

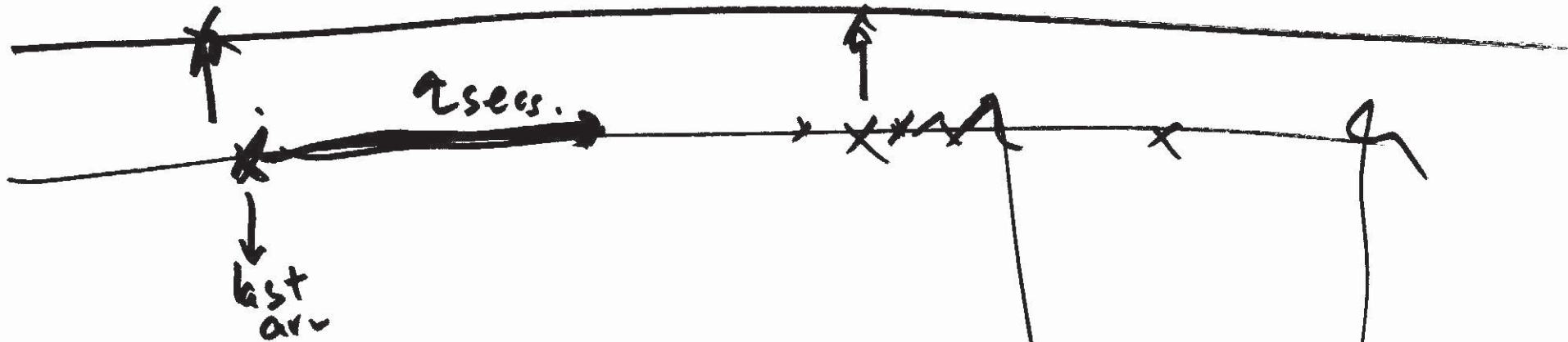
Poisson Process (cont'd).

Memoryless Property

Start a Poisson process:

τ seconds has elapsed since the last arrival.

~~pdf~~ of Conditional pdf of $t_1 - \tau$ is still poisson indep of τ



Fresh Start

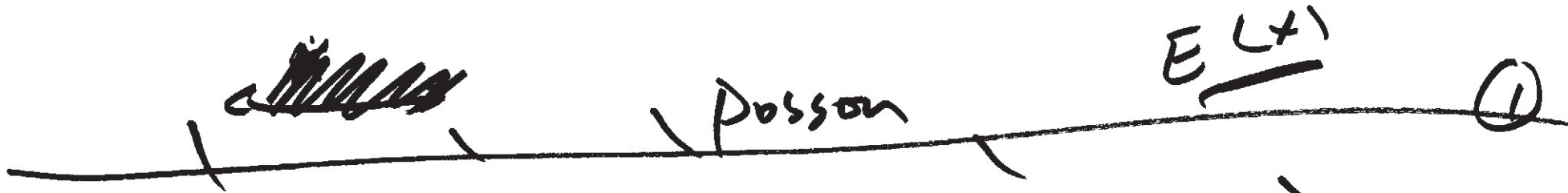
at time t , the history of the process after time t is also a poisson and indep of history of the process until time t .

merging + splitting of Poisson Process

merging

x, y

expect 1st order interval
time for 2 indep.
poisson proc



~~wait~~
merged
poisson

$E(x) + E(y)$

$M_x(s) = e^{E(x)(e^s - 1)}$

$M_y(s) = e^{E(y)(e^s - 1)}$

$$W = X + Y.$$

$$M_W(s) = M_X(s) M_Y(s) \\ = \frac{e^{sE(X)} - 1}{(E(X) + E(Y))(e^s - 1)}$$

$$P_W(w_0) = \frac{E(X) + E(Y)}{w_0!} e^{- (E(X) + E(Y)) w_0}$$

Sum of 2 Poisson Processes with arrival rate of λ_1 & λ_2 is another Poisson.

Splitting of Poisson

original

Poisson.

λ -arrival.



P keep
1-P Throwing

New process =
Poisson.
 λP .



Q1 PDF independent interarrival times between successive cars in highway is 12 sec

$$f_t(t_0) = \begin{cases} \frac{1}{12} & t_0 \geq 0 \\ 0 & t_0 < 0 \end{cases}$$

$\int_0^{\infty} f_t(t_0) dt_0 = 1$

$$e^{-t_0/12} \quad t_0 \geq 0 \rightarrow \lambda = \frac{1}{12}$$

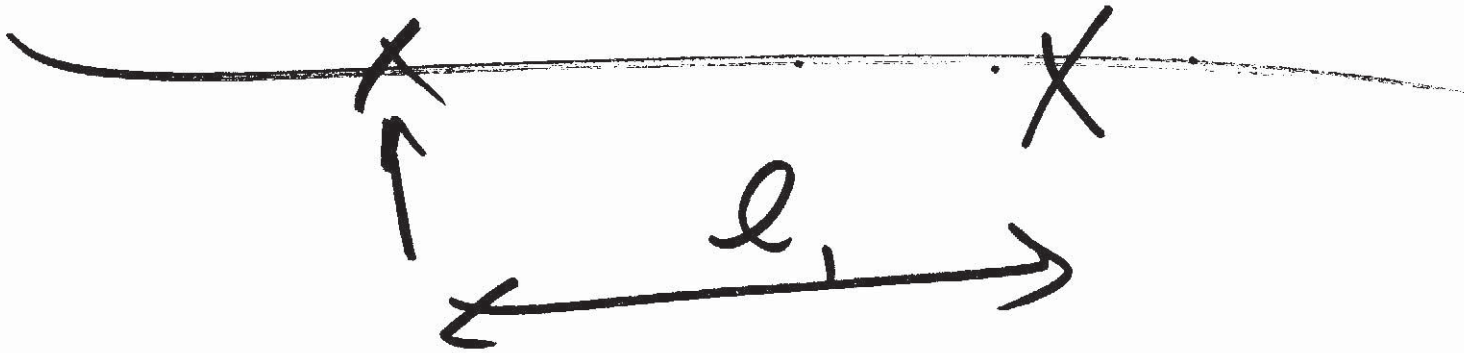
$$t_0 < 0$$

Q What ~~car~~ requires 12 secs to cross. Starts immediately after a car.

Prob of survives? $\left(\frac{t}{12}\right)^k e^{-t/12}$

$$P(k; t) = \frac{\left(\frac{t}{12}\right)^k e^{-t/12}}{k!} \quad k=0, 1, 2, \dots$$

$$P(0; 12) = \frac{e^{-1}}{0!} = 0.368$$



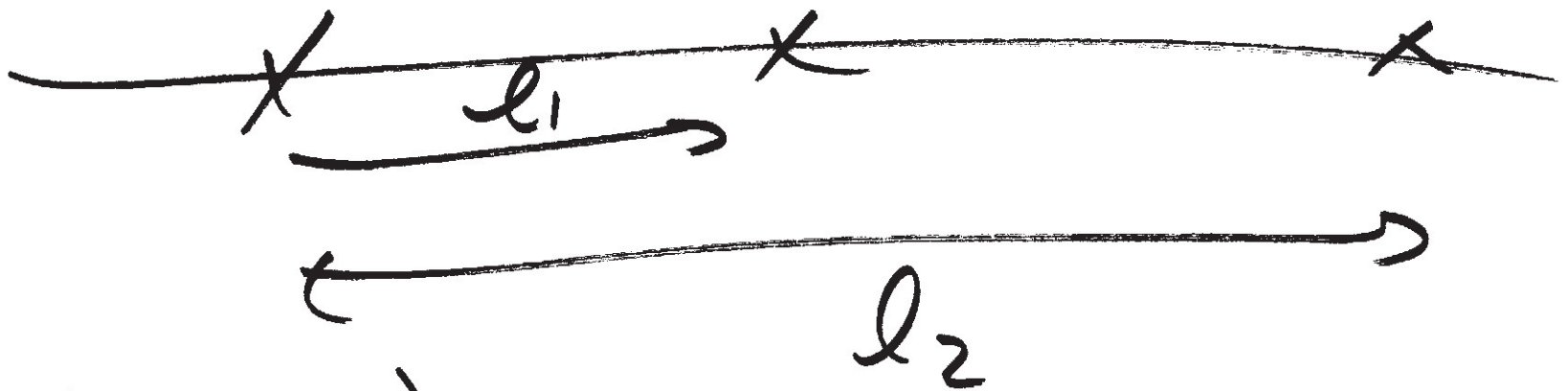
$$\text{Survival} = \Pr(l_1 > 12)$$

$$= \int_{t_0=12}^{\infty} f_t(t_0) dt_0 =$$

$$= \int_{t=12}^{\infty} \frac{1}{12} e^{-t/12} dt = 0.368$$

Q Slow wombat: $\frac{24 \text{ secs To cross}}{2 \text{ cats To die.}}$

what is prob of survival.



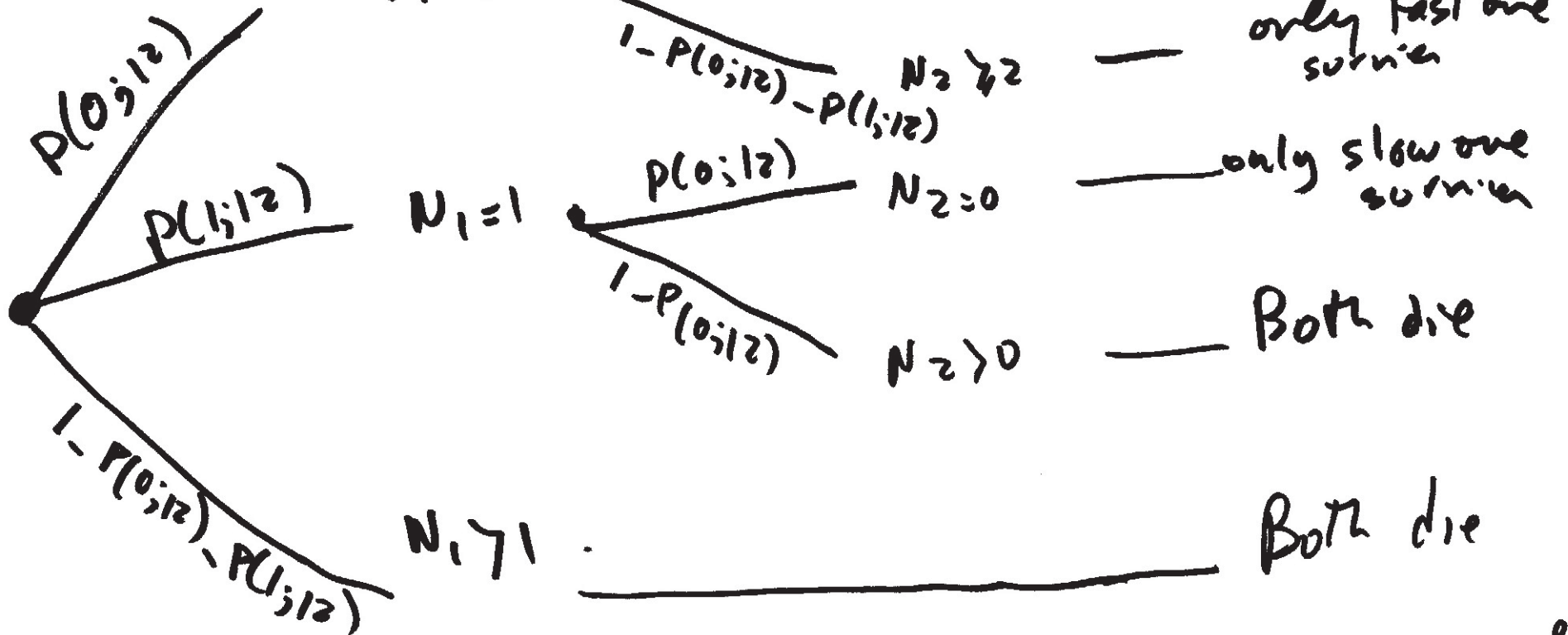
1, $P(l_2 > 24)$

2 $P(0; 24) + P(1; 24) = 3e^{-2} = 0.406$

Q

~~Both~~ Both leave at the same time. ~~immediately~~ immediately after a car.
What is Prob. that exactly one survives.

$N_1 = \# \text{ cars in first 12 seconds}$
 $N_2 = \# \text{ up cars in 2nd 12 seconds}$
Both sum



$P(\text{exactly one workstation serving}) =$

$$\begin{aligned} & P(N_1=0, N_2 \geq 2) + P(N_1=1, N_2=0) \\ \text{indep } \hookrightarrow & P(0;12) [1 - P(0;12) - P(1;12)] \\ & + P(1;12) P(0;12) \\ & = e^{-1} - e^{-2} = 0.233. \end{aligned}$$

Ex

$$f_t(t_0) = \begin{cases} \lambda e^{-\lambda t_0} \\ 0 \end{cases}$$

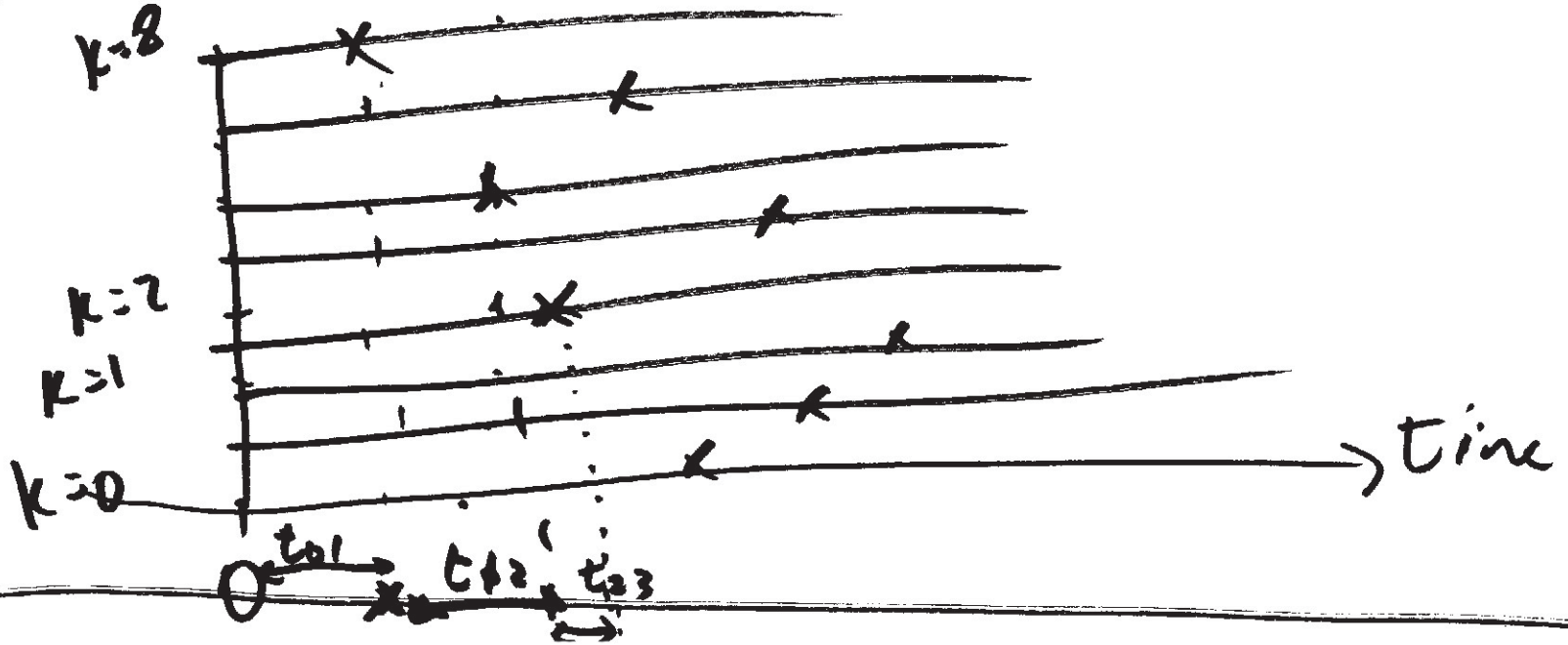
$t_0 > 0$
time.

lifetime of a bulb.

$t=0$. we turn 8 bulbs on.

$y =$ R.V. time until 3rd failure.

Q mean + variance and Transform of y .



Define t_{01} = time from start until 1st failure.

t_{12} = time from 1st failure to 2nd failure

t_{23} = time from 2nd failure to 3rd failure

$$Y = t_{01} + t_{12} + t_{23} \leftarrow \begin{array}{l} \text{Poisson} \\ \text{process} \\ \text{with} \\ \text{arrival} \\ \text{rate of} \\ 6\lambda. \end{array}$$

merger
a sum of 8
indep
Poisson
R.P.
with $= 8\lambda$.

Poisson
process
with arrival
rate
of 3λ .

t_{ij} are indep

$$\begin{aligned} E(Y) &= E(t_{01}) + E(t_{12}) + E(t_{23}) \\ &= \frac{1}{8\lambda} + \frac{1}{3\lambda} + \frac{1}{6\lambda} \end{aligned}$$

$$\begin{aligned}
 \sigma_y^2 &= \sigma_{t_{01}}^2 + \sigma_{t_{12}}^2 + \sigma_{t_{23}}^2 \\
 &= \left(\frac{1}{8\lambda}\right)^2 + \left(\frac{1}{7\lambda}\right)^2 + \left(\frac{1}{6\lambda}\right)^2
 \end{aligned}$$

$$M_y(s) = M_{t_{01}}(s) \times M_{t_{12}}(s) \times M_{t_{23}}(s)$$

$$M_y(s) = \frac{8\lambda}{s+8\lambda} \cdot \frac{7\lambda}{s+7\lambda} \cdot \frac{6\lambda}{s+6\lambda}$$

Ex Joe waiting for a bus. For:

Newport To Fresno

N

→

F.

Right

F

→

N

wrong.

Arrival ~~is~~ $\left\{ \begin{matrix} NF \\ FN \end{matrix} \right\}$ is poisson with rate

$\left\{ \begin{matrix} \lambda_{NF} \\ \lambda_{FN} \end{matrix} \right\} = \left\{ \begin{matrix} \lambda_{right} \\ \lambda_{wrong} \end{matrix} \right\}$

$K = \#$ of wrong buses until right bus arrives.

Q: PMF of K ? man.

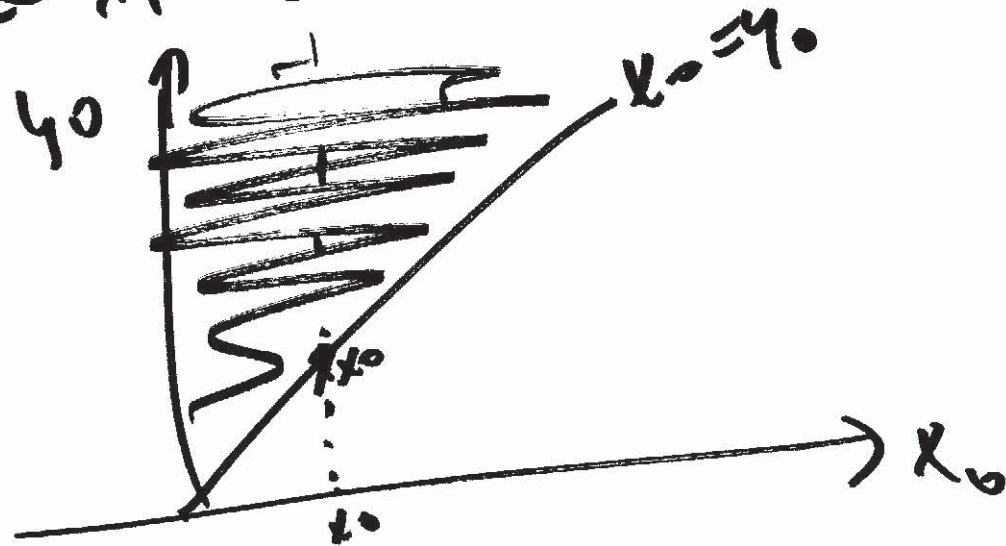
$x = r.v.$ wait for wrong bus.

$y = r.v.$ Time to wait for the ~~wrong~~ right bus

$$P(\text{next bus is wrong}) = \Pr(x < y)$$

$$f_x(x_0) = \lambda w e^{-\lambda w x_0}$$

$$f_y(y_0) = \lambda r e^{-\lambda r y_0}$$

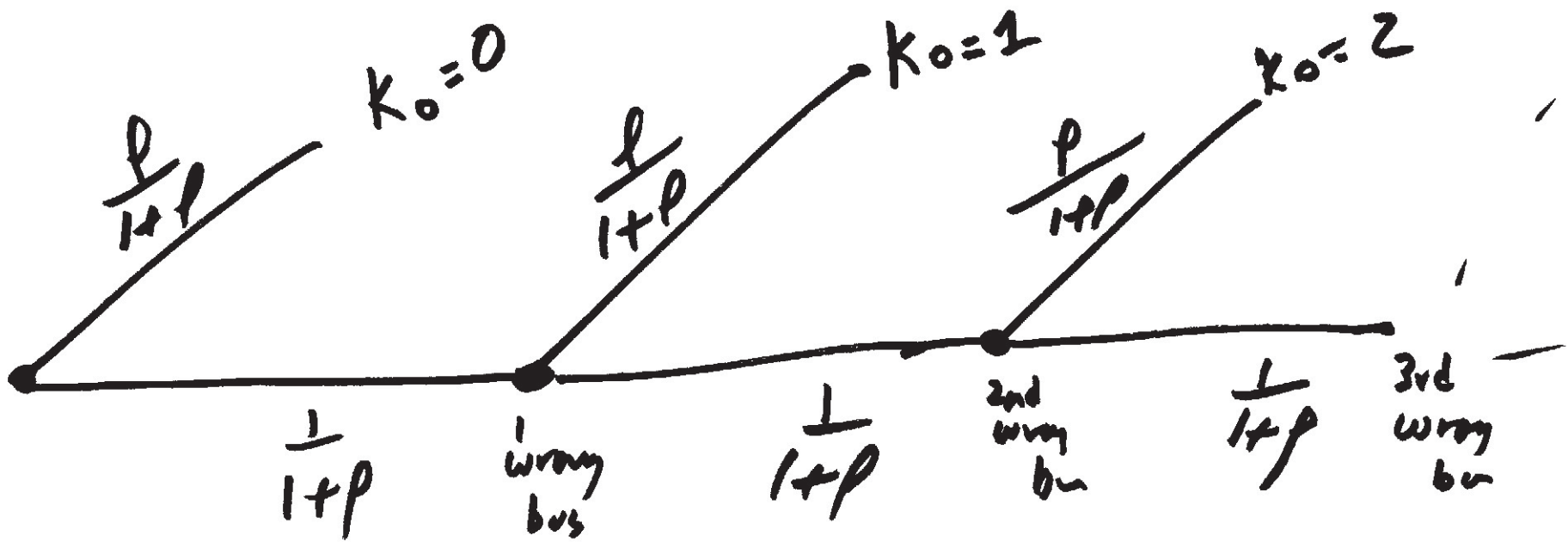


$$P(\text{next bus is wing}) = P(x < y) =$$

$$= \int_{x_0=0}^{\infty} dx_0 \int_{y_0=x_0}^{\infty} dy_0 \lambda_w dr e^{-\lambda_w x_0} e^{-\lambda_r y_0}$$

$$f = \frac{\lambda_w r}{\lambda_w}$$

$$P(\text{next bus is wing.}) = \frac{1}{1+f}$$



$$P_k(k_0) = \frac{p}{(1+p)^{k_0+1}}$$

$k_0 = 0, 1, 2, \dots$

To complete mean, Take transform, Then $s=0$
 $\frac{1}{p} = E(k)$

$$p \gg 1 \Rightarrow \lambda_r \gg \lambda_w \Rightarrow E(k) = 0$$

$$p \ll 1 \Rightarrow \lambda_r \ll \lambda_w \Rightarrow E(k) \rightarrow \infty$$