

systems

system Transform input into output

$$T[x(n_1, n_2)] = y(n_1, n_2)$$

input *output*

$$\begin{aligned} \text{- Linear : } & T \left\{ a x_1(n_1, n_2) + b x_2(n_1, n_2) \right\} \\ & = a T \left\{ x_1(n_1, n_2) \right\} + b T \left\{ x_2(n_1, n_2) \right\} \end{aligned}$$

Shift Invariance

$$- \frac{\text{If } \left\{ x(n_1, n_2) \right\} = y(n_1, n_2)}{\text{then } \dots}$$

$$\text{Then } T \left[x(n_1 - k_1, n_2 - k_2) \right] = Y(n_1 - k_1, n_2 - k_2)$$

2D- LSI system .

LSI \longrightarrow Impulse response.

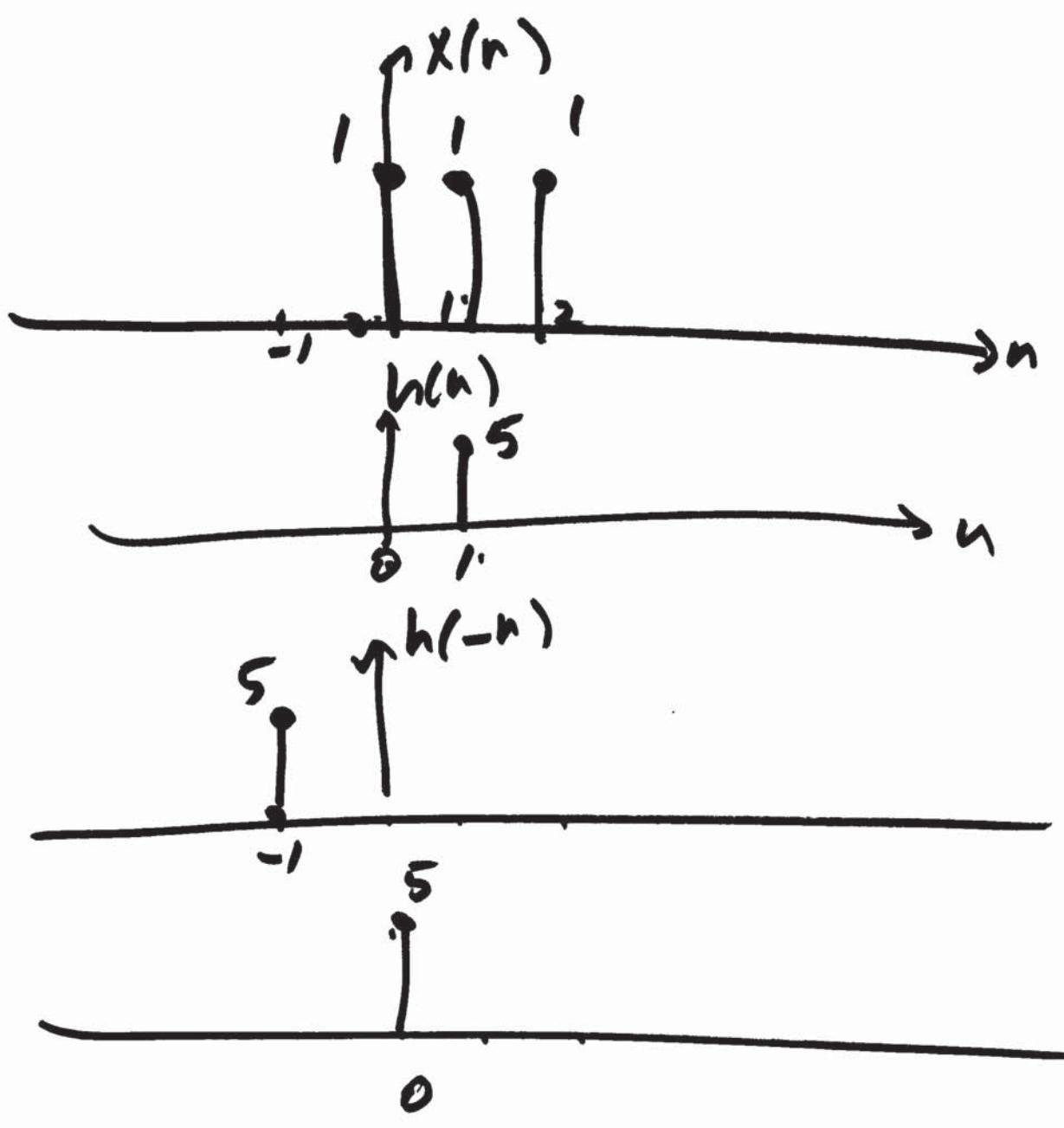
$$h(n_1, n_2)$$

- endles T_0 entirely characterizes an LSI system.
- tells you output given input.

$$y(n_1, n_2) = X * h \xrightarrow{\text{Convolution}}$$

$$y(n_1, n_2) = \sum_{k_1} \sum_{k_2} x(k_1, k_2) h(n_1 - k_1, n_2 - k_2)$$

$$y(n) = \sum_k x(k) h(n-k) \quad 1D$$



$$y(0) = 0$$

$$y(1) = 5$$

Separable LSI system

$$h(n_1, n_2) = \begin{bmatrix} h_1(n_1) & h_2(n_2) \end{bmatrix}$$

$x(n_1, n_2)$ $N \times N$

h : $M \times M$.



general:

$$y(n_1, n_2) = \sum_{k_1} \sum_{k_2} x(k_1, k_2) h(n_1 - k_1, n_2 - k_2)$$

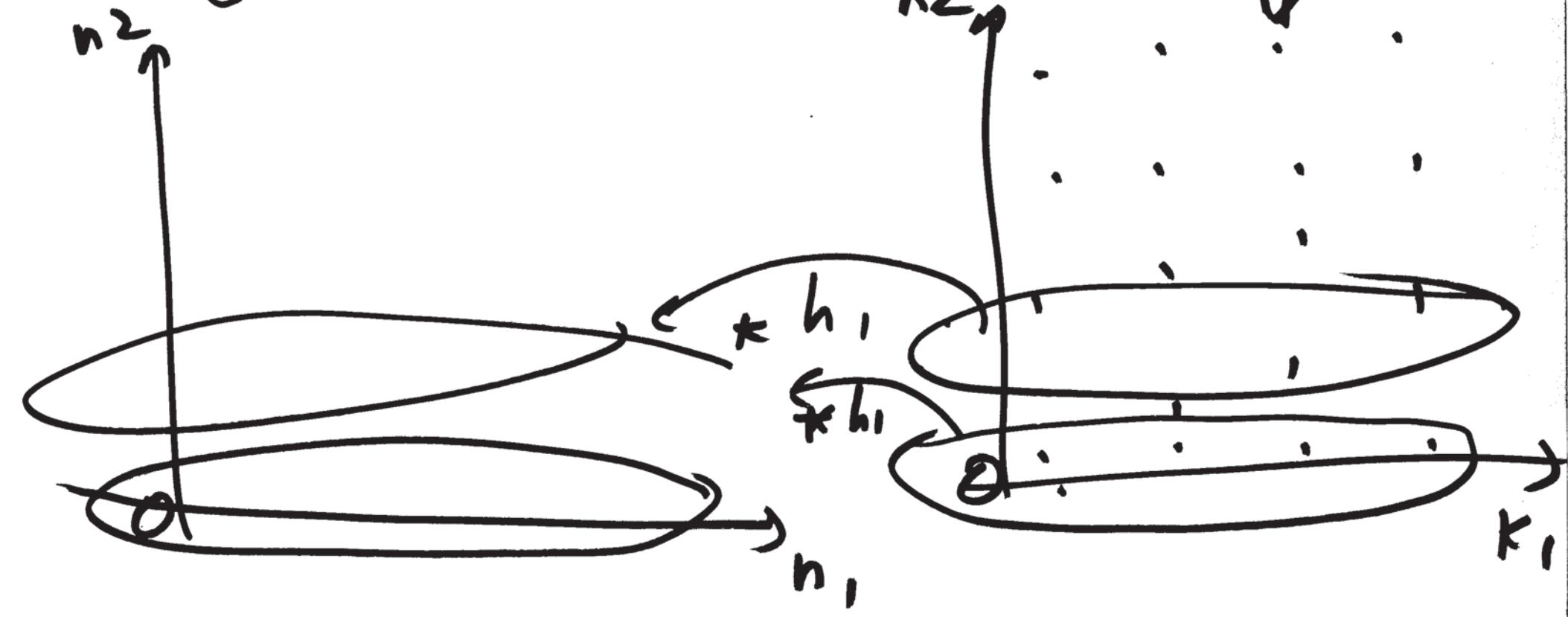
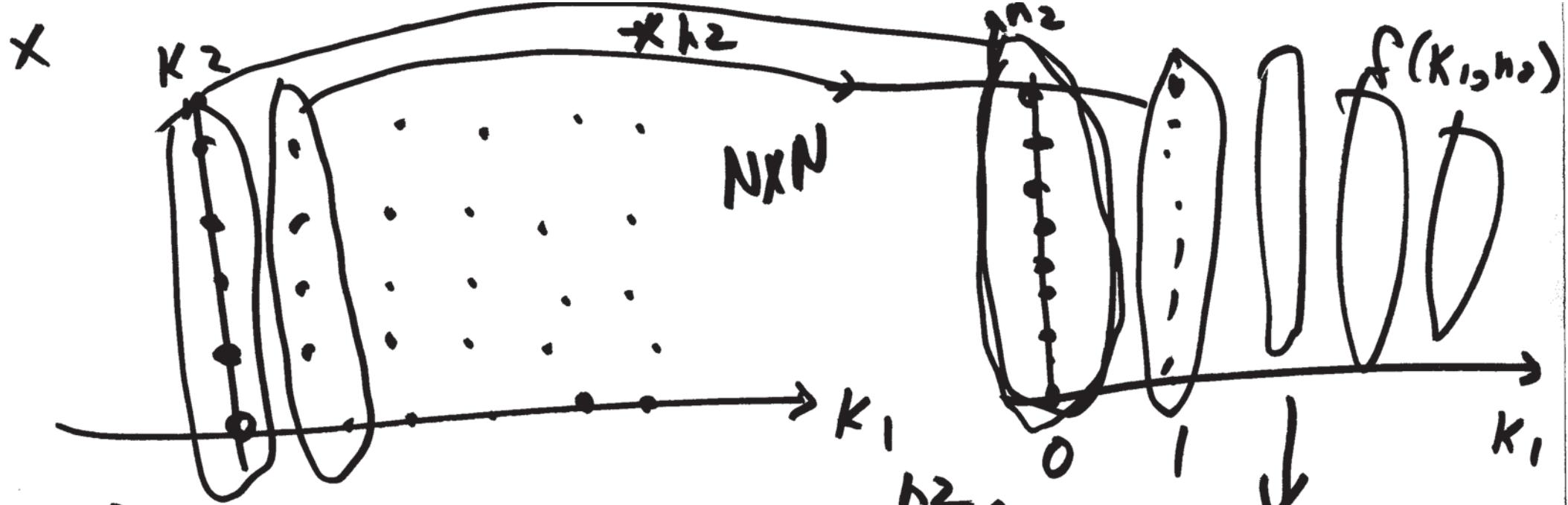
sep. sys.

$$= \sum_{k_1} \sum_{k_2} x(k_1, k_2) h_1(n_1 - k_1) h_2(n_2 - k_2)$$

$$= \sum_{k_1} h_1(n_1 - k_1)$$

$$\sum_{k_2} x(k_1, k_2) h_2(n_2 - k_2)$$

$f(k_1, n_2) =$
 $x(k_1) * h_2$



5

Sunji

1. Series of 1D convolites To get.

$f(k_1, n_2)$:

N columns \rightarrow N convolution.
 NM oper / convolit

$N^2 M$ op To build f

② Series of 1-D conv To get $g(f(n, n_1))$

N rows \rightarrow N convolite.
 NM op / convol

$N^2 M$

Total $2 \cdot N^2 M$.

LSI system

- * impulse response. $\rightarrow h(n_1, n_2)$
- + stability of LSI system.
- + BIBO stability \rightarrow
 - bounded input, bounded output.
- * Can show , $h(n_1, n_2) \rightarrow$ be BIBO stable .
 - necess + suff. cond.
$$\sum_{n_1=-\infty}^{+\infty} \sum_{n_2=-\infty}^{+\infty} |h(n_1, n_2)| < \infty$$

Finite impulse response

(FIR).

→ Always stable.

z^{-2}

z^{-1}

z^1

Infinite impulse Response

(IIR)

Some stable, some unstable.

z^{-2}

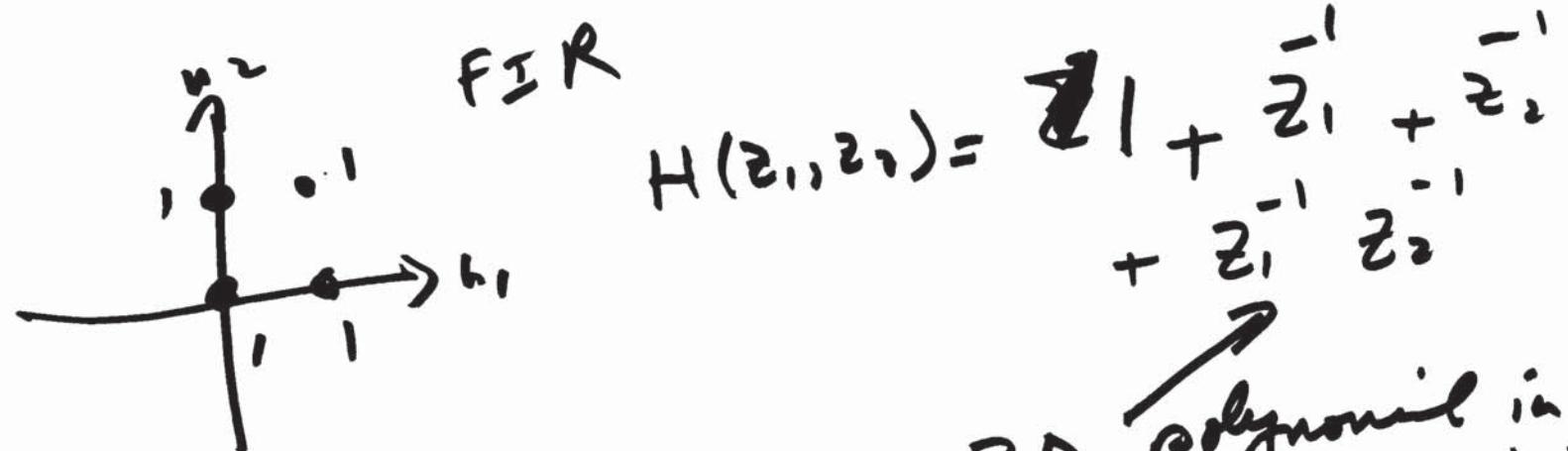
z^{-1}

z^1

$$\sum_{n=0}^{\infty} \frac{1}{n} \text{ blows up} \quad \sum_{n=0}^{\infty} \frac{1}{n^2} \text{ does not blow up.}$$

$\rightarrow h(n_1, n_2) \xrightarrow{\text{Z.T.}} \sum_{n_1} \sum_{n_2} h(n_1, n_2) z_1^{-n_1} z_2^{-n_2}$

$= H(z_1, z_2) = \sum_{n_1} \sum_{n_2} h(n_1, n_2) z_1^{-n_1} z_2^{-n_2}$



Z.D.F.T.

$$H(\omega_1, \omega_2) = \sum_{n_1} \sum_{n_2} h(n_1, n_2) e^{j\omega_1 n_1} e^{j\omega_2 n_2}$$



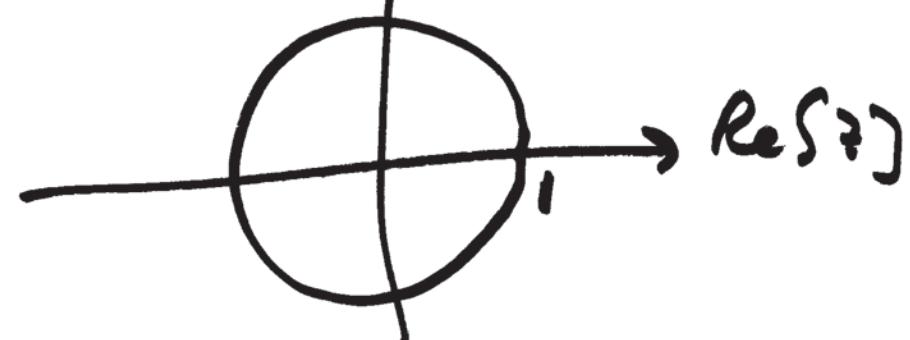
$$H(\omega_0) = [H(\omega)]_{\omega=\omega_0} = \left[\sum_{n=-P}^{+P} h(n) e^{-jn\omega_0} \right]_{\omega=\omega_0}$$

NOT a fn
of n

$$H(\omega) = \sum_{n=-\infty}^{+\infty} h(n) e^{-j\omega n} \quad \Rightarrow$$

$$H(z) = \sum_{n=-\infty}^{+\infty} h(n) z^{-n}$$

$$H(j\omega) = [H(z)]_{z=e^{j\omega}} \quad \tilde{x}_n(z)$$



$$H(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} \rightarrow h(n) = \dots$$

ROC: S outside circle

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 - \frac{1}{2}z^{-1}}$$

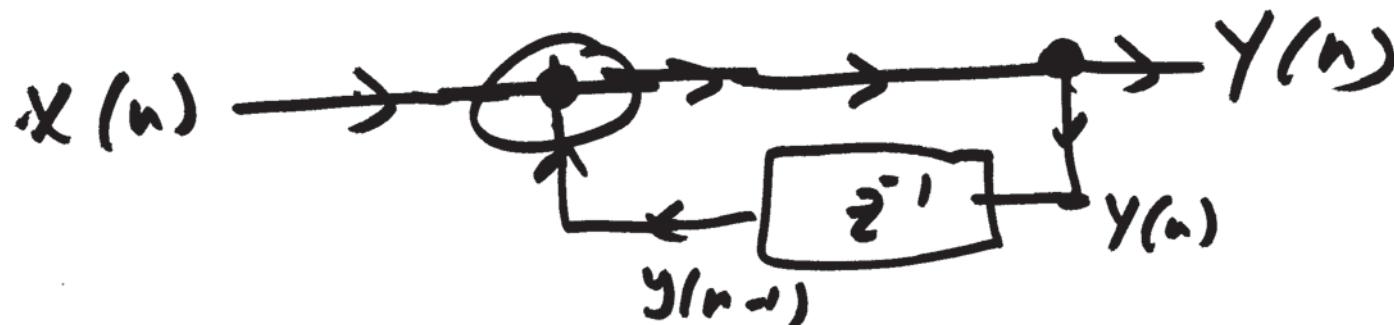
$\sum_{n=-\infty}^{\infty} |h(n)| < \infty$

$BIBO$

$$Y(z) \left[1 - \frac{1}{2} z^{-1} \right] = X(z)$$

~~$$y(n) - \frac{1}{2} y(n-1) = x(n)$$~~

$$y(n) = x(n) + \frac{1}{2} y(n-1)$$



pole

$$1 - \frac{1}{2} z^{-1} = 0 \Rightarrow z = \frac{1}{2} z^{-1}$$

$$z = \bar{z} \Rightarrow z = \frac{1}{2}$$

$R(z) = \frac{1}{2} u(n)$

Unstable

$$h(n) = 2^n u(n)$$

$$= 1 + 2 + 4 + 8 + \dots$$

$$H(z) = \frac{1}{1 - 2z^{-1}}$$

$$M(z) := \frac{1}{1 + 5z^{-1} + 3z^2 + 9z^{-3} + 12z^{-4} + 18z^{-5}}$$

2D polynomial can always
be factored.

→ Fundamental Thm of Algebra.

Any 1-D polynomial ~~cont~~ of deg. n
 can be factored into n
 polynomials of deg. 1.

$$= \frac{1}{\prod_{i=1}^n (1 - \alpha_i z^{-1})}$$

Story in 2D

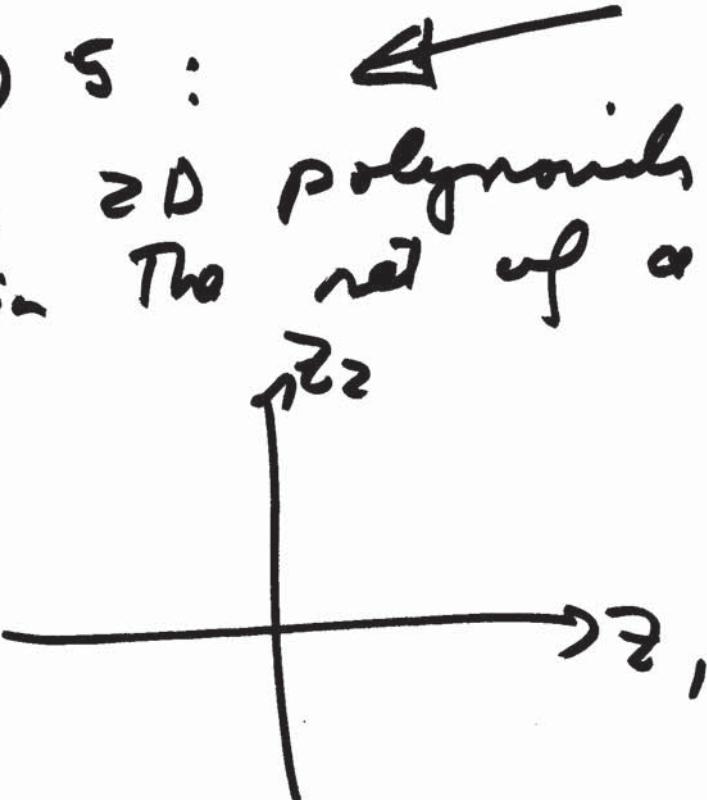
$$\underline{\text{IIR}} : \quad H(z_1, z_2) = \frac{1}{P(z_1^{-1}, z_2^{-1})}$$

$$P(z_1^{-1}, z_2^{-1}) = (1 - z_1^{-1})(1 - z_2^{-1})$$

Thm: Hayes 1980 says: ↗
 Set up reducible 2D polynomials is
 up measure 0 in the set of all 2D.
 polynomials.

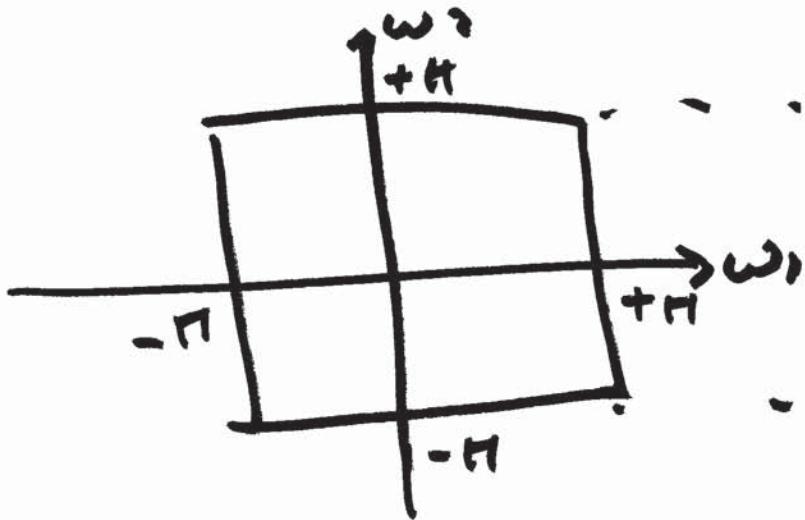
2D → unit bisurface

~~P(z₁, z₂)~~



Do The pole surface cross The
unit Bi-surface? \Rightarrow some Thus
covered later.

Bounding stability in 2D is hard

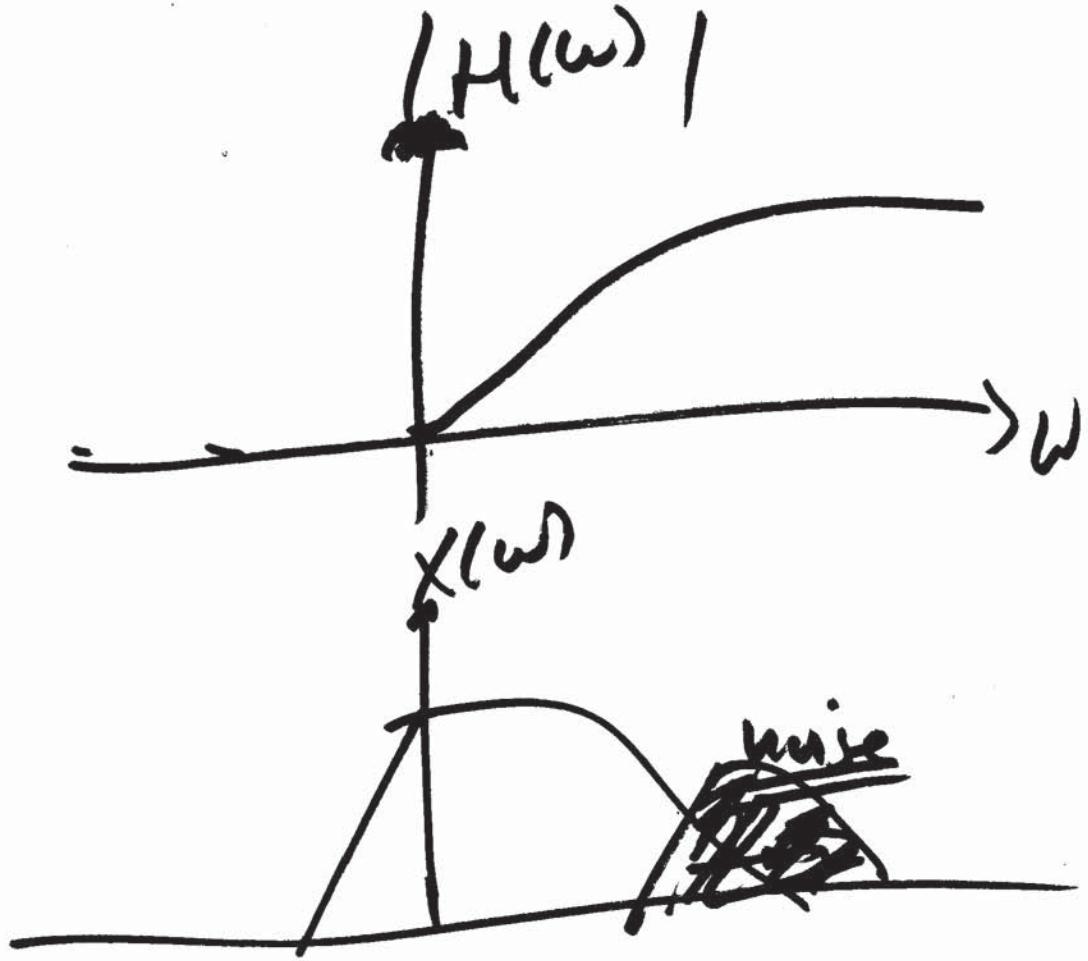


$x(\omega_1, \omega_2) \longrightarrow$

\nearrow \nearrow
 discrete
integer

$\tilde{x}(\omega_1, \omega_2)$

\nearrow \nearrow
 Real variable.



Signal.

