

# CS61B Lectures #27

## Today:

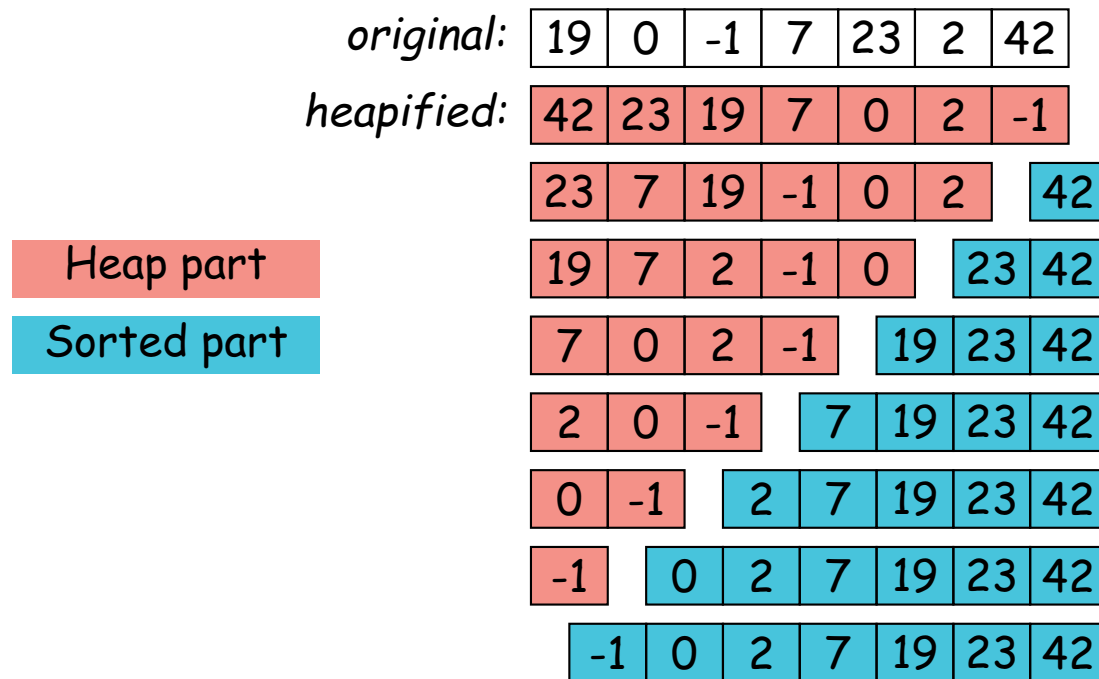
- Selection sorts, heap sort
- Merge sorts
- Quicksort

**Readings:** Today: *DS(IJ)*, Chapter 8; Next topic: Chapter 9.

# Sorting by Selection: Heapsort

**Idea:** Keep selecting smallest (or largest) element.

- Really bad idea on a simple list or vector.
- But we've already seen it in action: use heap.
- Gives  $O(N \lg N)$  algorithm ( $N$  remove-first operations).
- Since we remove items from end of heap, we can use that area to accumulate result:



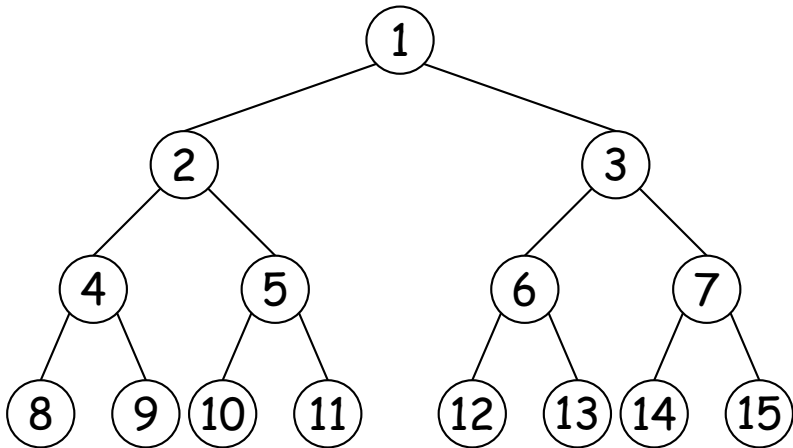
# Sorting By Selection: Initial Heapifying

- When covering heaps before, we created them by insertion in an initially empty heap.
- When given an array of unheaped data to start with, there is a faster procedure (assume heap indexed from 0):

```
void heapify(int[] arr) {  
    int N = arr.length;  
    for (int k = N / 2; k >= 0; k -= 1) {  
        for (int p = k, c = 0; 2*p + 1 < N; p = c) {  
            c = 2k+1 or 2k+2, whichever is < N  
            and indexes larger value in arr;  
            swap elements c and k of arr;  
        }  
    }  
}
```

- Looks like the procedure for re-inserting an element after the top element of the heap is removed, repeated  $N/2$  times.
- But instead of being  $\Theta(N \lg N)$ , it's just  $\Theta(N)$ .

# Cost of Creating Heap



1 node  $\times$  3 steps down

2 nodes  $\times$  2 steps down

4 nodes  $\times$  1 step down

- In general, worst-case cost for a heap with  $h + 1$  levels is

$$\begin{aligned} & 2^0 \cdot h + 2^1 \cdot (h - 1) + \dots + 2^{h-1} \cdot 1 \\ &= (2^0 + 2^1 + \dots + 2^{h-1}) + (2^0 + 2^1 + \dots + 2^{h-2}) + \dots + (2^0) \\ &= (2^h - 1) + (2^{h-1} - 1) + \dots + (2^1 - 1) \\ &= 2^{h+1} - 1 - h \\ &\in \Theta(2^h) = \Theta(N) \end{aligned}$$

- Alas, since the rest of heapsort still takes  $\Theta(N \lg N)$ , this does not improve its asymptotic cost.

# Merge Sorting

**Idea:** Divide data in 2 equal parts; recursively sort halves; merge results.

- Already seen analysis:  $\Theta(N \lg N)$ .
- Good for *external sorting*:
  - First break data into small enough chunks to fit in memory and sort.
  - Then repeatedly merge into bigger and bigger sequences.
- Can merge  $K$  sequences of *arbitrary size* on secondary storage using  $\Theta(K)$  storage:

```
Data[] V = new Data[K];
```

```
For all i, set V[i] to the first data item of sequence i;  
while there is data left to sort:
```

```
    Find k so that V[k] is smallest;
```

```
    Output V[k], and read new value into V[k] (if present).
```

# Illustration of Internal Merge Sort

For internal sorting, can use a *binomial comb* to orchestrate:

L: (9, 15, 5, 3, 0, 6, 10, -1, 2, 20, 8)

0:	0	
1:	0	
2:	0	
3:	0	

0 elements processed

0:	1	●	→	(9)
1:	0			
2:	0			
3:	0			

1 element processed

0:	0			
1:	1	●	→	(9, 15)
2:	0			
3:	0			

2 elements processed

0:	1	●	→	(5)
1:	1	●	→	(9, 15)
2:	0			
3:	0			

3 elements processed

0:	0			
1:	0			
2:	1	●	→	(3, 5, 9, 15)
3:	0			

4 elements processed

0:	0			
1:	1	●	→	(0, 6)
2:	1	●	→	(3, 5, 9, 15)
3:	0			

6 elements processed

0:	1	●	→	(8)
1:	1	●	→	(2, 20)
2:	0			
3:	1	●	→	(-1, 0, 3, 5, 6, 9, 10, 15)

11 elements processed

# Quicksort: Speed through Probability

## Idea:

- *Partition* data into pieces: everything  $>$  a *pivot* value at the high end of the sequence to be sorted, and everything  $\leq$  on the low end.
- Repeat recursively on the high and low pieces.
- For speed, stop when pieces are "small enough" and do insertion sort on the whole thing.
- Reason: insertion sort has low constant factors. By design, no item will move out of its will move out of its piece [why?], so when pieces are small, #inversions is, too.
- Have to choose pivot well. E.g.: *median* of first, last and middle items of sequence.

# Example of Quicksort

- In this example, we continue until pieces are size  $\leq 4$ .
- Pivots for next step are starred. Arrange to move pivot to dividing line each time.
- Last step is insertion sort.

16	10	13	18	-4	-7	12	-5	19	15	0	22	29	34	-1*
----	----	----	----	----	----	----	----	----	----	---	----	----	----	-----

-4	-5	-7	-1	18	13	12	10	19	15	0	22	29	34	16*
----	----	----	----	----	----	----	----	----	----	---	----	----	----	-----

-4	-5	-7	-1	15	13	12*	10	0	16	19*	22	29	34	18
----	----	----	----	----	----	-----	----	---	----	-----	----	----	----	----

-4	-5	-7	-1	10	0	12	15	13	16	18	19	29	34	22
----	----	----	----	----	---	----	----	----	----	----	----	----	----	----

- Now everything is "close to" right, so just do insertion sort:

-7	-5	-4	-1	0	10	12	13	15	16	18	19	22	29	34
----	----	----	----	---	----	----	----	----	----	----	----	----	----	----



# Performance of Quicksort

- Probabalistic time:
  - If choice of pivots good, divide data in two each time:  $\Theta(N \lg N)$  with a good constant factor relative to merge or heap sort.
  - If choice of pivots bad, most items on one side each time:  $\Theta(N^2)$ .
  - $\Omega(N \lg N)$  in best case, so insertion sort better for nearly ordered input sets.
- Interesting point: randomly shuffling the data before sorting makes  $\Omega(N^2)$  time *very* unlikely!

# Quick Selection

**The Selection Problem:** for given  $k$ , find  $k^{\text{th}}$  smallest element in data.

- Obvious method: sort, select element  $\#k$ , time  $\Theta(N \lg N)$ .
- If  $k \leq$  some constant, can easily do in  $\Theta(N)$  time:
  - Go through array, keep smallest  $k$  items.
- Get **probably  $\Theta(N)$  time** for all  $k$  by adapting quicksort:
  - Partition around some pivot,  $p$ , as in quicksort, arrange that pivot ends up at dividing line.
  - Suppose that in the result, pivot is at index  $m$ , all elements  $\leq$  pivot have indices  $\leq m$ .
  - If  $m = k$ , you're done:  $p$  is answer.
  - If  $m > k$ , recursively select  $k^{\text{th}}$  from left half of sequence.
  - If  $m < k$ , recursively select  $(k - m - 1)^{\text{th}}$  from right half of sequence.

# Selection Example

**Problem:** Find just item #10 in the sorted version of array:

*Initial contents:*

51	60	21	-4	37	4	49	10	40*	59	0	13	2	39	11	46	31
----	----	----	----	----	---	----	----	-----	----	---	----	---	----	----	----	----

0

*Looking for #10 to left of pivot 40:*

13	31	21	-4	37	4*	11	10	39	2	0	40	59	51	49	46	60
----	----	----	----	----	----	----	----	----	---	---	----	----	----	----	----	----

0

*Looking for #6 to right of pivot 4:*

-4	0	2	4	37	13	11	10	39	21	31*	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	-----	----	----	----	----	----	----

4

*Looking for #1 to right of pivot 31:*

-4	0	2	4	21	13	11	10	31	39	37	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	----	----	----	----	----	----	----

9

*Just two elements; just sort and return #1:*

-4	0	2	4	21	13	11	10	31	37	39	40	59	51	49	46	60
----	---	---	---	----	----	----	----	----	----	----	----	----	----	----	----	----

9

Result: 39

# Selection Performance

- For this algorithm, if  $m$  roughly in middle each time, cost is

$$\begin{aligned} C(N) &= \begin{cases} 1, & \text{if } N = 1, \\ N + C(N/2), & \text{otherwise.} \end{cases} \\ &= N + N/2 + \dots + 1 \\ &= 2N - 1 \in \Theta(N) \end{aligned}$$

- But in worst case, get  $\Theta(N^2)$ , as for quicksort.
- By another, non-obvious algorithm, can get  $\Theta(N)$  worst-case time for all  $k$  (take CS170).