

## Gram Schmidt Process

Before we begin, let's remind ourselves that the following subspaces are equivalent for any pairs of linearly independent vectors  $\vec{v}_1, \vec{v}_2$ :

- $\text{span}(\vec{v}_1, \vec{v}_2)$
- $\text{span}(\vec{v}_1, \alpha\vec{v}_2)$
- $\text{span}(\vec{v}_1, \vec{v}_1 + \vec{v}_2)$
- $\text{span}(\vec{v}_1, \vec{v}_1 - \vec{v}_2)$
- $\text{span}(\vec{v}_1, \vec{v}_2 - \alpha\vec{v}_1)$

Now what should  $\alpha$  be if we would like  $\vec{v}_1$  and  $\vec{v}_2 - \alpha\vec{v}_1$  to be orthogonal to each other? Intuitively,  $\alpha\vec{v}_1$  should be the projection of  $\vec{v}_2$  onto  $\vec{v}_1$ . Let's solve this algebraically using the definition of orthogonality:

$$\vec{v}_1 \text{ and } \vec{v}_2 - \alpha\vec{v}_1 \text{ are orthogonal} \tag{1}$$

$$\Leftrightarrow \vec{v}_1^T (\vec{v}_2 - \alpha\vec{v}_1) = 0 \tag{2}$$

$$\Leftrightarrow \vec{v}_1^T \vec{v}_2 - \alpha \|\vec{v}_1\|^2 = 0 \tag{3}$$

$$\Leftrightarrow \alpha = \frac{\vec{v}_1^T \vec{v}_2}{\|\vec{v}_1\|^2} \tag{4}$$

**Definition 17.1 (Orthonormal):** A set of vectors  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is orthonormal if all the vectors are mutually orthogonal to each other and all are of unit length.

Gram Schmidt is an algorithm that takes a set of linearly independent vectors  $\{\vec{v}_1, \dots, \vec{v}_n\}$  and generates an orthonormal set of vectors  $\{w_1, \dots, w_n\}$  that span the same vector space as the original set. Concretely,  $\{w_1, \dots, w_n\}$  needs to satisfy the following:

- $\text{span}(\{v_1, \dots, v_n\}) = \text{span}(\{w_1, \dots, w_n\})$
- $\{w_1, \dots, w_n\}$  is an orthonormal set of vectors

Now let's see how we can do this with a set of three vectors  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  that is linearly independent of each other.

- **Step 1:** Find unit vector  $\vec{w}_1$  such that  $\text{span}(\{\vec{w}_1\}) = \text{span}(\{\vec{v}_1\})$ .  
Since  $\text{span}(\{\vec{v}_1\})$  is a one dimensional vector space, the unit vector that span the same vector space would just be the normalized vector point at the same direction as  $\vec{v}_1$ . We have

$$\vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|}. \quad (5)$$

- **Step 2:** Given  $\vec{w}_1$  from the previous step, find  $\vec{w}_2$  such that  $\text{span}(\{\vec{w}_1, \vec{w}_2\}) = \text{span}(\{\vec{v}_1, \vec{v}_2\})$  and orthogonal to  $\vec{w}_1$ . We know that  $\vec{v}_2 - (\vec{v}_2^T \vec{w}_1) \vec{w}_1$  (the projection of  $\vec{v}_2$  on  $\vec{w}_1$ ) would be orthogonal to  $\vec{w}_1$  as seen earlier. Hence, a vector  $\vec{e}_2$  orthogonal to  $\vec{w}_1$  where  $\text{span}(\{\vec{w}_1, \vec{e}_2\}) = \text{span}(\{\vec{v}_1, \vec{v}_2\})$  is

$$\vec{e}_2 = \vec{v}_2 - (\vec{v}_2^T \vec{w}_1) \vec{w}_1. \quad (6)$$

Normalizing, we have  $\vec{w}_2 = \frac{\vec{e}_2}{\|\vec{e}_2\|}$ .

- **Step 3:** Now given  $\vec{w}_1$  and  $\vec{w}_2$  in the previous steps, we would like to find  $\vec{w}_3$  such that  $\text{span}(\{\vec{w}_1, \vec{w}_2, \vec{w}_3\}) = \text{span}(\{\vec{v}_1, \vec{v}_2, \vec{v}_3\})$ . We know that the projection of  $\vec{v}_3$  onto the subspace spanned by  $\vec{w}_1, \vec{w}_2$  is

$$(\vec{v}_3^T \vec{w}_2) \vec{w}_2 + (\vec{v}_3^T \vec{w}_1) \vec{w}_1. \quad (7)$$

We know that

$$\vec{e}_3 = \vec{v}_3 - (\vec{v}_3^T \vec{w}_2) \vec{w}_2 - (\vec{v}_3^T \vec{w}_1) \vec{w}_1 \quad (8)$$

is orthogonal to  $\vec{w}_1$  and  $\vec{w}_2$ . Normalizing, we have  $\vec{w}_3 = \frac{\vec{e}_3}{\|\vec{e}_3\|}$ .

We can generalize the above procedure for any number of linearly independent vectors as follows:

1: **Inputs:**

- A set of linearly independent vectors  $\{\vec{v}_1, \dots, \vec{v}_n\}$ .

2: **Outputs:**

- An orthonormal set of vectors  $\{\vec{w}_1, \dots, \vec{w}_n\}$  where  $\text{span}(\{\vec{v}_1, \dots, \vec{v}_n\}) = \text{span}(\{\vec{w}_1, \dots, \vec{w}_n\})$ .

3: **procedure** GRAM SCHMIDT( $\vec{v}_1, \dots, \vec{v}_n$ )

4:  $\vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|}$

5: **for**  $i = 2 \dots n$  **do**

6:  $\vec{e}_i \leftarrow \vec{v}_i - \sum_{j=1}^{i-1} (\vec{v}_i^T \vec{e}_j) \vec{w}_j$

7:  $\vec{w}_i \leftarrow \frac{\vec{e}_i}{\|\vec{e}_i\|}$

8: **end for**

9: **end procedure**