

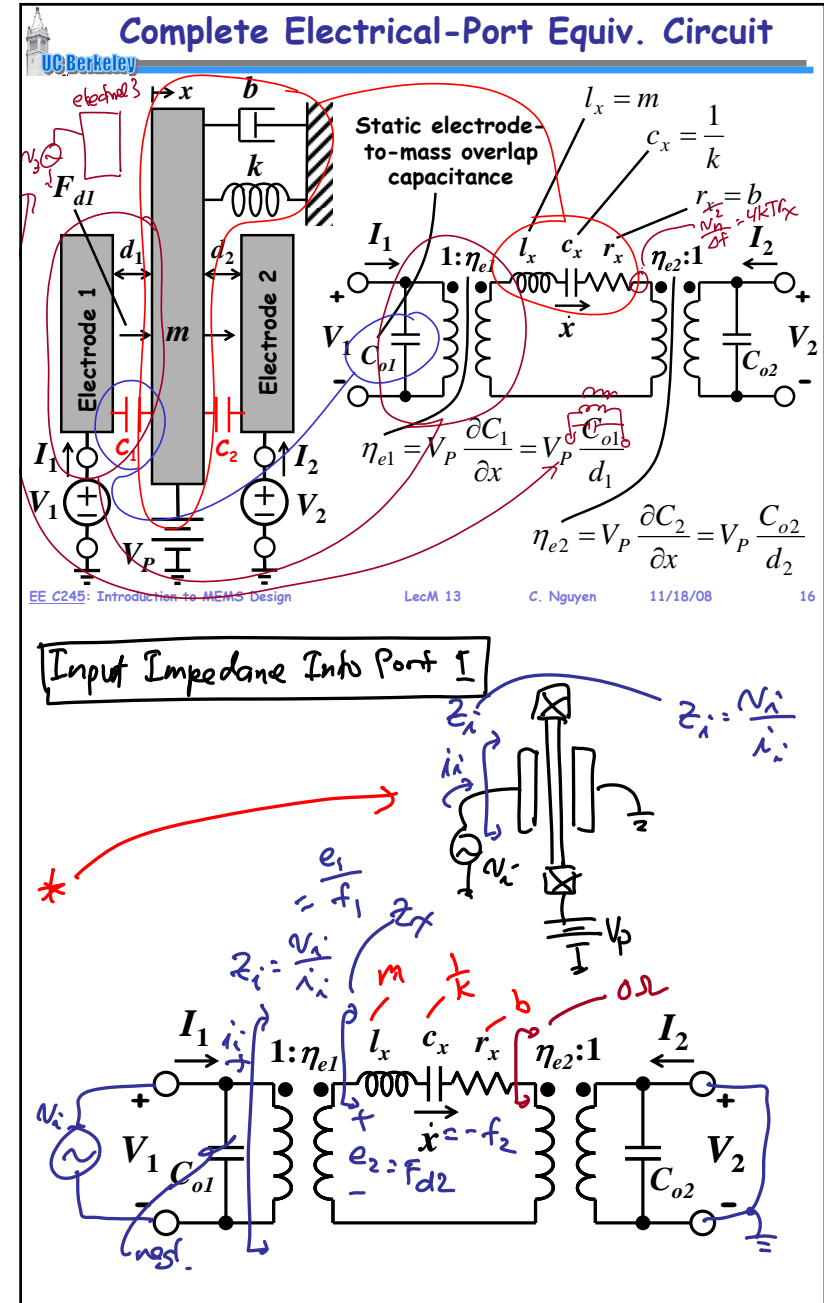
Lecture 25: Circuit Analysis & Gyros

- **Announcements:**
- **Module 14 & 15 now online**
- **HW#6 due this Friday at 9 a.m.**
- **Project Outbrief Signups: pick two days**
 - ↳ Wednesday, May 14? okay
 - ↳ Thursday, May 15? okay
 - ↳ Friday, May 9? okay

- **Equivalent Circuits II Lecture Topics:**
 - ↳ **Input Modeling**
 - Force-to-Velocity Equiv. Ckt.
 - Input Equivalent Ckt.
 - ↳ **Current Modeling**
 - Output Current Into Ground
 - Input Current
 - Complete Electrical-Port Equiv. Ckt.
 - ↳ **Impedance & Transfer Functions**

- **Reading: Senturia, Chpt. 14, Chpt. 16, Chpt. 21**
- **Lecture Topics:**
 - ↳ Gyroscopes
- **Reading: Senturia, Chpt. 14**
- **Lecture Topics:**
 - ↳ **Detection Circuits**
 - Velocity Sensing
 - Position Sensing

- **Last Time:**



$$\begin{bmatrix} e_2 \\ f_2 \end{bmatrix} = \begin{bmatrix} \eta & 0 \\ 0 & -\frac{1}{\eta} \end{bmatrix} \begin{bmatrix} e_1 \\ f_1 \end{bmatrix} \Rightarrow e_2 = \eta e_1 \rightarrow e_1 = \frac{e_2}{\eta}$$

$$f_2 = -\frac{1}{\eta} f_1 \rightarrow f_1 = -\eta f_2$$

$$\frac{e_1}{f_1} = \frac{e_2}{\eta} \left(\frac{1}{-\eta f_2} \right) = -\frac{1}{\eta^2} \frac{e_2}{f_2} \rightarrow \frac{V_i}{i_i} = Z_i = -\frac{1}{\eta^2} \frac{F_{d2}}{(-\dot{x}_2)}$$

$$Z_i = \frac{1}{\eta^2} Z_x$$

$$Z_i = \frac{1}{\eta^2} \left(j\omega L_x + \frac{1}{j\omega C_x} + r_x \right)$$

$$= j\omega \left(\frac{L_x}{\eta^2} \right) + \frac{1}{j\omega (\eta^2 C_x)} + \frac{r_x}{\eta^2}$$

L_{x1} C_{x1} R_{x1} $\frac{N_1^2}{\eta^2} = 4kTR_x \Delta f$

to model noise!

* Purely Electrical Equiv. Ckt.

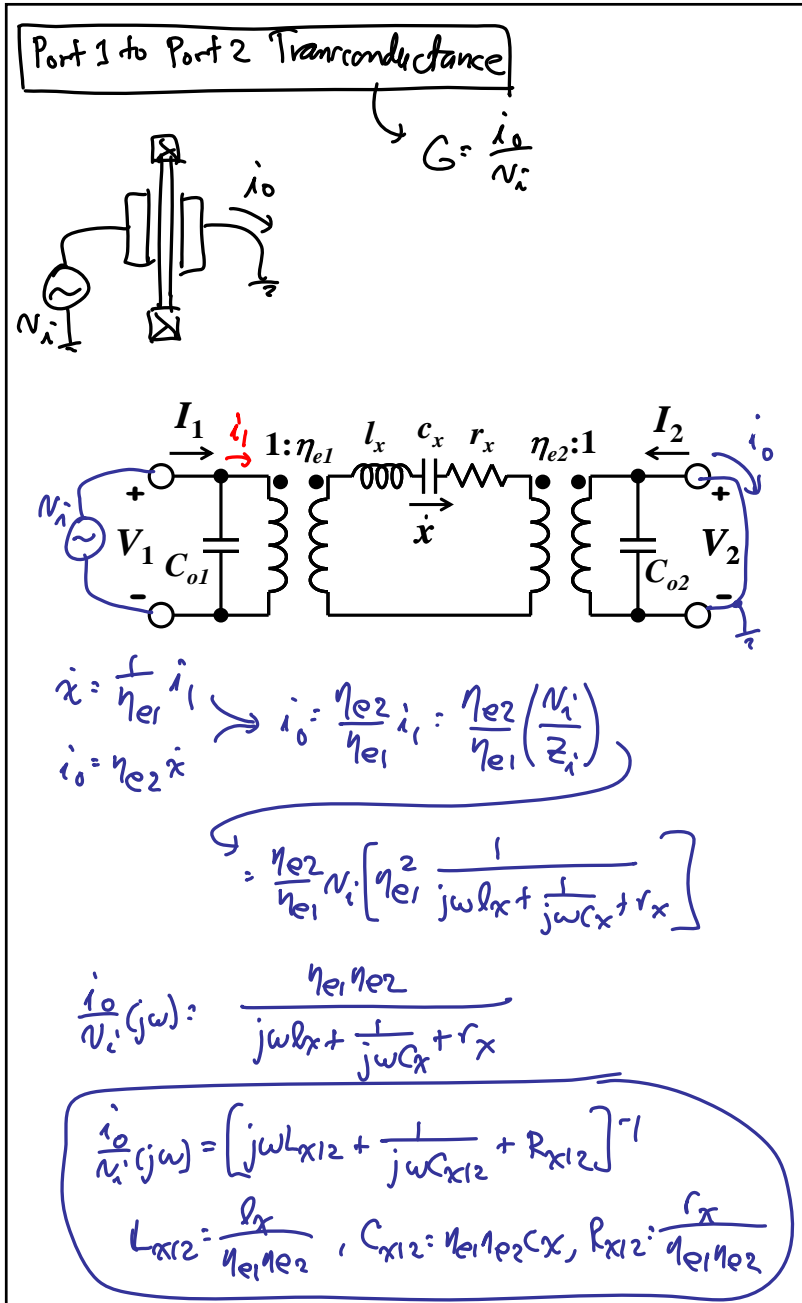
Transformer Inspection Analysis

Input Impedance Into Port 2

$$Z_i = \frac{N_1^2}{i_i} = \frac{Z_x}{\eta_{e2}^2}$$

$$= j\omega \left(\frac{L_x}{\eta_{e2}^2} \right) + \frac{1}{j\omega (\eta_{e2}^2 C_x)} + \frac{r_x}{\eta_{e2}^2}$$

L_{x2} C_{x2} R_{x2}



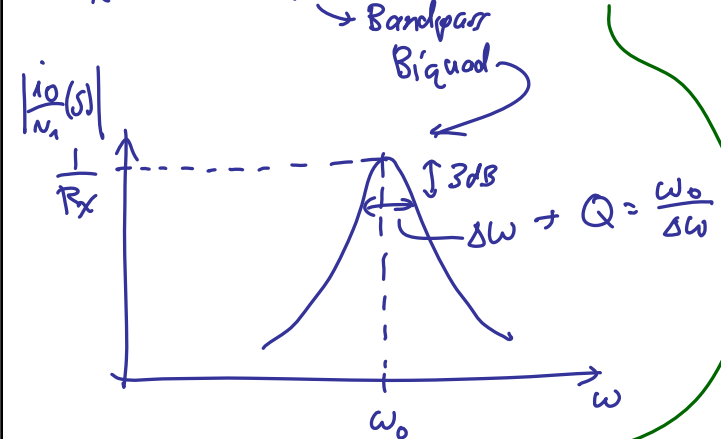
Separate freq. response & magnitude:

$$\frac{i_o}{N_i}(\omega) = \frac{1}{sL_x + \frac{1}{sC_x} + R_x} = \frac{s\left(\frac{1}{L_x}\right)}{s^2 + \frac{1}{L_x C_x} + s\left(\frac{R_x}{L_x}\right)}$$

$$\left[\frac{1}{L_x C_x} = \omega_0^2, Q = \frac{\omega_0 L_x}{R_x} \rightarrow \frac{R_x}{L_x} = \frac{\omega_0}{Q} \right]$$

$$\frac{i_o}{N_i}(s) = \frac{1}{R_x} \frac{s\left(\frac{\omega_0}{Q}\right)}{s^2 + s\left(\frac{\omega_0}{Q}\right) + \omega_0^2} = \frac{1}{R_x} \mathcal{H}(s)$$

Gain Term Freq. Shaping Term Resonance Magnitude



→ significance: Can just solve the ckt. @ resonance, then multiply by a proper $\mathcal{H}(s)$!