

Lecture 24: Sensing Circuits II & Integration

- **Announcements:**
- Project Slide Set #3 due Friday, April 26
- HW#7 online and due Friday, 5/10, at 9 a.m.
- Module 16 on Sensing Circuit Non-Idealities & Integration online

• Reading: Senturia, Chpt. 14

• Lecture Topics:

↳ Detection Circuits

- Velocity Sensing
- Position Sensing

• Reading: Senturia Chpt. 14, 15

• Lecture Topics:

↳ Ideal Op Amps

↳ Op Amp Non-Idealities

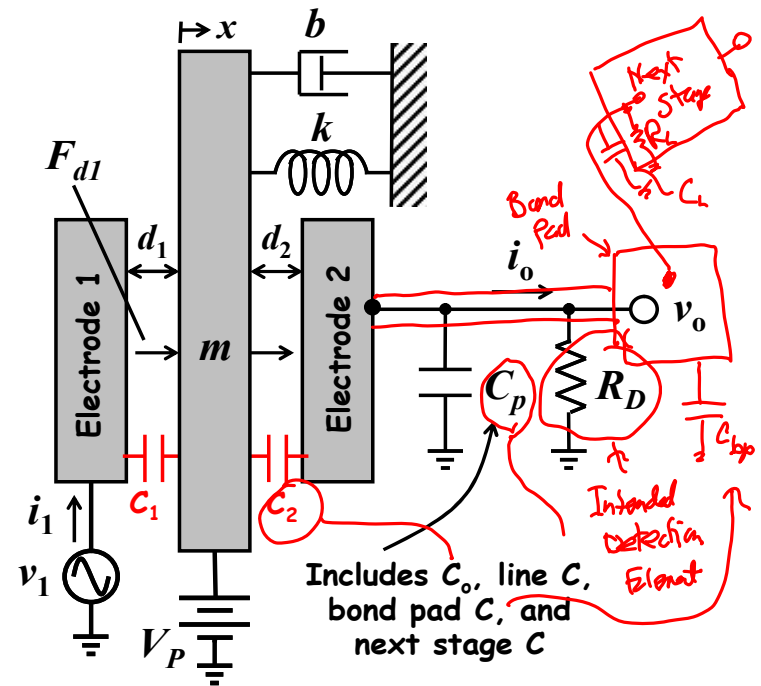
↳ MEMS-Transistor Integration

- Mixed
- MEMS-First
- MEMS-Last

• **Last Time:**

• Finished velocity sensing

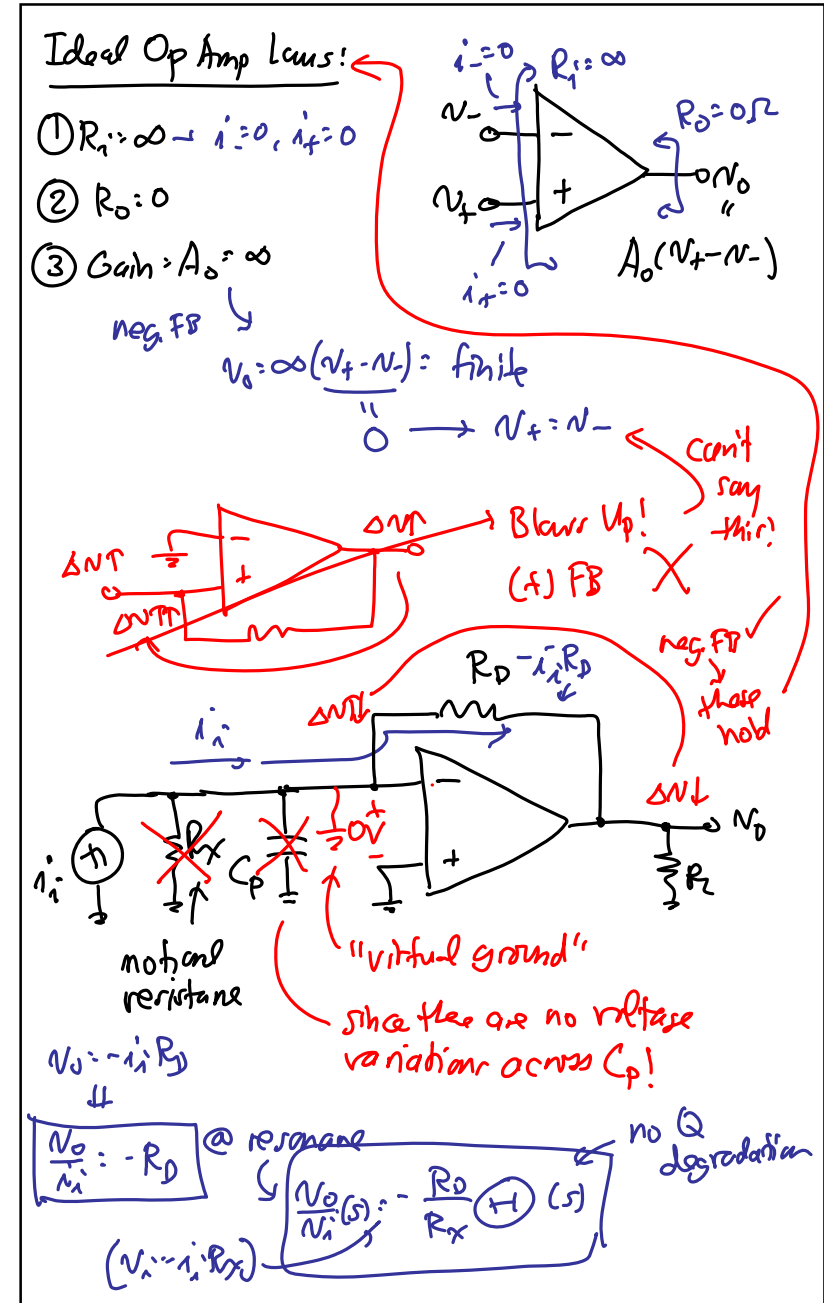
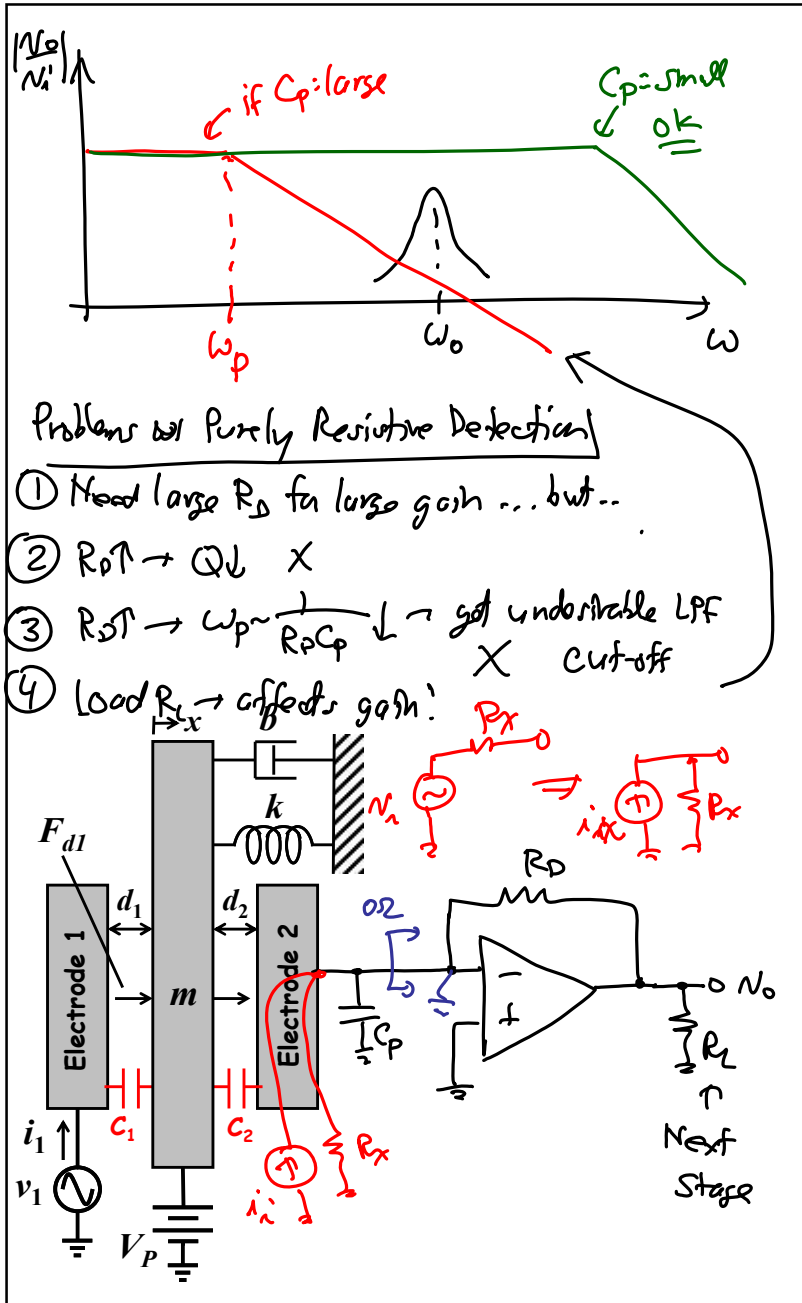
The Problem is Actually Bigger!



Now, we get:

$$\frac{V_o}{V_i}(s) \sim \frac{R_o}{R_x + R_D} \cdot \frac{1}{1 + \frac{s}{\omega_p}} \cdot (H)(s, \omega_o', Q')$$

$$\omega_p = \frac{1}{(R_x)(R_D)C_p}$$



- Now, go through position sensing slides in Module 14
- Then go through non-ideal op amp slides and integration in Module 16