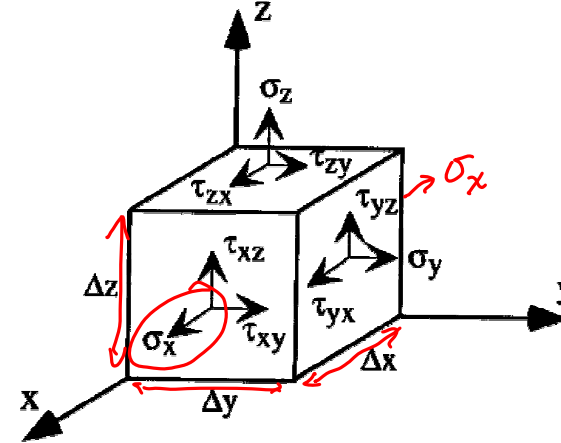


Lecture 10: Mechanics of Materials I

- Announcements:
- Module 7 on "Mechanics of Materials" online
- HW#2 online and due Tuesday, 2/28, at 10 a.m.
- -----
- Reading: Senturia Chpt. 3, Jaeger Chpt. 11, Handouts: "Bulk Micromachining of Silicon"
- Lecture Topics:
  - ↳ Bulk Micromachining
  - ↳ Anisotropic Etching of Silicon
  - ↳ Boron-Doped Etch Stop
  - ↳ Electrochemical Etch Stop
  - ↳ Isotropic Etching of Silicon
  - ↳ Deep Reactive Ion Etching (DRIE)
  - ↳ Wafer Bonding
- -----
- Reading: Senturia, Chpt. 8
- Lecture Topics:
  - ↳ Stress, strain, etc., for isotropic materials
  - ↳ Thin films: thermal stress, residual stress, and stress gradients
  - ↳ Internal dissipation
  - ↳ MEMS material properties and performance metrics
- -----
- Last Time: Going thru Module 6 ... finish this
- Move on to Module 7

Example. Exercise the "terms"

⇒ Determine the volume change  $\Delta V$  resulting from a uniaxial stress  $\sigma_x$  (along the x-direction)



Upon application of  $\sigma_x$ , what is  $\Delta V$ ?

$$\Delta x \rightarrow \Delta x(1 + \epsilon_x)$$

$$\Delta y \rightarrow \Delta y(1 - \nu \epsilon_x)$$

$$\Delta z \rightarrow \Delta z(1 - \nu \epsilon_x)$$

} assuming isotropic material  $\rightarrow$  same  $\nu$  along y & z

The resulting change in volume:  $\Delta V$

$$\Delta V = \Delta x \Delta y \Delta z (1 + \epsilon_x)(1 - \nu \epsilon_x)^2 - \Delta x \Delta y \Delta z$$

volume after application of  $\sigma_x$

$$= \Delta x \Delta y \Delta z [(1 + \epsilon_x)(1 - \nu \epsilon_x)^2 - 1]$$
 (Assume small strains)  $\Rightarrow (1 + \nu \epsilon_x)^n \approx (1 + n \nu \epsilon_x)$ 

$$\Delta V = \Delta x \Delta y \Delta z [(1 + \epsilon_x)(1 - 2\nu \epsilon_x) - 1]$$

$$\Delta V = \Delta x \Delta y \Delta z (1 - 2\nu) \epsilon_x$$

For  $\nu = 0.5$  (rubber)  $\rightarrow$  no  $\Delta V$ !  
 $\nu < 0.5 \rightarrow$  finite  $\Delta V$

For isotropic materials  $\rightarrow$  Module 7, pg. 13

**Important Case: Plane Stress**

$\Rightarrow$  common case for a thin-film coating on a rigid substrate

Take a closer look @ this region:  $\sigma_z = 0$

Get two components of stress:

$$\epsilon_x = \frac{1}{E} [\sigma_x - \nu(\sigma_y + 0)]$$

$$\epsilon_y = \frac{1}{E} [\sigma_y - \nu(\sigma_x + 0)]$$

Assume: Plane stress  $\rightarrow$  isotropic  $\rightarrow \sigma_x = \sigma_y = \sigma$   
 (symmetry in the xy-plane)  $\downarrow$   
 $\epsilon_x = \epsilon_y = \epsilon$

$$\epsilon_x = \frac{1}{E} [\sigma - \nu\sigma]$$

$$= \left( \frac{\sigma}{E} \right) \frac{1}{(1-\nu)} \Rightarrow \epsilon_x = \frac{\sigma}{E'}$$

where  $E' = \frac{E}{1-\nu} \triangleq$  Biaxial Modulus

Linear Thermal Expansion

temperature  $\uparrow$   $\rightarrow$  solids expand in volume

Definition: linear thermal expansion coefficient

$$\left. \begin{array}{l} \text{Linear Thermal} \\ \text{Exp. Coefficient} \end{array} \right\} \cong \alpha_T = \frac{d\epsilon_x}{dT} \quad [\text{Kelvin}^{-1}]$$

Remarks:

- ①  $\alpha_T$  values tend to be in the  $10^{-6}$  to  $10^{-7}$  range
- ②  $10^{-6} \text{K}^{-1} = 1 \mu\text{strain/K}$
- ③ In 3D, get volume thermal exp. coefficient:

$$\frac{\Delta V}{V} = 3\alpha_T \Delta T$$

- ④ For moderate  $\Delta T$ 's  $\rightarrow \alpha_T \approx \text{constant}$   
 $\rightarrow$  for larger  $\Delta T$ , then  $\alpha_T = f(T)$