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UC Berkeley CS61C : Machine Structures

Lecture 31 – Caches I

2007-04-06

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Powerpoint bad!! ⇒

Research done at the Univ of NSW says that "working memory", the brain part providing temporary storage, is limited (3-4 things for 20 sec unless rehearsal), and saying what is on slides splits attention, & bad.

slashdot.org/article.pl?sid=07/04/04/1319247

Review : Pipelining

- Pipeline challenge is hazards
  - Forwarding helps w/many data hazards
  - Delayed branch helps with control hazard in our 5 stage pipeline
  - Data hazards w/Loads ⇒ Load Delay Slot
    - Interlock ⇒ "smart" CPU has HW to detect if conflict with inst following load, if so it stalls
- More aggressive performance (discussed in section next week)
  - Superscalar (parallelism)
  - Out-of-order execution

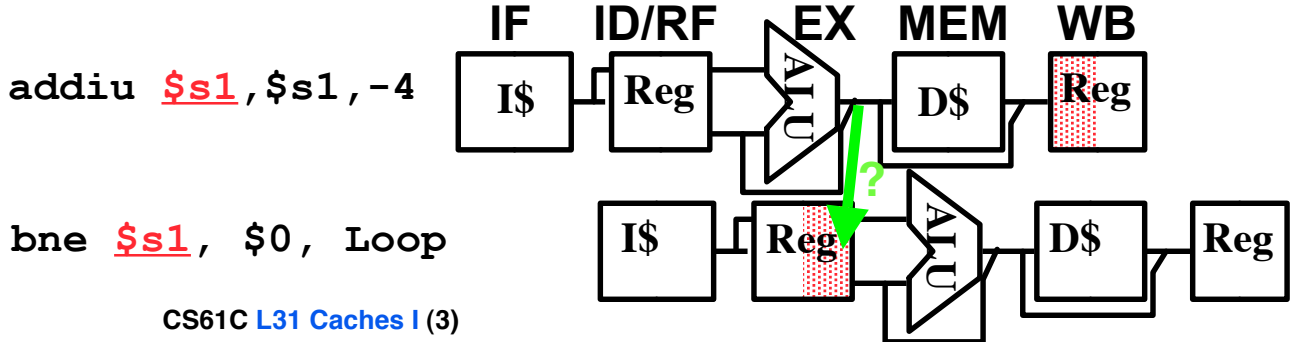
Peer Instruction (2/2)

Assume 1 instr/clock, delayed branch, 5 stage pipeline, forwarding, interlock on unresolved load hazards (after 10^3 loops, so pipeline full). Rewrite this code to reduce pipeline stages (clock cycles) per loop to as few as possible.

```
Loop:   lw    $t0, 0($s1)
        addu  $t0, $t0, $s2
        sw    $t0, 0($s1)
        addiu $s1, $s1, -4
        bne   $s1, $zero, Loop
        nop
```

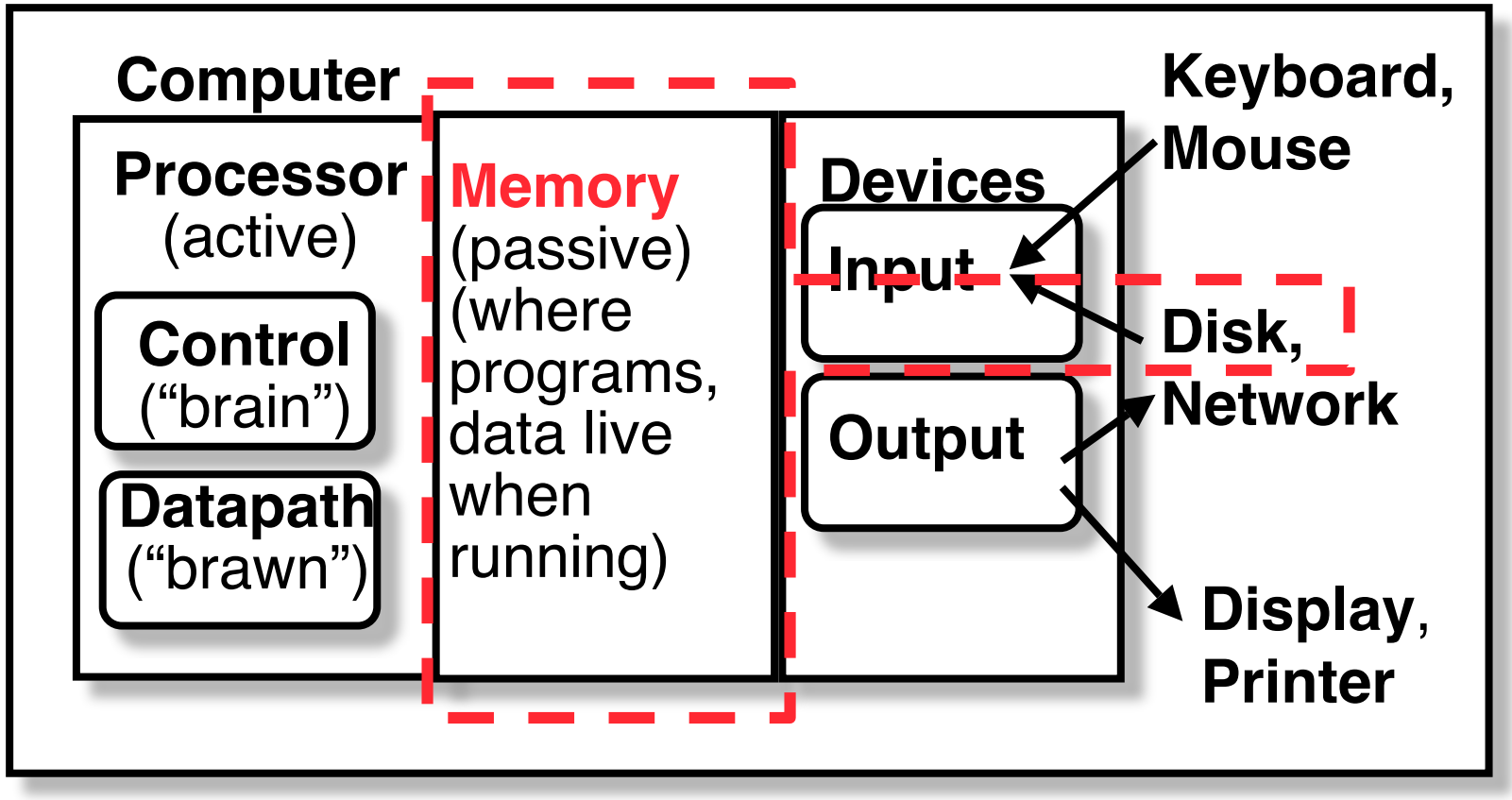
- How many pipeline stages (clock cycles) per loop iteration to execute this code?

Thanks to Peter Devore for catching this!



Patterson: Real HW has this forwarding (no stall), but for simplicity, COD doesn't (stall) - p. 419.

The Big Picture

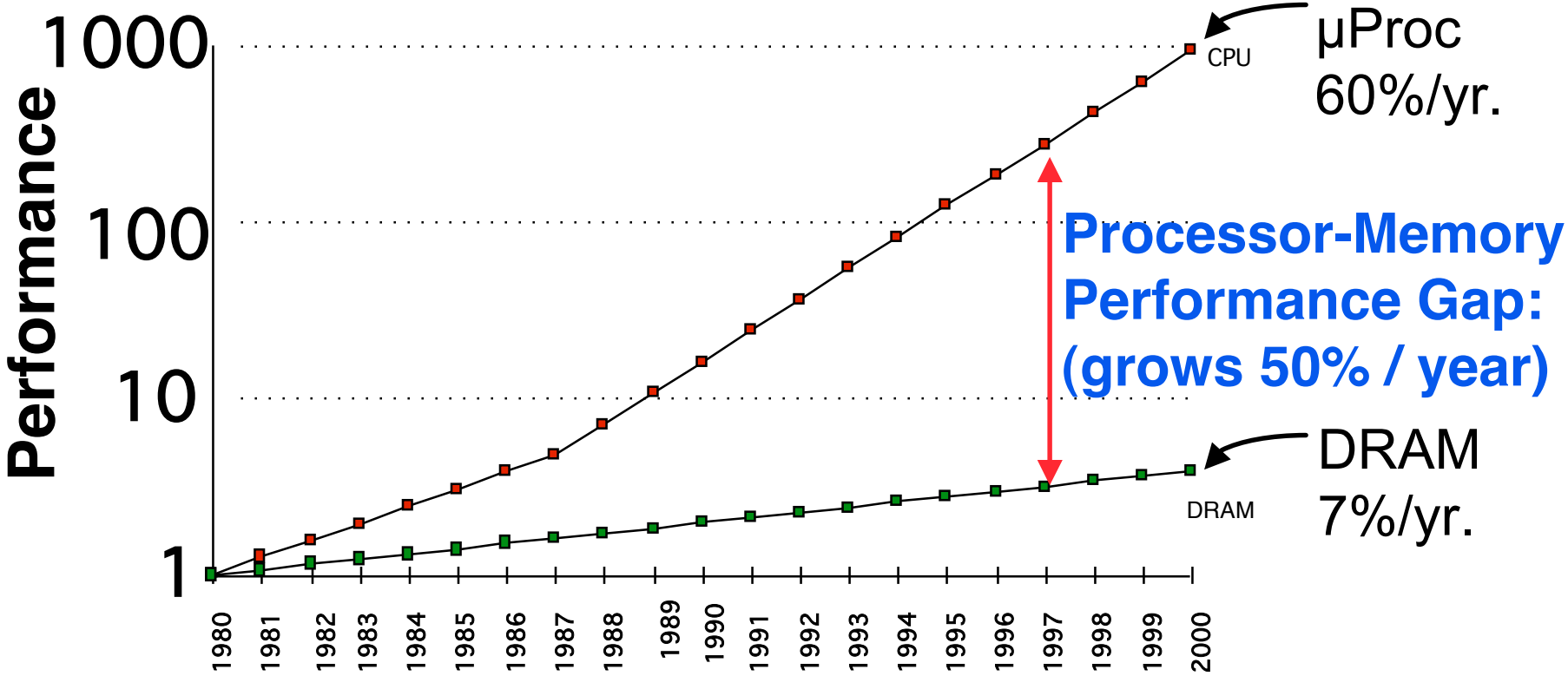


Memory Hierarchy

Storage in computer systems:

- **Processor**
  - **holds data in register file (~100 Bytes)**
  - **Registers accessed on nanosecond timescale**
- **Memory (we'll call "main memory")**
  - **More capacity than registers (~Gbytes)**
  - **Access time ~50-100 ns**
  - **Hundreds of clock cycles per memory access?!**
- **Disk**
  - **HUGE capacity (virtually limitless)**
  - **VERY slow: runs ~milliseconds**

Motivation: Why We Use Caches (written $)

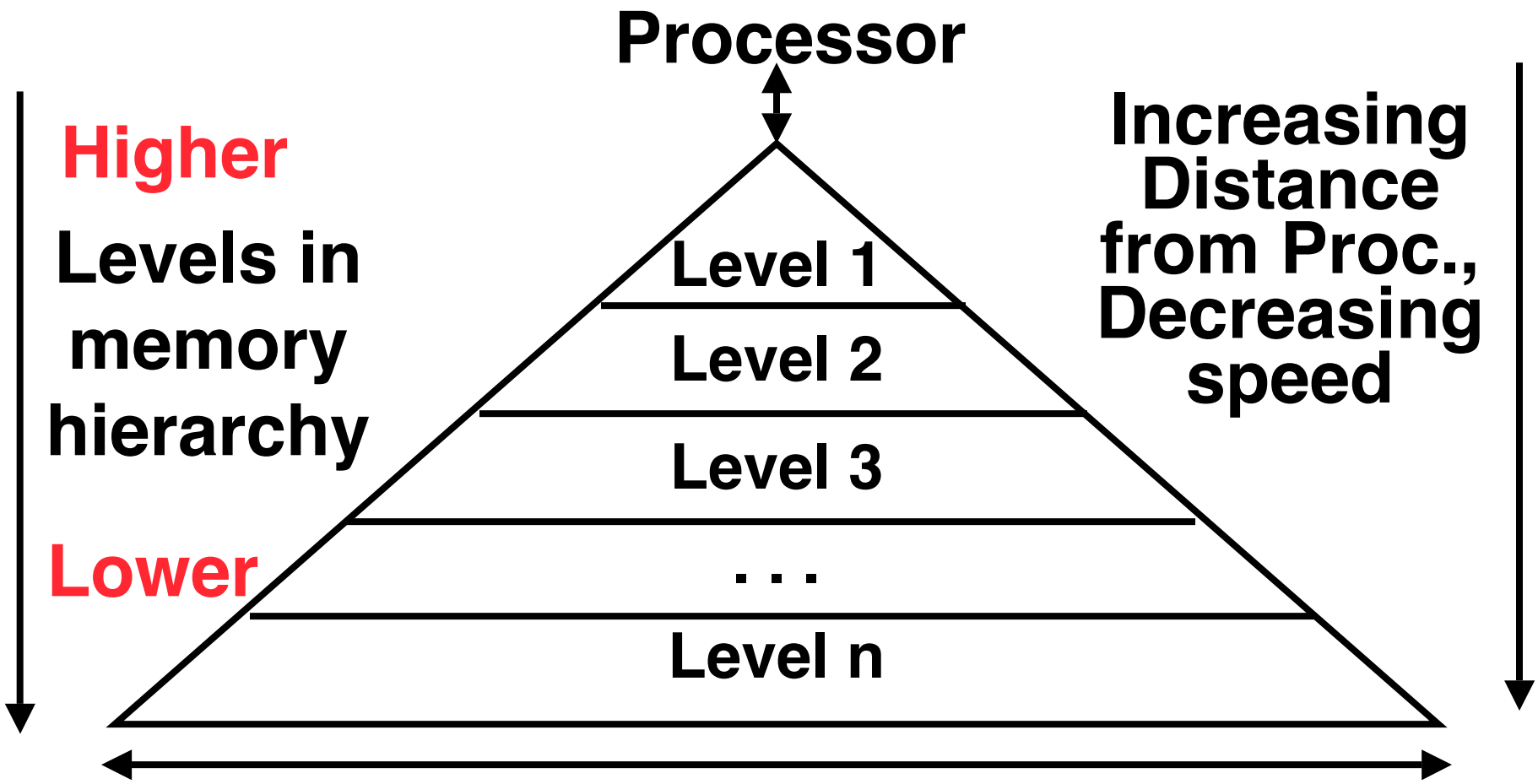


- 1989 first Intel CPU with cache on chip
- 1998 Pentium III has two levels of cache on chip

Memory Caching

- Mismatch between processor and memory speeds leads us to add a new level: a memory cache
- Implemented with same IC processing technology as the CPU (usually integrated on same chip): faster but more expensive than DRAM memory.
- Cache is a copy of a subset of main memory.
- Most processors have separate caches for instructions and data.

Memory Hierarchy



As we move to deeper levels the latency goes up and price per bit goes down.

Memory Hierarchy

- If level closer to Processor, it is:
  - smaller
  - faster
  - subset of lower levels (contains most recently used data)
- Lowest Level (usually disk) contains all available data (or does it go beyond the disk?)
- Memory Hierarchy presents the processor with the illusion of a very large very fast memory.

Memory Hierarchy Analogy: Library (1/2)

- You're writing a term paper (Processor) at a table in Doe
- Doe Library is equivalent to disk
  - essentially limitless capacity
  - very slow to retrieve a book
- Table is main memory
  - smaller capacity: means you must return book when table fills up
  - easier and faster to find a book there once you've already retrieved it

Memory Hierarchy Analogy: Library (2/2)

- Open books on table are cache
  - smaller capacity: can have very few open books fit on table; again, when table fills up, you must close a book
  - much, much faster to retrieve data
- Illusion created: whole library open on the tabletop
  - Keep as many recently used books open on table as possible since likely to use again
  - Also keep as many books on table as possible, since faster than going to library

Memory Hierarchy Basis

- Cache contains copies of data in memory that are being used.
- Memory contains copies of data on disk that are being used.
- Caches work on the principles of temporal and spatial locality.
  - Temporal Locality: if we use it now, chances are we'll want to use it again soon.
  - Spatial Locality: if we use a piece of memory, chances are we'll use the neighboring pieces soon.

Cache Design

- How do we organize cache?
- Where does each memory address map to?

  (Remember that cache is subset of memory, so multiple memory addresses map to the same cache location.)
- How do we know which elements are in cache?
- How do we quickly locate them?

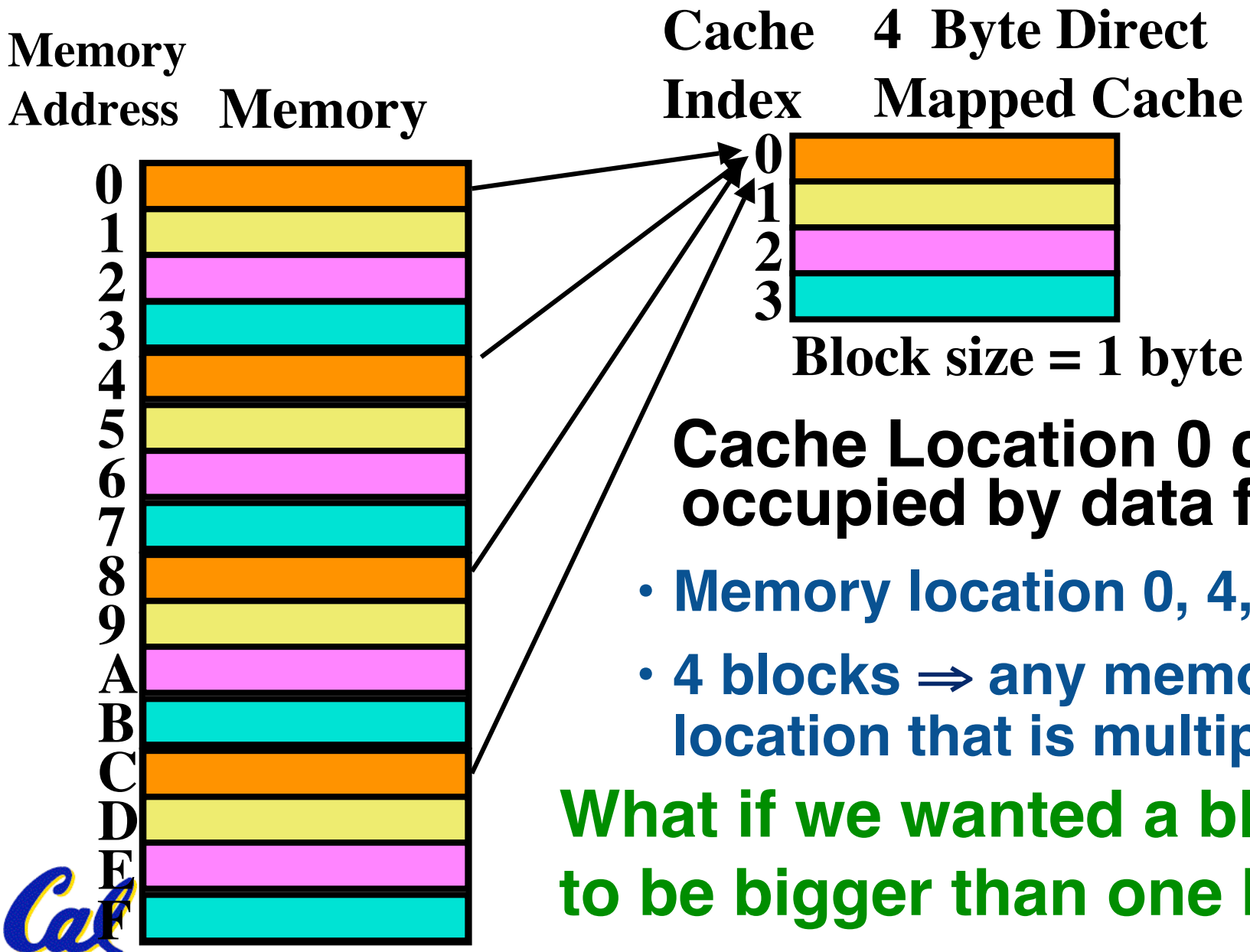
Administrivia

- Project 4 (on Caches) will be in optional groups of two.
- I'm releasing old CS61C finals
  - Check the course web page

Direct-Mapped Cache (1/4)

- In a direct-mapped cache, each memory address is associated with one possible block within the cache
  - Therefore, we only need to look in a single location in the cache for the data if it exists in the cache
  - Block is the unit of transfer between cache and memory

Direct-Mapped Cache (2/4)

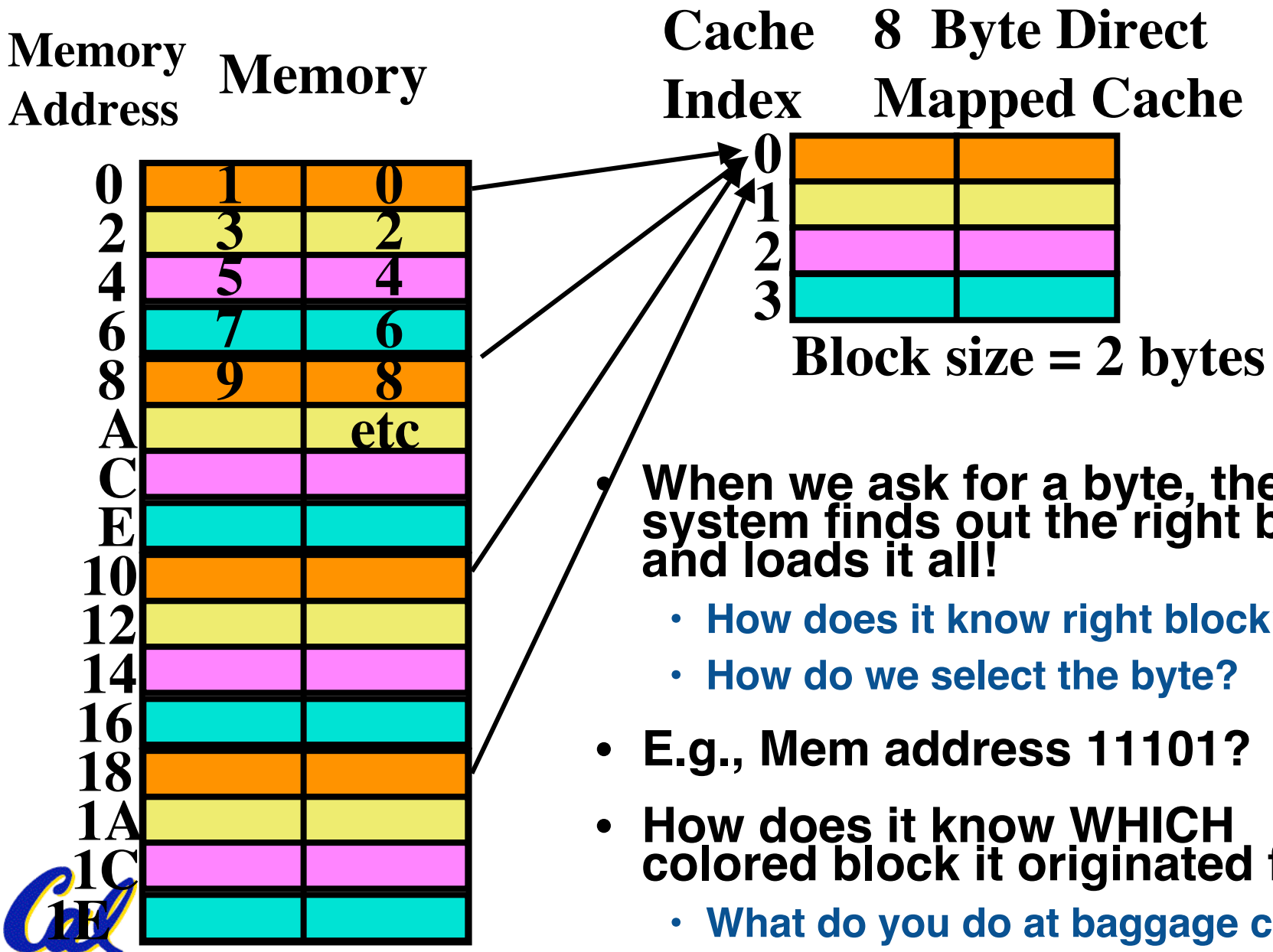


Cache Location 0 can be occupied by data from:

- Memory location 0, 4, 8, ...
- 4 blocks ⇒ any memory location that is multiple of 4

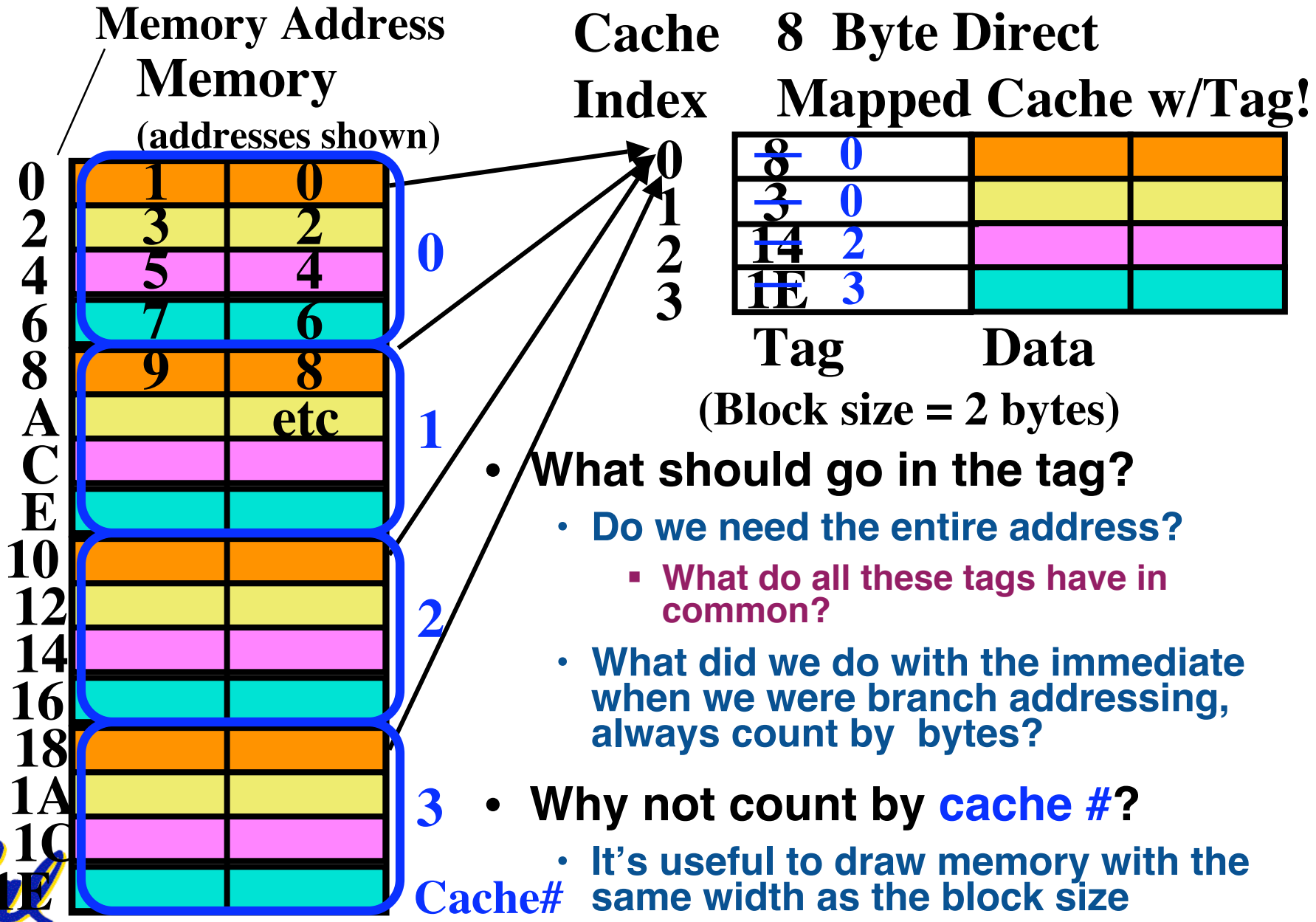
What if we wanted a block to be bigger than one byte?

Direct-Mapped Cache (3/4)



- When we ask for a byte, the system finds out the right block, and loads it all!
  - How does it know right block?
  - How do we select the byte?
- E.g., Mem address 11101?
- How does it know WHICH colored block it originated from?
  - What do you do at baggage claim?

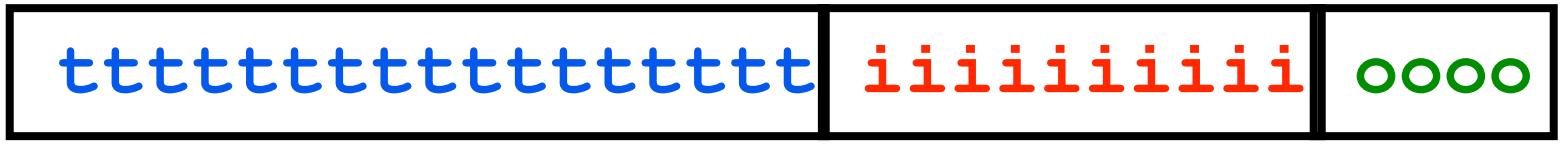
Direct-Mapped Cache (4/4)



- What should go in the tag?
  - Do we need the entire address?
    - What do all these tags have in common?
  - What did we do with the immediate when we were branch addressing, always count by bytes?
- Why not count by cache #?
  - It's useful to draw memory with the same width as the block size

Issues with Direct-Mapped

- Since multiple memory addresses map to same cache index, how do we tell which one is in there?
- What if we have a block size > 1 byte?
- Answer: divide memory address into three fields



tag to check if have correct block

index to select block

byte offset within block

Direct-Mapped Cache Terminology

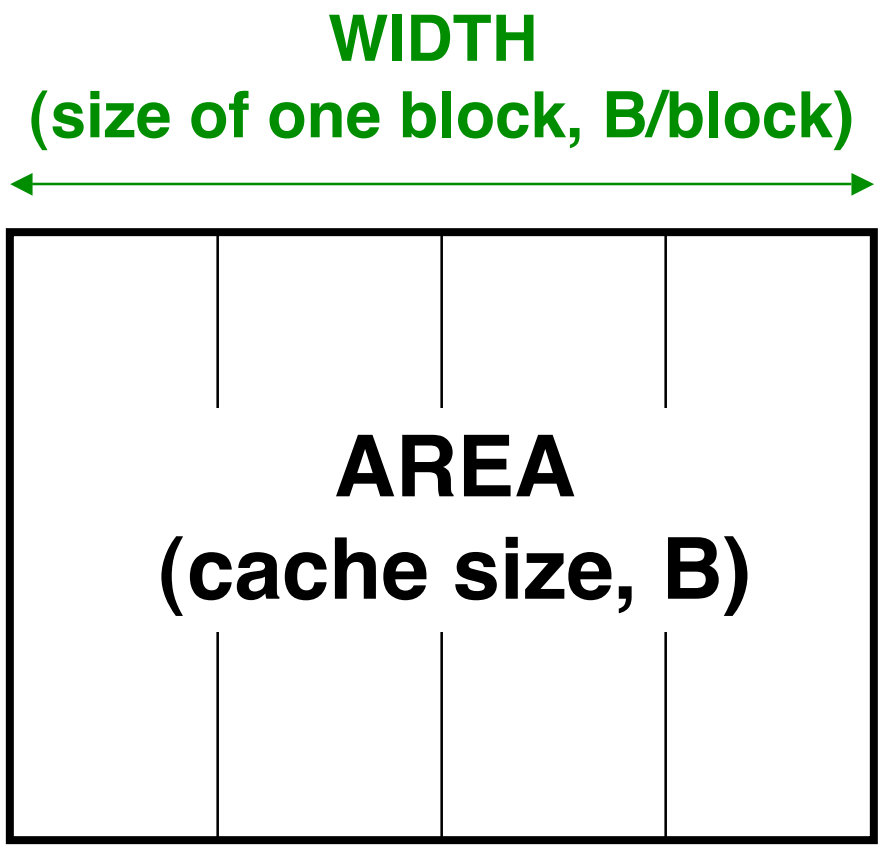
- All fields are read as unsigned integers.
- Index: specifies the cache index (which "row"/block of the cache we should look in)
- Offset: once we've found correct block, specifies which byte within the block we want
- Tag: the remaining bits after offset and index are determined; these are used to distinguish between all the memory addresses that map to the same location

TIO Dan's great cache mnemonic

AREA (cache size, B)
= HEIGHT (# of blocks)
*** WIDTH (size of one block, B/block)**

$$2^{(H+W)} = 2^H * 2^W$$

Tag	Index	Offset



Direct-Mapped Cache Example (1/3)

- Suppose we have a 16KB of data in a direct-mapped cache with 4 word blocks
- Determine the size of the tag, index and offset fields if we're using a 32-bit architecture
- Offset
  - need to specify correct byte within a block
  - block contains 4 words

    = 16 bytes

    = 2^4 bytes
  - need 4 bits to specify correct byte

Direct-Mapped Cache Example (2/3)

- Index: (~index into an "array of blocks")
  - need to specify correct block in cache
  - cache contains 16 KB = 2^{14} bytes
  - block contains 2^4 bytes (4 words)
  - # blocks/cache

$$= \frac{\text{bytes/cache}}{\text{bytes/block}}$$

$$= \frac{2^{14}\ \text{bytes/cache}}{2^4\ \text{bytes/block}}$$

$$= 2^{10}\ \text{blocks/cache}$$

  - need 10 bits to specify this many blocks

Direct-Mapped Cache Example (3/3)

- Tag: use remaining bits as tag
  - tag length = addr length – offset - index
    = 32 - 4 - 10 bits
    = 18 bits
  - so tag is leftmost 18 bits of memory address
- Why not full 32 bit address as tag?
  - All bytes within block need same address (4b)
  - Index must be same for every address within a block, so it's redundant in tag check, thus can leave off to save memory (here 10 bits)

Peer Instruction

A. Mem hierarchies were invented before 1950. (UNIVAC I wasn't delivered 'til 1951)

B. If you know your computer's cache size, you can often make your code run faster.

C. Memory hierarchies take advantage of spatial locality by keeping the most recent data items closer to the processor.

	ABC
0:	FFF
1:	FFT
2:	FTF
3:	FTT
4:	TFF
5:	TFT
6:	TTF
7:	TTT

Peer Instruction (2/2)

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        addiu $s1, $s1, -4
        bne   $s1, $zero, Loop
        nop
```

- **How many pipeline stages (clock cycles) per loop iteration to execute this code?**

1
2
3
4
5
6
7
8
9
10

And in Conclusion…

- We would like to have the capacity of disk at the speed of the processor: unfortunately this is not feasible.
- So we create a memory hierarchy:
  - each successively lower level contains "most used" data from next higher level
  - exploits temporal & spatial locality
  - do the common case fast, worry less about the exceptions (design principle of MIPS)
- Locality of reference is a Big Idea