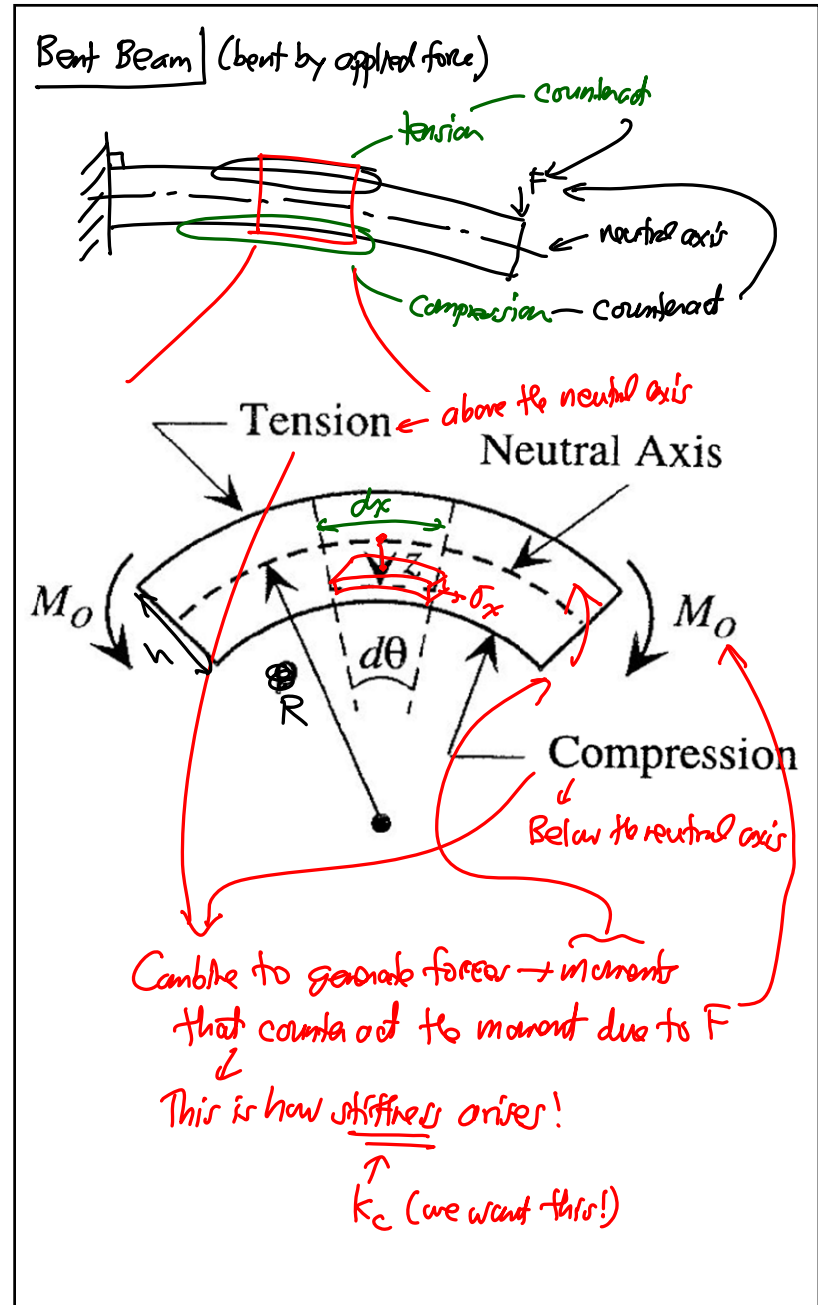


Lecture 11: Stress Gradients & Beam Combos

- Announcements:
- HW#3 online and due Wednesday morning (next week; this is a one week homework)
- Module 8 on Microstructural Elements online
- Again, this will be a 2 hour lecture
- Midterm is coming in a few weeks: Thursday, March 19
-
- Reading: Senturia, Chpt. 9
- Lecture Topics:
 - ↳ Bending of beams
 - ↳ Cantilever beam under small deflections
 - ↳ Cantilever with residual stress gradient
 - ↳ Combining cantilevers in series and parallel
 - ↳ Folded suspensions
 - ↳ Design implications of residual stress and stress gradients for folded-beam devices
-
- Last Time:
- Derived governing expression for beam bending



Beam Segment in Pure Bending

⇒ Consider the segment bounded by the dashed lines defining $d\theta$

At $z=0$: neutral axis → segment length = $dx = R d\theta$ (1)

At any z : segment length = $dL = (R-z)d\theta$ (2)

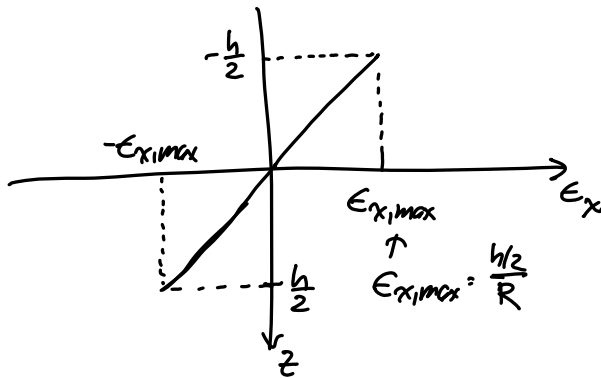
Combine (1) & (2): $dL = dx - z d\theta = dx - \frac{z}{R} dx$

Thus, the axial strain @ z :

$$\epsilon_x = \frac{dL - dx}{dx} = -\frac{z}{R}$$

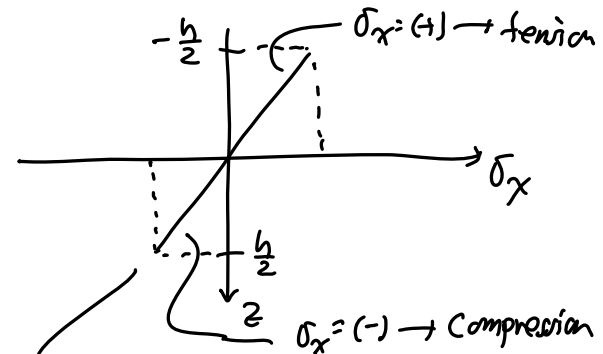
$$\epsilon_x = -\frac{z}{R}$$

Thus, the strain varies linearly along the beam thickness:



Of course, there is a corresponding axial stress:

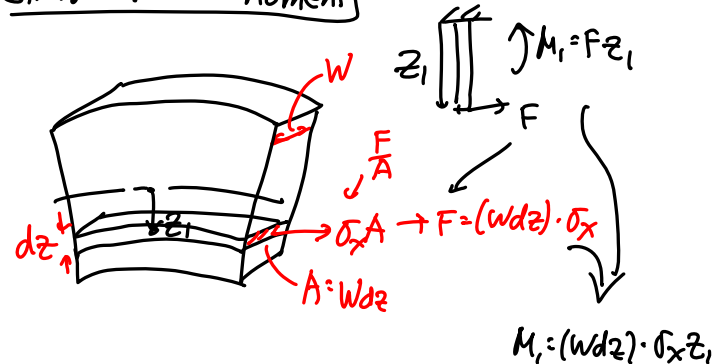
$$\sigma_x = \epsilon_x E = -\frac{zE}{R} = \sigma_x$$



This gradient of stress then generates an internal bending moment!

In response to the original applied moment (from F)

Stress → Force → Moment



⇒ integrate stress through the thickness of the beam:

$$M = \int_{-\frac{h}{2}}^{\frac{h}{2}} \underbrace{[w(z)\sigma_x]}_{\text{force}} \cdot \underbrace{z}_{\text{moment arm}} dz$$

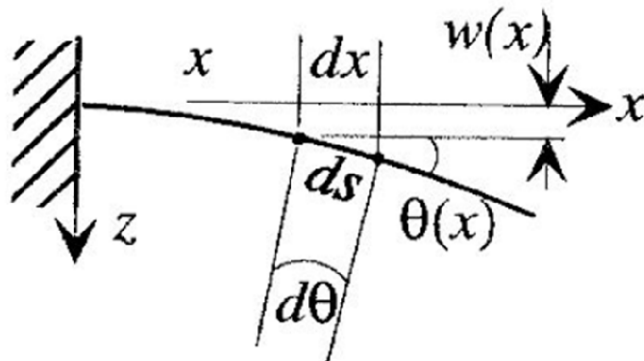
$$= - \int_{-\frac{h}{2}}^{\frac{h}{2}} \frac{Ewz^2}{R} dz \Rightarrow M = - \left(\frac{1}{12} Wh^3 \right) \frac{E}{R}$$

$\left[\sigma_x = - \frac{zE}{R} \right]$ $\frac{1}{12} Wh^3 = I \triangleq \text{Moment of Inertia}$

$\frac{1}{R} = - \frac{M}{EI}$

Note: (+) radius of curvature
(-) internal bending moment

Differential Equation for Beam Bending



Write out some geometric relationships:

⇒ then use small angle approx:

$$\cos\theta = \frac{dx}{ds} \rightarrow ds = \frac{dx}{\cos\theta} \rightarrow ds \approx dx$$

$$\tan\theta = \frac{dw}{dx} = \text{slope of the beam @ this point} \rightarrow \theta \approx \frac{dw}{dx} \quad (1)$$

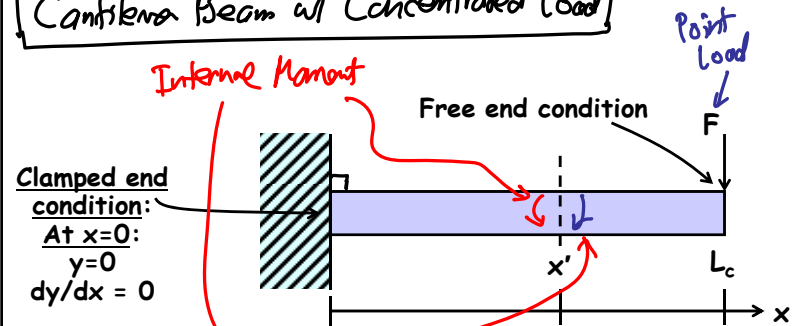
$$ds = R d\theta \rightarrow \frac{1}{R} = \frac{d\theta}{ds} \rightarrow \frac{1}{R} = \frac{d^2w}{dx^2} \quad (2)$$

Inserting (1) into (2)

$\frac{1}{R} = \frac{d^2w}{dx^2} = - \frac{M}{EI}$

← Diff. Eqn. for Small Angle Beam Bending

Cantilever Beam w/ Concentrated Load



Internal Moment @ position x: $M = -F(L-x)$

Thus: $\frac{d^2w}{dx^2} = \frac{F}{EI}(L-x)$

w/ { Clamped End B.C.: $w(x=0)=0, \frac{dw}{dx}(x=0)=0$
Free End B.C.: none

Solve for w :
 \Rightarrow use Laplace; a trial solution:
 $w = A + Bx + Cx^2 + Dx^3$, then apply B.C.'s

$w = \frac{FL}{2EI} x^2 \left(1 - \frac{x}{3L}\right)$

Deflection @ x due to a point load F applied @ $x=L$

Maximum Deflection \rightarrow occurs @ $x=L$:
 $w_{max} = \left(\frac{L^3}{3EI}\right) F \rightarrow F = \left(\frac{3EI}{L^3}\right) w(x=L)$

stiffness $\Delta k_c @ x=L$

Whoa $k_c = \frac{3EI}{L^3} @ x=L$

In general, stiffness is a function of location

$[I = \frac{1}{12} Wh^3] \Rightarrow k_c = \frac{1}{4} EW \frac{h^3}{L^3}$

Ex. $L = 100 \mu m, W = 2 \mu m, h = 2 \mu m$
 polysilicon $\rightarrow E = 150 \text{ GPa}$
 $k_c = \frac{1}{4} (150 \text{ G}) (2 \mu) \left(\frac{2 \mu}{100 \mu}\right)^3 = \underline{0.6 \text{ N/m}}$

Maximum Stress in a Bent Cantilever

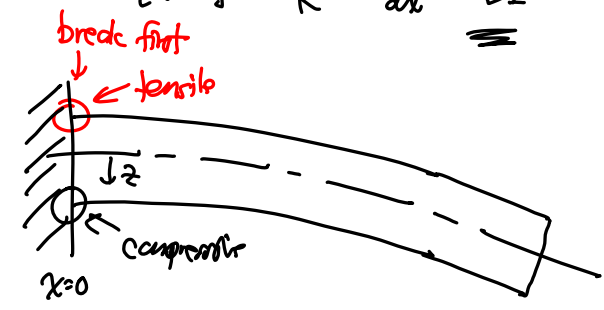
From before, the radius of curvature is given by

$\frac{1}{R} = \frac{d^2 w}{dx^2} = \frac{F}{EI} (L-x)$

$\Rightarrow \frac{1}{R}$ is maximized (i.e., R is minimized)

When $x=0$:

$[x=0] \Rightarrow \frac{1}{R} = \frac{d^2 w}{dx^2} = \frac{FL}{EI}$



Stress is maximized:

- ① At the top surface \rightarrow tensile
- ② At the bottom surface \rightarrow compressive

$\epsilon_{max} = \frac{z}{R} = \frac{h}{2} \frac{1}{R} = \frac{h}{2} \frac{FL}{2EI} = \epsilon_{max}$

$[I: \frac{1}{12}Wh^3] \Rightarrow \epsilon_{max} = \frac{1}{2} \frac{FL}{E} \left(\frac{12}{Wh^3} \right) = \frac{6L}{EWh^2} F$

$\sigma_{max} = \epsilon_{max} E = \frac{6L}{Wh^2} F$

(maximum stress in a bent cantilever subjected to a force F at its tip)

Stress Gradients in Cantilevers

- ① Deposit film @ high temp.
- ② Cool it down.

Before release

Stress before release

↓ Now, release ...

After release, but before bending

- ① Remove the sac. layer → beam free to do what it wants!
- ② Beam stretches → removes average axial stress
- ③ Bends to relieve stress gradient

Stress after release but before bend

After bending

After bending

Bending Due to Stress Gradients

Find the radius of curvature:

Prior to release, axial stress: $\sigma = \sigma_0 - \frac{\sigma_1}{(H/2)} z$

The internal moment:

$$M_x = \int_{-H/2}^{H/2} [(w \cdot dz) \sigma] \cdot z = \int_{-H/2}^{H/2} w \left(z \sigma_0 - \frac{\sigma_1 z^2}{(H/2)} \right) dz$$

$$= w \left(\frac{1}{2} \sigma_0 z^2 - \frac{2 \sigma_1 z^3}{3H} \right) \Big|_{-H/2}^{H/2}$$

$$= w \left(\frac{1}{2} \sigma_0 \frac{H^2}{4} - \frac{2}{3} \sigma_1 \frac{H^2}{8} - \frac{1}{2} \sigma_0 \frac{H^2}{4} + \frac{2}{3} \sigma_1 \frac{H^2}{8} \right)$$

ans stress cancels

$$M_x = -\frac{1}{6} \sigma_1 w H^2$$

Thus, the radius of curvature:

$$\frac{1}{R} = -\frac{M_x}{E'I} \rightarrow R = \frac{E'I}{M_x} = \frac{1}{2} \frac{E'H}{\sigma_1}$$

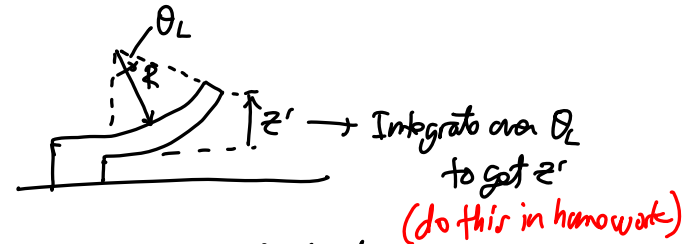
\times
Biaxial Modulus

$[I = \frac{1}{12} w H^3]$

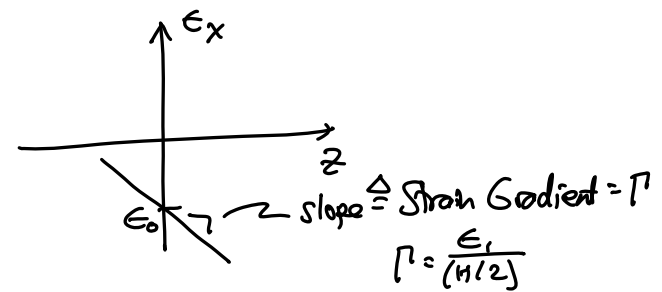
$$R = \frac{1}{2} \frac{E}{(1-\nu)} \frac{H}{\sigma_1}$$

Radius of Curvature for a Cantilever w/ a Stress Gradient

Radius of Curvature $\rightarrow z'$



Definition. Strain Gradient



$$R = \frac{1}{2} \frac{E}{(1-\nu)} \frac{H}{\sigma_1} = \frac{H}{2} \frac{E'}{\sigma_1} = \frac{(H/2)}{\epsilon_1} = \frac{1}{1/R} \rightarrow \boxed{1/R}$$

Series Combination of Springs

Guided: maintain 90°

combination + stiffness = k_c

also, a combination stiffness = k_c

Fixed ↓ maintain 90°

Free (just like two combos)

Series: $y_{tot} > y_1, y_{tot} > y_2 \Rightarrow y_{tot} = y_1 + y_2$

What's the force here? → F

$$y(L) = \frac{F}{k} = 2y(L_c) = 2\left(\frac{F}{k_c}\right) = F\left(\frac{1}{k_c} + \frac{1}{k_c}\right)$$

stiffness of the whole thing

$$\frac{1}{k} = \frac{1}{k_c} + \frac{1}{k_c} \Rightarrow k = k_c || k_c$$

Definition for "||" $\left\{ \begin{aligned} A || B &= \frac{1}{\frac{1}{A} + \frac{1}{B}} = \frac{AB}{A+B} \end{aligned} \right.$

Parallel Combination of Springs

Parallel: $y_{tot} = y_a = y_b$

$$y(L) = \frac{F}{k} = \frac{F_a}{k_a} = \frac{F_b}{k_b} = \frac{F}{2} \left(\frac{1}{k_a} \right)$$

of the whole thing

$$k = 2k_a$$

In general $k_{tot} = k_a + k_b$

For EE's: Springs combine like capacitors

