

CS 188: Artificial Intelligence

Spring 2006

Lecture 17: Bayes' Nets III

3/16/2006

Dan Klein – UC Berkeley

Today

- Last time:
 - Bayes nets
 - Conditional independence
- Today:
 - More conditional independence
 - Inference to answer queries

Reachability (the Bayes' Ball)

- **Correct algorithm:**

- Start at source node
- Try to reach target by search

- States: node, along with previous arc

- **Successor function:**

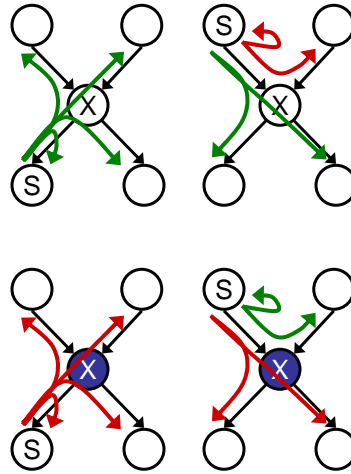
- **Unobserved nodes:**

- To any child
- To any parent if coming from a child (or start)

- **Observed nodes:**

- From parent to parent

- If you can't reach a node, it's conditionally independent of the start node



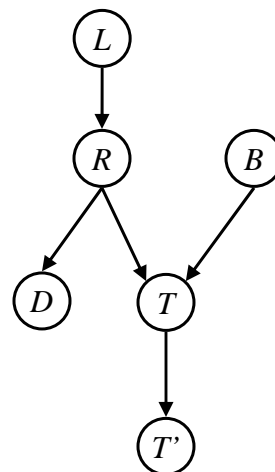
Example

$$L \perp\!\!\!\perp T' | T \quad \text{Yes}$$

$$L \perp\!\!\!\perp B \quad \text{Yes}$$

$$L \perp\!\!\!\perp B | T$$

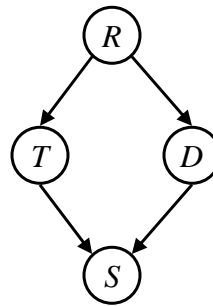
$$L \perp\!\!\!\perp B | T'$$



Example

- Variables:

- R: Raining
- T: Traffic
- D: Roof drips
- S: I'm sad



- Questions:

$$T \perp\!\!\!\perp D$$

$$T \perp\!\!\!\perp D | R \quad \text{Yes}$$

$$T \perp\!\!\!\perp D | R, S$$

Summary

- Bayes nets compactly encode joint distributions
- Guaranteed independencies of distributions can be deduced from BN graph structure
- The Bayes' ball algorithm (aka d-separation)
- A Bayes net may have other independencies that are not detectable until you inspect its specific distribution

Inference

- Inference: calculating some statistic from a joint probability distribution

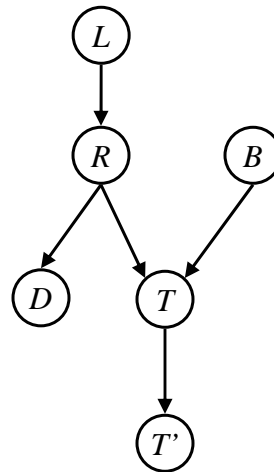
- Examples:

- Posterior marginal probability:

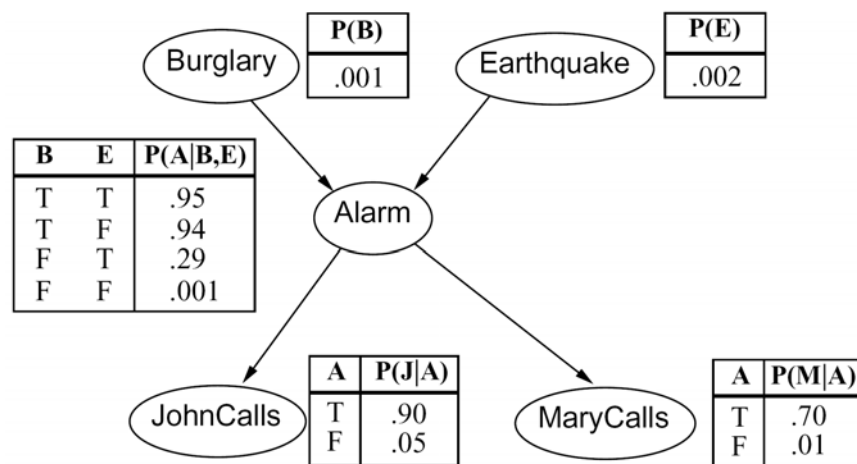
$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$



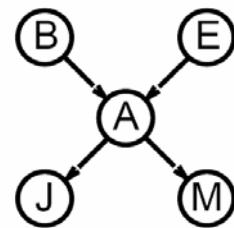
Reminder: Alarm Network



Atomic Inference

- Given unlimited time, inference in BNs is easy
- Recipe:
 - State the marginal probabilities you want
 - Figure out ALL the atomic probabilities you need
 - Calculate and combine them
- Example:

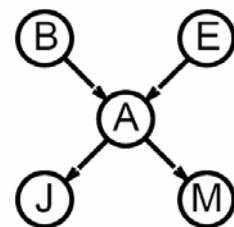
$$P(b|j, m) = \frac{P(b, j, m)}{P(j, m)}$$



Example

$$P(b|j, m) = \frac{P(b, j, m)}{P(j, m)}$$

$$\begin{aligned}
 P(b, j, m) &= P(b, e, a, j, m) + \\
 &\quad P(b, \bar{e}, a, j, m) + \\
 &\quad P(b, e, \bar{a}, j, m) + \\
 &\quad P(b, \bar{e}, \bar{a}, j, m) \\
 &= \sum_{e, a} P(b, e, a, j, m)
 \end{aligned}$$



Where did we use the BN structure?

We didn't!

Example

$$P(b, j, m) =$$

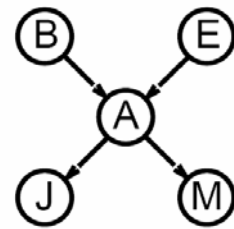
$$\begin{aligned} &P(b)P(e)P(a|b, e)P(j|a)P(m|a) + \\ &P(b)P(e)P(\bar{a}|b, e)P(j|\bar{a})P(m|\bar{a}) + \\ &P(b)P(\bar{e})P(a|b, \bar{e})P(j|a)P(m|a) + \\ &P(b)P(\bar{e})P(\bar{a}|b, \bar{e})P(j|\bar{a})P(m|\bar{a}) \end{aligned}$$

Example

$$P(b|j, m) = \frac{P(b, j, m)}{P(j, m)}$$

$$P(b, j, m) = \sum_{e, a} P(b, e, a, j, m)$$

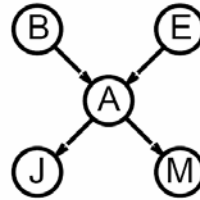
$$P(\bar{b}, j, m) = \sum_{e, a} P(\bar{b}, e, a, j, m)$$



$$\begin{pmatrix} P(b, j, m) \\ P(\bar{b}, j, m) \end{pmatrix} \xrightarrow{\text{Normalize}} \begin{pmatrix} P(b|j, m) \\ P(\bar{b}|j, m) \end{pmatrix}$$

Inference by Enumeration

- Atomic inference is extremely slow!
- Slightly clever way to save work:
 - Move the sums as far right as possible
 - Example:



$$\begin{aligned}
 P(b, j, m) &= \sum_{e, a} P(b, e, a, j, m) \\
 &= \sum_{e, a} P(b)P(e)P(a|b, e)P(j|a)P(m|a) \\
 &= P(b) \sum_e P(e) \sum_a P(a|b, e)P(j|a)P(m|a)
 \end{aligned}$$

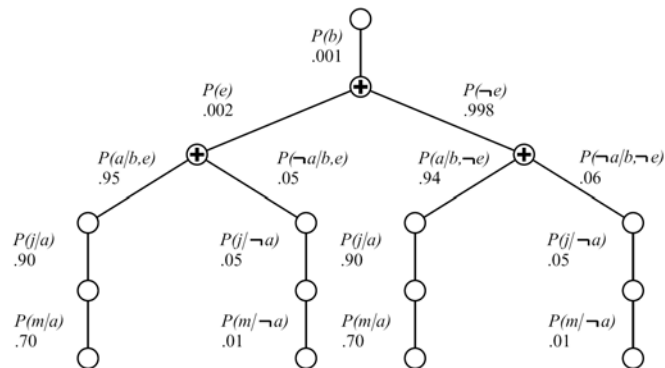
Example

$$\begin{aligned}
 P(b, j, m) = & P(b)P(e)P(a|b, e)P(j|a)P(m|a) + \\
 & P(b)P(e)P(\bar{a}|b, e)P(j|\bar{a})P(m|\bar{a}) + \\
 & P(b)P(\bar{e})P(a|b, \bar{e})P(j|a)P(m|a) + \\
 & P(b)P(\bar{e})P(\bar{a}|b, \bar{e})P(j|\bar{a})P(m|\bar{a})
 \end{aligned}$$

$$P(b) \left\{ \begin{array}{l} \overset{\oplus}{P(e)} \left\{ \begin{array}{ll} P(a|b, e) & P(j|a)P(m|a) \\ P(\bar{a}|b, e) & P(j|\bar{a})P(m|\bar{a}) \end{array} \right. \\ \overset{\oplus}{P(\bar{e})} \left\{ \begin{array}{ll} P(a|b, \bar{e}) & P(j|a)P(m|a) \\ P(\bar{a}|b, \bar{e}) & P(j|\bar{a})P(m|\bar{a}) \end{array} \right. \end{array} \right.$$

Evaluation Tree

- View the nested sums as a computation tree:

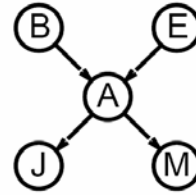


- Still repeated work: calculate $P(m|a)$ $P(j|a)$ twice, etc.

Variable Elimination: Idea

- Lots of redundant work in the computation tree!
- We can save time if we cache all partial results
- This is the basic idea behind variable elimination

Basic Objects



- Track objects called **factors**
- Initial factors are local CPTs

$$\underbrace{P(B)}_{f_B(B)} \quad \underbrace{P(J|A)}_{f_J(A, J)} \quad \underbrace{P(A|B, E)}_{f_A(A, B, E)}$$

- During elimination, create new factors
- Anatomy of a factor:

4 numbers, one for each value of D and E

$$f_{A\bar{B}\bar{C}D}(D, E)$$

Variables introduced → (points to A)

Variables summed out → (points to B, C)

Argument variables, always non-evidence variables → (points to D, E)

Basic Operations

- First basic operation: **join factors**
- Combining two factors:
 - **Just like a database join**
 - Build a factor over the union of the domains
- Example:

$$f_1(A, B) \times f_2(B, C) \longrightarrow f_3(A, B, C)$$

$$f_3(a, b, c) = f_1(a, b) \cdot f_2(b, c)$$

$$"P(a, b|c) = P(a|b) \cdot P(b|c)"$$

Basic Operations

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A **projection** operation
- Example:

$$f_{\bar{A}B}(b) = \sum_a f_{AB}(a, b)$$

$$“P(b) = \sum_a P(a, b)”$$

Example

$$P(b, j, m)$$

$$= \underbrace{P(b)}_B \sum_e \underbrace{P(e)}_E \sum_a \underbrace{P(a|b, e)}_A \underbrace{P(j|a)}_J \underbrace{P(m|a)}_M$$

$$= f_B(b) \sum_e f_E(e) \sum_a f_A(a, b, e) f_J(a) f_M(a)$$

$$= f_B(b) \sum_e f_E(e) \sum_a f_{AJM}(a, b, e)$$

$$= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e)$$

Example

$$\begin{aligned}P(b, j, m) &= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e) \\&= f_B(b) \sum_e f_{\bar{A}EJM}(b, e) \\&= f_B(b) f_{\bar{A}\bar{E}JM}(b) \\&= f_{\bar{A}B\bar{E}JM}(b)\end{aligned}$$

General Variable Elimination

- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Project out H
- Join all remaining factors and normalize

Example

$$P(B|j, m) \propto P(B, j, m)$$

$\underbrace{P(B)}$	$\underbrace{P(E)}$	$\underbrace{P(A B, E)}$	$\underbrace{P(j A)}$	$\underbrace{P(m A)}$
$f_B(B)$	$f_E(E)$	$f_A(A, B, E)$	$f_J(A)$	$f_M(A)$

Choose A

$$\begin{array}{c}
 f_A(A, B, E) \\
 f_J(A) \\
 f_M(A)
 \end{array}
 \xrightarrow{\times} f_{AJM}(A, B, E) \xrightarrow{\Sigma} f_{\bar{A}JM}(B, E)$$

$f_B(B)$	$f_E(E)$	$f_{\bar{A}JM}(B, E)$
----------	----------	-----------------------

Example

$f_B(B)$	$f_E(E)$	$f_{\bar{A}JM}(B, E)$
----------	----------	-----------------------

Choose E

$$\begin{array}{c}
 f_E(E) \\
 f_{\bar{A}JM}(B, E)
 \end{array}
 \xrightarrow{\times} f_{\bar{A}EJM}(B, E) \xrightarrow{\Sigma} f_{\bar{A}\bar{E}JM}(B)$$

$f_B(B)$	$f_{\bar{A}\bar{E}JM}(B)$
----------	---------------------------

Finish

$$\begin{array}{c}
 f_B(B) \\
 f_{\bar{A}\bar{E}JM}(B)
 \end{array}
 \xrightarrow{\times} f_{\bar{A}B\bar{E}JM}(B) \xrightarrow{\text{Normalize}} P(B|j, m)$$