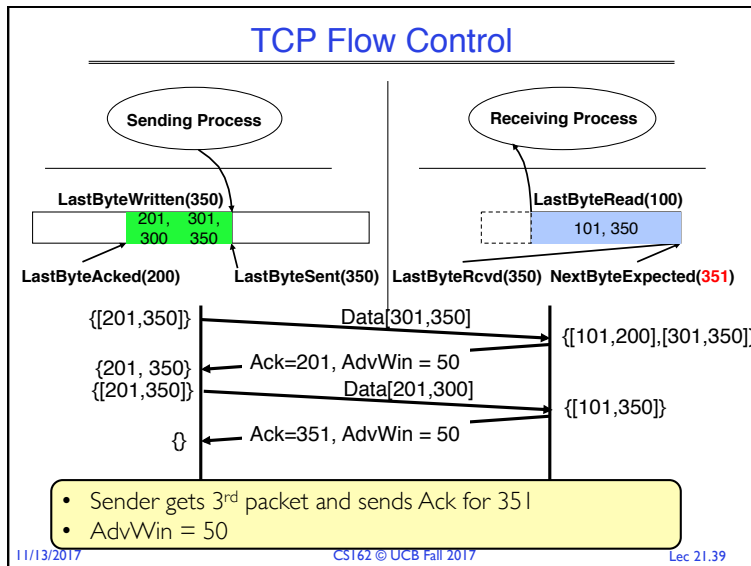
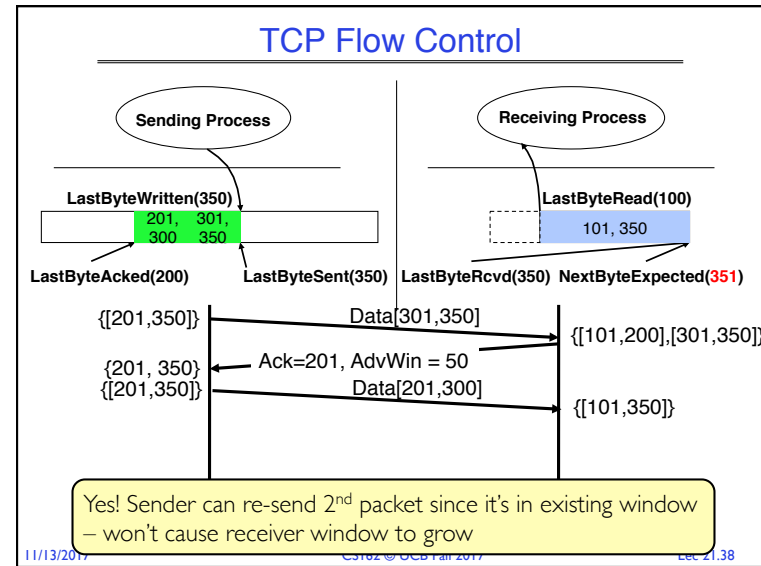
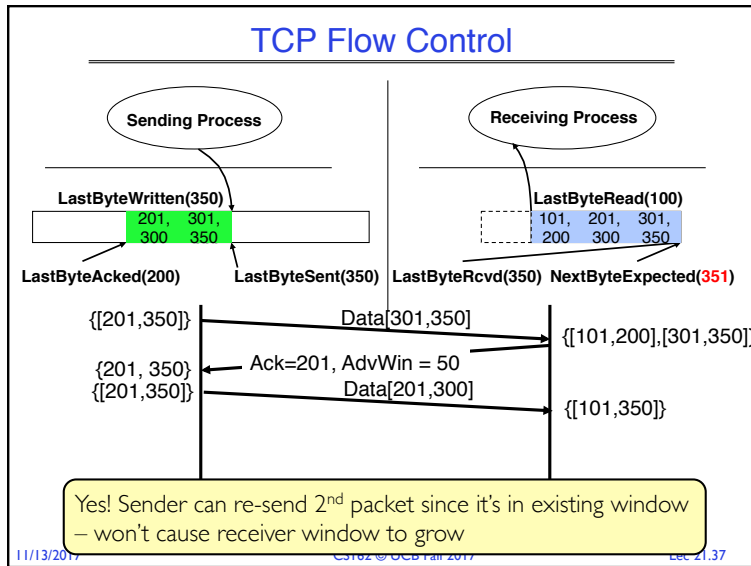












Discussion

- Why not have a huge buffer at the receiver (memory is cheap)?
- Sending window (SndWnd) also depends on network congestion
 - **Congestion control**: ensure that a fast sender doesn't overwhelm a router in the network (discussed in detail in cs168)
- In practice there is another set of buffers in the protocol stack, at the **link layer** (i.e., Network Interface Card)

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Administrivia

- Midterm 3 coming up on **Wen 11/29 6:30-8PM**
 - All topics up to and including Lecture 24
 - » Focus will be on Lectures 17 – 24 and associated readings, and Projects 3
 - » But expect 20-30% questions from materials from Lectures 1-16
 - Closed book
 - 2 sides hand-written notes both sides

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BREAK

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Goals of Today's Lecture

- TCP flow control
- **Two-Phase Commit**

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General's Paradox

- Constraints of problem:
 - Two generals, on separate mountains
 - Can only communicate via messengers
 - Messengers can be captured
- Problem: need to coordinate attack
 - If they attack at different times, they all die
 - If they attack at same time, they win
- Named after Custer, who died at Little Big Horn because he arrived a couple of days too early

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General's Paradox

- Can messages over an unreliable network be used to guarantee two entities do something simultaneously?
 - Remarkably, "no", even if all messages get through

- No way to be sure last message gets through!

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Two-Phase Commit

- Since we can't solve the General's Paradox (i.e. simultaneous action), let's solve a related problem
- Distributed transaction:** Two or more machines agree to do something, or not do it, **atomically**
- Two-Phase Commit protocol:** Developed by Turing Award winner Jim Gray (first Berkeley CS PhD, 1969)

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Two-Phase Commit Protocol

- Persistent stable log on each machine:** keep track of whether commit has happened
 - If a machine crashes, when it wakes up it first checks its log to recover state of world at time of crash
- Prepare Phase:**
 - The global coordinator requests that all participants will promise to commit or **rollback** the **transaction**
 - Participants record promise in log, then acknowledge
 - If anyone votes to abort, coordinator writes "**Abort**" in its log and tells everyone to abort; each records "**Abort**" in log
- Commit Phase:**
 - After all participants respond that they are prepared, then the coordinator writes "**Commit**" to its log
 - Then asks all nodes to commit; they respond with ACK
 - After receive ACKs, coordinator writes "**Got Commit**" to log
- Log used to guarantee that all machines either commit or don't

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2PC Algorithm

- One coordinator
- N workers (replicas)
- High level algorithm description:
 - Coordinator asks all workers if they can commit
 - If all workers reply “**VOTE-COMMIT**”, then coordinator broadcasts “**GLOBAL-COMMIT**”
 - Otherwise coordinator broadcasts “**GLOBAL-ABORT**”
 - Workers obey the **GLOBAL** messages
- Use a persistent, stable log on each machine to keep track of what you are doing
 - If a machine crashes, when it wakes up it first checks its log to recover state of world at time of crash

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Detailed Algorithm

Coordinator Algorithm

Coordinator sends **VOTE-REQ** to all workers

- If receive **VOTE-COMMIT** from all N workers, send **GLOBAL-COMMIT** to all workers
- If doesn't receive **VOTE-COMMIT** from all N workers, send **GLOBAL-ABORT** to all workers

Worker Algorithm

- Wait for **VOTE-REQ** from coordinator
- If ready, send **VOTE-COMMIT** to coordinator
- If not ready, send **VOTE-ABORT** to coordinator
 - And immediately abort

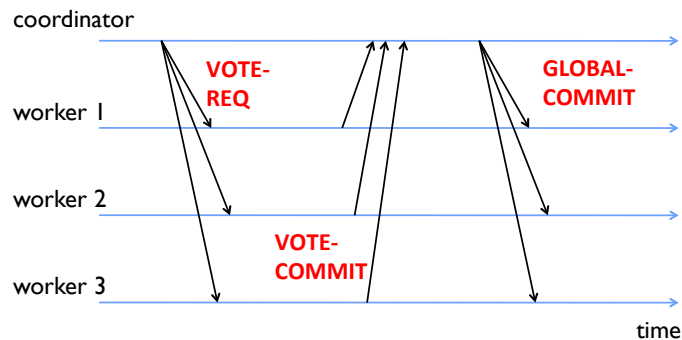
- If receive **GLOBAL-COMMIT** then commit
- If receive **GLOBAL-ABORT** then abort

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Failure Free Example Execution



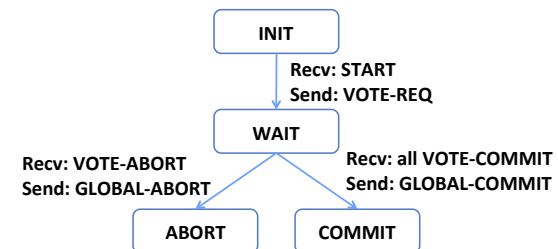
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State Machine of Coordinator

- Coordinator implements simple state machine:

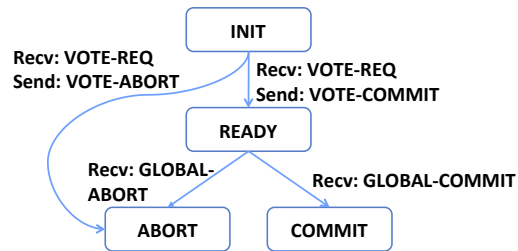


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State Machine of Workers



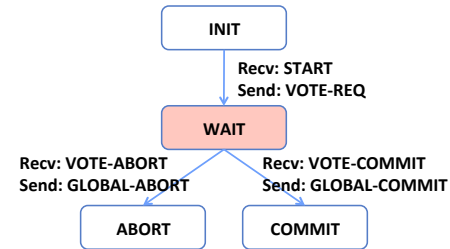
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Dealing with Worker Failures

- Failure only affects states in which the coordinator is waiting for messages
- Coordinator only waits for votes in "WAIT" state
- In WAIT, if doesn't receive N votes, it times out and sends GLOBAL-ABORT

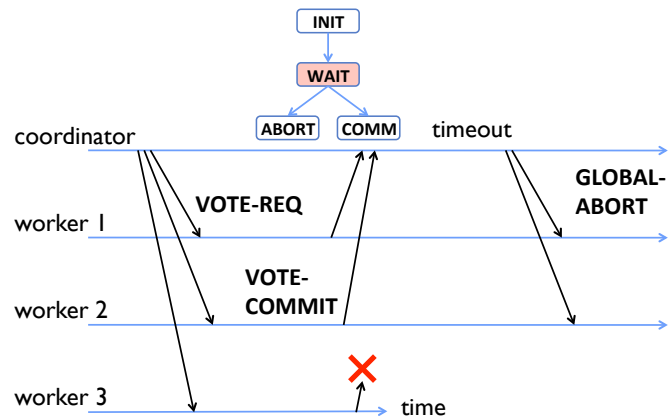


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Example of Worker Failure



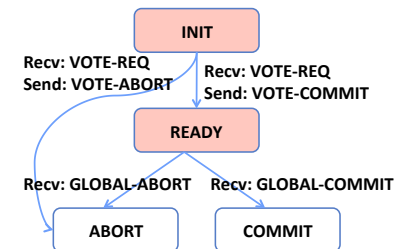
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Dealing with Coordinator Failure

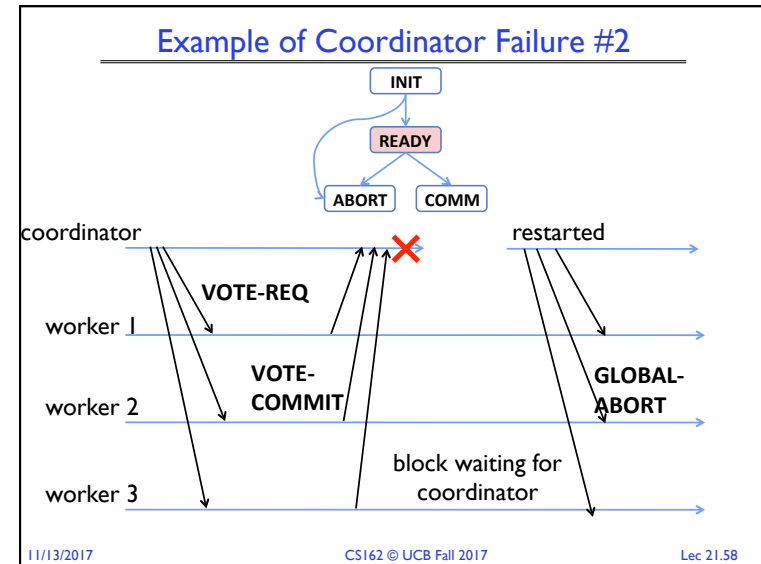
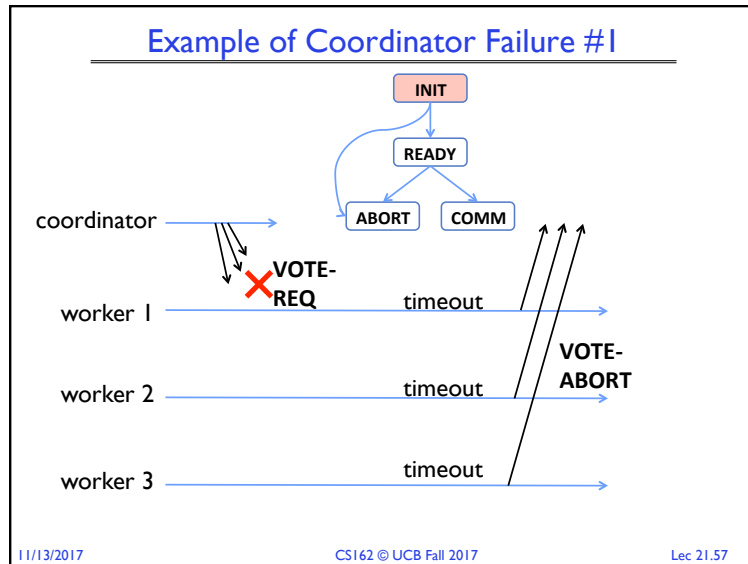
- Worker waits for VOTE-REQ in INIT
 - Worker can time out and abort (coordinator handles it)
- Worker waits for GLOBAL-* message in READY
 - If coordinator fails, workers must **BLOCK** waiting for coordinator to recover and send GLOBAL_* message



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- ### Durability
- All nodes use **stable storage** to store current state
 - stable storage is non-volatile storage (e.g. backed by disk) that guarantees atomic writes.
 - Upon recovery, it can restore state and resume:
 - Coordinator aborts in **INIT**, **WAIT**, or **ABORT**
 - Coordinator commits in **COMMIT**
 - Worker aborts in **INIT**, **ABORT**
 - Worker commits in **COMMIT**
 - Worker asks Coordinator in **READY**
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- ### Blocking for Coordinator to Recover
- A worker waiting for global decision can ask fellow workers about their state
 - If another worker is in **ABORT** or **COMMIT** state then coordinator must have sent **GLOBAL-***
 - » Thus, worker can safely abort or commit, respectively
 - If another worker is still in **INIT** state then both workers can decide to abort
 - If all workers are in ready, need to **BLOCK** (don't know if coordinator wanted to abort or commit)
-
- The diagram shows a state transition for a worker: INIT → READY → ABORT/COMM. Transitions: Recv: VOTE-REQ / Send: VOTE-ABORT (INIT to READY); Recv: VOTE-REQ / Send: VOTE-COMMIT (READY to INIT); Recv: GLOBAL-ABORT (READY to ABORT); Recv: GLOBAL-COMMIT (READY to COMMIT).
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Distributed Decision Making Discussion (1/2)

- Why is distributed decision making desirable?
 - Fault Tolerance!
 - A group of machines can come to a decision even if one or more of them fail during the process
 - » Simple failure mode called "failstop" (different modes later)
 - After decision made, result recorded in multiple places

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Distributed Decision Making Discussion (2/2)

- Undesirable feature of Two-Phase Commit: Blocking
 - One machine can be stalled until another site recovers:
 - » Site B writes "**prepared to commit**" record to its log, sends a "**yes**" vote to the coordinator (site A) and crashes
 - » Site A crashes
 - » Site B wakes up, check its log, and realizes that it has voted "**yes**" on the update. It sends a message to site A asking what happened. At this point, B cannot decide to abort, because update may have committed
 - » B is blocked until A comes back
 - A blocked site holds resources (locks on updated items, pages pinned in memory, etc) until learns fate of update

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PAXOS

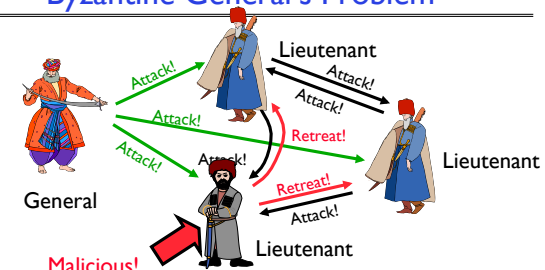
- **PAXOS**: An alternative used by Google and others that does not have this blocking problem
 - Develop by Leslie Lamport (Turing Award Winner)
- What happens if one or more of the nodes is malicious?
 - **Malicious**: attempting to compromise the decision making

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Byzantine General's Problem



- Byzantine General's Problem (n players):
 - One General and $n-1$ Lieutenants
 - Some number of these (f) can be insane or malicious
- The commanding general must send an order to his $n-1$ lieutenants such that the following Integrity Constraints apply:
 - IC1: All loyal lieutenants obey the same order
 - IC2: If the commanding general is loyal, then all loyal lieutenants obey the order he sends

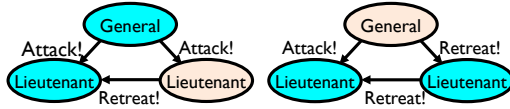
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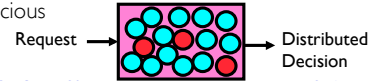
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Byzantine General's Problem (con't)

- Impossibility Results:
 - Cannot solve Byzantine General's Problem with $n=3$ because one malicious player can mess up things



- With f faults, need $n > 3f$ to solve problem
- Various algorithms exist to solve problem
 - Original algorithm has #messages exponential in n
 - Newer algorithms have message complexity $O(n^2)$
 - » One from MIT, for instance (Castro and Liskov, 1999)
- Use of BFT (Byzantine Fault Tolerance) algorithm
 - Allow multiple machines to make a coordinated decision even if some subset of them ($< n/3$) are malicious



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Summary

- TCP flow control
 - Ensures a fast sender does not overwhelm a slow receiver
 - Receiver tells sender how many more bytes it can receive without overflowing its buffer (i.e., AdvertisedWindow)
 - The ack(nowledgement) contains sequence number N of **next byte the receiver expects**, i.e., receiver has received all bytes **in sequence** up to and including $N-1$
- Two-phase commit: distributed decision making
 - First, make sure everyone guarantees they will commit if asked (prepare)
 - Next, ask everyone to commit

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