

Parallel-Plate Capacitive Nonlinearity

• **Example:** clamped-clamped laterally driven beam with balanced electrodes

• **Nomenclature:**

V_a or v_A $v_a = |v_a| \cos \omega t$ V_d V_d

V_A V_a or $v_A = V_A + v_a$

Total Value AC or Signal Component (lower case variable; lower case subscript)
DC Component (upper case variable; upper case subscript)

Conductive Structure

Electrode

k_m

d_1

m

x

F_{dl}

V_1

V_P

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Voltage-Controllable Center Frequency

Anchor Micromechanical Resonator Electrode Silicon Nitride

V_P

Isolation Oxide

Silicon Substrate

• **Quadrature force \Rightarrow voltage-controllable electrical stiffness:**

$k_e = \frac{\epsilon_0 A_e}{d^3} V_P^2$ Electrode Overlap Area

Gap

$f_0 = \frac{1}{2\pi} \sqrt{\frac{k_m - k_e}{m_f}}$

Frequency [MHz]

DC-Bias [V_P]

$A_e = 88 \mu m^2$

$d = 1000 \text{ \AA}$

1.1%

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Microresonator Thermal Stability

Fractional frequency change [ppm]

Temperature [$^{\circ}C$]

AT-Cut Quartz Crystal at various angles

35°05'

35°10'

35°15'

35°20'

35°25'

35°30'

Drive electrode

Anchor

Sense electrode

Resonant beam

Poly-Si uresonator -17ppm/ $^{\circ}C$

-1.7ppm/ $^{\circ}C$

• Thermal stability of poly-Si micromechanical resonator is 10X worse than the worst case of AT-cut quartz crystal

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Geometric-Stress Compensation

• Use a temperature dependent mechanical stiffness to null frequency shifts due to Young's modulus thermal dep.

[Hsu et al, IEDM'00]

electrode

bias

electrode

W_1

W_2

L_1

L_2

$d = 1038 \text{ \AA}$

2.5 μm

2.2 μm

Amplitude [dB]

Frequency [MHz]

$Q = 10,317$

Fractional Frequency Change [ppm]

Temperature [K]

-2.5ppm/ $^{\circ}C$

L_2/L_1

60/40

50/40

70/40

40/40

80/40

30/40

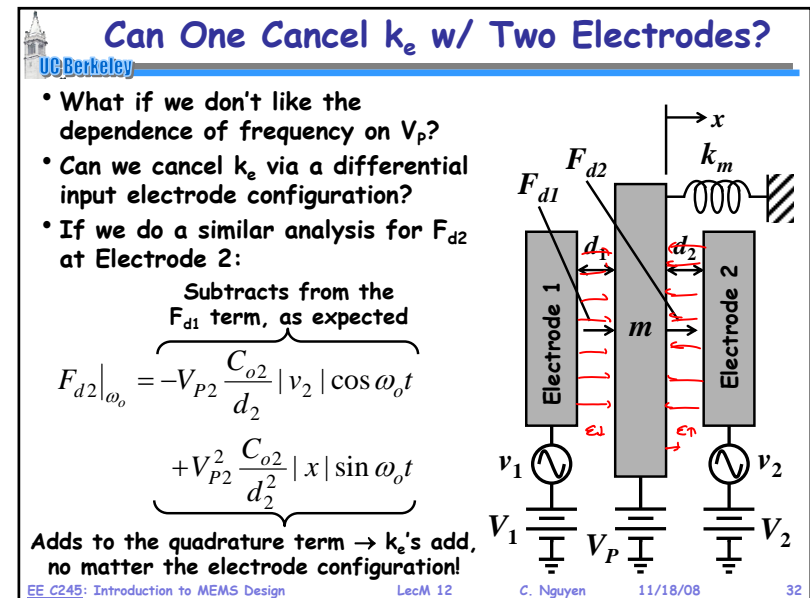
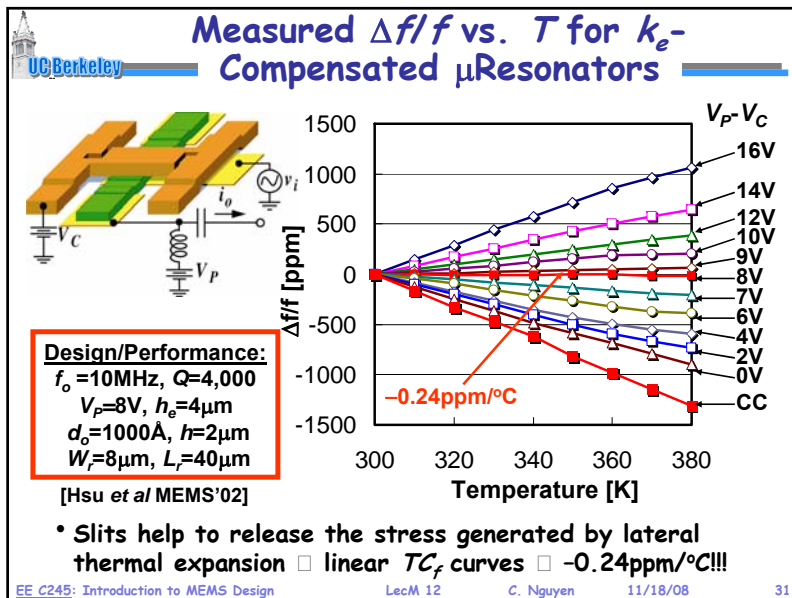
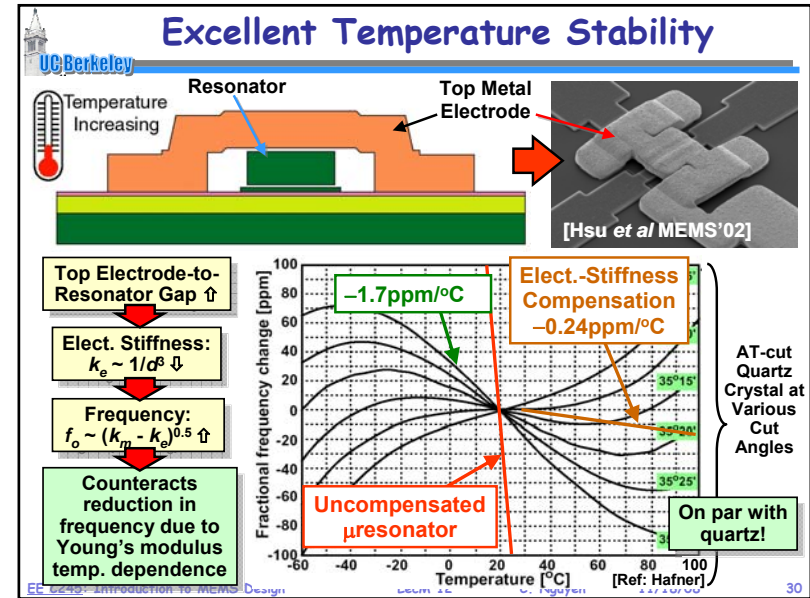
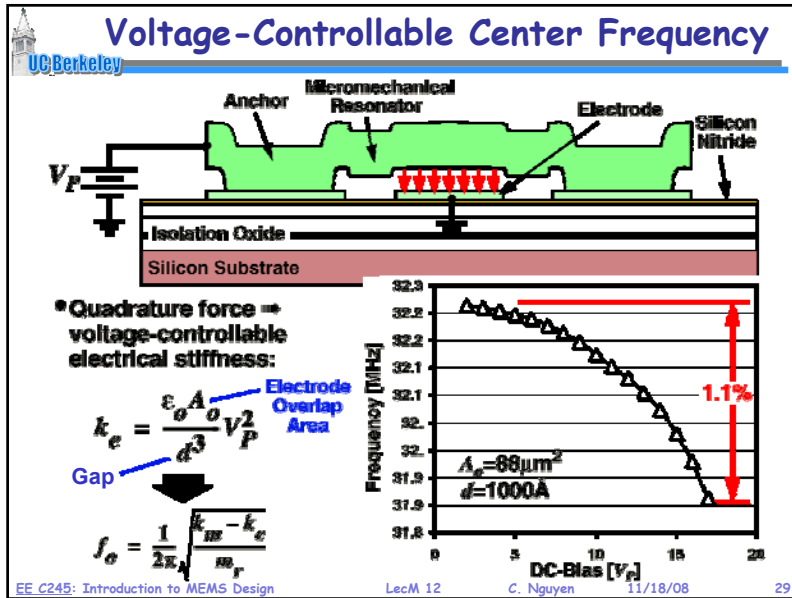
• **Problems:**

stress relaxation

compromised design flexibility

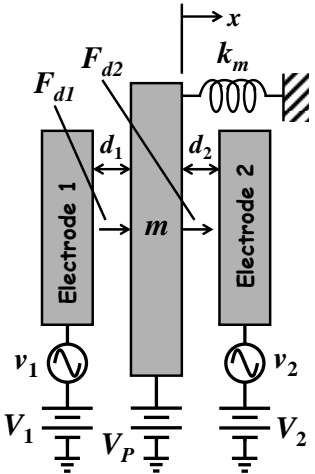
[Hsu et al IEDM 2000]

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Problems With Parallel-Plate C Drive

- Nonlinear voltage-to-force transfer function
 - Resonance frequency becomes dependent on parameters (e.g., bias voltage V_P)
 - Output current will also take on nonlinear characteristics as amplitude grows (i.e., as x approaches d_0)
 - Noise can alias due to nonlinearity
- Range of motion is small
 - For larger motion, need larger gap ... but larger gap weakens the electrostatic force
 - Large motion is often needed (e.g., by gyroscopes, vibromotors, optical MEMS)



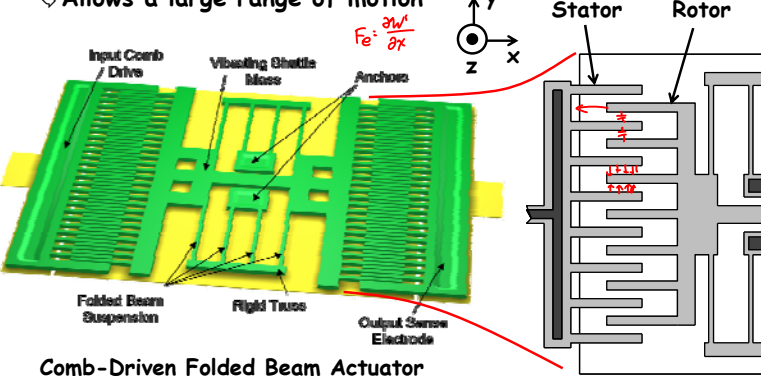
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Electrostatic Comb Drive

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Electrostatic Comb Drive

- Use of comb-capacitive transducers brings many benefits
 - Linearizes voltage-generated input forces
 - (Ideally) eliminates dependence of frequency on dc-bias
 - Allows a large range of motion



Comb-Driven Folded Beam Actuator

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