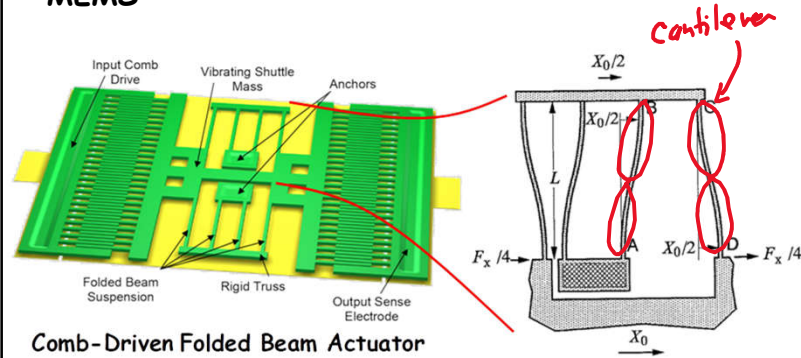


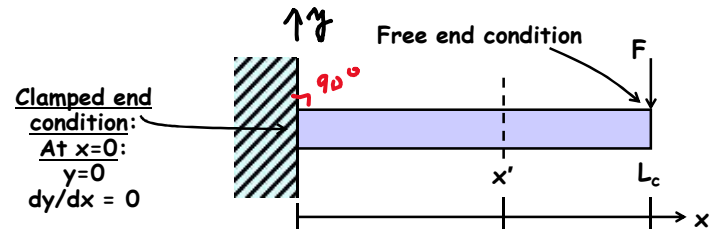
Lecture 13: Beam Bending

- **Announcements:**
- HW#3 due Thursday, 3/7, at 9 a.m.
- Module 8 on "Microstructural Elements" online
- HW#4 online and due Tuesday, 3/19, 9 a.m.
- Midterm less than 3 weeks away
- -----
- Reading: Senturia, Chpt. 9
- Lecture Topics:
 - ↪ Bending of beams
 - ↪ Cantilever beam under small deflections
 - ↪ Combining cantilevers in series and parallel
 - ↪ Folded suspensions
 - ↪ Design implications of residual stress and stress gradients
- -----
- **Last Time:**
- Looking at forces & moments in equilibrium
- Now, continue with this ...

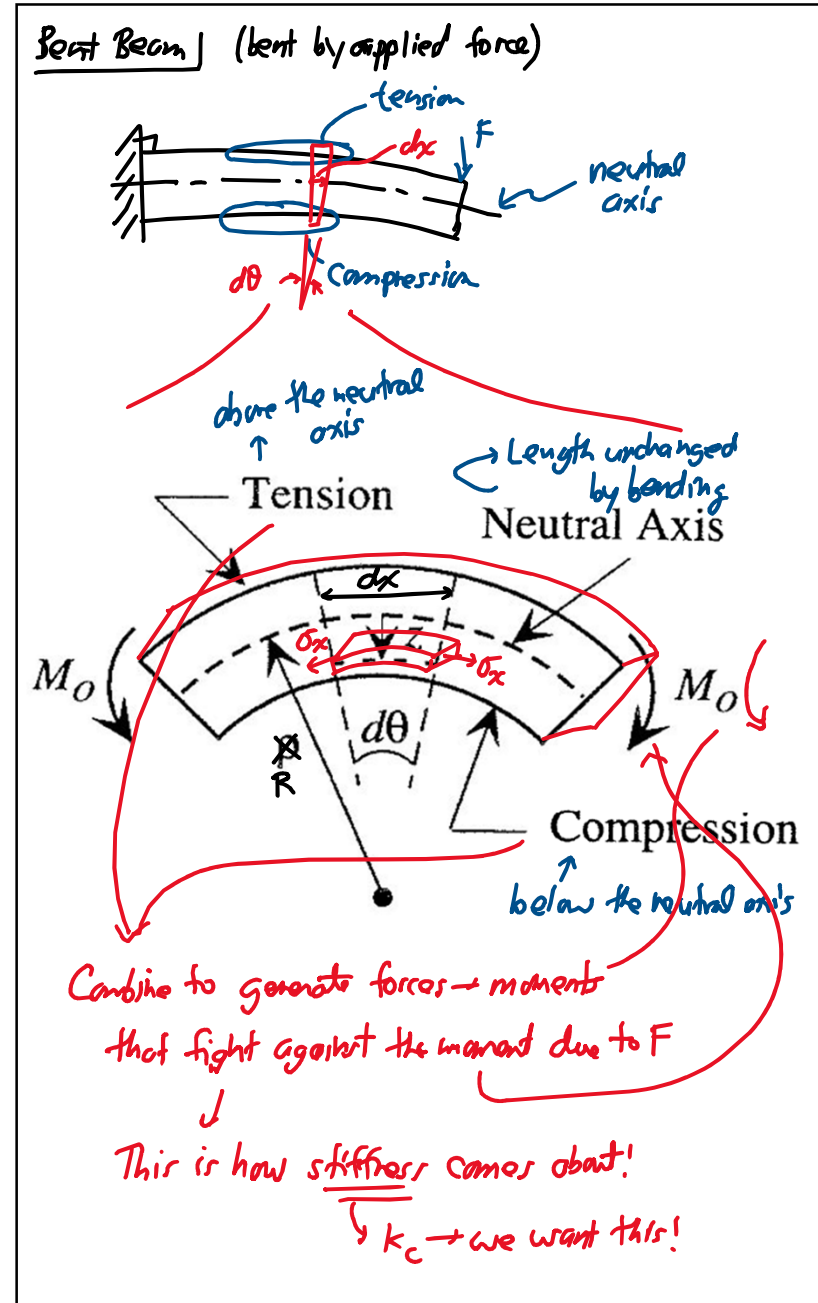
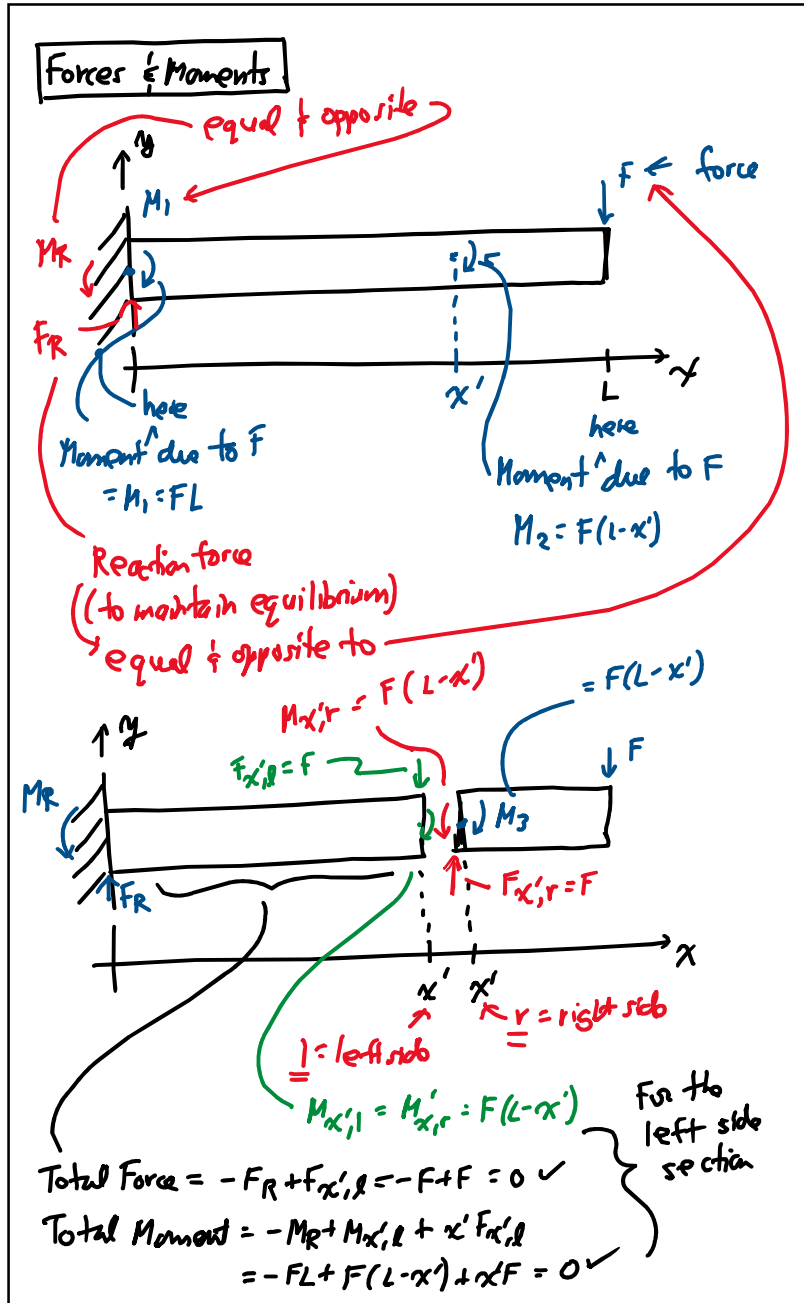
- Springs and suspensions very common in MEMS
- Coils are popular in the macro-world; but not easy to make in the micro-world
- Beams: simpler to fabricate and analyze; become "stronger" on the micro-scale → use beams for MEMS



Problem: Bending a Cantilever Beam



- **Objective:** Find relation between tip deflection $y(x=L_c)$ and applied load F
- **Assumptions:**
 1. Tip deflection is small compared with beam length
 2. Plane sections (normal to beam's axis) remain plane and normal during bending, i.e., "pure bending"
 3. Shear stresses are negligible



Beam Segment in Pure Bending

⇒ consider the segment bounded by the dashed lines defining $d\theta$

At $z=0$: neutral axis → segment length = $dx = R d\theta$ (1)

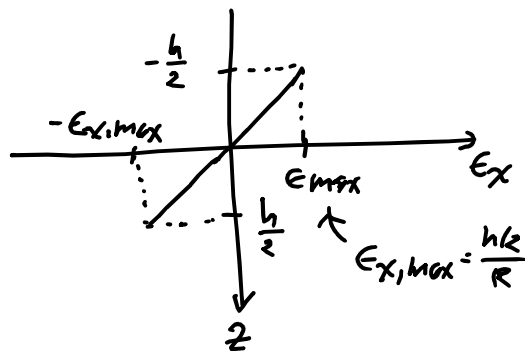
At any z : segment length = $dL = (R-z) d\theta$ (2)

Combine (1) & (2): $dL = dx - z d\theta = dx - \frac{z}{R} dx$

Thus, the axial strain @ z :

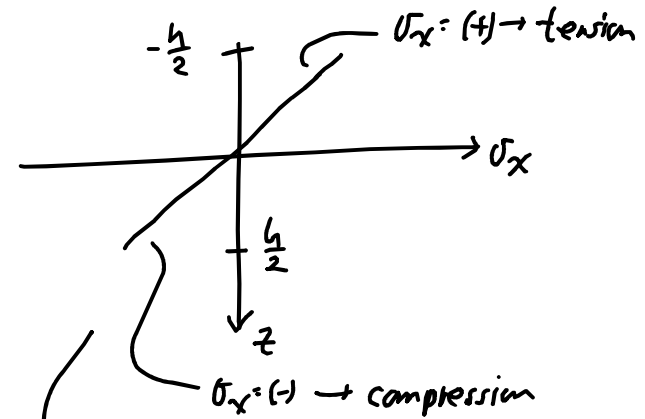
$$\epsilon_x = \frac{dL - dx}{dx} = -\frac{z}{R} = \epsilon_x$$

Thus, the strain varies linearly along the beam thickness:



Of course, there is a corresponding axial stress:

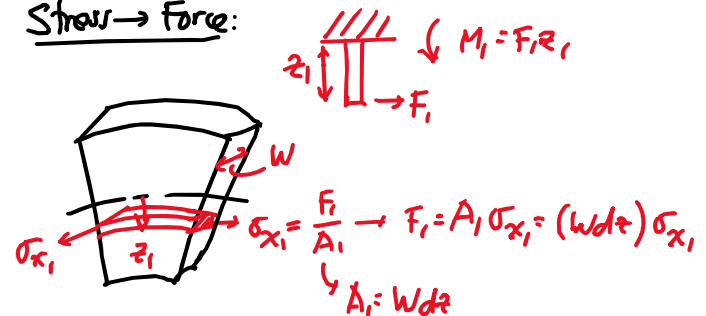
$$\sigma_x = \epsilon_x E = -\frac{zE}{R} = \sigma_x$$



This gradient of stress generates a bending moment!

In response to the original applied moment (generated by F)

Stress → Force:



⇒ Integrate stress through the thickness of the beam:

$$M = \int_{-\frac{h}{2}}^{\frac{h}{2}} \underbrace{[(w dz) \sigma_x]}_{\text{force}} \cdot z$$

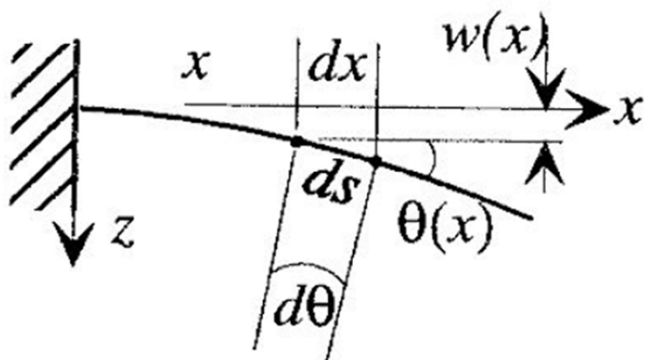
$$= \int_{-\frac{h}{2}}^{\frac{h}{2}} \frac{E w z^2}{R} dz \Rightarrow M = - \left(\frac{1}{12} w h^3 \right) \frac{E}{R}$$

$\left[\sigma_x = - \frac{z E}{R} \right]$ $\frac{1}{12} w h^3 = I \triangleq \text{Moment of Inertia}$

$\frac{1}{R} = - \frac{M}{EI}$

Note: (+) radius of curvature
(-) internal bending moment

Differential Equation for Beam Bending



Write out some geometric relationships:

⇒ then use small angle approx:

$$\cos \theta = \frac{dx}{ds} \rightarrow ds = \frac{dx}{\cos \theta} \rightarrow ds \approx dx$$

$$\tan \theta = \frac{dw}{dx} = \text{slope of the beam @ this point} \rightarrow \theta \approx \frac{dw}{dx} \quad (1)$$

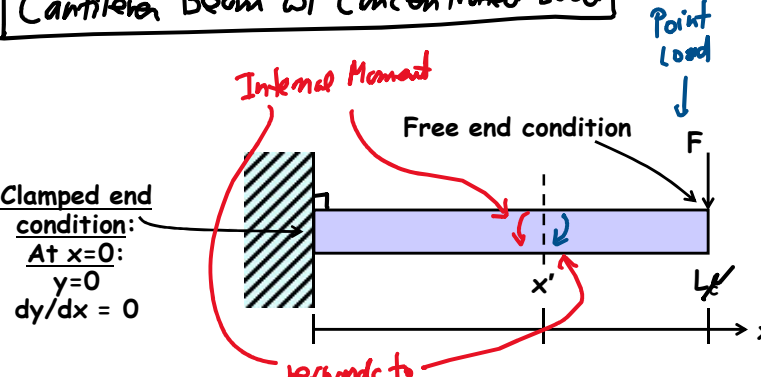
$$ds = R d\theta \rightarrow \frac{1}{R} = \frac{d\theta}{ds} \rightarrow \frac{1}{R} = \frac{d^2 w}{dx^2} \quad (2)$$

Invert (1) into (2):

$\frac{1}{R} = \frac{d^2 w}{dx^2} = - \frac{M}{EI}$

Diff. Eqn. for Small Angle Beam Bending

Cantilever Beam w/ Concentrated Load



Clamped end condition: At $x=0$: $y=0$, $dy/dx = 0$

Free end condition

Point Load F

Internal Moment

Internal Moment @ position x : $M = -F(L-x)$

Thus: $\frac{d^2 w}{dx^2} = \frac{F}{EI}(L-x)$

Clamped End B.C.: $w(x=0)=0, \frac{dw}{dx}(x=0)=0$
Free-End B.C: none

Solve to get w :

⇒ Use Laplace; or a trial solution:

$w = A + Bx + Cx^2 + Dx^3$, then
apply B.C.'s

$$w = \frac{FL}{2EI} x^2 \left(1 - \frac{x}{3L}\right)$$

Deflection @ x due to a point load F
applied @ $x=L$

Maximum Deflection → occurs @ $x=L$:

$$w_{max} = \left(\frac{L^3}{3EI}\right) F \rightarrow F = \left(\frac{3EI}{L^3}\right) w(x=L) = k_c w(x=L)$$

stiffness $= k_c @ x=L$

where $k_c = \frac{3EI}{L^3}$

$[I = \frac{1}{12} Wh^3] \rightarrow k_c = \frac{1}{4} EW \frac{h^3}{L^3}$

Can now be used to solve general beam systems!

Ex. $L=100\mu m, W=2\mu m, h=2\mu m$
polysilicon → $E=150GPa$

$$k_c = \frac{1}{4} (150G) (2\mu) \left(\frac{2\mu}{100\mu}\right)^3 = \underline{\underline{0.6 N/m}}$$

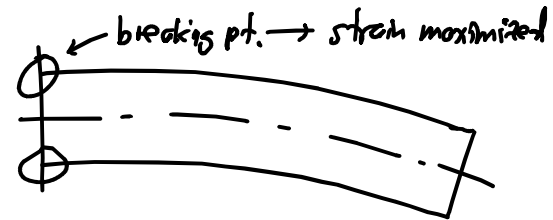
Maximum Stress in a Bent Cantilever

From before, the radius of curvature is given by

$$\frac{1}{R} = \frac{d^2w}{dx^2} = \frac{F}{EI} (L-x)$$

⇒ $\frac{1}{R}$ maximizes (i.e., R minimizes) when

$$x=0: \frac{1}{R} = \frac{d^2w}{dx^2} = \frac{FL}{EI}$$



Strain maximizer:

- ① At top surface → tensile
- ② At bottom surface → compressive

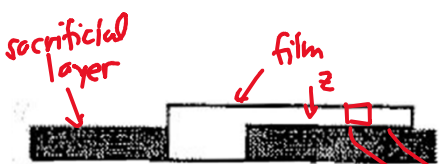
$$\epsilon_{max} = \frac{z}{R} = \frac{h}{2} \frac{1}{R} = \left(\frac{h}{2} \frac{FL}{EI}\right) = \epsilon_{max}$$

$$[I = \frac{1}{12} Wh^3] \Rightarrow \epsilon_{max} = \frac{6L}{EWh^2} F$$

Stress Gradient in a Cantilever

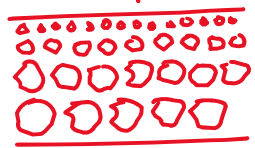
⇒ study beam bending due to a stress gradient

① Deposit film @ high temp.
 ② Cool it down.




Before release

High Temp.



Low Temp.

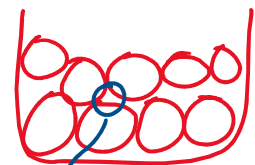
tensile with respect to



relatively compressive

Stress before release

Longer Marbles

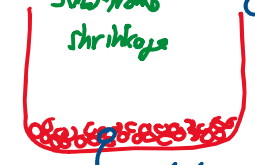


space between marbles

Small Marbles

substrate shrinks

Compress wrt to substrate



much less space between
 they pack better!

Compression

σ_x

$-H/2$

$H/2$

z

σ_0