


EE C245 - ME C218 Introduction to MEMS Design Fall 2012

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Lecture Module 1: Admin & Overview


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Instructor: Prof. Clark T.-C. Nguyen

- Education: Ph.D., University of California at Berkeley, 1994
- 1995: joined the faculty of the Dept. of EECS at the University of Michigan
- 2006: (came back) joined the faculty of the Dept. of EECS at UC Berkeley
- Research: exactly the topic of this course, with a heavy emphasis on vibrating RF MEMS
- Teaching: (at the UofM) mainly transistor circuit design courses; (UC Berkeley) 140, 143, 243, 245
- 2001: founded Discera, the first company to commercialize vibrating RF MEMS technology
- Mid-2002 to 2005: DARPA MEMS program manager
 - ↳ ran 10 different MEMS-based programs
 - ↳ topics: power generation, chip-scale atomic clock, gas analyzers, nuclear power sources, navigation-grade gyros, on-chip cooling, micro environmental control


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Course Overview

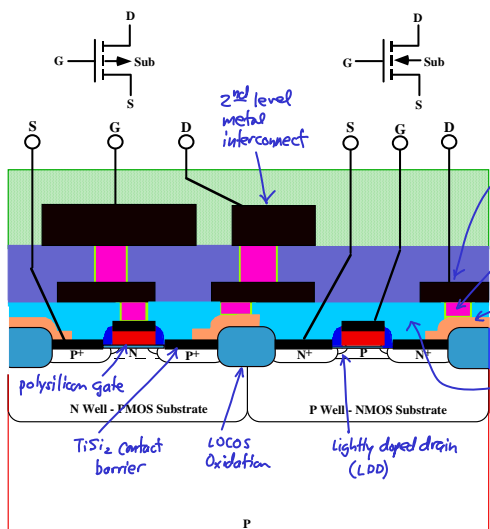
- **Goals of the course:**
 - ↗ Accessible to a broad audience (minimal prerequisites)
 - ↗ Design emphasis
 - Exposure to the techniques useful in analytical design of structures, transducers, and process flows
 - ↗ Perspective on MEMS research and commercialization circa 2010
- **Related courses at UC Berkeley:**
 - ↗ EE 143: Microfabrication Technology
 - ↗ EE 147: Introduction to MEMS
 - ↗ ME 119: Introduction to MEMS (mainly fabrication)
 - ↗ BioEng 121: Introduction to Micro and Nano Biotechnology and BioMEMS
 - ↗ ME C219 - EE C246: MEMS Design
- **Assumed background for EE C245:** graduate standing in engineering or physical/bio sciences

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What Should You Know?

Typical mid-2000's CMOS Process (good down to ~0.25µm)



You should either already know or be able to learn independently & very quickly:

- ① How to deposit or grow those different layers.
- ② How to pattern or otherwise form the shapes of the layers shown.
- ③ What determines the order by which the different layers are formed, e.g., temperature limits, topography limits, etc...

We will review those things, but we will do this very fast!

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What Should You Know?

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Basic Clot. Analysis & Design Using Op Amps

Ex.

Find the transfer function $\frac{V_o}{V_i}(s)$.

Ideal Op Amp Rules: (Apply when there's neg. FB)

- ① $V_i = V_-$
- ② $R_i = \infty$ (infinite input resistance)

Virtual Ground

$R_f \parallel \frac{1}{sC_f} = \frac{R_f}{1 + sR_fC_f}$

$I_i = \frac{V_i}{R_i}$

$V_o = -I_i \left(R_f \parallel \frac{1}{sC_f} \right) = -\frac{V_i}{R_i} \left(R_f \parallel \frac{1}{sC_f} \right) \Rightarrow \frac{V_o}{V_i}(s) = -\frac{R_f}{R_i} \frac{1}{1 + sR_fC_f} = -\frac{R_f}{R_i} \frac{1}{1 + \frac{s}{\omega_b}} = \frac{V_o}{V_i}(s)$

$\omega_b = \frac{1}{R_fC_f}$


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Course Overview

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- The mechanics of the course are summarized in the course handouts, given out in lecture today
 - ↪ Course Information Sheet
 - Course description
 - Course mechanics
 - Textbooks
 - Grading policy
 - ↪ Syllabus
 - Lecture by lecture timeline w/ associated reading sections
 - Midterm Exam: tentatively set for Thursday, Oct. 28
 - Final Exam: Friday, Dec. 17, 7-10 p.m.
 - Change this Final Exam time?
 - Project due date TBD (but near semester's end)

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Lecture Outline

- Reading: Senturia, Chapter 1
- Lecture Topics:
 - ↳ Definitions for MEMS
 - ↳ MEMS roadmap
 - ↳ Benefits of Miniaturization


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MEMS: Micro Electro Mechanical System

- A device constructed using micromachining (MEMS) tech.
- A micro-scale or smaller device/system that operates mainly via a mechanical or electromechanical means
- At least some of the signals flowing through a MEMS device are best described in terms of mechanical variables, e.g., displacement, velocity, acceleration, temperature, flow

Input:
voltage, current
acceleration, velocity
light, heat ...

MEMS

Output:
voltage, current
acceleration, velocity
light, heat, ...

Control:
voltage, current
acceleration
velocity
light, heat, ...

Transducer to Convert **Control** to a **Mechanical Variable** (e.g., displacement, velocity, stress, heat, ...)


[Wu, UCLA]

Angle set by mechanical means to control the path of light

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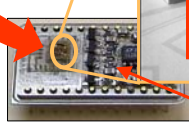
Other Common Attributes of MEMS

- Feature sizes measured in microns or less
- Merges computation with sensing and actuation to change the way we **perceive** and **control** the physical world
- Planar lithographic technology often used for fabrication
 - can use fab equipment identical to those needed for IC's
 - however, some fabrication steps transcend those of conventional IC processing

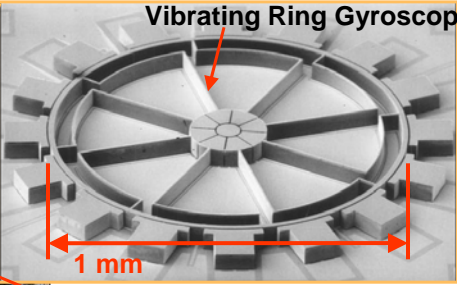


80 mm

Gimballed, Spinning Macro-Gyroscope



MEMS Technology
(for 80X size Reduction)




1 mm

[Najafi, Michigan] Micromechanical Vibrating Ring Gyroscope

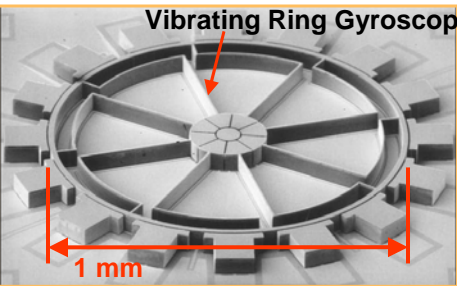
Signal Conditioning Circuits

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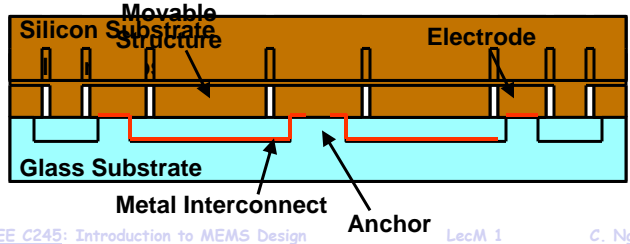
Bulk Micromachining and Bonding

- Use the wafer itself as the structural material
- Adv: very large aspect ratios, thick structures
- Example: deep etching and wafer bonding



1 mm

[Najafi, Michigan] Micromechanical Vibrating Ring Gyroscope



Movable Structure


Silicon Substrate

Electrode

Glass Substrate


Metal Interconnect

Anchor

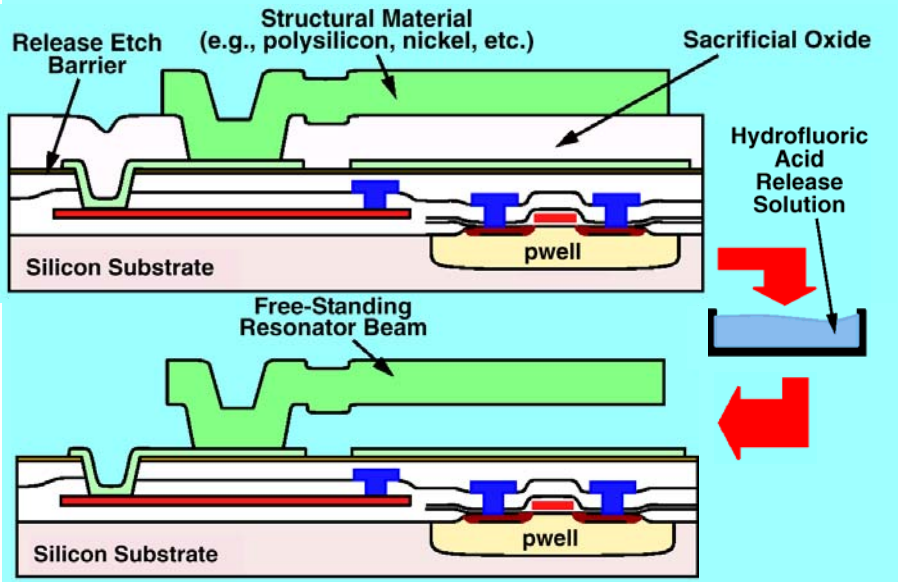


[Pisano, UC Berkeley] Microrotor (for a microengine)

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Surface Micromachining



Release Etch Barrier

Structural Material (e.g., polysilicon, nickel, etc.)

Sacrificial Oxide

Hydrofluoric Acid Release Solution

Silicon Substrate

pwell

Free-Standing Resonator Beam

Silicon Substrate

pwell

- Fabrication steps compatible with planar IC processing


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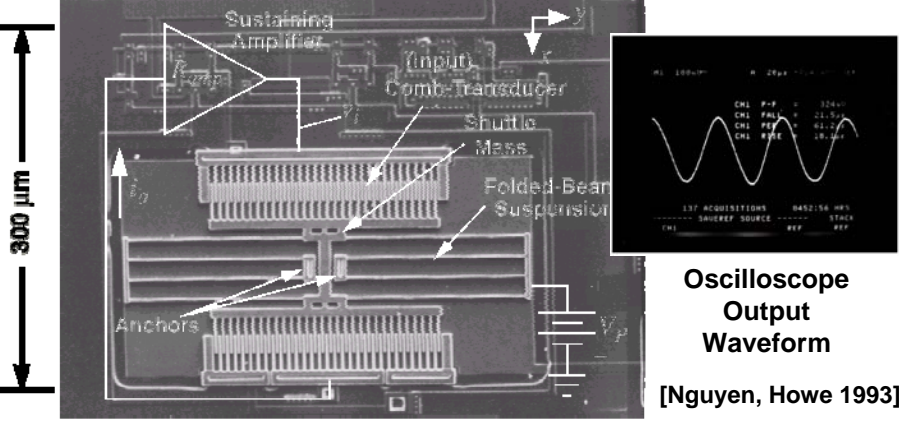
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Single-Chip Ckt/MEMS Integration

- Completely monolithic, low phase noise, high-Q oscillator (effectively, an integrated crystal oscillator)



300 μm

Sustaining Amplifier

Input

Comb. Transducer

Shuttle

Mass

Folded-Beam Suspension

Anchors

Oscilloscope Output Waveform

[Nguyen, Howe 1993]

- To allow the use of $>600^{\circ}\text{C}$ processing temperatures, tungsten (instead of aluminum) is used for metallization


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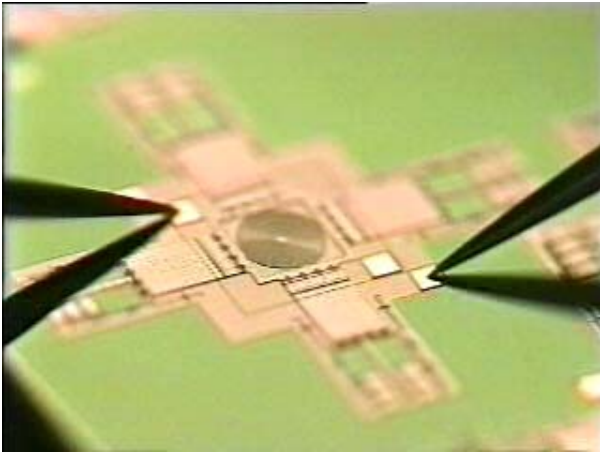
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3D Direct-Assembled Tunable L



[Ming Wu, UCLA]

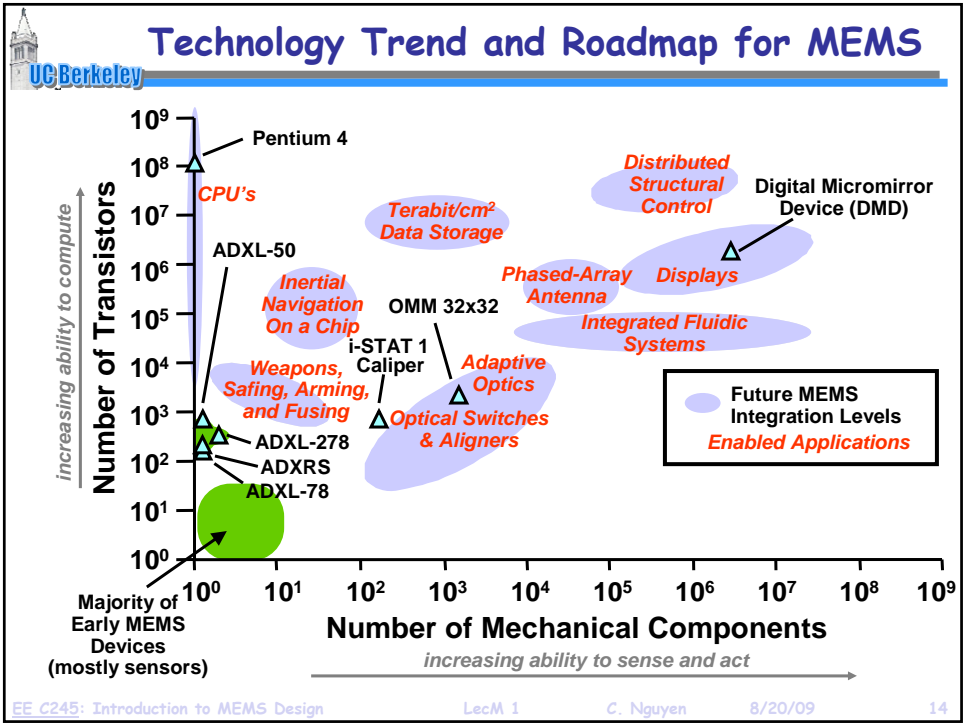
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Example: Micromechanical Accelerometer

The MEMS Advantage

>30X size reduction

accelerometer mechanism

allows integration with electronics

Tiny mass means small output

⇒ need integrated transistor circuits to compensate

Basic Operation Principle

$x \propto F_i = ma$

Displacement

Spring

Inertial Force

Proof Mass

Acceleration

x_0

x

a

400 μm

Analog Devices ADXL 78

Technology for MEMS

Analog Devices ADXRS Integrated Gyroscope

Adv.: small size

OMM 8x8 Optical Cross-Connect Switch

Adv.: faster switching, low loss, larger networks

Caliper Microfluidic Chip

Adv.: small size, small sample, fast analysis speed

TI Digital Micromirror Device

Adv.: low loss, fast switching, high fill factor

Weapons, Safing, Arming, and Fusing

Optical Switches & Aligners

Adaptive Optics

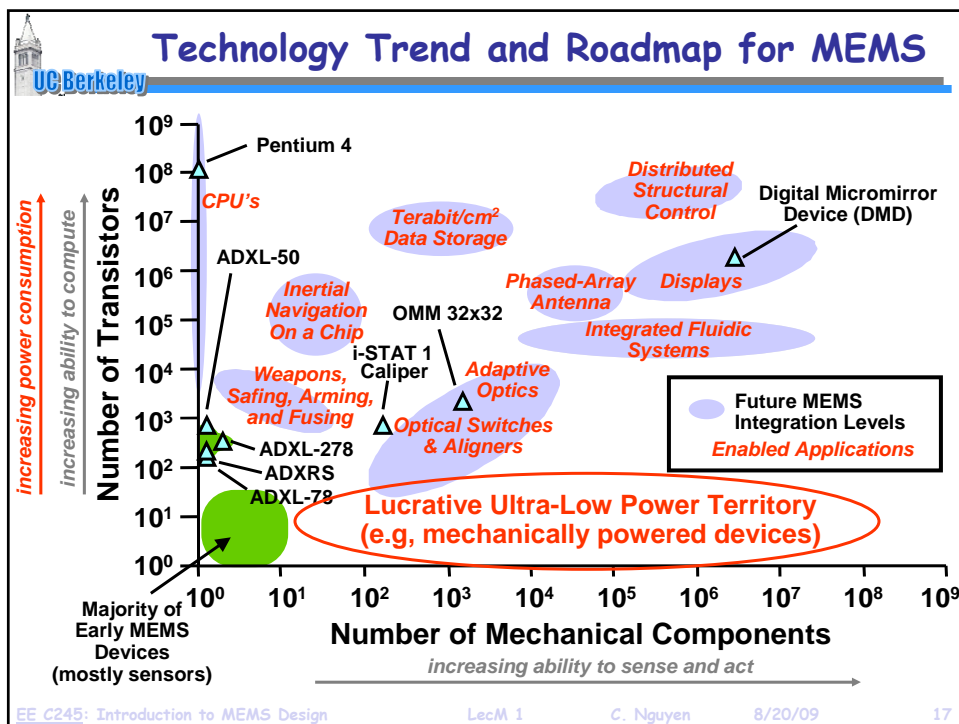
Integrated Fluidic Systems

Number of Mechanical Components

increasing ability to sense and act

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Benefits of Size Reduction: MEMS

- Benefits of size reduction clear for IC's in elect. domain
 \Rightarrow size reduction \Rightarrow speed, low power, complexity, economy
- MEMS: enables a similar concept, but ...
MEMS extends the benefits of size reduction beyond the electrical domain

↓

Performance enhancements for application domains beyond those satisfied by electronics in the same general categories

Speed	\Rightarrow	Frequency \uparrow , Thermal Time Const. \downarrow
Power Consumption	\Rightarrow	Actuation Energy \downarrow , Heating Power \downarrow
Complexity	\Rightarrow	Integration Density \uparrow , Functionality \uparrow
Economy	\Rightarrow	Batch Fab. Pot. \uparrow (esp. for packaging)
Robustness	\Rightarrow	g-Force Resilience \uparrow

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