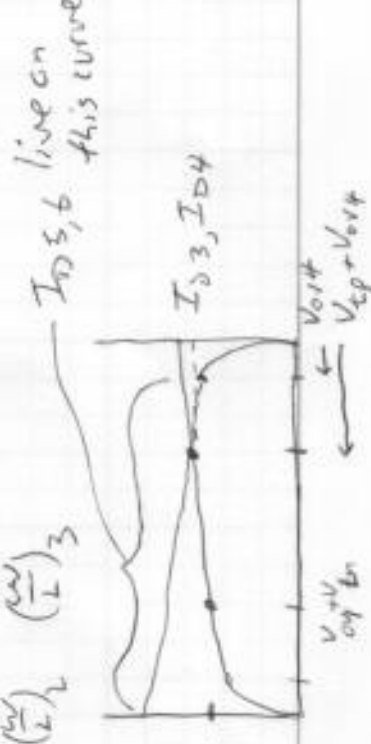
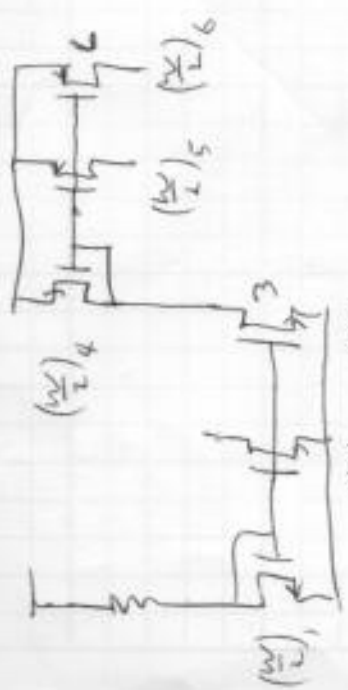
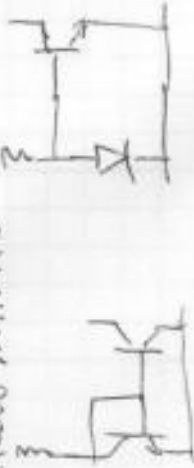


Resistor
Sources & sinks

2 stage
sizing & biasing
input range, output swing
differential gain
common mode gain



Current mirrors

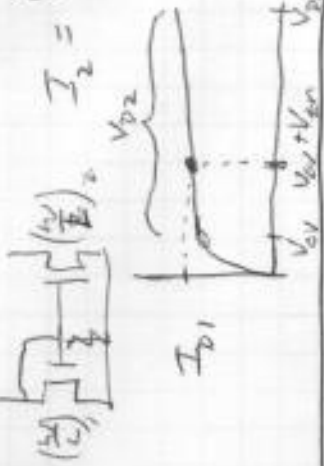


$$I_{ref} = \frac{V_{cc} - V_{ov6}}{R}$$

$$I_1 = \frac{V_{D0} - (V_{ov1} + V_{ov})}{R}$$

$$I_2 = \left(\frac{W/L}{W/L}\right)_2 (1 + \lambda \Delta V)$$

may be negative



Feedback

Say I want a gain of 100
±1% from $V_{in} = 0$ to 10mV
 $V_{out} = 0$ to 1V



can design for $A_v = 100$

↑
not a problem

- but 1) input at 0? hard/impossible
2) r_o varies w/ V_{out}
 V_{t2} , μ_{eff} varies w/ temperature
3) bias varies w/ supply
4) everything varies run-to-run and
supply-to-supply (due to transistor)

Compare to

ideal op-amp: $A_v = \frac{99k + 1k}{1k} = 100$



99 copies in layout if careful, 0.1% match

What if it's not an ideal op-amp?

- input offset $\neq 0$
- input current $\neq 0$
- common mode gain $\neq 0$
- differential gain $< \infty$

need % error $< 1\% = 10^{-2} = \frac{1}{Af}$

$f = 10^2$ also

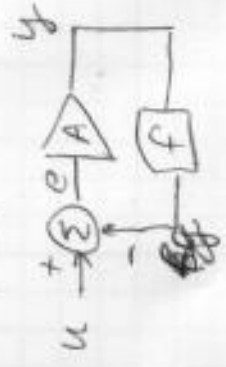
need $A > \frac{1}{(\% \text{ error}) f} = \frac{1}{(10^{-2})(10^2)} = 10^4$

As long as $A > 10^4$ over

- Process
- Voltage (supply)
- temperature
- input/output swing

then finite gain causes less than 1% error

12.8 perspective



$y = Ae$
 $= A(u - Ay)$
 $(1 + Af)y = Ae$
 $H(s) = \frac{y}{u} = \frac{A}{1 + Af} \approx \frac{1}{f}$ if $A \gg 1$

finite A:

$H(s) = \frac{A}{1 + Af} = \frac{A}{Af} \frac{1}{1 + \frac{1}{Af}} = \frac{1}{f} \frac{1}{1 + (\text{loop gain})}$
 difference from 1 is error
 $\approx \frac{1}{f} (1 - \frac{1}{Af})$
 % error

Definitions $V_{cm} = \frac{V_+ + V_-}{2}$
 $V_{dm} = V_+ - V_-$

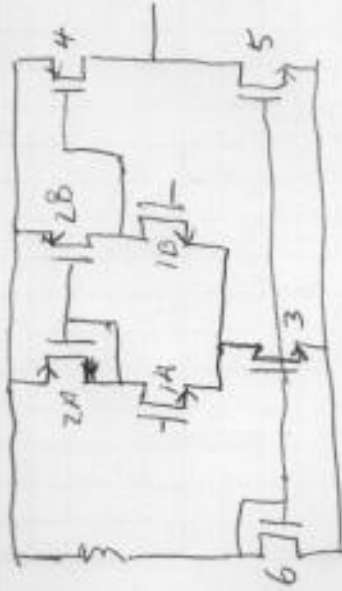
$A = \text{op-amp gain}$

$T = Af = \text{loop gain}$

$\frac{A}{1 + Af} = \text{closed loop gain}$



$V_{dm} = 3 \mu A$
 $mV?$



Device sizing/bias point
 differential gain,
 common mode gain
 I/O range/swing

Input range

$$V_{i, \text{cm}, \text{min}} = V_{ov3} + V_{en} + V_{ov1}$$

$$V_{i, \text{cm}, \text{max}} = V_{D2A} + V_{en}$$

$$= (V_{DD} - |V_{tp}| + V_{ov2}) + V_{en}$$

$$\approx V_{DD} - |V_{ov2}|$$

Since $V_{en} \approx -V_{ep}$ typically

$$V_{o, \text{max}} = V_{DD} - |V_{ov2}|$$

$$V_{o, \text{min}} = V_{icm} - V_{en}$$

Sizing & bias

$$I_{D2A} + I_{D2B} = I_{D3}$$

the mirror sets up just the right safe voltage (V_{G2A}) to pass this current

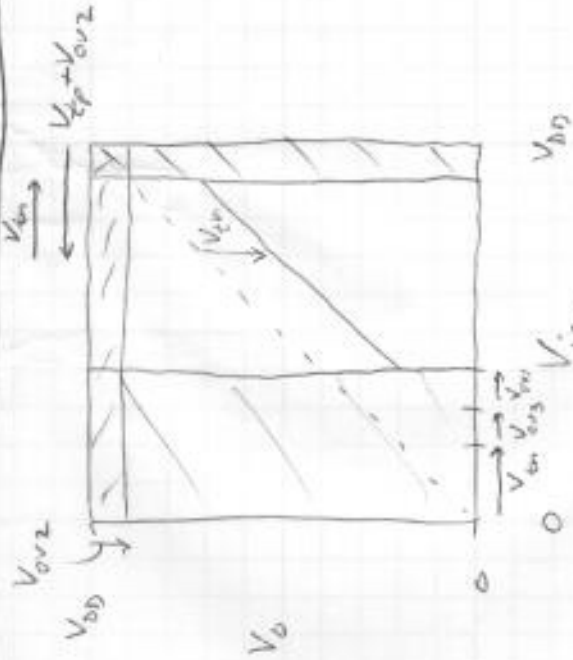
This is also the DC bias point of V_{G4}

$$\text{If } \left(\frac{W}{L}\right)_5 = \left(\frac{W}{L}\right)_3 \text{ then } I_{D1} = I_{D5} \approx I_{D3}$$

M4 must carry the same current as M2A & B

$$\text{so make } \left(\frac{W}{L}\right)_4 = \left(\frac{W}{L}\right)_{2A} + \left(\frac{W}{L}\right)_{2B} = 2 \left(\frac{W}{L}\right)_{2A}$$

$$\text{If } \left(\frac{W}{L}\right)_5 = \alpha \left(\frac{W}{L}\right)_3 \quad \left(\frac{W}{L}\right)_4 = 2\alpha \left(\frac{W}{L}\right)_{2A}$$



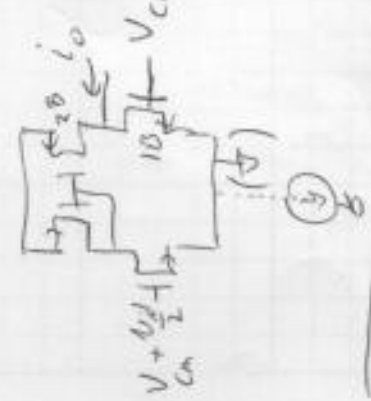
How does 2-stage change this picture?

$$V_{o, \text{min}} = V_{ov5}$$

Differential gain

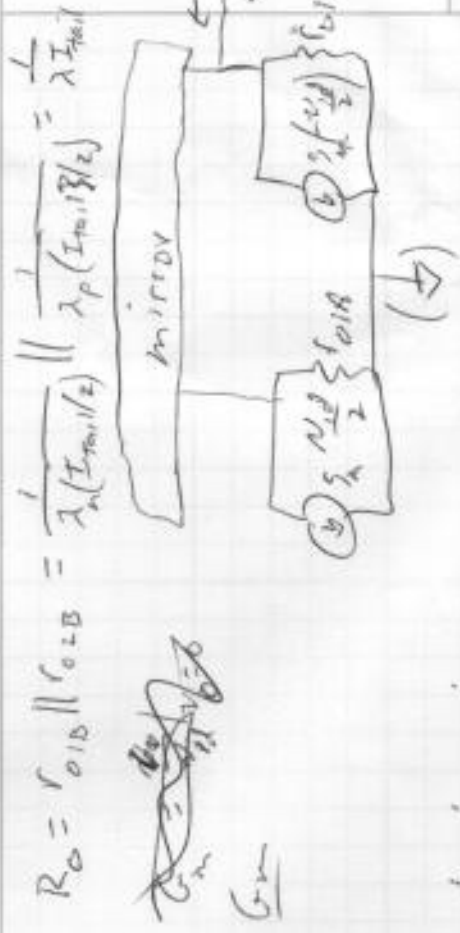
common false assumption gives the right answer & some intuition.

Assume (incorrectly) that the tail is virtual ground



$$G_m = \frac{i_o}{v_{id}} \Big|_{v_o=0}$$

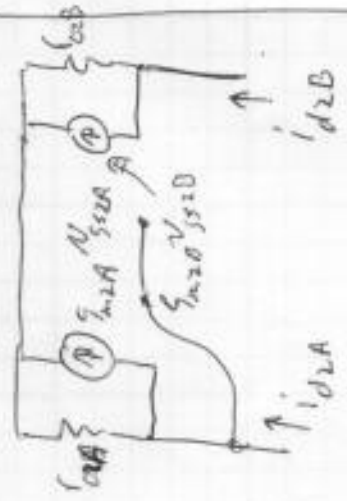
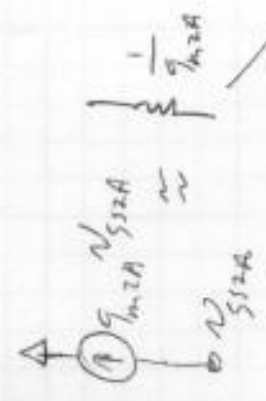
$$R_o = \frac{v_o}{i_o} \Big|_{v_{id}=0}$$



$$i_o = i_{d1B} + i_{d2B}$$

$$i_{d1B} = g_m \left(\frac{v_{id}}{2} \right) = - \frac{g_m v_{id}}{2}$$

$$R_o = r_{o1B} || r_{o2B} = \frac{1}{\lambda_n (I_{tail}/2)} || \frac{1}{\lambda_p (I_{tail}/2)} = \frac{1}{\lambda I_{tail}}$$



$$i_{d2B} = g_m2B v_{SS2B} \Big|_{\text{mirror}}$$

$$= g_m2B v_{SS2A}$$

$$= g_m2B \left(i_{d2A} \frac{1}{g_m2A} \right)$$

$$= i_{d2A}$$

$$i_{d2A} = -i_{d1A} = -g_m \frac{v_{id}}{2}$$

$$i_o = i_{d1B} + i_{d2B} = - \frac{g_m v_{id}}{2} - \frac{g_m v_{id}}{2} = -g_m v_{id}$$

$$= -g_m v_{id}$$

$$A_{v1} = -G_m R_o = +g_m \left(r_{o1} || r_{o2} \right) = 2 \left(\frac{I_{tail}/2}{V_{ov}} \right) \frac{1}{\lambda I_{tail}}$$

$$= \frac{1}{\lambda} \frac{V_A}{V_{ov}} = \frac{V_A}{V_{ov}}$$