

Lecture 15: Beam Combos II

- **Announcements:**
- HW#4 online, due Tuesday, 3/19, 9 a.m.
- Midterm Exam: Thursday, March 21, 11-12:30 p.m., 293 Cory (right here)
- No lecture next Tuesday, 3/19
 - ↳ The EECS Faculty Retreat is this day
 - ↳ I will post a video lecture instead

Reading: Senturia, Chpt. 9

Lecture Topics:

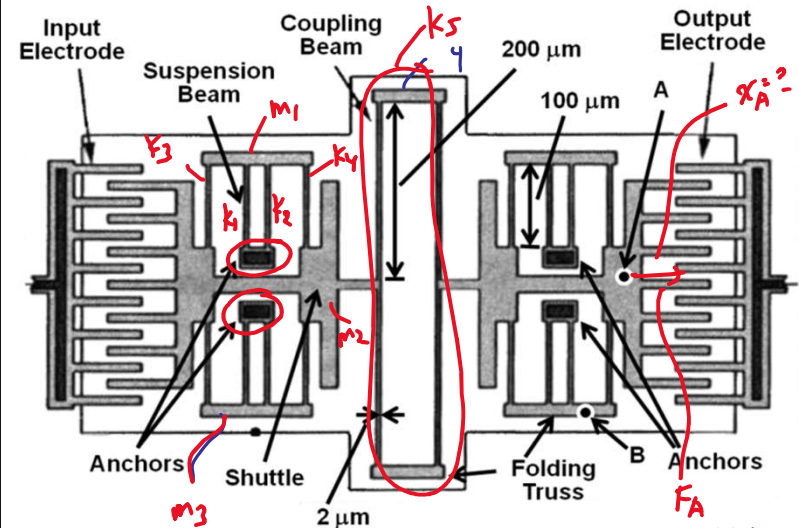
- ↳ Bending of beams
- ↳ Cantilever beam under small deflections
- ↳ Combining cantilevers in series and parallel
- ↳ Folded suspensions
- ↳ Design implications of residual stress and stress gradients

Last Time:

- Spring circuits
- Continue with this



Analyzing an Interconnected Ensemble of Beams
(Springs) & Masses



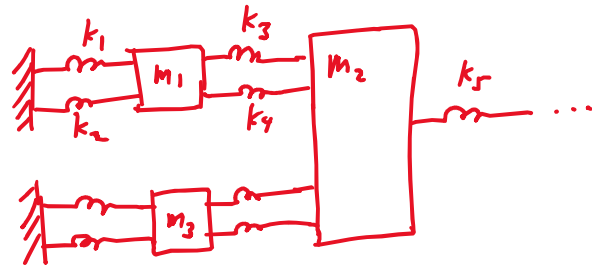
Typical Questions: → all demand knowledge of $x = f(F)$

- ① How does the structure move in response to a force at a specific location. → in turn requires we know stiffness!
- ② What is the frequency response to an AC force that applied at a specific location.
- ③ Noise?
- ④ Response to environmental stimuli? (e.g, rotation)
- ⑤ How does stress affect the behavior of the structure?

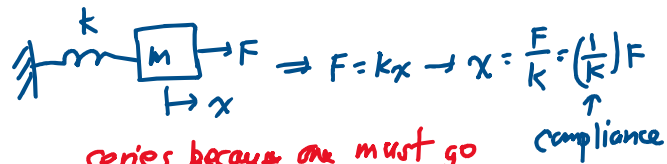
Procedure:

- Build the ckt. (extract the ckt.)
↳ in the x-direction (for this example)

Anchra

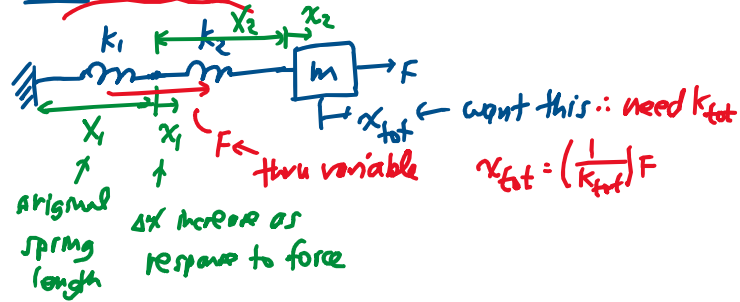


- Analyze to get $x \cdot f(F)$ force
↑ displacement



series because one must go thru both k_1 & k_2 to get from anchor to forcing pt.

- Case 1: series connection of springs forcing pt.



$$x_{tot} = x_1 + x_2 = F \left(\frac{1}{k_1} + \frac{1}{k_2} \right) = \frac{F}{\left(\frac{1}{k_1} + \frac{1}{k_2} \right)} = \frac{F}{k_{tot}}$$

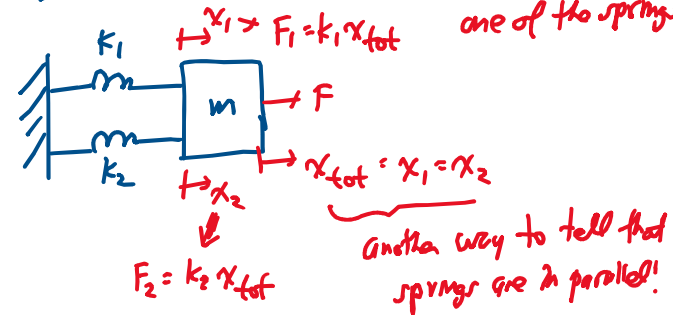
$\left[x_1 = \frac{F}{k_1}, x_2 = \frac{F}{k_2} \right]$

“||” operator $\triangleq A || B = \frac{1}{\frac{1}{A} + \frac{1}{B}} = \frac{AB}{A+B}$

$k_{tot} = k_1 || k_2$ (for k_1 & k_2 in series)

For EE's: $\frac{1}{C_1} || \frac{1}{C_2} \equiv \frac{1}{C_{tot} = C_1 C_2}$
springs combine like capacitors

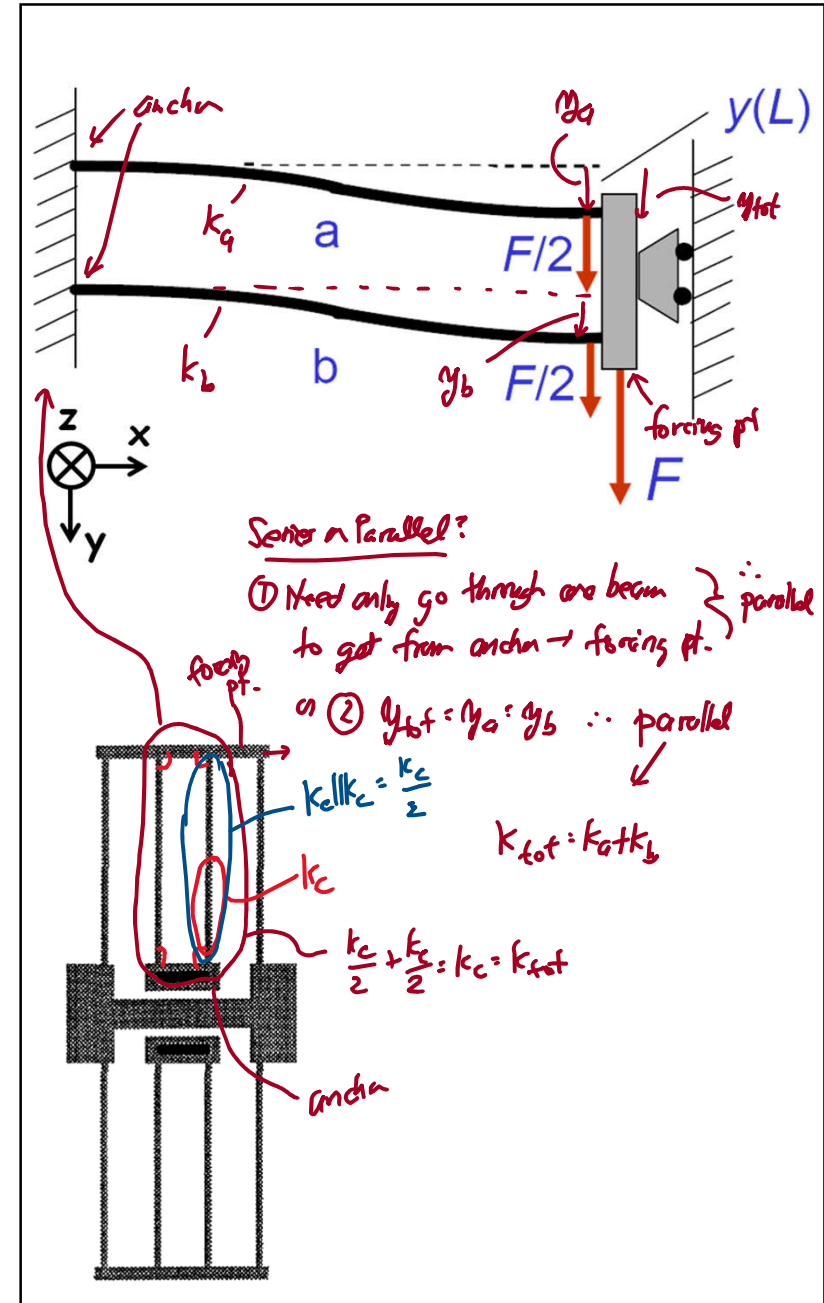
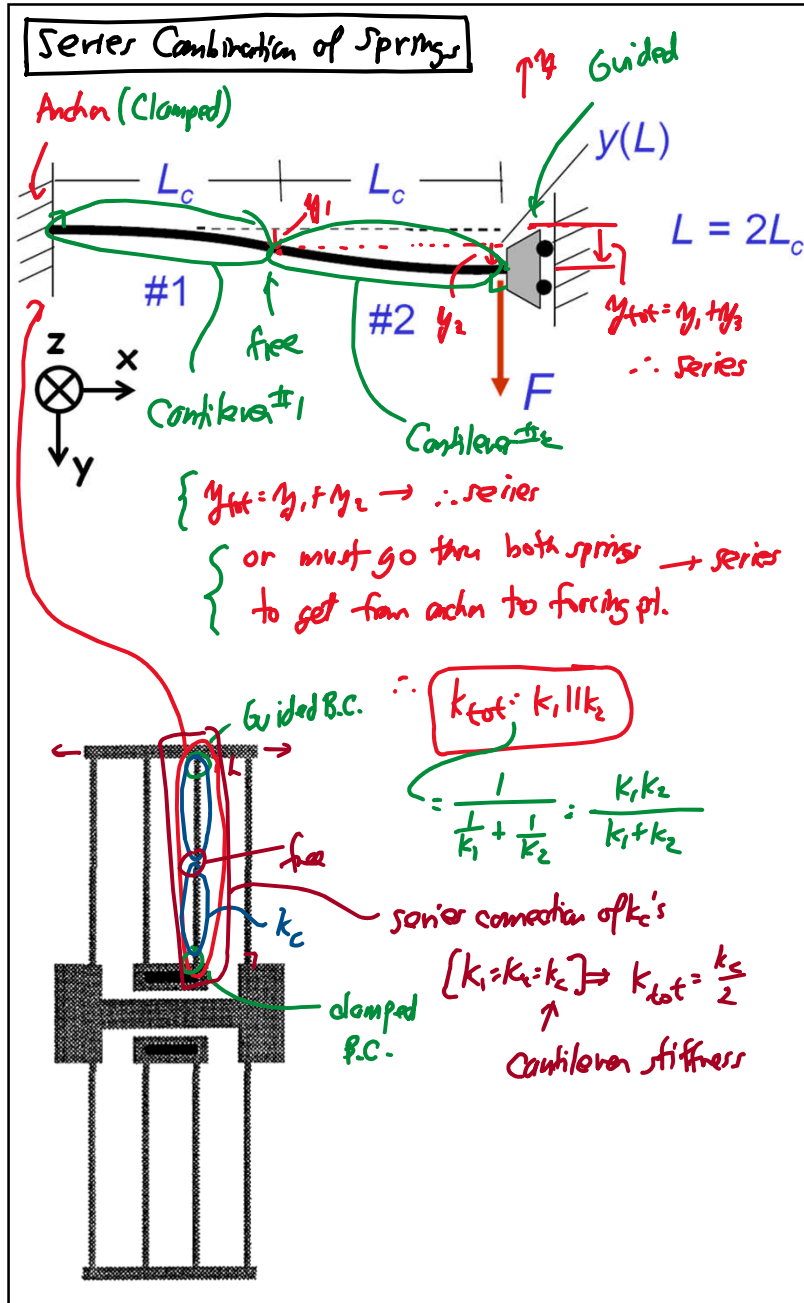
- Case 2: parallel springs to forcing pt. via only one of the springs



$$F = F_1 + F_2 = (k_1 + k_2) x_{tot}$$

k_{tot}

$k_{tot} = k_1 + k_2$ (for k_1 & k_2 in parallel)



Get k_b :

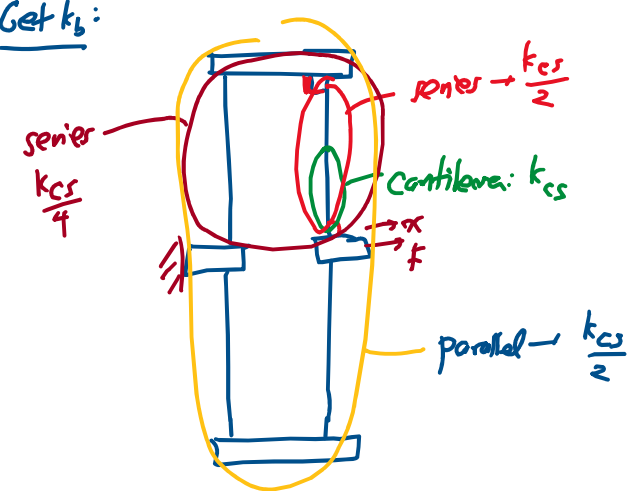


Diagram labels and notes:

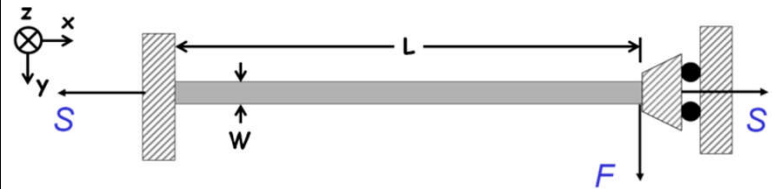
- Senior: $\frac{k_{cs}}{4}$
- Center: $\frac{k_{cs}}{2}$
- Cantilever: k_{cs}
- Parallel: $\frac{k_{cs}}{2}$

$\therefore k_A = k_c + k_{combined}$
 $= k_c + k_c || k_b = k_c + k_c || \frac{k_{cs}}{2} = k_A$

where $k_c = 2Eh \left(\frac{W}{L_r}\right)^3$
 $k_{cs} = 2Eh \left(\frac{W}{L_{cs}}\right)^3$

Tensioned Spring (Non-Ideality)

- Important case for MEMS suspensions, since the thin films comprising them are often under residual stress
- Consider small deflection case: $y(x) \ll L$



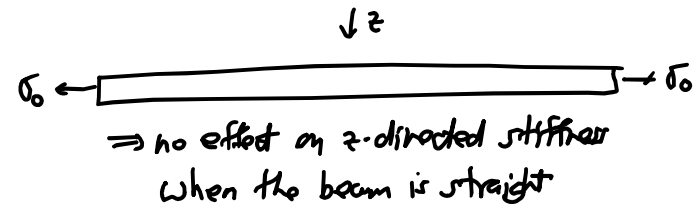
Governing differential equation: (Euler Beam Equation)

$$EI_z \frac{d^4 y}{dx^4} - S \frac{d^2 y}{dx^2} = F \delta(x-L)$$

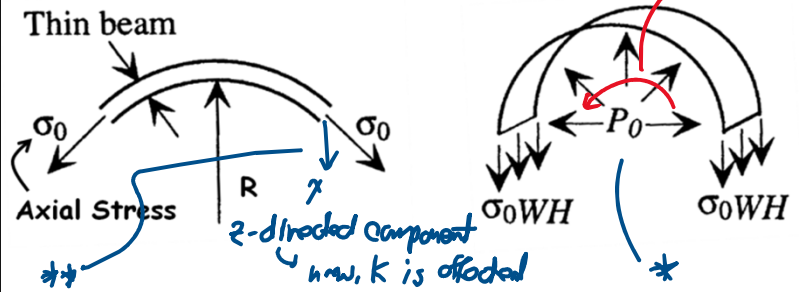
Axial Load Unit impulse @ $x=L$

Heuristic Derivation for the Euler Beam Equation

Consider first a straight beam under an axial stress:



... but when the beam bends:



* Upward pressure P_0 to counteract the downward force from σ_0 to keep everything in static equilibrium

For ease of analysis:

Assume the beam bends to an angle π
 ↓ Downward vertical force: $2\sigma_0 WH$

Get upward force due to P_0 :

$$P_2(\theta) = P_0 \sin \theta$$

$$F_u = \int_0^\pi (P_0 \sin \theta) W (R d\theta)$$

$$= -P_0 W R \cos \theta \Big|_0^\pi$$

$$= 2RW P_0$$

[Equilibrium] $\rightarrow 2RW P_0 = 2\sigma_0 WH \rightarrow P_0 = \frac{\sigma_0 H}{R}$

$\left[q_0 = \frac{\text{beam load}}{\text{unit length}} = P_0 W, \frac{1}{R} = \frac{d^2 w}{dx^2} \right]$ beam displacement

$q_0 = \sigma_0 WH \frac{d^2 w}{dx^2}$ generalizes to the case of small displacements & angles

Using the Differential Beam Bending Eq

$$\frac{d^2 w}{dx^2} = -\frac{M}{EI} \quad \text{???} \quad \frac{d^4 w}{dx^4} = \frac{q}{EI}$$

$\frac{\text{load}}{\text{unit length}}$

* Relationship Between Forces & Moments on a Fully-Loaded Differential Beam Element

