

Lecture 26: Equivalent Input Noise

• **Announcements:**

- HW#6 due Thursday, April 27
- Project Slide Set #3 due Friday, April 28
- Module 17 on Noise & MDS has been online

• **Reading:** Senturia Chpt. 16

• **Lecture Topics:**

↳ Minimum Detectable Signal

↳ Noise

– Circuit Noise Calculations

– Noise Sources

– Equivalent Input-Referred Noise

↳ Gyro MDS

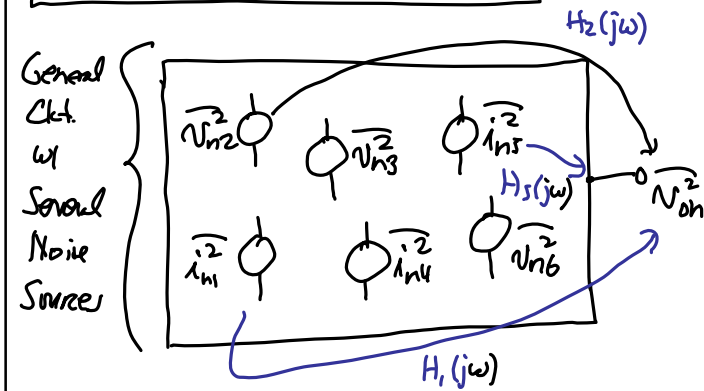
– Equivalent Noise Circuit

– Example ARW Determination

• **Last Time:**

- Circuit noise calculations
- Now, move to noise sources and examples ...

Systematic Noise Calculation Procedure



Assume noise sources are uncorrelated.

① For $\overline{i_{n1}^2}$, replace w/ a source i_{n1} .

② Calculate $N_{on1}(\omega) = i_{n1}(\omega) H_1(j\omega)$
(treating it like a deterministic signal)

③ Determine $\overline{N_{on1}^2} = \overline{i_{n1}^2} \cdot |H_1(j\omega)|^2$

④ Repeat for each noise source:

$$\overline{V_{on2}^2} = f(\overline{V_{n2}^2}), \overline{V_{on3}^2} = f(\overline{V_{n3}^2}), \dots$$

⑤ Add noise power (mean-square values)

$$\overline{N_{onTOT}^2} = \overline{N_{on1}^2} + \overline{N_{on2}^2} + \overline{N_{on3}^2} + \overline{N_{on4}^2} + \dots$$

$$N_{onRMS} = \sqrt{\overline{N_{on1}^2} + \overline{N_{on2}^2} + \overline{N_{on3}^2} + \overline{N_{on4}^2} + \dots}$$

↑
total rms value

Why $\frac{\overline{v_{nR}^2}}{\Delta f} = 4kTR$? (a heuristic argument)

Consider an RC ckt:

$E = \frac{1}{2}kT = \frac{1}{2}C\overline{v_c^2} \rightarrow \overline{v_c^2} = \frac{kT}{C}$ ← integrated noise over all freqs.
(total mean-square voltage integrated over all freqs.)

Question: What value of $\frac{\overline{v_{nR}^2}}{\Delta f}$ gives us this (assume white noise)

$$\overline{v_c^2} = \int_0^{\infty} \left| \frac{1}{1+j\omega RC} \right|^2 \frac{\overline{v_{nR}^2}}{\Delta f} d\omega = \frac{kT}{C}$$

[noise is white] $\rightarrow = \frac{1}{2\pi} \frac{\overline{v_{nR}^2}}{\Delta f} \int_0^{\omega_b} \frac{\omega_b^2}{\omega_b^2 + \omega^2} d\omega$
[$\omega_b = \frac{1}{RC}$]

$\left[\int \frac{dx}{x^2+a^2} = \frac{1}{a} \tan^{-1}\left(\frac{x}{a}\right) \right]$

$$= \frac{1}{2\pi} \frac{\overline{v_{nR}^2}}{\Delta f} \frac{\omega_b^2}{\omega_b} \tan^{-1}\left(\frac{\omega}{\omega_b}\right) \Big|_0^{\infty}$$

$$= \frac{1}{2\pi} \frac{\overline{v_{nR}^2}}{\Delta f} \left(\frac{\pi}{2} \omega_b - 0 \right) = \frac{1}{4} \omega_b \frac{\overline{v_{nR}^2}}{\Delta f} = \frac{kT}{C} \rightarrow *$$

* $\frac{\overline{v_{nR}^2}}{\Delta f} = 4kT \left(\frac{\omega_b}{C} \right) \Rightarrow \frac{\overline{v_{nR}^2}}{\Delta f} = 4kTR$ ✓

bandwidth

Example: Typical Noise Numbers

Measure w/ AC voltmeter

Measure on a Spectrum Analyzer

Probability

Amplitude

Get Gaussian amplitude distribution

