

EE105 – Fall 2014

Microelectronic Devices and Circuits

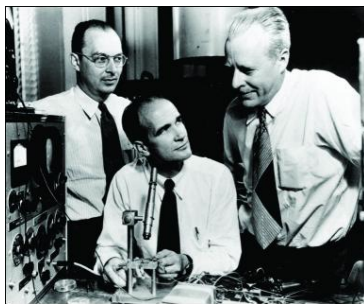
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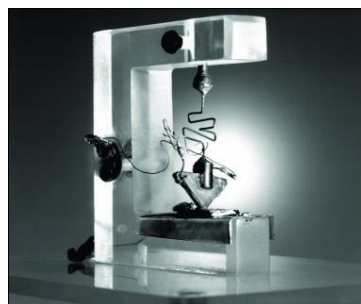
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Invention of Transistors - 1947



Bardeen, Shockley, and Brattain at Bell Labs - Brattain and Bardeen invented the bipolar transistor in 1947.



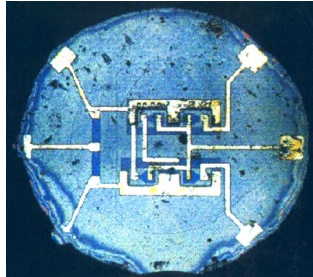
Point contact Ge bipolar transistor



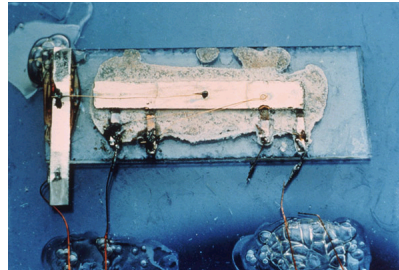
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The First Integrated Circuits - 1958



R. N. Noyce
Fairchild Semiconductor
Co-Founder of both
Fairchild and Intel
(deceased 1990)



Jack Kilby
Texas Instruments
Invented IC during his first year at TI
(Nobel Prize 2000)

“Unitary Circuit” made of Si

“Solid Circuit” made of Ge

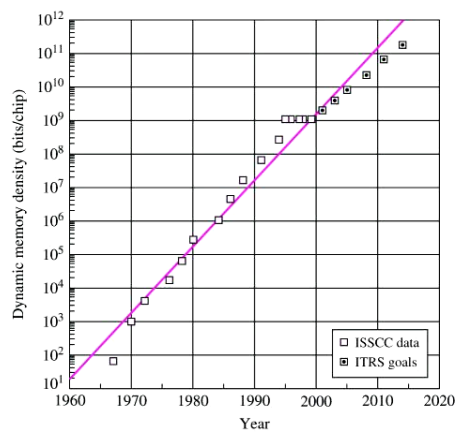


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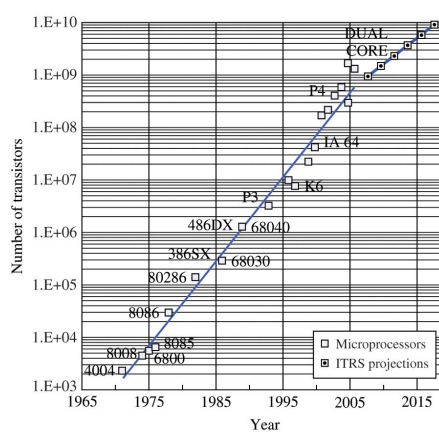


Moore's Law

**Memory chip density
versus time**



**Microprocessor complexity
versus time**

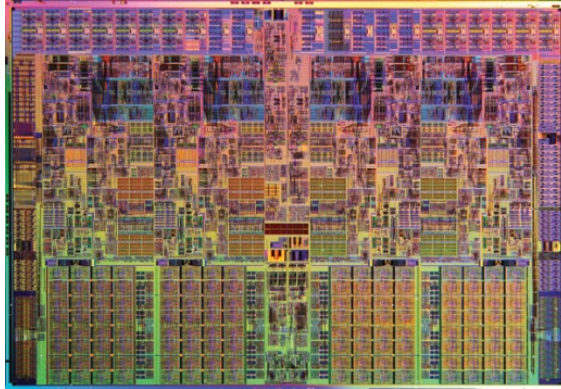


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Intel Core i7 Microprocessor (4 Cores)

~ 1.1 Billion Transistors



Most powerful processor has about 10B transistors today.
Most powerful FPGA has 20B+ transistors.

http://en.wikipedia.org/wiki/Transistor_count



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Moore's Paper in 1965

Cramming more components onto integrated circuits

With unit cost falling as the number of components per circuit rises, by 1975 economics may dictate squeezing as many as 65,000 components on a single silicon chip

By Gordon E. Moore

Director, Research and Development Laboratories, Fairchild Semiconductor
division of Fairchild Camera and Instrument Corp.

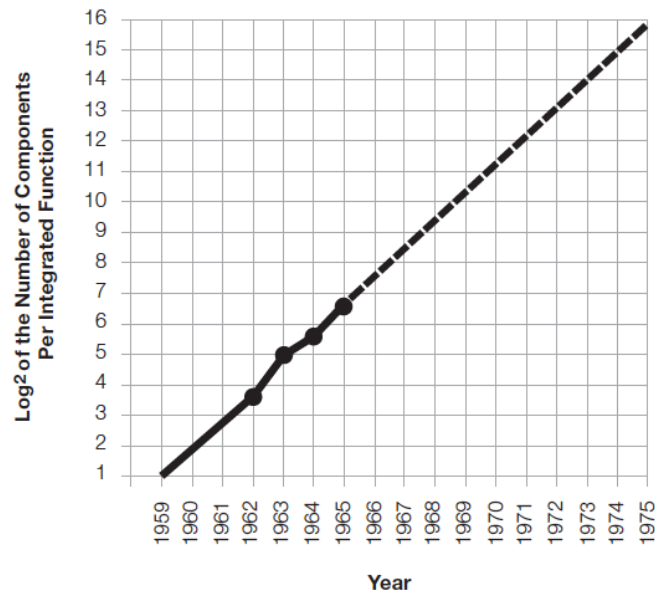
Dr. Gordon E. Moore is one of the new breed of electronic engineers, schooled in the physical sciences rather than in electronics. He earned a B.S. degree in chemistry from the University of California and a Ph.D. degree in physical chemistry from the California Institute of Technology. He was one of the founders of Fairchild Semiconductor and has been director of the research and development laboratories since 1959.



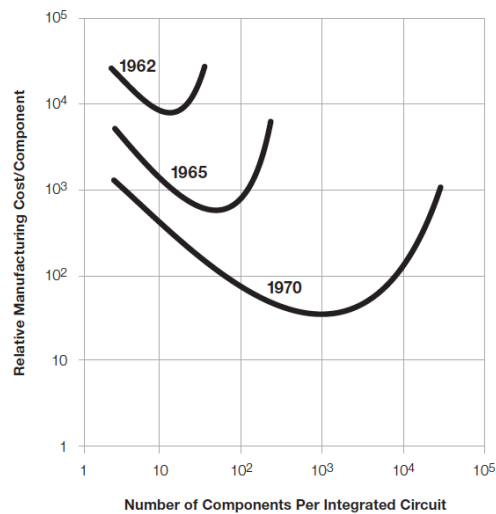
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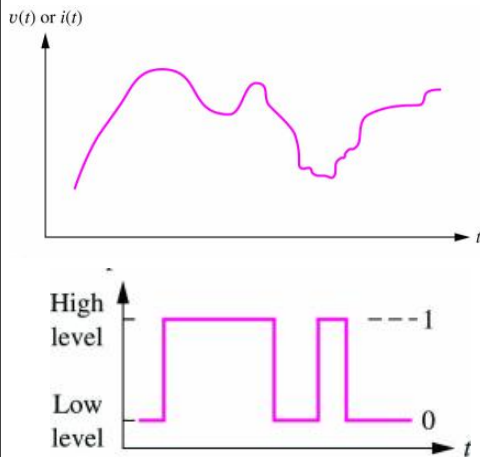
Moore's Law in 1965



Moore's Argument



Digital vs Analog



- Analog electrical signals take on continuous values
- Digital signals appear at discrete levels. Usually we use binary signals which utilize only two levels.
- One level is referred to as logical 1 and logical 0 is assigned to the other level.

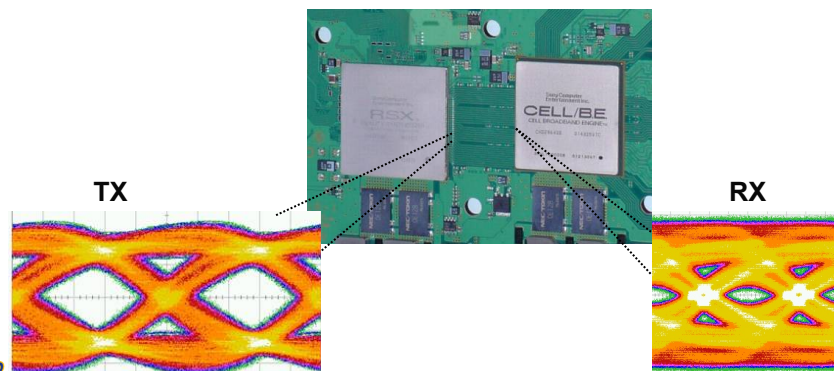


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Why Analog?

- The “real” world is analog
 - Analog is required to interface to just about anything
 - Even to get two digital chips to talk to each other:

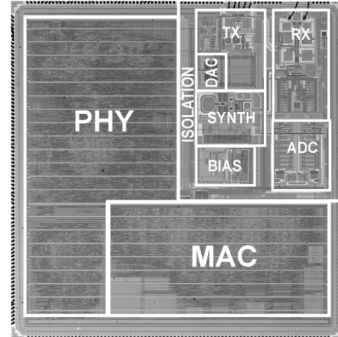
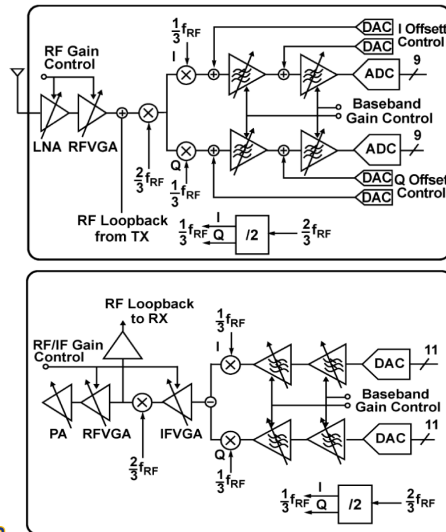


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(Elad Alon)



Another Example: RF Transceiver



Source: Mehta et al, "An 802.11g WLAN SoC", JSSC Dec. 2005

- Analog needs to provide gain + filtering with low noise and distortion

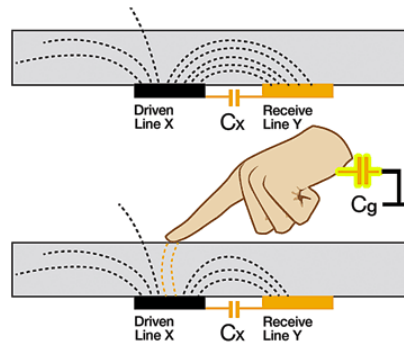


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(Elad Alon)



Sensing



- Similar to communications – analog needed for signal conditioning

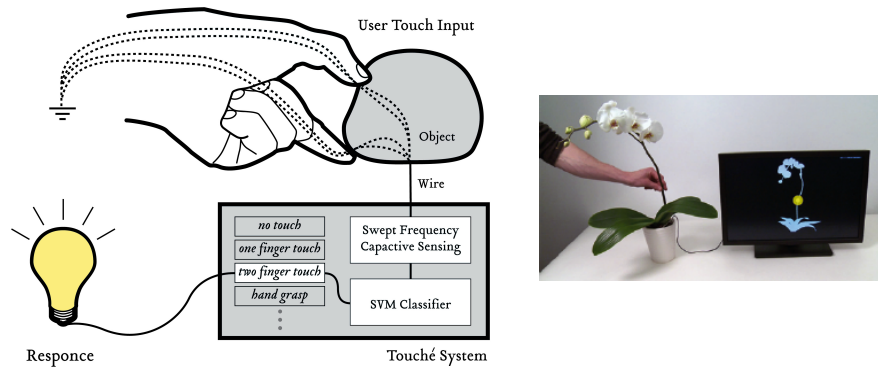


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(Elad Alon)



Creative Touch Sensors



<http://www.ivanpoupyrev.com/projects/touche.php>

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Internet of Things (IoT)



Adapted from
Rabaey, ASPDAC, 2008

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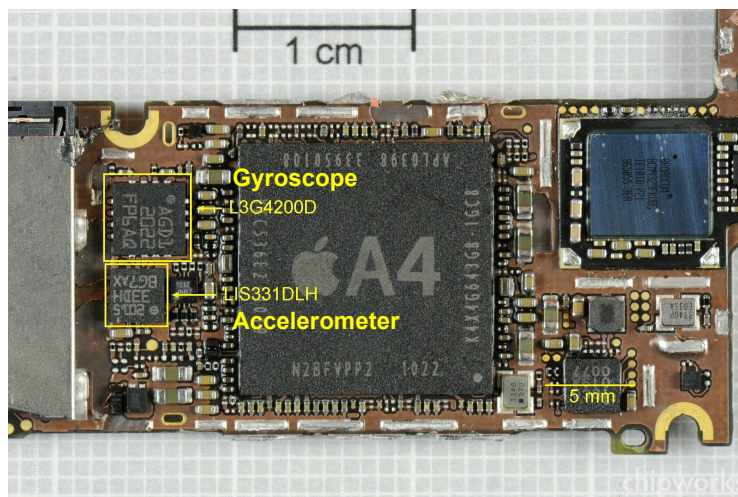
Sensors in a Phone



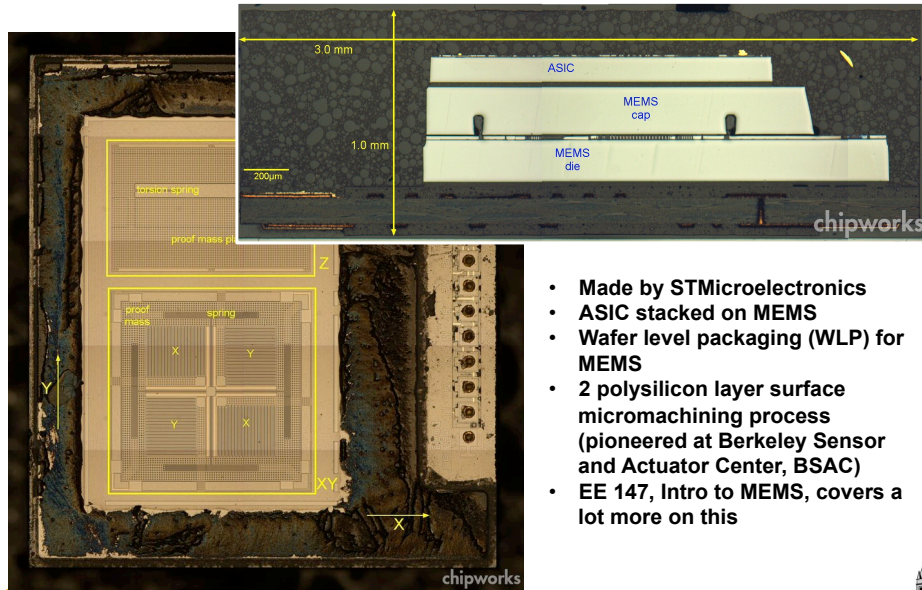
Lots of sensors:

- 9DoF motion sensing,
 - 3 axis accelerometer
 - 3 axis gyroscope
 - 3 axis compass
- 3 microphones,
- 2 image sensors,
- ambient light and proximity sensors,
- archetypal touch screen sensor.

Inside iPhone4



Accelerometer in iPhone4



- Made by STMicroelectronics
- ASIC stacked on MEMS
- Wafer level packaging (WLP) for MEMS
- 2 polysilicon layer surface micromachining process (pioneered at Berkeley Sensor and Actuator Center, BSAC)
- EE 147, Intro to MEMS, covers a lot more on this

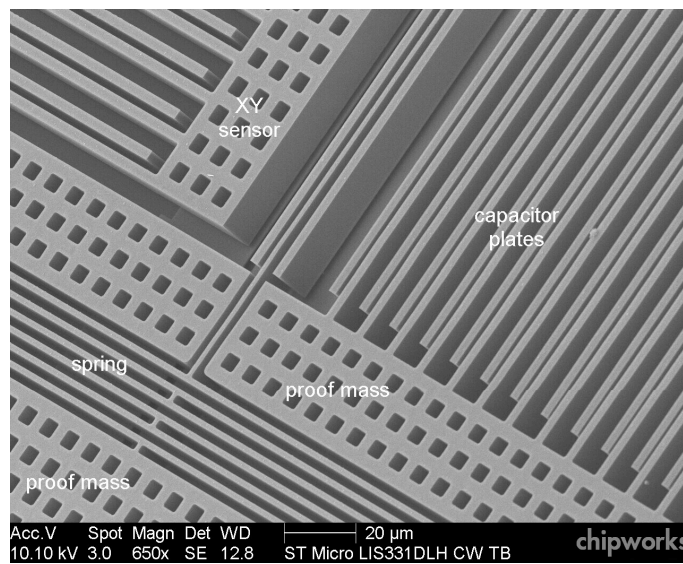


www.memsjournal.com/2010/12/motion-sensing-in-the-iphone-4-mems-accelerometer.html

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Accelerometer in iPhone4



Acc.V Spot Magn Det WD | 20 μm
10.10 kV 3.0 650x SE 12.8 ST Micro LIS331DLH CW TB

chipworks

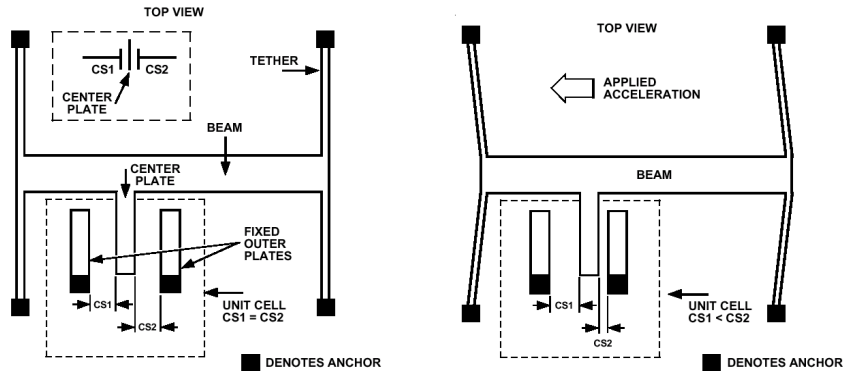


www.memsjournal.com/2010/12/motion-sensing-in-the-iphone-4-mems-accelerometer.html

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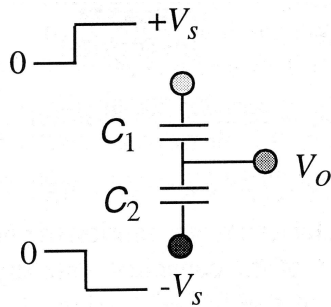
Differential Capacitive Accelerometer



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Differential Capacitive Sensing



$$V_0 = -V_s + \frac{C_1}{C_1 + C_2} \cdot 2V_s$$

$$= \frac{C_1 - C_2}{C_1 + C_2} V_s$$

$$C_1 = C \frac{x_0}{x_0 + \delta x} \quad C_2 = C \frac{x_0}{x_0 - \delta x}$$

For small displacement:

$$C_1 - C_2 = C \left(\frac{x_0}{x_0 + \delta x} - \frac{x_0}{x_0 - \delta x} \right)$$

$$= C \frac{-2x_0 \delta x}{x_0^2 - \delta x^2} \approx -C \frac{2}{x_0} \delta x$$

$$C_1 + C_2 \approx 2C$$

$$V_0 \approx -\frac{\delta x}{x_0} V_s$$

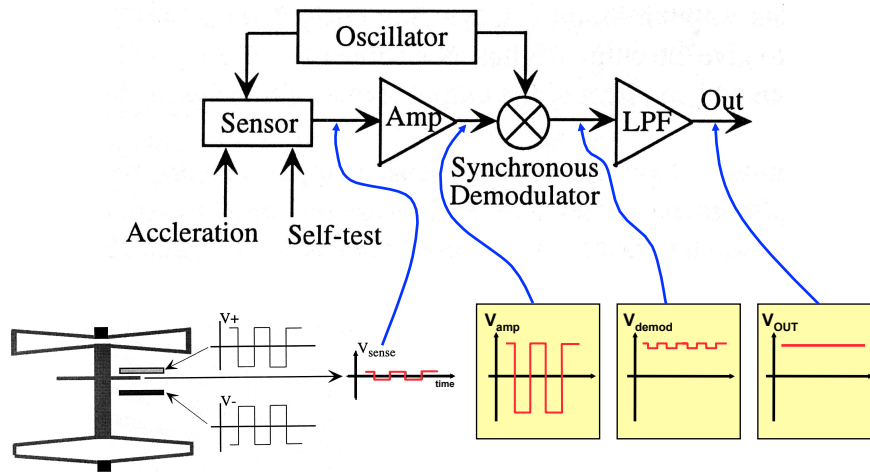
Output voltage is linearly proportional to the displacement



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ADXL Block Diagram – Open Loop



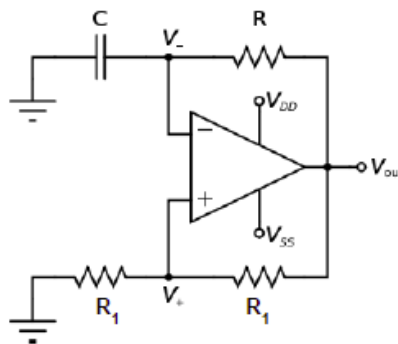
- Minimum detectable capacitance change: 20 aF (aF = 10^{-18} F)
- Minimum detectable displacement: 0.02 nm (1/5 of hydrogen atom)



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What You Learned in EE40



- Resistors, capacitors, inductors
- KCL, KVL
- Ideal OP Amp
- Time/frequency domain analysis
- Bode Plot

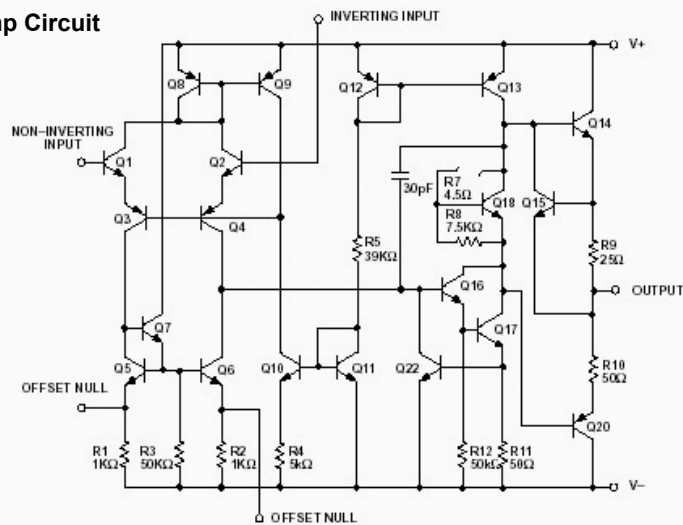


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What You Will Learn in EE 105

Op Amp Circuit

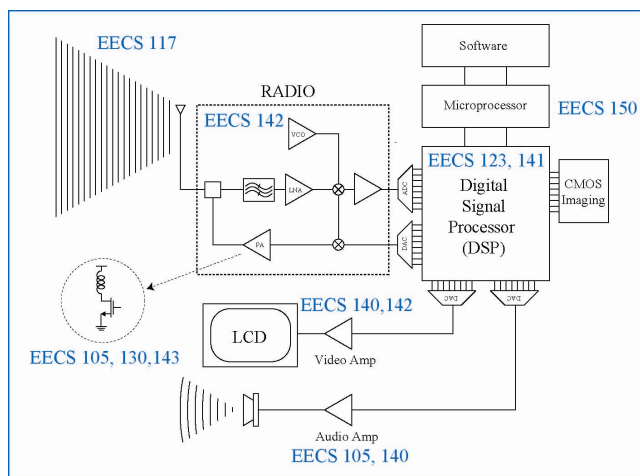


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EECS 105 in the Grand Scheme

• Example: Cell Phone



ENTIRE SYSTEM: EECS 120, 126, 121

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Circuit Simulation

- **SPICE (Simulation Program with Integrated Circuit Emphasis)**
 - Developed at UC Berkeley!
 - Outgrowth of CANCE (Computer Analysis of Nonlinear Circuits, Excluding Radiation)
- **We will use HSPICE in class (Read the Tutorial online)**
- **Many other versions of SPICE**
 - LTSPICE free download from Linear Technology
<http://www.linear.com/designtools/software/#LTspice>
 - However, GSIs will only focus on HSPICE, and answer questions related to HSPICE

