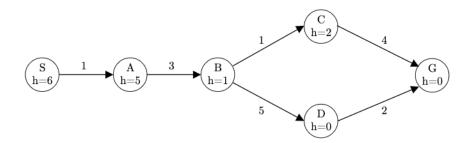
## CS 188 Spring 2021 Artificial Intelligence MT Review: Search

## Q1. Search

- (a) Consider a graph search problem where for every action, the cost is at least  $\epsilon$ , with  $\epsilon > 0$ . Assume the used heuristic is consistent.
  - (i) [true or false] Depth-first graph search is guaranteed to return an optimal solution.
  - (ii) [true or false] Breadth-first graph search is guaranteed to return an optimal solution.
  - (iii) [true or false] Uniform-cost graph search is guaranteed to return an optimal solution.
  - (iv) [true or false] Greedy graph search is guaranteed to return an optimal solution.
  - (v) [true or false] A\* graph search is guaranteed to return an optimal solution.
  - (vi) [true or false] A\* graph search is guaranteed to expand no more nodes than depth-first graph search.
  - (vii) [true or false] A\* graph search is guaranteed to expand no more nodes than uniform-cost graph search.
- (b) Let  $h_1(s)$  be an admissible A\* heuristic. Let  $h_2(s) = 2h_1(s)$ . Then:
  - (i) [true or false] The solution found by  $A^*$  tree search with  $h_2$  is guaranteed to be an optimal solution.
  - (ii) [true or false] The solution found by  $A^*$  tree search with  $h_2$  is guaranteed to have a cost at most twice as much as the optimal path.
  - (iii) [true or false] The solution found by  $A^*$  graph search with  $h_2$  is guaranteed to be an optimal solution.
- (c) The heuristic values for the graph below are not correct. For which single state (S, A, B, C, D, or G) could you change the heuristic value to make everything admissible and consistent? What range of values are possible to make this correction?

  State:

  Range:



## Q2. Power Pellets

Consider a Pacman game where Pacman can eat 3 types of pellets:

•	Normal	pellets	(n-pellets),	which	are	worth	one	point.
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- Decaying pellets (d-pellets), which are worth max(0, 5-t) points, where t is time.
- Growing pellets (g-pellets), which are worth t points, where t is time.

The pellet's point value stops changing once eaten. For example, if Pacman eats one g-pellet at t = 1 and one d-pellet at t = 2, Pacman will have won 1 + 3 = 4 points.

Pacman needs to find a path to win at least 10 points but he wants to minimize distance travelled. The cost between states is equal to distance travelled.

(a)	Which of the following must be including for a minimum, sufficient state space?  Pacman's location Location and type of each pellet How far Pacman has travelled Current time How many pellets Pacman has eaten and the point value of each eaten pellet Total points Pacman has won Which pellets Pacman has eaten					
(b)	<ul> <li>Which of the following are admissible heuristics? Let x be the number of points won so far.</li> <li>□ Distance to closest pellet, except if in the goal state, in which case the heuristic value is 0.</li> <li>□ Distance needed to win 10 − x points, determining the value of all pellets as if they were n-pellets.</li> <li>□ Distance needed to win 10 − x points, determining the value of all pellets as if they were g-pellets (i.e. all pellet values will be t.)</li> <li>□ Distance needed to win 10 − x points, determining the value of all pellets as if they were d-pellets (i.e. all pellet values will be max(0,5 − t).</li> <li>□ Distance needed to win 10 − x points assuming all pellets maintain current point value (g-pellets stop increasing in value and d-pellets stop decreasing in value)</li> <li>□ None of the above</li> </ul>					
(c)	instead of finding a path which minimizes distance, Pacman would like to find a path which minimizes the following: $C_{new} = a*t+b*d$ where $t$ is the amount of time elapsed, $d$ is the distance travelled, and $a$ and $b$ are non-negative constants such that $a+b=1$ . Pacman knows an admissible heuristic when he is trying to minimize time (i.e. when $a=1,b=0$ ), $h_t$ , and when he is trying to minimize distance, $h_d$ (i.e. when $a=0,b=1$ ). Which of the following heuristics is guaranteed to be admissible when minimizing $C_{new}$ ? $\Box mean(h_t,h_d) \qquad \Box min(h_t,h_d) \qquad \Box max(h_t,h_d) \qquad \Box a*h_t+b*h_d$					
	☐ None of the above					