

CSI 62 Operating Systems and Systems Programming Lecture 3

Processes (con't), Fork, Introduction to I/O

August 30th, 2017
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<http://cs162.eecs.berkeley.edu>

Recall: Four fundamental OS concepts

- Thread
 - Single unique execution context
 - Program Counter, Registers, Execution Flags, Stack
- Address Space w/ translation
 - Programs execute in an *address space* that is distinct from the memory space of the physical machine
- Process
 - An instance of an executing program is a *process* consisting of an *address space* and *one or more threads of control*
- Dual Mode operation/Protection
 - Only the “system” has the ability to access certain resources
 - The OS and the hardware are protected from user programs and user programs are isolated from one another by *controlling the translation* from program virtual addresses to machine physical addresses

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Process Control Block

(Assume single threaded processes for now)

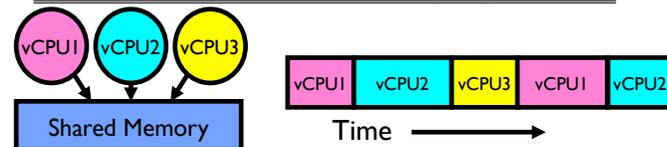
- Kernel represents each process as a process control block (PCB)
 - Status (running, ready, blocked, ...)
 - Registers, SP, ... (when not running)
 - Process ID (PID), User, Executable, Priority, ...
 - Execution time, ...
 - Memory space, translation tables, ...
- Kernel Scheduler maintains a data structure containing the PCBs
- Scheduling algorithm selects the next one to run

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Recall: give the illusion of multiple processors?



- Assume a single processor. How do we provide the *illusion* of multiple processors?
 - Multiplex in time!
 - Multiple “virtual CPUs”
- Each virtual “CPU” needs a structure to hold, i.e., **PCB**:
 - Program Counter (PC), Stack Pointer (SP)
 - Registers (Integer, Floating point, others...?)
- How switch from one virtual CPU to the next?
 - Save PC, SP, and registers in current **PCB**
 - Load PC, SP, and registers from new **PCB**
- What triggers switch?
 - Timer, voluntary yield, I/O, other things

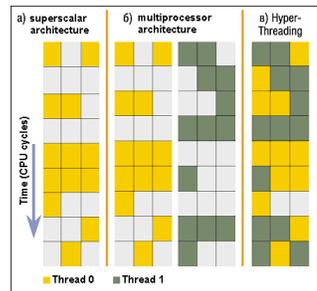
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Simultaneous MultiThreading/Hyperthreading

- Hardware technique
 - Superscalar processors can execute multiple instructions that are independent
 - Hyperthreading **duplicates register state** to make a second “thread,” allowing more instructions to run
- Can schedule each thread as if were separate CPU
 - But, sub-linear speedup!
- Original technique called “Simultaneous Multithreading”
 - <http://www.cs.washington.edu/research/smt/index.html>
 - SPARC, Pentium 4/Xeon (“Hyperthreading”), Power 5



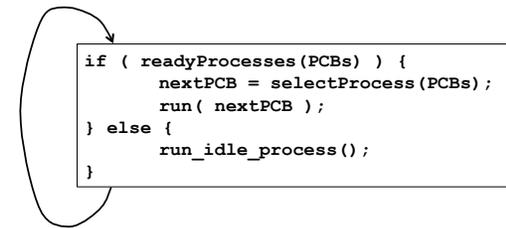
Colored blocks show instructions executed

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Scheduler



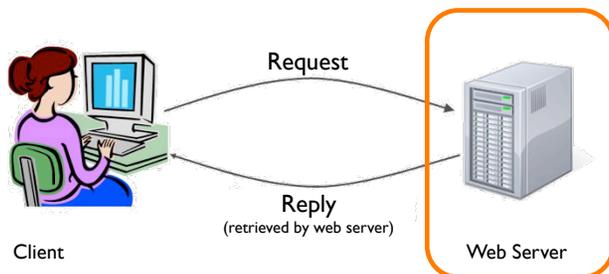
- Scheduling: Mechanism for deciding which processes/threads receive the CPU
- Lots of different scheduling policies provide ...
 - Fairness or
 - Realtime guarantees or
 - Latency optimization or ..

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Putting it together: web server

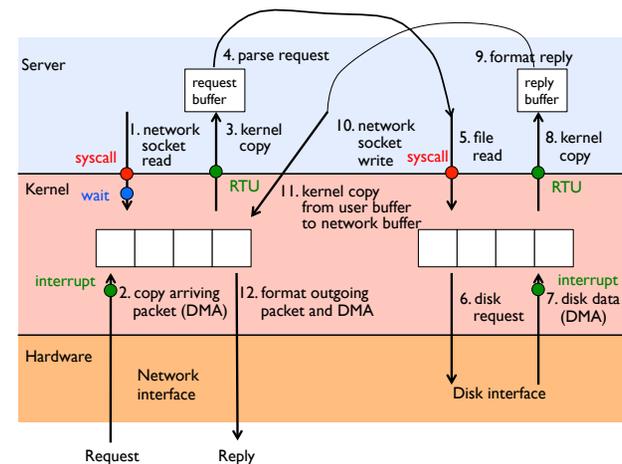


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Putting it together: web server



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Recall: 3 types of Kernel Mode Transfer

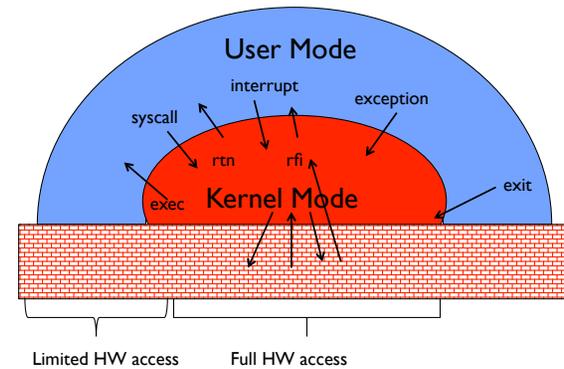
- Syscall
 - Process requests a system service, e.g., exit
 - Like a function call, but “outside” the process
 - Does not have the address of the system function to call
 - Like a Remote Procedure Call (RPC) – for later
 - Marshall the syscall ID and arguments in registers and execute syscall
- Interrupt
 - External asynchronous event triggers context switch
 - e.g., Timer, I/O device
 - Independent of user process
- Trap or Exception
 - Internal synchronous event in process triggers context switch
 - e.g., Protection violation (segmentation fault), Divide by zero, ...

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Recall: User/Kernel (Privileged) Mode



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Implementing Safe Kernel Mode Transfers

- Important aspects:
 - Separate kernel stack
 - Controlled transfer into kernel (e.g., syscall table)
- Carefully constructed kernel code packs up the user process state and sets it aside
 - Details depend on the machine architecture
- Should be impossible for buggy or malicious user program to cause the kernel to corrupt itself

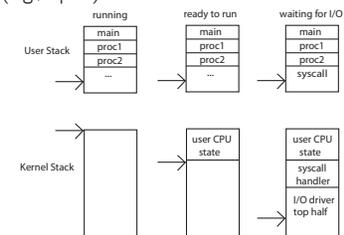
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Need for Separate Kernel Stacks

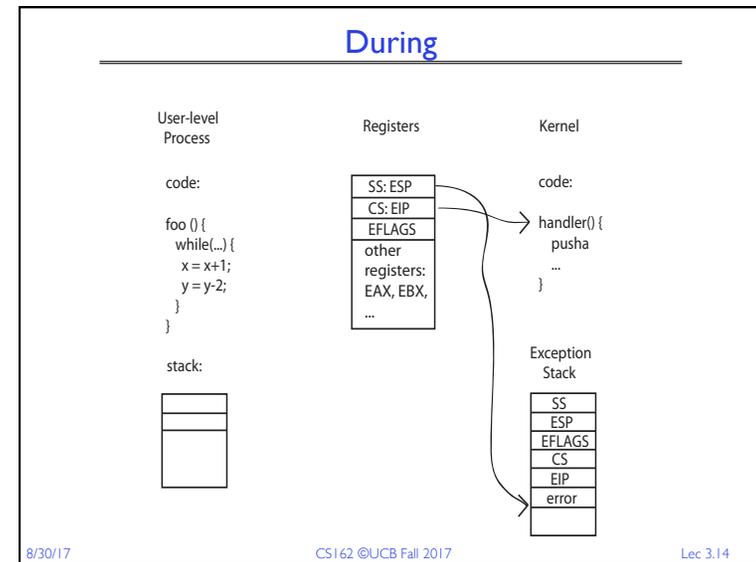
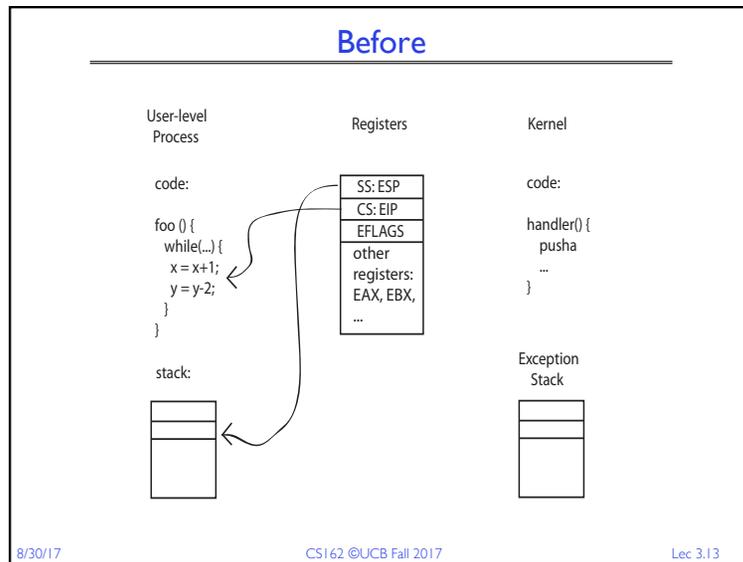
- Kernel needs space to work
- Cannot put anything on the user stack (Why?)
- Two-stack model
 - OS thread has interrupt stack (located in kernel memory) plus User stack (located in user memory)
 - Syscall handler copies user args to kernel space before invoking specific function (e.g., open)
 - Interrupts (???)



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- ### Kernel System Call Handler
- Vector through well-defined syscall entry points!
 - Table mapping system call number to handler
 - Locate arguments
 - In registers or on user (!) stack
 - Copy arguments
 - From user memory into kernel memory
 - Protect kernel from malicious code evading checks
 - Validate arguments
 - Protect kernel from errors in user code
 - Copy results back
 - Into user memory
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- ### Hardware support: Interrupt Control
- Interrupt processing not visible to the user process:
 - Occurs between instructions, restarted transparently
 - No change to process state
 - What can be observed even with perfect interrupt processing?
 - Interrupt Handler invoked with interrupts 'disabled'
 - Re-enabled upon completion
 - Non-blocking (run to completion, no waits)
 - Pack up in a queue and pass off to an OS thread for hard work
 - » wake up an existing OS thread
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Hardware support: Interrupt Control

- OS kernel may enable/disable interrupts
 - On x86: CLI (disable interrupts), STI (enable)
 - Atomic section when select next process/thread to run
 - Atomic return from interrupt or syscall
- HW may have multiple levels of interrupt
 - Mask off (disable) certain interrupts, eg., lower priority
 - Certain Non-Maskable-Interrupts (NMI)
 - » e.g., kernel segmentation fault

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The diagram illustrates the hardware support for interrupt control. It shows a central 'Interrupt Controller' block containing a 'Priority Encoder' and an 'Interrupt Mask'. The controller is connected to a 'Network' (represented by a green vertical arrow), a 'Timer' (yellow box), and a 'Software Interrupt' (pink box). The controller sends an 'Interrupt' signal to the 'CPU' (blue circle) and an 'IntID' (interrupt ID) signal. The CPU has an 'Int Disable' flag and is also connected to an 'NMI' (Non-Maskable Interrupt) line. A 'Control' signal is shown between the CPU and the controller.

- Interrupts invoked with interrupt lines from devices
- Interrupt controller chooses interrupt request to honor
 - Mask enables/disables interrupts
 - Priority encoder picks highest enabled interrupt
 - Software Interrupt Set/Cleared by Software
 - Interrupt identity specified with ID line
- CPU can disable all interrupts with internal flag
- Non-Maskable Interrupt line (NMI) can't be disabled

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How do we take interrupts safely?

- **Interrupt vector**
 - Limited number of entry points into kernel
- Kernel interrupt stack
 - Handler works regardless of state of user code
- Interrupt masking
 - Handler is non-blocking
- Atomic transfer of control
 - “Single instruction”-like to change:
 - » Program counter
 - » Stack pointer
 - » Memory protection
 - » Kernel/user mode
- Transparent restartable execution
 - User program does not know interrupt occurred

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Can a process create a process ?

- Yes! Unique identity of process is the “process ID” (or PID)
- **fork()** system call creates a *copy* of current process with a new PID
- Return value from **fork()**: integer
 - When > 0:
 - » Running in (original) **Parent** process
 - » return value is **pid** of new child
 - When = 0:
 - » Running in new **Child** process
 - When < 0:
 - » Error! Must handle somehow
 - » Running in original process
- **All state of original process duplicated in both Parent and Child!**
 - Memory, File Descriptors (next topic), etc...

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fork1.c

```
#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#include <unistd.h>
#include <sys/types.h>

#define BUFSIZE 1024
int main(int argc, char *argv[])
{
    char buf[BUFSIZE];
    size_t readlen, writelen, slen;
    pid_t cpid, mypid;
    pid_t pid = getpid(); /* get current processes PID */
    printf("Parent pid: %d\n", pid);
    cpid = fork();
    if (cpid > 0) { /* Parent Process */
        mypid = getpid();
        printf("[%d] parent of [%d]\n", mypid, cpid);
    } else if (cpid == 0) { /* Child Process */
        mypid = getpid();
        printf("[%d] child\n", mypid);
    } else {
        perror("Fork failed");
        exit(1);
    }
    exit(0);
}
```

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fork2.c

```
int status;
...
cpid = fork();
if (cpid > 0) { /* Parent Process */
    mypid = getpid();
    printf("[%d] parent of [%d]\n", mypid, cpid);
    tcpid = wait(&status);
    printf("[%d] bye %d(%d)\n", mypid, tcpid, status);
} else if (cpid == 0) { /* Child Process */
    mypid = getpid();
    printf("[%d] child\n", mypid);
}
...
```

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Process Races: fork3.c

```
int i;
cpid = fork();
if (cpid > 0) {
    mypid = getpid();
    printf("[%d] parent of [%d]\n", mypid, cpid);
    for (i=0; i<10; i++) {
        printf("[%d] parent: %d\n", mypid, i);
        // sleep(1);
    }
} else if (cpid == 0) {
    mypid = getpid();
    printf("[%d] child\n", mypid);
    for (i=0; i>-10; i--) {
        printf("[%d] child: %d\n", mypid, i);
        // sleep(1);
    }
}

• Question: What does this program print?
• Does it change if you add in one of the sleep() statements?
```

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UNIX Process Management

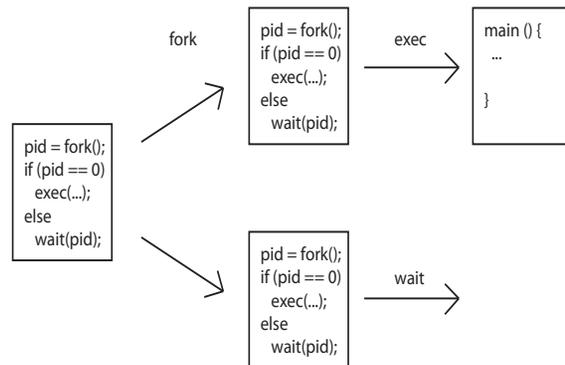
- UNIX **fork** – system call to create a copy of the current process, and start it running
 - No arguments!
- UNIX **exec** – system call to *change the program* being run by the current process
- UNIX **wait** – system call to wait for a process to finish
- UNIX **signal** – system call to send a notification to another process
- UNIX man pages: **fork(2)**, **exec(3)**, **wait(2)**, **signal(3)**

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UNIX Process Management



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Administrivia: Getting started

- **THIS Friday (9/1) is early drop day! Very hard to drop afterwards...**
- Work on Homework 0 **due on Monday!**
 - Get familiar with all the cs162 tools
 - Submit to autograder via git
- Participation: Attend section! Get to know your TA!
- Group sign up via autograder then TA form next week (after EDD)
 - Get finding groups of 4 people ASAP
 - Priority for same section; if cannot make this work, keep same TA

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Volunteers for RISE Camp?

- RISE Camp 2017, **September 7-8**
 - Between 130-150 attendees
 - Talks and training for the latest software developed by RISE Lab (successor if AMP Lab)
- You'll get:
 - Amazon gift certificate for \$25
 - An event T-Shirt and
 - Free food ;-)
 - Talk with people involved in the project
- If interested contact boban@eecs.berkeley.edu or me

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5 min break

Shell

- A shell is a job control system
 - Allows programmer to create and manage a set of programs to do some task
 - Windows, MacOS, Linux all have shells
- Example: to compile a C program

```
cc -c sourcefile1.c
cc -c sourcefile2.c
ln -o program sourcefile1.o sourcefile2.o
./program
```



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Signals – infloop.c

```
#include <stdlib.h>
#include <stdio.h>
#include <sys/types.h>

#include <unistd.h>
#include <signal.h>

void signal_callback_handler(int signum)
{
    printf("Caught signal %d - phew!\n", signum);
    exit(1);
}

int main() {
    signal(SIGINT, signal_callback_handler);

    while (1) {}
}
```

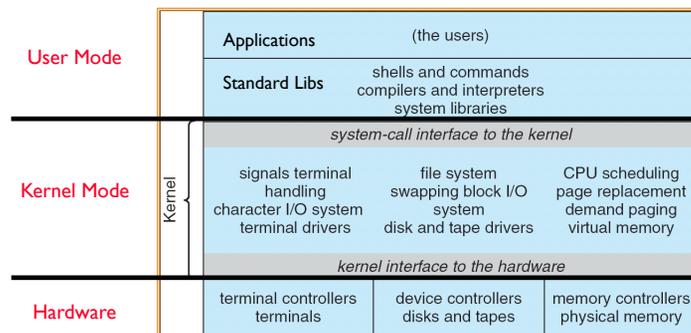
Got top?

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Recall: UNIX System Structure



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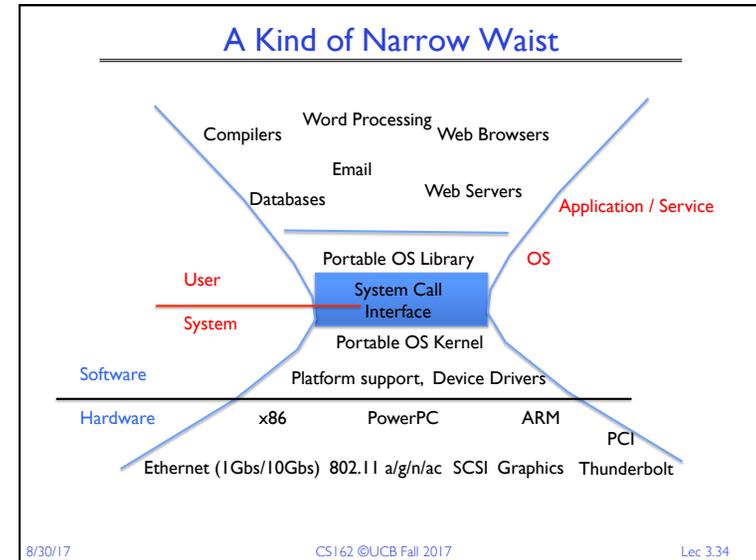
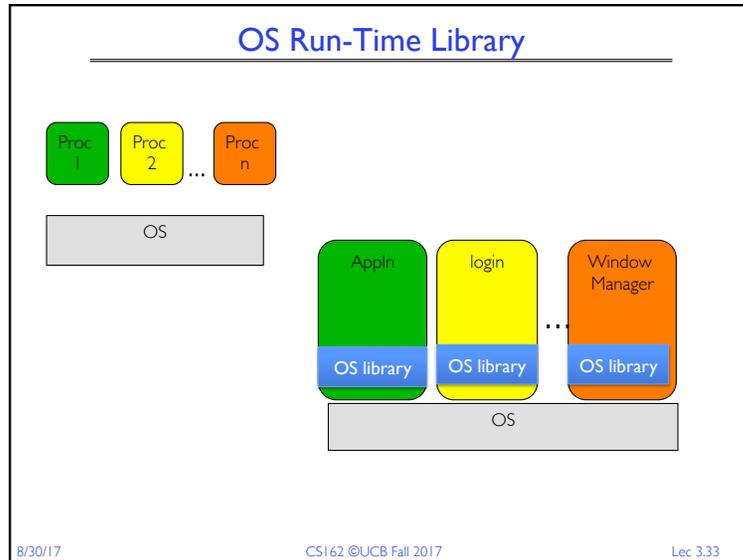
How Does the Kernel Provide Services?

- You said that applications request services from the operating system via **syscall**, but ...
- I've been writing all sort of useful applications and I never ever saw a "syscall" !!!
- That's right.
- It was buried in the programming language runtime library (e.g, libc.a)
- ... Layering

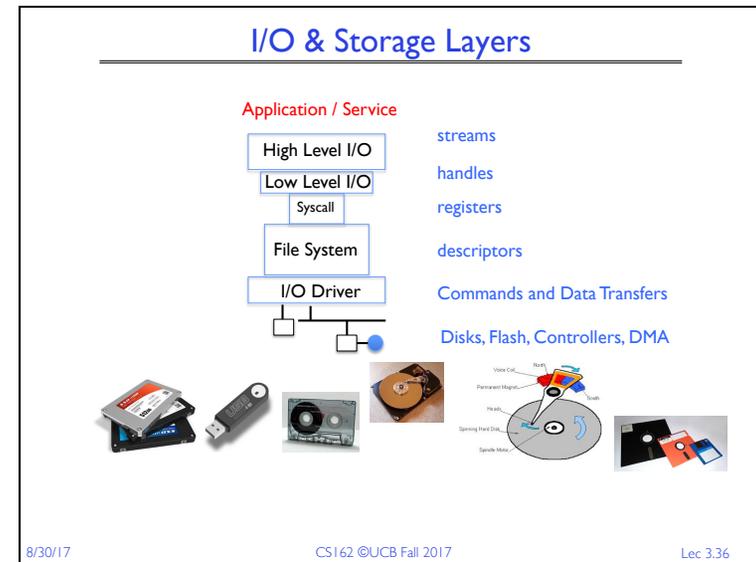
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- ### Key Unix I/O Design Concepts
- Uniformity
 - file operations, device I/O, and interprocess communication through open, read/write, close
 - Allows simple composition of programs
 - » find | grep | wc ...
 - Open before use
 - Provides opportunity for access control and arbitration
 - Sets up the underlying machinery, i.e., data structures
 - Byte-oriented
 - Even if blocks are transferred, addressing is in bytes
 - Kernel buffered reads
 - Streaming and block devices looks the same
 - read blocks process, yielding processor to other task
 - Kernel buffered writes
 - Completion of out-going transfer decoupled from the application, allowing it to continue
 - Explicit close
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Summary

- Process: execution environment with Restricted Rights
 - Address Space with One or More Threads
 - Owns memory (address space)
 - Owns file descriptors, file system context, ...
 - Encapsulate one or more threads sharing process resources
- Interrupts
 - Hardware mechanism for regaining control from user
 - Notification that events have occurred
 - User-level equivalent: Signals
- Native control of Process
 - Fork, Exec, Wait, Signal
- Basic Support for I/O
 - Standard interface: open, read, write, seek
 - Device drivers: customized interface to hardware

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The File System Abstraction

- High-level idea
 - Files live in hierarchical namespace of filenames
- File
 - Named collection of data in a file system
 - File data
 - » Text, binary, linearized objects
 - File Metadata: information about the file
 - » Size, Modification Time, Owner, Security info
 - » Basis for access control
- Directory
 - “Folder” containing files & Directories
 - Hierarchical (graphical) naming
 - » Path through the directory graph
 - » Uniquely identifies a file or directory
 - `/home/ff/cs162/public_html/fa16/index.html`
 - Links and Volumes (later)

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