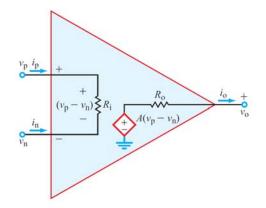


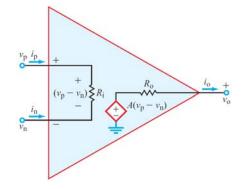
### **Equivalent Circuit and Specifications**



Parameter	Typical Range	Ideal Op Amp
Open-loop gain A Input resistance $R_i$ Output resistance $R_o$ Supply voltage $V_{cc}$	$\begin{array}{c} 10^{4} \ {\rm to} \ 10^{8} \ ({\rm V/V}) \\ 10^{6} \ {\rm to} \ 10^{13} \ \Omega \\ 1 \ {\rm to} \ 100 \ \Omega \\ 5 \ {\rm to} \ 24 \ {\rm V} \end{array}$	$ \begin{array}{c} \infty \\ \infty \ \Omega \\ 0 \ \Omega \end{array} \\ As specified by manufacturer $

- In other words, Op Amps are *really* close to ideal.
- Note that the output voltage swing is typically limited to around  $\mathrm{V}_{\mathrm{CC}}$

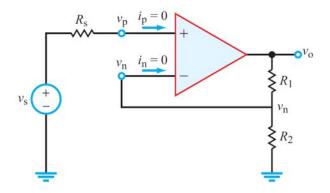
### But how should we use an Op Amp?



- The gain is huge, and the dynamic range is limited. This would normally limit the input signal to a few  $\mu V!$
- Additionally, the gain is usually very poorly controlled, and can vary a lot with temperature, etc., and from part to part.
- Instead, we use "negative feedback" to bring the gain under control.

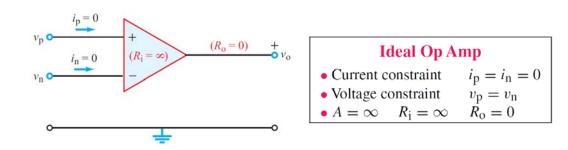
### What is negative feedback

- Conceptually, it is taking a "piece" of the output, and providing it to the  $V_N$  or "inverting" input
- Since the output is  $A_V \cdot (V_P V_N)$ , the larger the output, the more the feedback "piece" works to reduce the ouput.
- Overall, this reduces the "effective" gain of the amplifier.
- In fact, if we assume  $A_V$  is  $\infty,$  then the ultimate result is that  $V_P$  must be equal to  $V_N$



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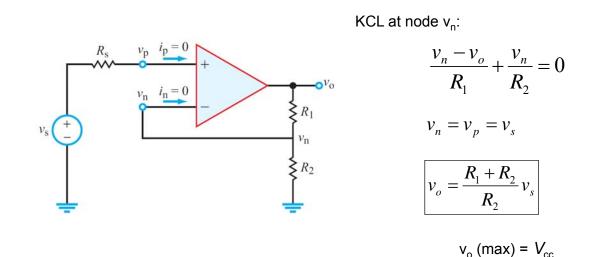
### Ideal Op Amps with Negative Feedback



Start with the following "golden rules"

- $V_P = V_N$  (due to effect of infinite gain and negative feedback)
- $I_p = I_n = 0$  (due to infinite input resistance of ideal Op Amp)
- Since the output has zero output resistance, you won't actually need a KCL at the output node, since the output voltage is entirely determined by the input voltages and feedback conditions

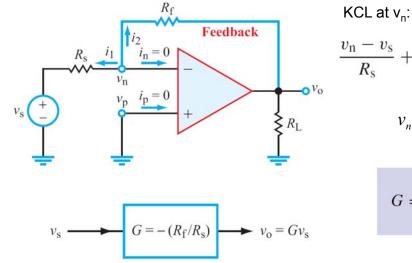
### **Non-inverting Amplifier**



Interestingly, the gain of the Op Amp, A<sub>V</sub>, no longer appears in the equation. This is a benefit of feedback with nearly ideal amplifiers... we can achieve the desired result purely by the choice of external components

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## **Inverting Amplifier**

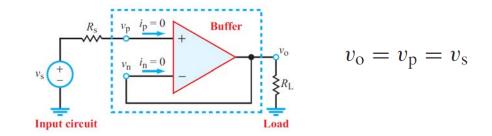


 $\frac{v_{\rm n} - v_{\rm s}}{R_{\rm s}} + \frac{v_{\rm n} - v_{\rm o}}{R_{\rm f}} + i_{\rm n} = 0.$  $v_n = v_p = 0$ 

$$G = \frac{v_{\rm o}}{v_{\rm s}} = -\left(\frac{R_{\rm f}}{R_{\rm s}}\right).$$

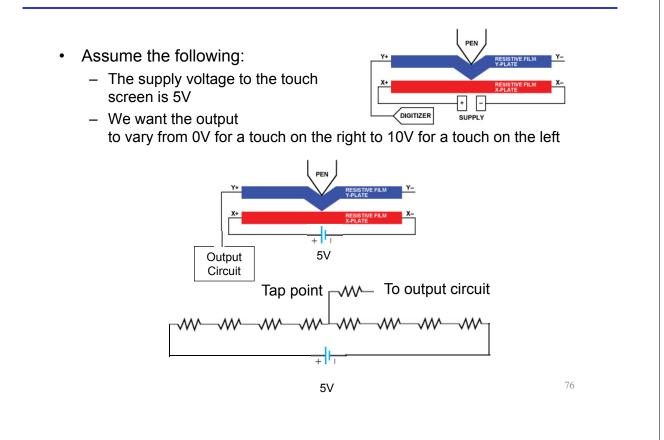
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### Voltage Follower or Buffer



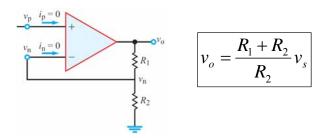
#### $\boldsymbol{v}_{o}$ is immune to input and load resistors

## Design Exercise: Touch Screen Sensor



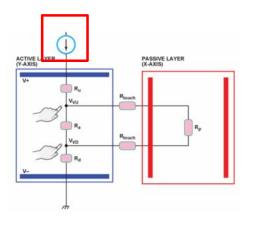
## Design Exercise: Touch Screen Sensor

• We want a non-inverting amplifier with a gain of 2



# Design Exercise: Current Source

• In the multi-touch version, we needed a current source

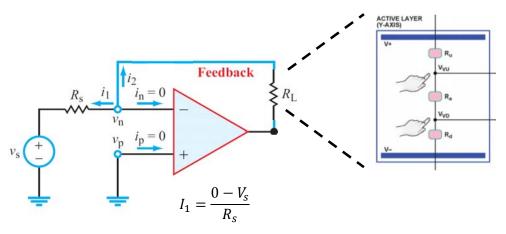


• In this next exercise, we'll use an Op Amp to convert a battery (which is a voltage source) into a current source

## **Design Exercise: Current Source**

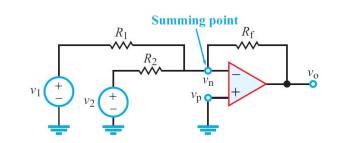
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- · Remember the golden rules for an ideal Op Amp
  - $-V_{-}=V_{+}$
  - I<sub>in</sub> = 0
- · We have to use negative feedback to use the golden rules



Since  $I_n = 0$ , then  $I_1 = I_2$ . In other words, we have made a constant current source with an output current of  $-V_S / R_S$  79

## **Optional Exercises: Summing Amplifier**



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### **Optional Exercises: Difference Amplifier**

