CS 61C: Great Ideas in Computer Architecture (Machine Structures) Lecture 32: Pipeline Parallelism 3

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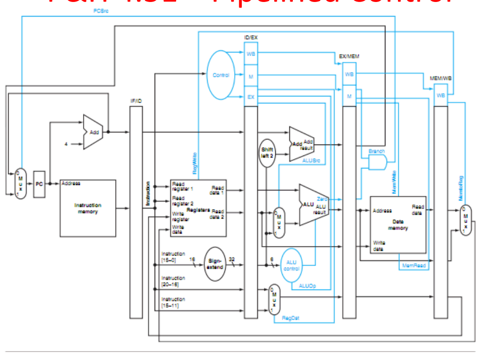
P&H 4.51 – Pipelined Control



Hazards

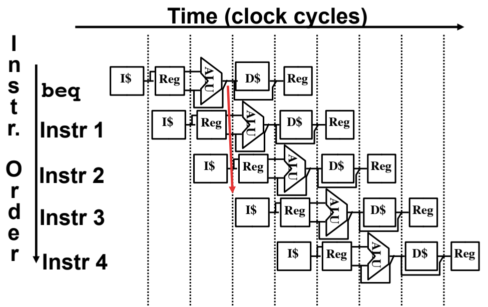
Situations that prevent starting the next logical instruction in the next clock cycle

1. Structural hazards
   – Required resource is busy (e.g., roommate studying)
2. Data hazard
   – Need to wait for previous instruction to complete its data read/write (e.g., pair of socks in different loads)
3. Control hazard
   – Deciding on control action depends on previous instruction (e.g., how much detergent based on how clean prior load turns out)

3. Control Hazards

- Branch determines flow of control
  – Fetching next instruction depends on branch outcome
  – Pipeline can't always fetch correct instruction
    - Still working on ID stage of branch
- BEQ, BNE in MIPS pipeline
- Simple solution Option 1: *Stall* on every branch until have new PC value
  – Would add 2 bubbles/clock cycles for every Branch! (~ 20% of instructions executed)

Stall => 2 Bubbles/Clocks



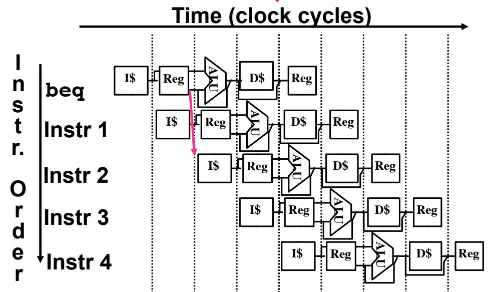
Where do we do the compare for the branch?

Control Hazard: Branching

- Optimization #1:
  – Insert special branch comparator in Stage 2
  – As soon as instruction is decoded (Opcode identifies it as a branch), immediately make a decision and set the new value of the PC
  – Benefit: since branch is complete in Stage 2, only one unnecessary instruction is fetched, so only one no-op is needed
  – Side Note: means that branches are idle in Stages 3, 4 and 5

Question: What's an efficient way to implement the equality comparison?

One Clock Cycle Stall



Branch comparator moved to Decode stage.

Control Hazards: Branching

- Option 2: *Predict* outcome of a branch, fix up if guess wrong
  - Must cancel all instructions in pipeline that depended on guess that was wrong
  - This is called "flushing" the pipeline
- Simplest hardware if we predict that all branches are NOT taken
  - Why?

Control Hazards: Branching

- Option #3: Redefine branches
  - Old definition: if we take the branch, none of the instructions after the branch get executed by accident
  - New definition: whether or not we take the branch, the single instruction immediately following the branch gets executed (the *branch-delay slot*)
- *Delayed Branch* means *we always execute inst after branch*
- This optimization is used with MIPS

Example: Nondelayed vs. Delayed Branch

Nondelayed Branch

```
   or  $8, $9, $10
   add $1, $2, $3
   sub $4, $5, $6
   beq $1, $4, Exit
   xor $10, $1, $11

Exit:
```

Delayed Branch

```
   add $1, $2,$3
   sub $4, $5, $6
   beq $1, $4, Exit
   or  $8, $9, $10
   xor $10, $1, $11

Exit:
```

Control Hazards: Branching

- Notes on Branch-Delay Slot
  - Worst-Case Scenario: put a no-op in the branch-delay slot
  - Better Case: place some instruction preceding the branch in the branch-delay slot—as long as the changed doesn't affect the logic of program
    - Re-ordering instructions is common way to speed up programs
    - Compiler usually finds such an instruction 50% of time
    - Jumps also have a delay slot …

Greater Instruction-Level Parallelism (ILP)

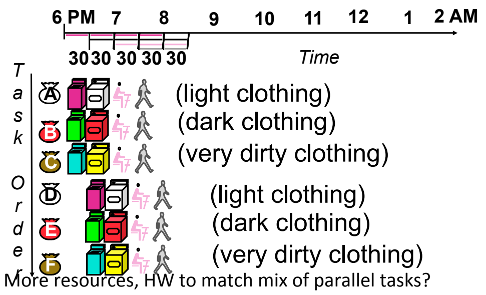
§4.10 Parallelism and Advanced Instruction Level Parallelism

- Deeper pipeline (5 => 10 => 15 stages)
  - Less work per stage ⇒ shorter clock cycle
- Multiple issue "superscalar"
  - Replicate pipeline stages ⇒ multiple pipelines
  - Start multiple instructions per clock cycle
  - CPI < 1, so use Instructions Per Cycle (IPC)
  - E.g., 4GHz 4-way multiple-issue
    - 16 BIPS, peak CPI = 0.25, peak IPC = 4
  - But dependencies reduce this in practice

Multiple Issue

- Static multiple issue
  - Compiler groups instructions to be issued together
  - Packages them into “issue slots”
  - Compiler detects and avoids hazards
- Dynamic multiple issue
  - CPU examines instruction stream and chooses instructions to issue each cycle
  - Compiler can help by reordering instructions
  - CPU resolves hazards using advanced techniques at runtime

Superscalar Laundry: Parallel per stage



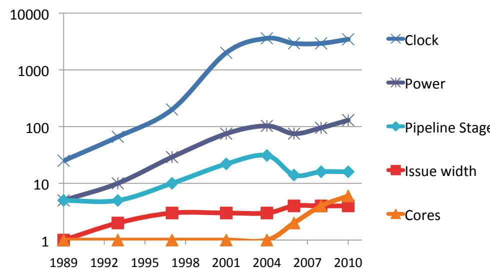
- More resources, HW to match mix of parallel tasks?

Pipeline Depth and Issue Width

- Intel Processors over Time

Microprocessor	Year	Clock Rate	Pipeline Stages	Issue width	Cores	Power
i486	1989	25 MHz	5	1	1	5W
Pentium	1993	66 MHz	5	2	1	10W
Pentium Pro	1997	200 MHz	10	3	1	29W
P4 Willamette	2001	2000 MHz	22	3	1	75W
P4 Prescott	2004	3600 MHz	31	3	1	103W

Pipeline Depth and Issue Width



Static Multiple Issue

- Compiler groups instructions into “issue packets”
  - Group of instructions that can be issued on a single cycle
  - Determined by pipeline resources required
- Think of an issue packet as a very long instruction
  - Specifies multiple concurrent operations

Scheduling Static Multiple Issue

- Compiler must remove some/all hazards
  - Reorder instructions into issue packets
  - No dependencies within a packet
  - Possibly some dependencies between packets
    - Varies between ISAs; compiler must know!
  - Pad issue packet with nop if necessary

MIPS with Static Dual Issue

- Two-issue packets
  - One ALU/branch instruction
  - One load/store instruction
  - 64-bit aligned
    - ALU/branch, then load/store
    - Pad an unused instruction with nop

Address	Instruction type	Pipeline Stages						
n	ALU/branch	IF	ID	EX	MEM	WB		
n + 4	Load/store	IF	ID	EX	MEM	WB		
n + 8	ALU/branch		IF	ID	EX	MEM	WB	
n + 12	Load/store		IF	ID	EX	MEM	WB	
n + 16	ALU/branch			IF	ID	EX	MEM	WB

Hazards in the Dual-Issue MIPS

- More instructions executing in parallel
- EX data hazard
  - Forwarding avoided stalls with single-issue
  - Now can't use ALU result in load/store in same packet
    - `add  $t0, $s0, $s1`
      `load $s2, 0($t0)`
    - Split into two packets, effectively a stall
- Load-use hazard
  - Still one cycle use latency, but now two instructions
- More aggressive scheduling required

Scheduling Example

- Schedule this for dual-issue MIPS

```
Loop: lw   $t0, 0($s1)       # $t0=array element
      addu $t0, $t0, $s2     # add scalar in $s2
      sw   $t0, 0($s1)       # store result
      addi $s1, $s1,–4       # decrement pointer
      bne  $s1, $zero, Loop  # branch $s1!=0
```

	ALU/branch	Load/store	cycle
Loop:			1
			2
			3
			4

Scheduling Example

- Schedule this for dual-issue MIPS

```
Loop: lw   $t0, 0($s1)       # $t0=array element
      addu $t0, $t0, $s2     # add scalar in $s2
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      addi $s1, $s1,–4       # decrement pointer
      bne  $s1, $zero, Loop  # branch $s1!=0
```

	ALU/branch	Load/store	cycle
Loop:	nop	`lw   $t0, 0($s1)`	1
			2
			3
			4

Scheduling Example

- Schedule this for dual-issue MIPS

```
Loop: lw   $t0, 0($s1)       # $t0=array element
      addu $t0, $t0, $s2     # add scalar in $s2
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```

	ALU/branch	Load/store	cycle
Loop:	nop	`lw   $t0, 0($s1)`	1
	`addi $s1, $s1,–4`	nop	2
			3
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	ALU/branch	Load/store	cycle
Loop:	nop	`lw   $t0, 0($s1)`	1
	`addi $s1, $s1,–4`	nop	2
	`addu $t0, $t0, $s2`	nop	3
			4

Scheduling Example

- Schedule this for dual-issue MIPS

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Loop: lw   $t0, 0($s1)      # $t0=array element
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      addi $s1, $s1,–4      # decrement pointer
      bne  $s1, $zero, Loop # branch $s1!=0
```

	ALU/branch	Load/store	cycle
Loop:	nop	lw $t0, 0($s1)	1
	addi $s1, $s1,–4	nop	2
	addu $t0, $t0, $s2	nop	3
	bne $s1, $zero, Loop	sw $t0, 4($s1)	4

- IPC = 5/4 = 1.25 (c.f. peak IPC = 2)

Loop Unrolling

- Replicate loop body to expose more parallelism
  - Reduces loop-control overhead
- Use different registers per replication
  - Called "register renaming"
  - Avoid loop-carried "anti-dependencies"
    - Store followed by a load of the same register
    - Aka "name dependence"
      - Reuse of a register name

Loop Unrolling Example

	ALU/branch	Load/store	cycle
Loop:	addi $s1, $s1,–16	lw $t0, 0($s1)	1
	nop	lw $t1, 12($s1)	2
	addu $t0, $t0, $s2	lw $t2, 8($s1)	3
	addu $t1, $t1, $s2	lw $t3, 4($s1)	4
	addu $t2, $t2, $s2	sw $t0, 16($s1)	5
	addu $t3, $t4, $s2	sw $t1, 12($s1)	6
	nop	sw $t2, 8($s1)	7
	bne $s1, $zero, Loop	sw $t3, 4($s1)	8

- IPC = 14/8 = 1.75
  - Closer to 2, but at cost of registers and code size

Dynamic Multiple Issue

- "Superscalar" processors
- CPU decides whether to issue 0, 1, 2, … each cycle
  - Avoiding structural and data hazards
- Avoids the need for compiler scheduling
  - Though it may still help
  - Code semantics ensured by the CPU

Dynamic Pipeline Scheduling

- Allow the CPU to execute instructions *out of order* to avoid stalls
  - But commit result to registers in order
- Example

```
lw    $t0, 20($s2)
addu  $t1, $t0, $t2
subu   $s4, $s4, $t3
slti  $t5, $s4, 20
```

  - Can start subu while addu is waiting for lw

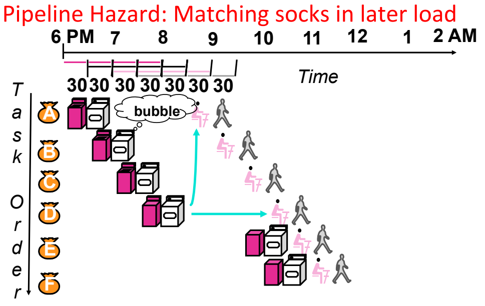
Why Do Dynamic Scheduling?

- Why not just let the compiler schedule code?
- Not all stalls are predicable
  - e.g., cache misses
- Can't always schedule around branches
  - Branch outcome is dynamically determined
- Different implementations of an ISA have different latencies and hazards

Speculation

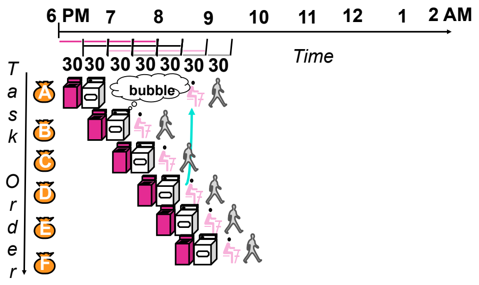
- "Guess" what to do with an instruction
  - Start operation as soon as possible
  - Check whether guess was right
    - If so, complete the operation
    - If not, roll-back and do the right thing
- Common to static and dynamic multiple issue
- Examples
  - Speculate on branch outcome (Branch Prediction)
    - Roll back if path taken is different
  - Speculate on load
    - Roll back if location is updated

Pipeline Hazard: Matching socks in later load



- A depends on D; stall since folder tied up;

Out-of-Order Laundry: Don't Wait



- A depends on D; rest continue; need more resources to allow out-of-order

Out Of Order Intel

- All use OOO since 2001

Microprocessor	Year	Clock Rate	Pipeline Stages	Issue width	Out-of-order/ Speculation	Cores	Power
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Does Multiple Issue Work?

The BIG Picture

- Yes, but not as much as we'd like
- Programs have real dependencies that limit ILP
- Some dependencies are hard to eliminate
  - e.g., pointer aliasing
- Some parallelism is hard to expose
  - Limited window size during instruction issue
- Memory delays and limited bandwidth
  - Hard to keep pipelines full
- Speculation can help if done well

"And in Conclusion.."

- Pipelining is an important form of ILP
- Challenge is (are?) hazards
  - Forwarding helps w/many data hazards
  - Delayed branch helps with control hazard in 5 stage pipeline
  - Load delay slot / interlock necessary
- More aggressive performance:
  - Longer pipelines
  - Superscalar
  - Out-of-order execution
  - Speculation