

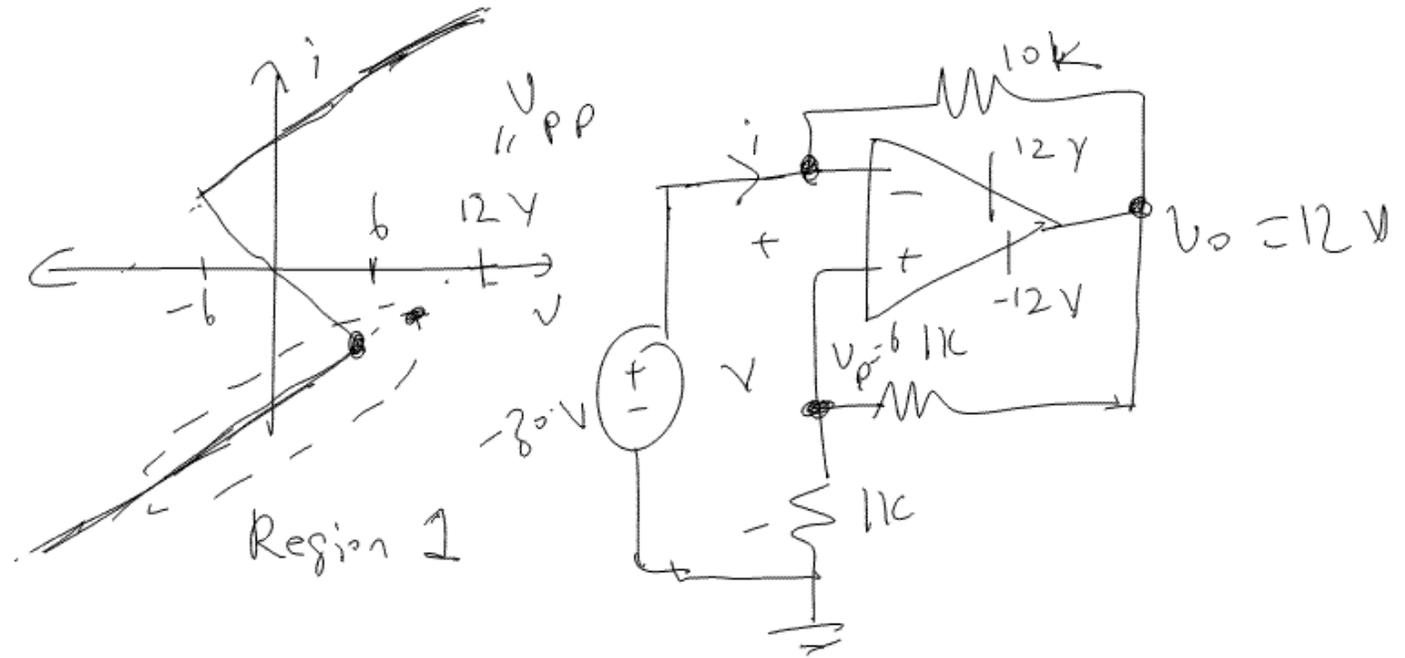
Lecture 15 - More op-amp examples/project info

- Administrivia
- *Extra op-amp problems are up
 - HW #4 solutions are up
 - Nonlinear problem set is up (turn in with)
 - Active filters notes up ⇒ check Project ^{HW #5} section on lab page!
 - PICK UP MIDTERM, OLD HW & LABS (from lab, ask TA). I have asked TAs to email me lab scores. Start making sure online grades are correct!
 - Midterm regrade deadline extended to 08/03/05

BAD SCANNER,
SORRY!

* No time to even come up with answers → talk to me in O.H.

(Q. 1.)



In Region 1, op-amp is positive saturated

$$\Rightarrow v_o = 12V$$

$$\therefore v_p = 6V$$

Notice, $v_o = A(v_p - v_n)$ & if $v_n < v_p$
 $\Rightarrow v_o = 12V$

If $v = 7V \Rightarrow v_n = 7V$

$\therefore v_o = A(6 - 7) = -A < < 0$

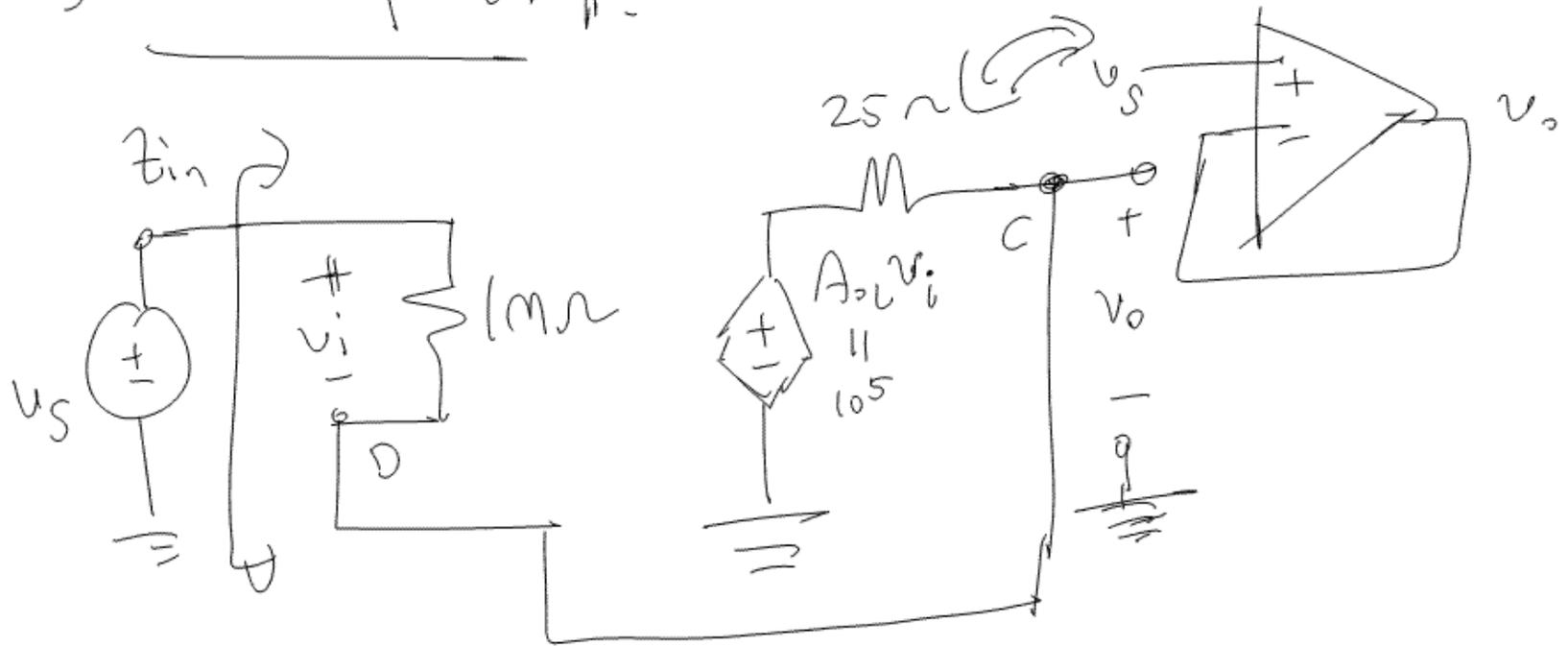
$\Rightarrow \boxed{v_o = -12V}$

If $v = -30V \Rightarrow v_n = -30V$, (assume $v_o = 12V$)

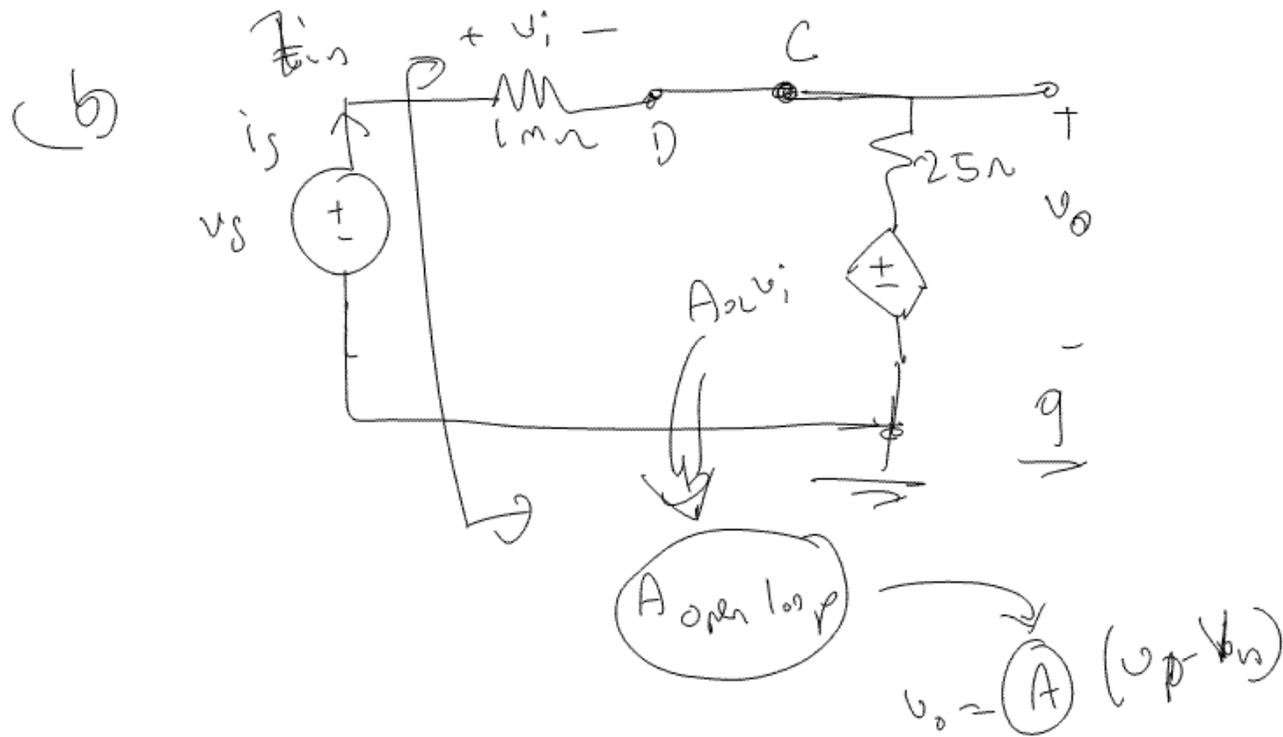
$v_o = A(6 - (-30)) \gg \gg 0$

$\Rightarrow v_o = 12V \checkmark$

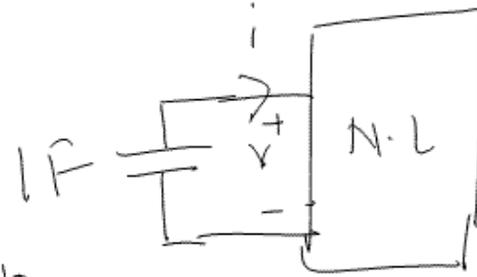
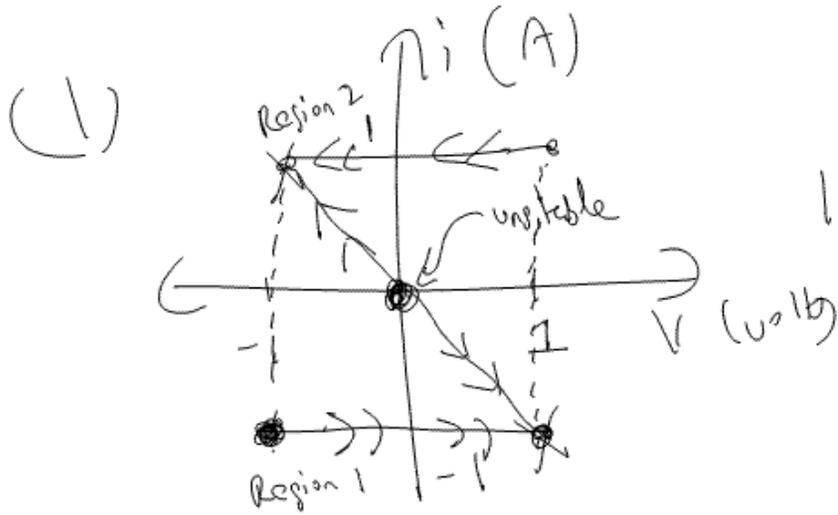
(Q.2) Problem (4-39 #):



(a) $\frac{v_o}{v_s} \rightarrow$ circuit analysis! $(v_o \approx 0.9999 v_s)$
 $(v_o \approx 1.0001 v_s)$



Two more nonlinear $i-v$ examples:



Assuming $v(0) = -1 \text{ V}$,

$$i(0) = -1 \text{ A}$$

$$i(t) = i_f + (i_i - i_f)e^{-t/\tau}$$

find & sketch $i(t)$,
 $v(t)$?

Step (1): Find eq. points & dynamic route.

$$\dot{i} = -C \frac{dv}{dt} \Rightarrow \frac{dv}{dt} = 0 \quad \text{for equilibrium}$$

$$\Rightarrow \boxed{\bar{i} = 0}$$

$$i > 0, v' < 0 \mid i < 0, v' > 0 \Rightarrow \text{Dynamic route}$$

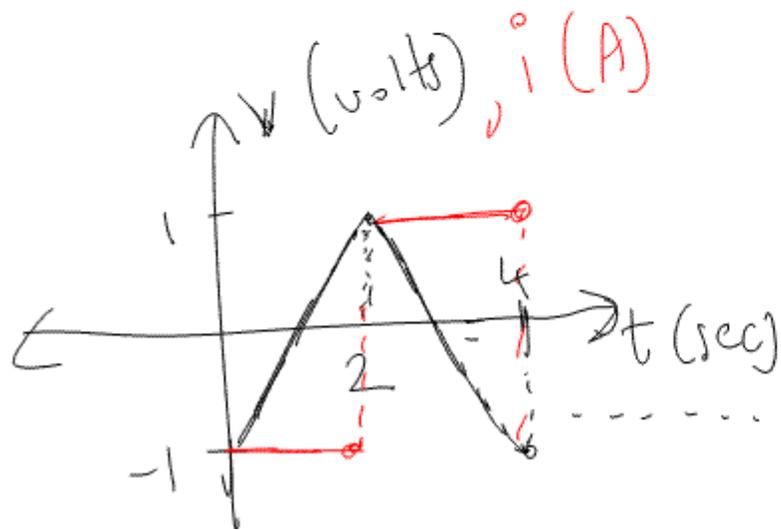
Step (2) We find i_i, i_f, τ

$$i_i = -1 A, \quad i_f = -1 A \Rightarrow \text{constant current source}$$

\therefore We have to go back to first principles.

$$i = -C \frac{dy}{dt} \Rightarrow -1 \overset{\substack{\text{In region 1, } i = -1A}}{A} = (1F) \frac{dy}{dt}$$

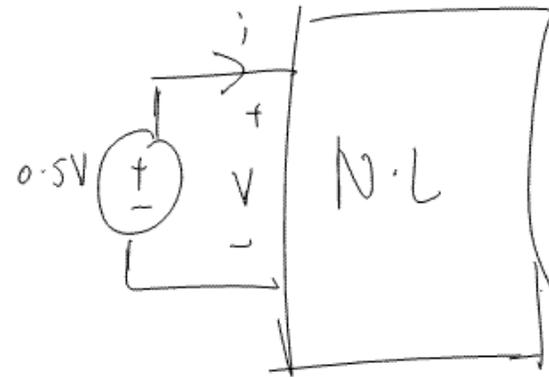
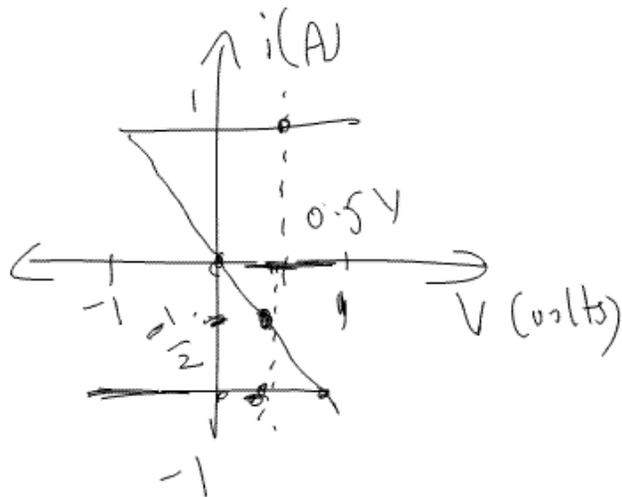
$$\Rightarrow \frac{dy}{dt} = 1 \text{ V/sec}$$



$$\Rightarrow v(t) = t + v_0$$

$$v(0) = v_0 = -1 \text{ V}$$

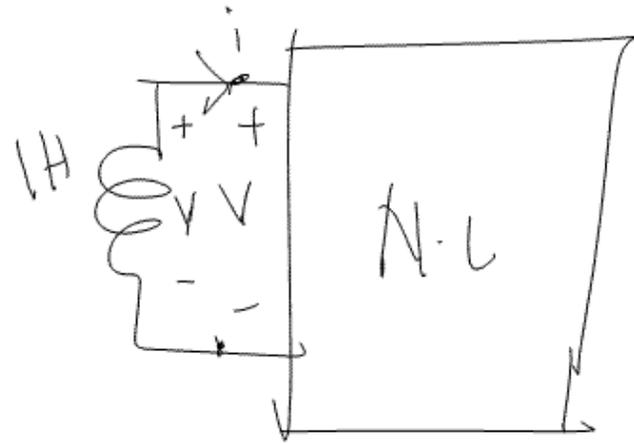
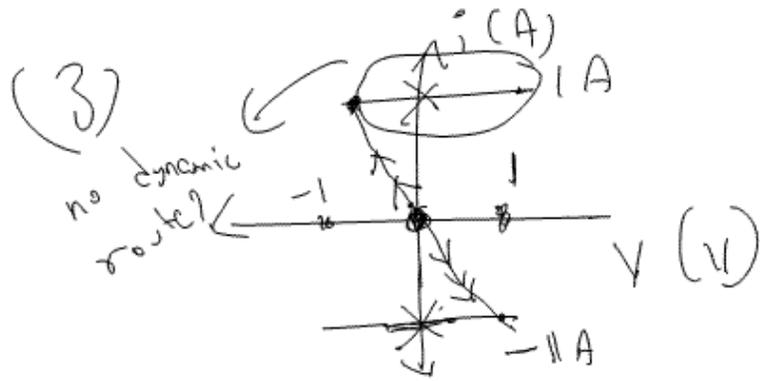
(2)



In the circuit above, find i .

Sol: If $V = 0.5$ V, we can see from the graph $i = 1$ A, $-\frac{1}{2}$ A, -1 A.

Of course, in reality only one solution is valid, but we don't have enough info. for that!



Assuming $v(0) = -\delta$ (δ is a very small +ve number)

& $i(0) = \epsilon$, (ϵ is a very small +ve number),

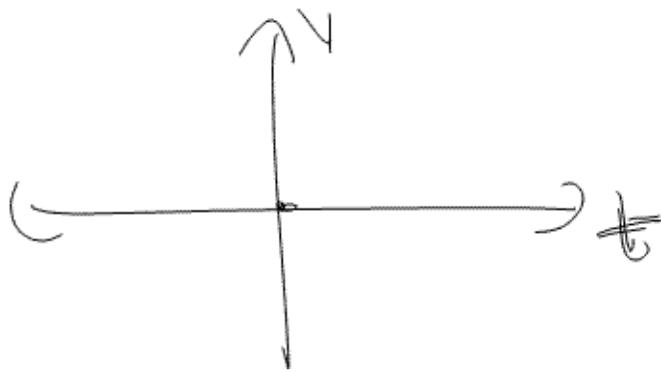
find & sketch $i(t)$, $v(t)$.

Step (1): Find eq. points & dynamic route

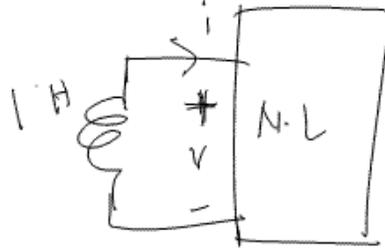
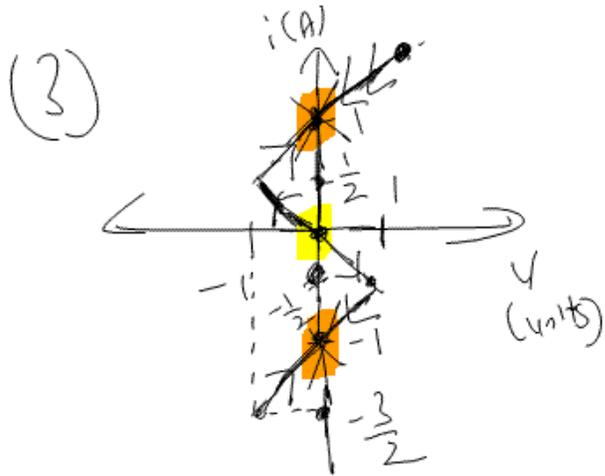
Eq. points: $V = -L \frac{di}{dt} \Rightarrow \begin{cases} V > 0, & \frac{di}{dt} < 0 \\ V < 0, & \frac{di}{dt} > 0 \end{cases}$

$\frac{di}{dt} = 0 \Rightarrow V = 0$

[This makes sense since
at equilibrium, inductors are short circuits]



Bad
problem 😞



Assuming $v(0) = 1$ V
 $i(0) = \frac{3}{2}$ A,
 find & sketch
 $v(t), i(t)$

Step (1): Find eq. points & dynamic route

$$v = -L \frac{di}{dt}$$

stable \Rightarrow $v = 0$

$(0, 0)$; $(0, 1)$; $(0, -1)$ stable

$v > 0, i'(t) < 0$
 $v < 0, i'(t) > 0$

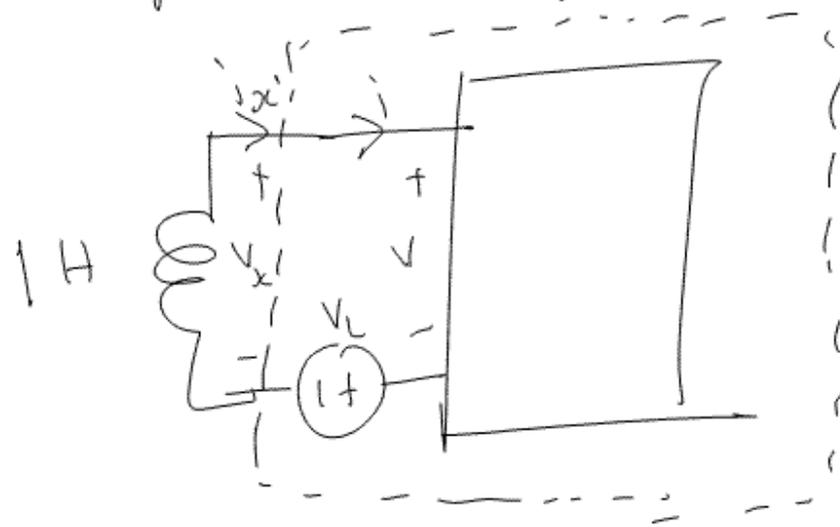
Note, This circuit is a flip-flop because we have two stable states and they can be used to model memory.

(Q:) How do we move from one equilibrium point to another?

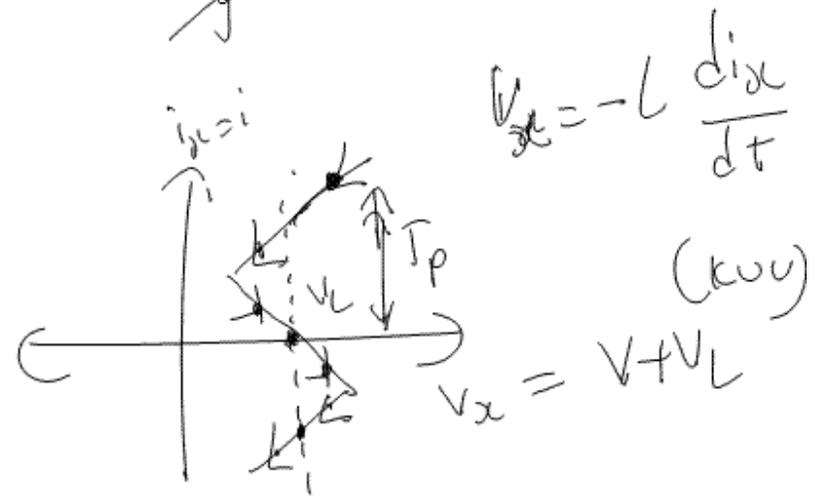
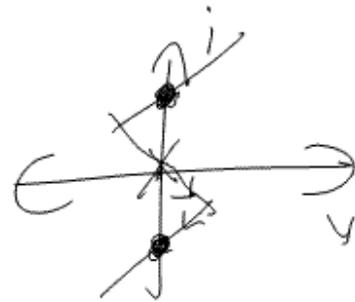
Mechanical Analogy:



In circuit, you give the system energy i.e...
 you apply voltage.



$(V_L > 0)$

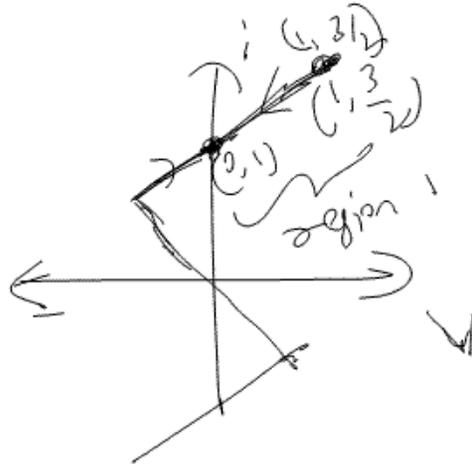


$V_x = -L \frac{di_x}{dt}$

(kwy)

$v_x = v + V_L$

Find $v(t)$
 (assuming $V_L = 0$)

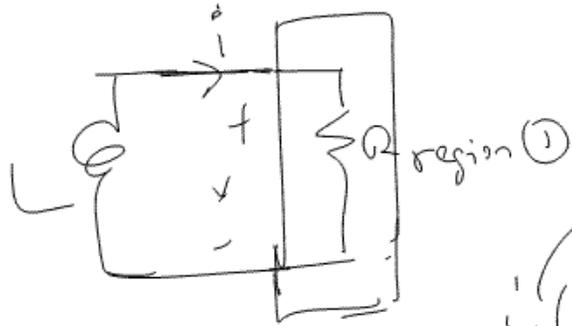


$$v(t) = v_f + (v_i - v_f) e^{-t/\tau}$$

$$v_i = 1 \text{ V}$$

$$v_f = 0 \text{ V}$$

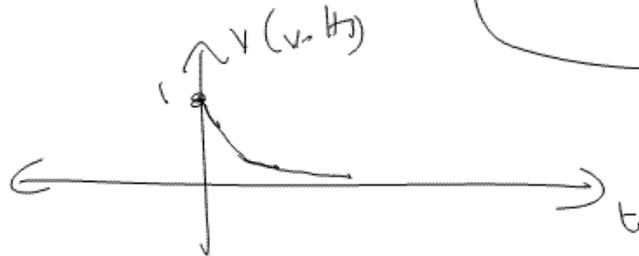
$$\tau = \frac{L}{R_{eq}} = \frac{L}{\Delta i - v}$$



$$\therefore v(t) = \frac{1 \text{ V}}{2} e^{-t/2 \text{ sec}}$$

$$= \frac{1 \text{ H}}{2}$$

$$= 2 \text{ sec}$$

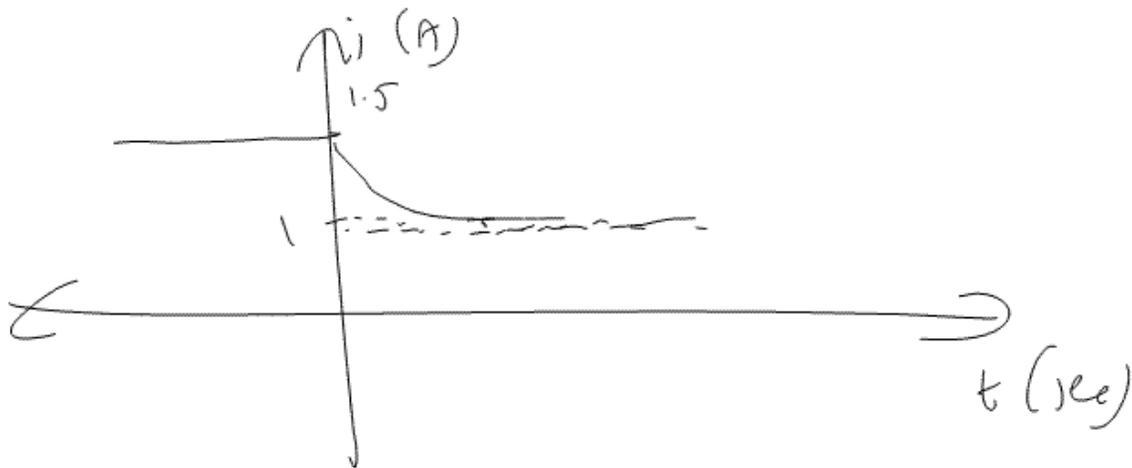


find $i(t)$

$$i(t) = i_f + (i_i - i_f) e^{-t/\tau}$$

$$= 1 + (1.5 - 1) e^{-t/\tau}$$

$$i(t) = 1 + 0.5 e^{-t/2 \text{ sec}} \text{ Am}$$



Friday → Finish flip-flop

↳ Diodes.