

**Lecture 24: Gyroscopes & Sensing Circuits**

**Announcements:**

- HW#6 online and due Friday, April 22
- Module 14 on Sensing Circuits online
- Module 15 on Gyros, Noise, & MDS online
- Project slide #3 due Friday, April 29
- I will be at the EECS Retreat this coming Thursday, so the lecture will be recorded and on video

↳ Please watch the Thursday Lecture video before class on Tuesday, next week

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- Reading: Senturia, Chpt. 14, Chpt. 16, Chpt. 21

**Lecture Topics:**

↳ Gyroscopes

- Reading: Senturia, Chpt. 14

**Lecture Topics:**

↳ Detection Circuits

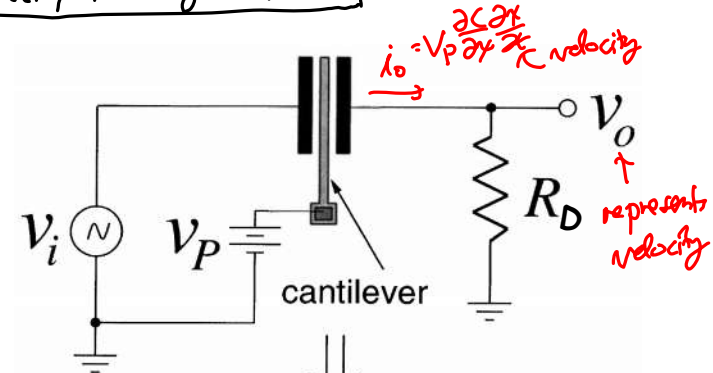
- Velocity Sensing
- Position Sensing

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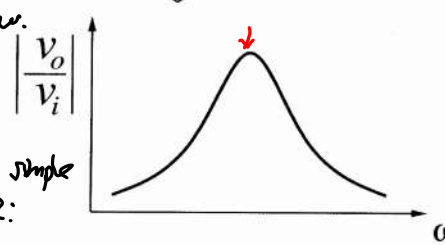
**Last Time:**

- Started gyroscopes by going through slides 1-6 in Module 15
- Now, continue with this, going through slide 16

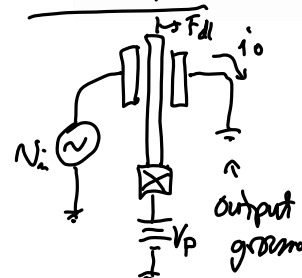
**Velocity-to-Voltage Conversion**



Neglect Co for now.



First, review the simple case w/  $R_D = 0$ :



@ resonance:  $\frac{x_i}{F_{dl}}(j\omega_0) = \frac{j\omega_0 Q}{jk} = \frac{\omega_0 Q}{k}$

$\frac{x_i}{F_{dl}}(s) = \frac{\omega_0 Q}{k} (H)(s)$  ← at all freqs.

$(H)(s) = \frac{s(\omega_0/Q)}{s^2 + s(\omega_0/Q) + \omega_0^2}$

$[F_{dl} = \eta_1 v_i]$

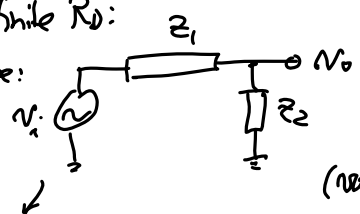
$\frac{x_i}{v_i}(s) = \eta_1 \frac{\omega_0 Q}{k} (H)(s)$

$(i_o = \eta_2 \dot{x}_i) \Rightarrow \frac{i_o}{v_i}(s) = \eta_1 \eta_2 \frac{\omega_0 Q}{k} (H)(s) = \frac{\eta_1 \eta_2 Q}{m \omega_0} (H)(s)$

$\frac{1}{R \times 12}$

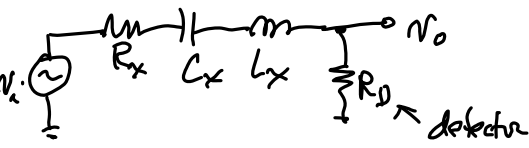
Now, include finite  $R_D$ :

⇒ Really here:



$$\frac{v_o}{v_i} = \frac{z_2}{z_1 + z_2}$$

(voltage divider)



detector

$$\frac{v_o}{v_i}(s) = \frac{R_D}{R_x + \frac{1}{sC_x} + sL_x + R_D} = \dots \text{math} \dots$$

$$= \frac{R_D}{R_x + R_D} \frac{s \left( \frac{R_x + R_D}{L_x} \right)}{s^2 + s \left( \frac{R_x + R_D}{L_x} \right) + \frac{1}{L_x C_x}}$$

Gain Term      Freq. Shaping Term

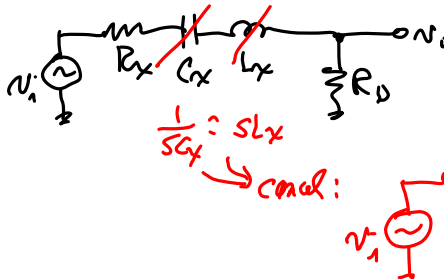
$$\left[ Q = \frac{\omega_0 L_x}{R_x} \rightarrow Q' = \frac{\omega_0 L_x}{R_x + R_D} \rightarrow \frac{R_x + R_D}{L_x} = \frac{\omega_0}{Q'} \right]$$

$$\frac{v_o}{v_i}(s) = \frac{R_D}{R_x + R_D} \frac{s(\omega_0/Q')}{s^2 + s(\omega_0/Q') + \omega_0^2}$$

$$\frac{v_o}{v_i}(s) = \frac{R_D}{R_x + R_D} \cdot \mathcal{H}(s, Q')$$

↓  
 $Q' = Q \left( \frac{R_x}{R_x + R_D} \right)$

Analysis @ Resonance:



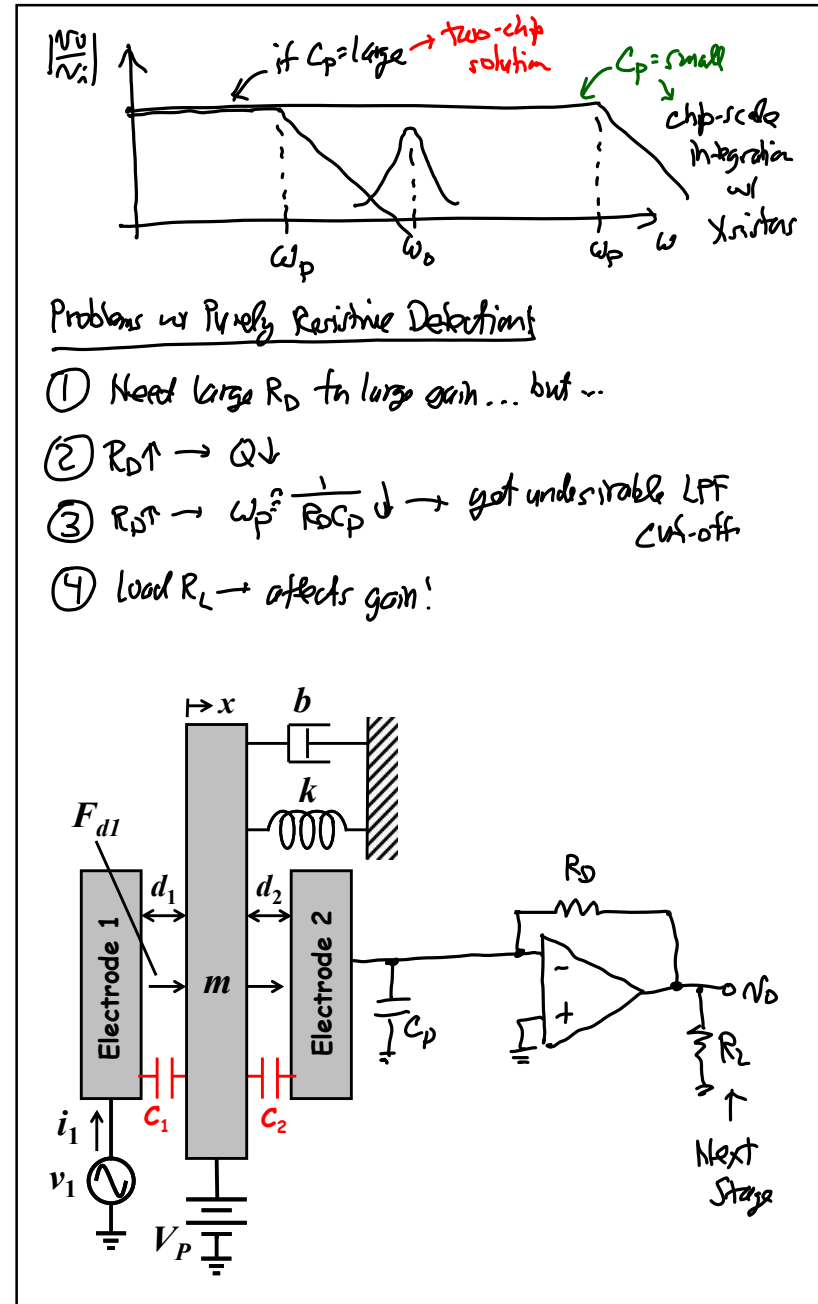
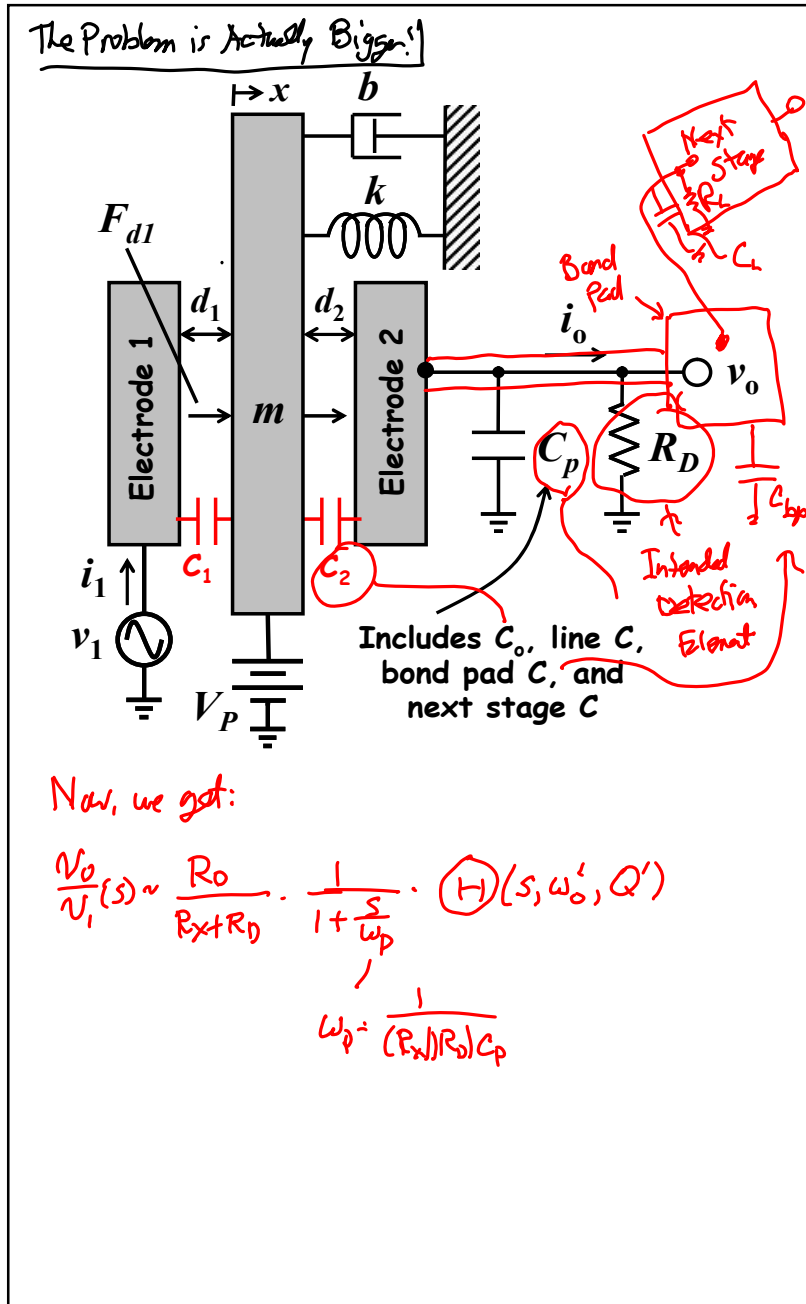
$\frac{1}{sC_x} = sL_x$   
→ cancel:

@ resonance

Convert from resonance to general freq.:  $x \mathcal{H}(s, Q')$

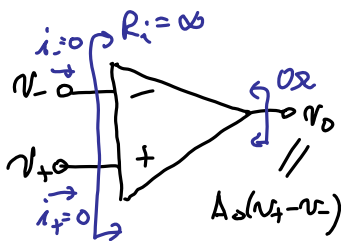
$$\frac{v_o}{v_i}(s) = \frac{R_D}{R_x + R_D} \mathcal{H}(s, Q'), \text{ where } Q' = Q \left( \frac{R_x}{R_x + R_D} \right)$$

very fast, by inspection!



Ideal Op Amp Laws

- ①  $R_i = \infty \rightarrow i_- = i_+ = 0$
- ②  $R_o = 0$
- ③ Gain =  $A_o = \infty$   
neg. FB  $\rightarrow V_+ = V_-$



The diagram shows an ideal operational amplifier with the following characteristics:

- Input resistance  $R_i = \infty$ , resulting in zero input currents  $i_+ = 0$  and  $i_- = 0$ .
- Output resistance  $R_o = 0$ .
- Open-loop gain  $A_o = \infty$ .
- When negative feedback is applied, the inputs are at the same potential:  $V_+ = V_-$ .
- The output voltage is  $V_o = A_o(V_+ - V_-)$ .