# CS 188: Artificial Intelligence Spring 2006

Lecture 17: Bayes' Nets III 3/16/2006

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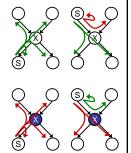
# Today

- Last time:
  - Bayes nets
  - Conditional independence
- Today:
  - More conditional independence
  - Inference to answer queries

# Reachability (the Bayes' Ball)

- Correct algorithm:
  - Start at source node
  - Try to reach target by search
  - States: node, along with
  - Successor function:

    - Unobserved nodes:
       To any child
       To any parent if coming from a child (or start)
    - Observed nodes:
       From parent to parent
  - If you can't reach a node, it's conditionally independent of the start node



## Example

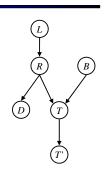
Yes Yes

 $L \perp \!\!\! \perp B | T$ 

 $L \perp \!\!\! \perp B | T'$ 

 $L \perp \!\!\! \perp T' | T$ 

 $L \bot\!\!\!\bot B$ 



# Example

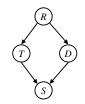
Yes

- Variables:
  - R: Raining
  - T: Traffic
  - D: Roof drips
  - S: I'm sad
- Questions:

 $T \! \perp \!\!\! \perp \!\!\! D$ 

 $T \perp \!\!\! \perp D | R$ 

 $T \perp\!\!\!\perp D | R, S$ 



# Summary

- Bayes nets compactly encode joint distributions
- Guaranteed independencies of distributions can be deduced from BN graph structure
- The Bayes' ball algorithm (aka d separation)
- A Bayes net may have other independencies that are not detectable until you inspect its specific distribution

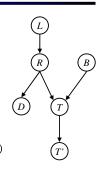
#### Inference

- Inference: calculating some statistic from a joint probability distribution
- Examples:
  - Posterior marginal probability:

$$P(Q|E_1 = e_1, \dots E_k = e_k)$$

Most likely explanation:

$$\operatorname{argmax}_q P(Q=q|E_1=e_1\ldots)$$



#### 

### **Atomic Inference**

- Given unlimited time, inference in BNs is easy
- Recipe:
  - State the marginal probabilities you want
  - Figure out ALL the atomic probabilities you need
  - Calculate and combine them
- Example:

$$P(b|j,m) = \frac{P(b,j,m)}{P(j,m)}$$



# Example

$$P(b|j,m) = \frac{P(b,j,m)}{P(j,m)}$$
 B (E) 
$$P(b,j,m) = P(b,e,a,j,m) + P(b,e,\bar{a},j,m) + P(b,e,\bar{a},j,m) + P(b,\bar{e},\bar{a},j,m)$$
 Where did we use the BN structure? 
$$= \sum_{e,a} P(b,e,a,j,m)$$
 We didn't!

# Example

$$P(b,j,m) = P(b)P(e)P(a|b,e)P(j|a)P(m|a) + P(b)P(e)P(\bar{a}|b,e)P(j|\bar{a})P(m|\bar{a}) + P(b)P(\bar{e})P(a|b,\bar{e})P(j|a)P(m|a) +$$

 $P(b)P(\bar{e})P(\bar{a}|b,\bar{e})P(j|\bar{a})P(m|\bar{a})$ 

$$P(b|j,m) = \frac{P(b,j,m)}{P(j,m)}$$

$$P(b,j,m) = \sum_{e,a} P(b,e,a,j,m)$$

$$P(\bar{b},j,m) = \sum_{e,a} P(\bar{b},e,a,j,m)$$

$$\begin{pmatrix} P(b,j,m) \\ P(\bar{b},j,m) \end{pmatrix}$$
Normalize 
$$\begin{pmatrix} P(b|j,m) \\ P(\bar{b}|j,m) \\ P(\bar{b}|j,m) \end{pmatrix}$$

Example

# Inference by Enumeration

- Atomic inference is extremely slow!
- Slightly clever way to save work:
  - Move the sums as far right as possible
  - Example:



$$P(b, j, m) = \sum_{e,a} P(b, e, a, j, m)$$

$$= \sum_{e,a} P(b)P(e)P(a|b, e)P(j|a)P(m|a)$$

$$= P(b)\sum_{e} P(e)\sum_{a} P(a|b, e)P(j|a)P(m|a)$$

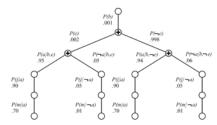
### Example

$$P(b,j,m) = P(b)P(e)P(a|b,e)P(j|a)P(m|a) + P(b)P(e)P(\bar{a}|b,e)P(j|\bar{a})P(m|\bar{a}) + P(b)P(\bar{e})P(a|b,\bar{e})P(j|a)P(m|a) + P(b)P(\bar{e})P(\bar{a}|b,\bar{e})P(j|\bar{a})P(m|\bar{a})$$

$$P(b) \begin{cases} P(e) & \begin{cases} P(a|b,e) & P(j|a)P(m|a) \\ P(\overline{a}|b,e) & P(j|\overline{a})P(m|\overline{a}) \end{cases} \\ P(\overline{e}) & \begin{cases} P(a|b,\overline{e}) & P(j|a)P(m|a) \\ P(\overline{a}|b,\overline{e}) & P(j|\overline{a})P(m|\overline{a}) \end{cases} \end{cases}$$

### **Evaluation Tree**

• View the nested sums as a computation tree:



• Still repeated work: calculate P(m | a) P(j | a) twice, etc.

#### Variable Elimination: Idea

- Lots of redundant work in the computation tree!
- We can save time if we cache all partial results
- This is the basic idea behind variable elimination

# **Basic Objects**

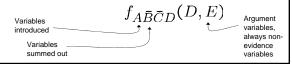


- Track objects called factors
- Initial factors are local CPTs

$$P(B)$$
  $P(J|A)$   $P(A|B,E)$   $P(A|B,E)$ 

- During elimination, create new factors
- Anatomy of a factor:

4 numbers, one for each value of D and E



# Basic Operations

- First basic operation: join factors
- Combining two factors:
- Just like a database join
- Build a factor over the union of the domains
- Example:

$$f_1(A,B) \times f_2(B,C) \longrightarrow f_3(A,B,C)$$
  
 $f_3(a,b,c) = f_1(a,b) \cdot f_2(b,c)$   
" $P(a,b|c) = P(a|b) \cdot P(b|c)$ "

# **Basic Operations**

- Second basic operation: marginalization
- Take a factor and sum out a variable
  - · Shrinks a factor to a smaller one
  - A projection operation
- Example:

$$f_{\bar{A}B}(b) = \sum_{a} f_{AB}(a,b)$$

"
$$P(b) = \sum_{a} P(a, b)$$
"

## Example

$$=\underbrace{P(b)}_{B} \sum_{e} \underbrace{P(e)}_{E} \sum_{a} \underbrace{P(a|b,e)}_{A} \underbrace{P(j|a)}_{J} \underbrace{P(m|a)}_{M}$$

$$= f_B(b) \sum_e f_E(e) \sum_a f_A(a, b, e) f_J(a) f_M(a)$$

$$= f_B(b) \sum_e f_E(e) \sum_a f_{AJM}(a, b, e)$$

$$= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e)$$

# Example

$$= f_B(b) \sum_e f_E(e) f_{\bar{A}JM}(b, e)$$

$$= f_B(b) \sum_e f_{\bar{A}EJM}(b,e)$$

$$= f_B(b) f_{\bar{A}\bar{E}JM}(b)$$

$$=f_{\bar{A}B\bar{E}JM}(b)$$

### **General Variable Elimination**

- Query:  $P(Q|E_1 = e_1, \dots E_k = e_k)$
- Start with initial factors:
  - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
  - Pick a hidden variable H
  - Join all factors mentioning H
  - Project out H
- Join all remaining factors and normalize

# Example

$$P(B|j,m) \propto P(B,j,m)$$

#### Choose A

$$f_A(A,B,E)$$





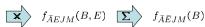
$$f_B(B)$$
  $f_E(E)$   $f_{\bar{A}JM}(B,E)$ 

# Example

 $f_B(B)$  $f_E(E)$  $f_{\bar{A}JM}(B,E)$ 

#### Choose E

 $f_E(E)$  $f_{\bar{A}JM}(B,E)$ 





 $f_{\bar{A}\bar{E}JM}(B)$ 



Finish

$$f_B(B)$$
  
 $f_{\bar{A}\bar{E}JM}(B)$ 



 $f_B(B)$ 



