



$$(\underline{au}: N_{0} \geq V_{00} - V_{TN} \rightarrow M_{1} \text{ saturated}$$

$$i_{D(sot)}^{2} = \frac{k_{H}}{2} (V_{GS} - V_{TN})^{2} = -C_{L} \frac{dv_{C}}{dt}$$

$$dt = \frac{2C_{L} CV_{C}}{K_{N} (V_{GS} - V_{TN})^{2}} = \frac{-2C_{L} dv_{C}}{K_{N} (V_{DS} - V_{TN})^{2}}$$

$$[V_{GS}^{2} V_{0H}^{2} V_{DD} = N_{T}]$$

$$\int_{t_{0}}^{t_{1}} dt = \int_{V_{DD}}^{V_{DO} - V_{TN}} \frac{2C_{L}}{K_{N} (V_{DO} - V_{TN})^{2}}$$

$$(t_{1} - t_{0}) = -\frac{2C_{L}}{K_{N} (V_{DO} - V_{TN})} \frac{V_{TN}}{V_{DO} - V_{TN}} = 2C_{L} R_{ON} \frac{V_{TN}}{V_{DD} - V_{TN}}$$

$$e^{\frac{1}{K_{D} C} V_{DO} - V_{TN}} \frac{V_{TN}}{V_{DO} - V_{TN}} = 2C_{L} R_{ON} \frac{V_{TN}}{V_{DD} - V_{TN}}$$

$$e^{\frac{1}{K_{D} C} V_{DO} - V_{DN}} \frac{1}{T_{O}} \frac{V_{TN}}{V_{DO} - V_{TN}} \frac{1}{T_{O}} \frac{1}{T_{O}} C_{L}$$

$$\begin{aligned} & \left( \underbrace{ane}_{i} \cdot \mathcal{N}_{0} < V_{DS} \cdot V_{TN} \rightarrow M_{i} \right) insor\\ & \dot{n}_{D}(lin) = -C_{L} \frac{dN_{c}}{dt} \\ & K_{N}(\mathcal{N}_{GS} - V_{TN} - \frac{\mathcal{N}_{DS}}{2}) \mathcal{N}_{DS} = -C_{L} \frac{dV_{c}}{dt} \\ & \left[ \mathcal{N}_{DS} = \mathcal{N}_{c-1} \mathcal{N}_{GS} = V_{DD} \right] \Rightarrow \left\{ K_{N}(V_{DO} \cdot V_{TN} - \frac{N_{c}}{2}) \mathcal{N}_{c} = C_{i} \frac{dM_{c}}{dt} \right\} \\ & \int_{t_{i}}^{t_{2}} \frac{K_{N}}{2C_{c}} dt = -\int_{V_{i}}^{V_{2}} \frac{dV_{c}}{(2(V_{DO} - V_{TN}) - \mathcal{N}_{c}]} \mathcal{N}_{c} \\ & \left( \int \frac{dx}{(a-x)x} = \int \frac{dx}{a(a-x)} + \int \frac{dy}{ax} \\ & = \frac{1}{a} \int \left[ \frac{1}{a-x} + \frac{1}{x} \right] dx = \frac{1}{a} ln\left(\frac{x}{a-x}\right) \right] \\ & \left( V_{2} = \frac{V_{DD}}{2} \cdot V_{i} = V_{DO} - V_{TN} \right] \Rightarrow \\ & \frac{K_{N}}{2C_{L}} \left( t_{2} - t_{i} \right) = -\frac{1}{2(V_{DO} - V_{TN})} ln\left( \frac{V_{c}}{2(V_{DO} - V_{TN}) - \mathcal{N}_{c}} \right) \right) \\ & \int_{V_{DD}}^{V_{DD}} - V_{TN} \\ & = -\frac{1}{2(V_{DS} - V_{TN})} ln\left( \frac{V_{DD}}{4V_{D} - V_{TN} - V_{DD}} \right) \end{aligned}$$

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# CTN 11/30/18

<u>EE 105</u>: Microelectronic Devices & Circuits <u>Lecture 40w</u>: Complex Gates

> $(t_2, t_1) = \frac{C_2}{K_N(V_{100} - V_{1N})} l_n \left[ \frac{4(V_{100} - V_{1N}) - V_{20}}{V_{100}} \right]$  $= \frac{C_{L}}{k_{L}(k_{D}-V_{TN})} \ln \left\{ \frac{4(V_{DD}-V_{TN})}{V_{TD}} - 1 \right\}$  $(t_2-t_1) = \operatorname{Ron} C_L \ln \left[ \frac{4(V_{DD}-V_{TN})}{V_{DD}} - 1 \right]$  $t_{PH2} = (t_2 - t_1) + (t_1 - t_2) = (t_2 - t_2)$ =  $\left[ R_{on}C_{L} \right] h \left[ \frac{4(V_{DO} - V_{TN})}{V_{DD}} - 1 \right] + \frac{2V_{TN}}{(V_{DO} - V_{TN})} \right]^{2} t_{pHL}$ Where Ron = KIX (VOB-VITX) toffe : RonCi × f(100,1/11) tput: output: L=>4 - connect CL to VOD -> PMOS on, NMOS off NI 1,0- $\int_{-\infty}^{-\infty} M_{P} \cdot OV \rightarrow V_{DD}$ ٥٧

Through a similar analysis:	
$\left(\frac{1}{2}\rho_{LH} = R_{CA}C_{L}\left[\frac{4(V_{DU} - IV_{TP})}{V_{DD}} - 1\right] + \frac{2(V_{TP})}{(V_{DD} - IV_{TP})}\right]$	
tp= tput + Epite	

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- a conductive path connecting V<sub>DD</sub> and ground in steady-state
  Otherwise, too much current will flow and dissipate
- power
- $\boldsymbol{\cdot}$  Should also minimize this path during transitions



# CTN 11/30/18





- What's Next? (cont.)
- <u>EE147</u>: Microelectromechanical Systems (MEMS)
  - ♥ I'm biased, but ... this is the coolest stuff, period!
  - $\textcircled{} here a \ \ here \ \ h$
  - $\textcircled{} b \mathsf{M} \mathsf{e} \mathsf{thods}$  for fabricating tiny mechanics
  - Mechanical circuit design
  - Sou'll learn that all of your EE math skills and circuit techniques can just as easily be applied to mechanical devices and systems
  - $\textcircled{} \mathsf{Applications}$  to sensing and RF