


EE C247B - ME C218 Introduction to MEMS Design Spring 2014

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Lecture Module 1: Admin & Overview


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Instructor: Prof. Clark T.-C. Nguyen

- **Education**: Ph.D., University of California at Berkeley, 1994
- **1995**: joined the faculty of the Dept. of EECS at the University of Michigan
- **2006**: (came back) joined the faculty of the Dept. of EECS at UC Berkeley
- **Research**: exactly the topic of this course, with a heavy emphasis on vibrating RF MEMS
- **Teaching**: (at the UofM) mainly transistor circuit design courses: (UC Berkeley) 140/240A, 143, 243, 245
- **2001**: founded Discera, the first company to commercialize vibrating RF MEMS technology
- **Mid-2002 to 2005**: DARPA MEMS program manager
 - ↳ ran 10 different MEMS-based programs
 - ↳ **topics**: power generation, chip-scale atomic clock, gas analyzers, nuclear power sources, navigation-grade gyros, on-chip cooling, micro environmental control


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Course Overview

- **Goals of the course:**
 - ↪ Accessible to a broad audience (minimal prerequisites)
 - ↪ Design emphasis
 - Exposure to the techniques useful in analytical design of structures, transducers, and process flows
 - ↪ Perspective on MEMS research and commercialization circa 2013
- **Related courses at UC Berkeley:**
 - ↪ EE 143: Microfabrication Technology
 - ↪ EE 147/247A: Introduction to MEMS
 - ↪ ME 119: Introduction to MEMS (mainly fabrication)
 - ↪ BioEng 121: Introduction to Micro and Nano Biotechnology and BioMEMS
 - ↪ ME C219 - EE C246: MEMS Design
- **Assumed background for EE C245:**
 - ↪ graduate standing in engineering or physical/bio sciences
 - ↪ may change to require 247A next year

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Course Overview

- **The mechanics of the course are summarized in the course handouts, given out in lecture today**
 - ↪ Course Information Sheet
 - Course description
 - Course mechanics
 - Textbooks
 - Grading policy
 - ↪ Syllabus
 - Lecture by lecture timeline w/ associated reading sections
 - Midterm Exam: tentatively on Thursday, March 20
 - Final Exam: Friday, May 16, 7-10 p.m. (Group 20)
 - Project due date TBD (but near semester's end)

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What Should You Know?

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Typical mid-2000's CMOS Process (good down to ~0.25µm)

You should either already know or be able to learn independently & very quickly:

- ① How to deposit or grow those different layers.
- ② How to pattern or otherwise form the shapes of the layers shown.
- ③ What determines the order by which the different layers are formed, e.g., temperature limits, topography limits, etc...

We will review these things, but we will do this very fast!

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What Should You Know?

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- Basic circuit analysis & design using op amps
- **Example:** Find the transfer function $v_o(s)/v_i(s)$ of the circuit below.

$R_f \parallel \frac{1}{sC_f} = \frac{1}{\frac{1}{R_f} + \frac{1}{sC_f}} = \frac{R_f}{1 + sR_fC_f}$

Virtual ground!


Ideal Op Amp Rules: (apply these when have neg. FB)

- ① $v_+ = v_-$
- ② $R_i \rightarrow \infty \rightarrow i_- = i_+ = 0$
- ③ $R_o = 0 \Omega$

$v_o = -i_- (R_f \parallel \frac{1}{sC_f}) = \frac{v_i}{R_1} (R_f \parallel \frac{1}{sC_f}) \Rightarrow \frac{v_o(s)}{v_i(s)} = -\frac{R_f}{R_1} \frac{1}{1 + sR_fC_f} = -\frac{R_f}{R_1} \frac{1}{1 + \frac{s}{\omega_0}} = \frac{v_o(s)}{v_i(s)}$

$\omega_0 = \frac{1}{R_f C_f}$


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Lecture Outline

- Reading: Senturia, Chapter 1
- Lecture Topics:
 - ↳ Definitions for MEMS
 - ↳ MEMS roadmap
 - ↳ Benefits of Miniaturization

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MEMS: Micro Electro Mechanical System

- A device constructed using micromachining (MEMS) tech.
- A micro-scale or smaller device/system that operates mainly via a mechanical or electromechanical means
- At least some of the signals flowing through a MEMS device are best described in terms of mechanical variables, e.g., displacement, velocity, acceleration, temperature, flow

Input:

voltage, current
acceleration, velocity
light, heat ...

MEMS

Output:

voltage, current
acceleration, velocity
light, heat, ...

Transducer to Convert **Control** to a **Mechanical Variable** (e.g., displacement, velocity, stress, heat, ...)

Control:

voltage, current
acceleration
velocity
light, heat, ...


Angle set by mechanical means to control the path of light

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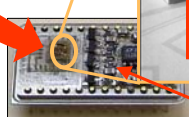
Other Common Attributes of MEMS

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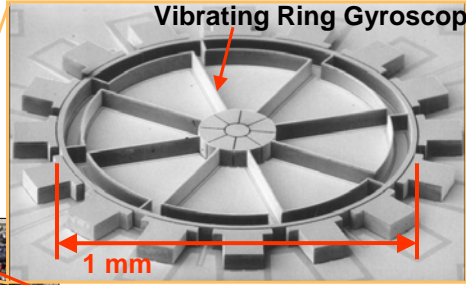
- Feature sizes measured in microns or less



80 mm
Gimbaled, Spinning
Macro-Gyroscope



Signal Conditioning Circuits



[Najafi, Michigan]
Micromechanical
Vibrating Ring Gyroscope

1 mm

MEMS Technology
(for 80X size Reduction)

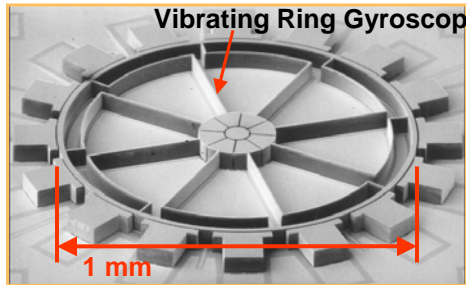
- Merges computation with sensing and actuation to change the way we **perceive** and **control** the physical world
- Planar lithographic technology often used for fabrication
 - can use fab equipment identical to those needed for IC's
 - however, some fabrication steps transcend those of conventional IC processing

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Bulk Micromachining and Bonding

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- Use the wafer itself as the structural material
- Adv:** very large aspect ratios, thick structures
- Example:** deep etching and wafer bonding

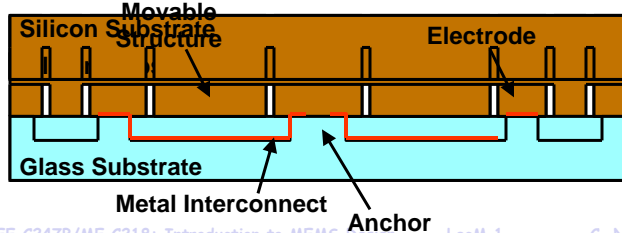


[Najafi, Michigan]



[Pisano, UC Berkeley]

Microrotor
(for a microengine)



Silicon Substrate Movable Structure Electrode

Glass Substrate Metal Interconnect Anchor

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Surface Micromachining

The diagram illustrates the surface micromachining process in two stages. In the top stage, a silicon substrate with a p-well contains a structural material (e.g., polysilicon, nickel, etc.) and a sacrificial oxide layer. A release etch barrier is also present. In the bottom stage, hydrofluoric acid release solution is applied, which etches away the sacrificial oxide layer, resulting in a free-standing resonator beam. Labels include: Release Etch Barrier, Structural Material (e.g., polysilicon, nickel, etc.), Sacrificial Oxide, Hydrofluoric Acid Release Solution, Silicon Substrate, pwell, and Free-Standing Resonator Beam.

- Fabrication steps compatible with planar IC processing

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Single-Chip Ckt/MEMS Integration

The micrograph shows a single-chip integrated circuit/MEMS device with various components labeled: Sustaining Amplifier, Input, Comb. Transducer, Shuttle, Mass, Folded-Beam Suspension, and Anchors. A vertical scale bar indicates 300 μm. An inset shows an oscilloscope output waveform with the following data:

CH1	P-P	=	324mV
CH1	FW	=	21.5μs
CH1	PER	=	61.2μs
CH1	PER	=	16.1μs

Oscilloscope Output Waveform

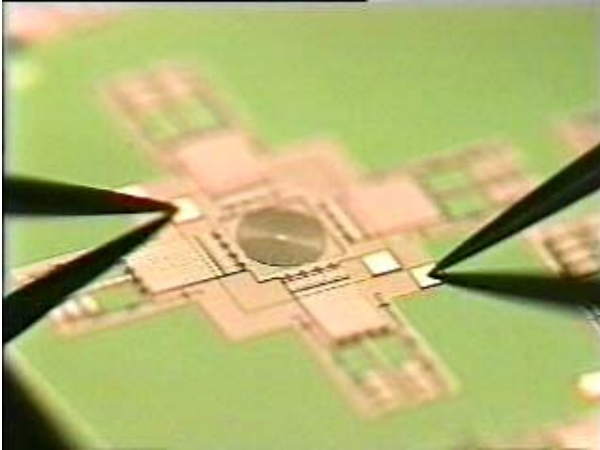
[Nguyen, Howe 1993]

- Completely monolithic, low phase noise, high-Q oscillator (effectively, an integrated crystal oscillator)
- To allow the use of >600°C processing temperatures, tungsten (instead of aluminum) is used for metallization

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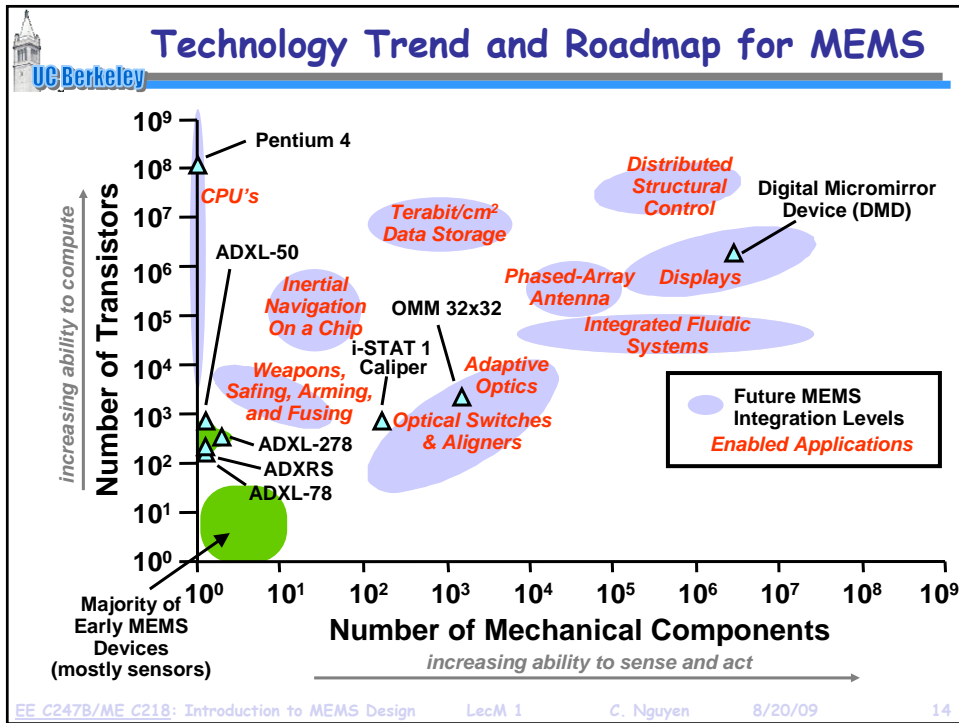
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3D Direct-Assembled Tunable L



[Ming Wu, UCLA]

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Example: Micromechanical Accelerometer

The MEMS Advantage:

- >30X size reduction
- accelerometer mechanism
- allows integration

Basic Operation Principle

$x \propto F_i = ma$

Analog Devices ADXL 78

400 μm

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Technology for MEMS

Adv.: small size

Adv.: faster switching, low loss, larger networks

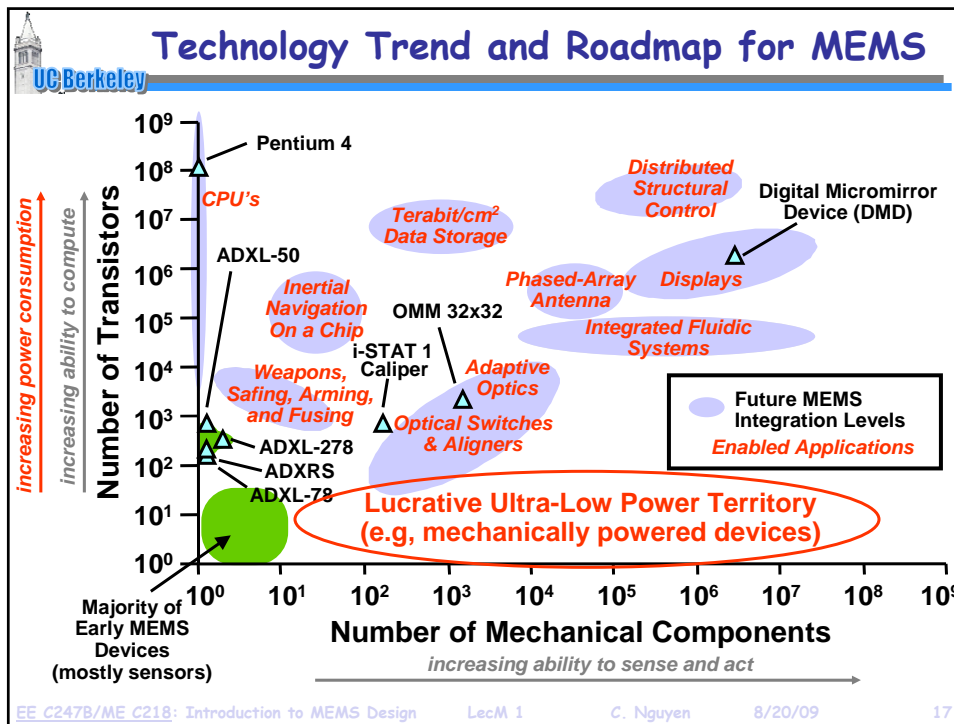
Adv.: low loss, fast switching, high fill factor

Adv.: small size, small sample, fast analysis speed

Number of Mechanical Components

increasing ability to sense and act

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Benefits of Size Reduction: MEMS

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- Benefits of size reduction clear for IC's in elect. domain
 - ↪ size reduction ⇔ speed, low power, complexity, economy
- MEMS: enables a similar concept, but ...
 - MEMS extends the benefits of size reduction beyond the electrical domain**

↓

Performance enhancements for application domains beyond those satisfied by electronics in the same general categories

- Speed → Frequency ↑ , Thermal Time Const. ↓
- Power Consumption → Actuation Energy ↓ , Heating Power ↓
- Complexity → Integration Density ↑ , Functionality ↑
- Economy → Batch Fab. Pot. ↑ (esp. for packaging)
- Robustness → g-Force Resilience ↑

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