

Lecture 3-4: Benefits of Scaling II

- Announcements:
- As announced last time, I am on travel right now
- This is a pre-recorded video
- The notes from last time are online, as well as the video - both in the Lecture link table
- Modules 1 & 2 are online (also, in the Lecture link table)
- Get your computer accounts by following the instructions at the end of the Course Info Sheet
- HW#1 is online and due Thursday, Feb. 7, at 9 a.m. via Gradescope, which Kyle will set up for you
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- Today:
- Reading: Senturia, Chapter 1
- Lecture Topics:
 - ↳ Benefits of Miniaturization
 - ↳ Examples
 - GHz micromechanical resonators
 - Chip-scale atomic clock
 - Micro gas chromatograph
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- Last Time:
- Going through Module 2, looking at how scaling vibrating RF MEMS provides both benefits and problems that one must circumvent
- Continue with this now

Scaling: 2x, 1/2x
↓

① Scale all dimension equally by a factor S

$$f_0 \sim \frac{S}{S^2} = \frac{1}{S}$$

② If scale L only: $f_0 = \frac{1}{S^2}$ → even faster rate in freq!
 (...but problems...)

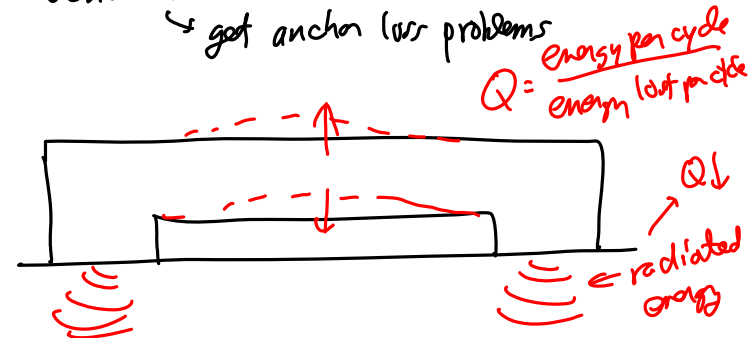
Example.

$$L = 4 \mu\text{m} \rightarrow f_0 = (1.03)(8076) \frac{24}{(4\mu)^2} = 1.04 \text{ GHz}$$

ignore width effects → really need $\sim 3 \mu\text{m}$
 questionable thing to do

Remarks.

- ① Eq.(1) not accurate when $L \approx W \approx h$
- ② When $L \approx h$ (a when it isn't more than $10 \times h$)
 ↳ get anchor (our problems)



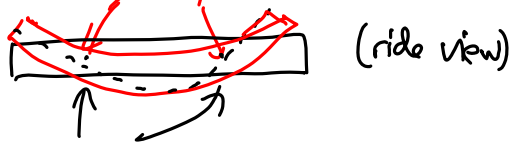
↓
Soln:

③ Solution: use nanodimensions! ✓
 ex. $h=300\text{nm}$, $L \sim 1\mu\text{m}$
 $k \rightarrow$ small
 \rightarrow very little anchor loss $\rightarrow Q \sim 1,000$

↓
Problem: power handling ↓ when size ↓
 ↓
Soln: use massive numbers in arrays

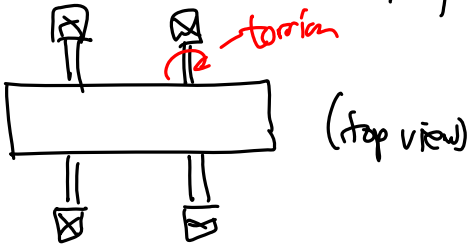
④ Better Soln: use other geometries

Free-Free Beam: nodal point



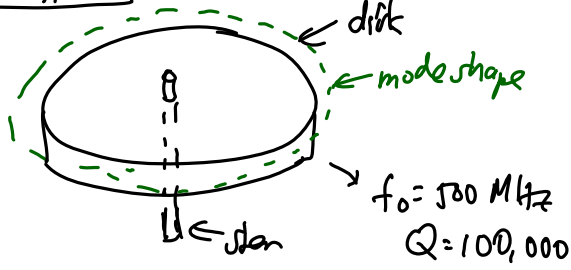
(side view)

no vertical motion → less loss from pumping into the substrate

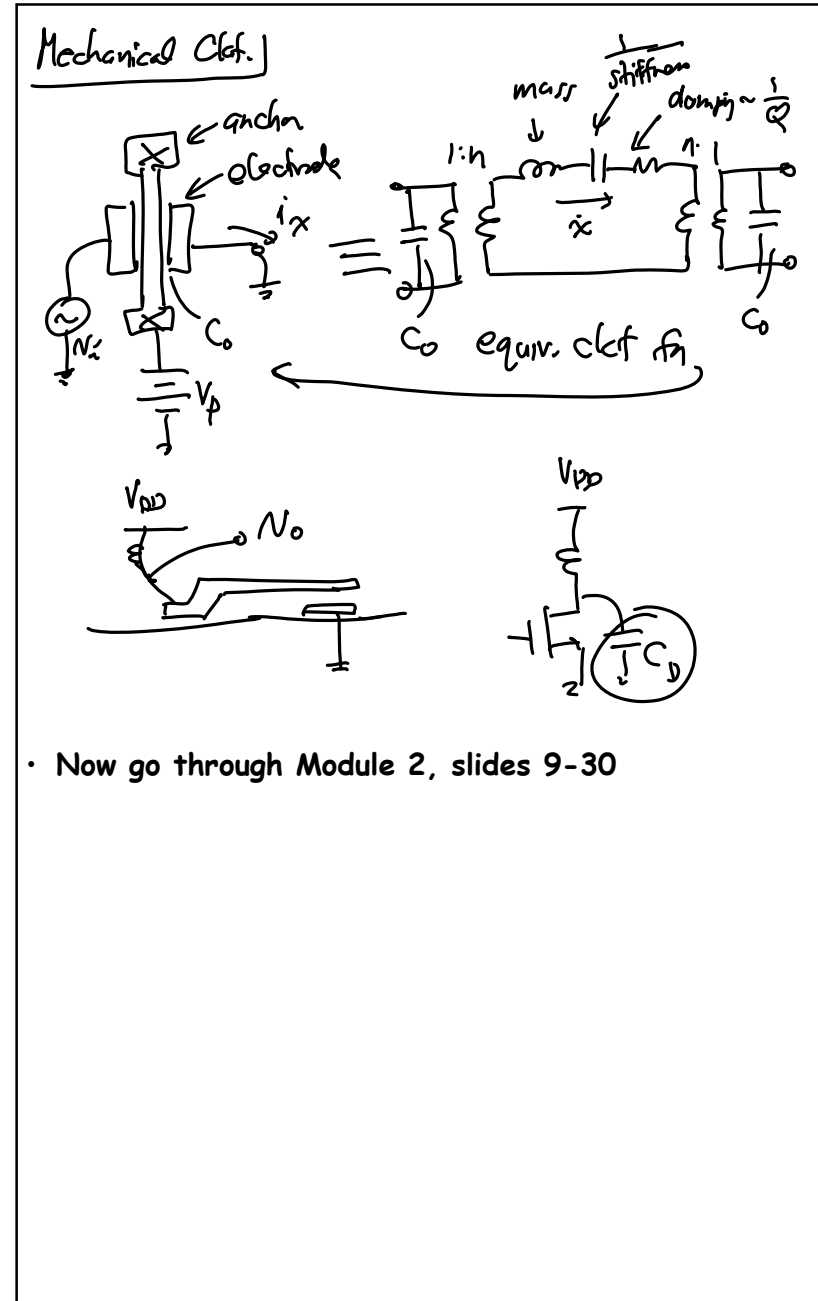
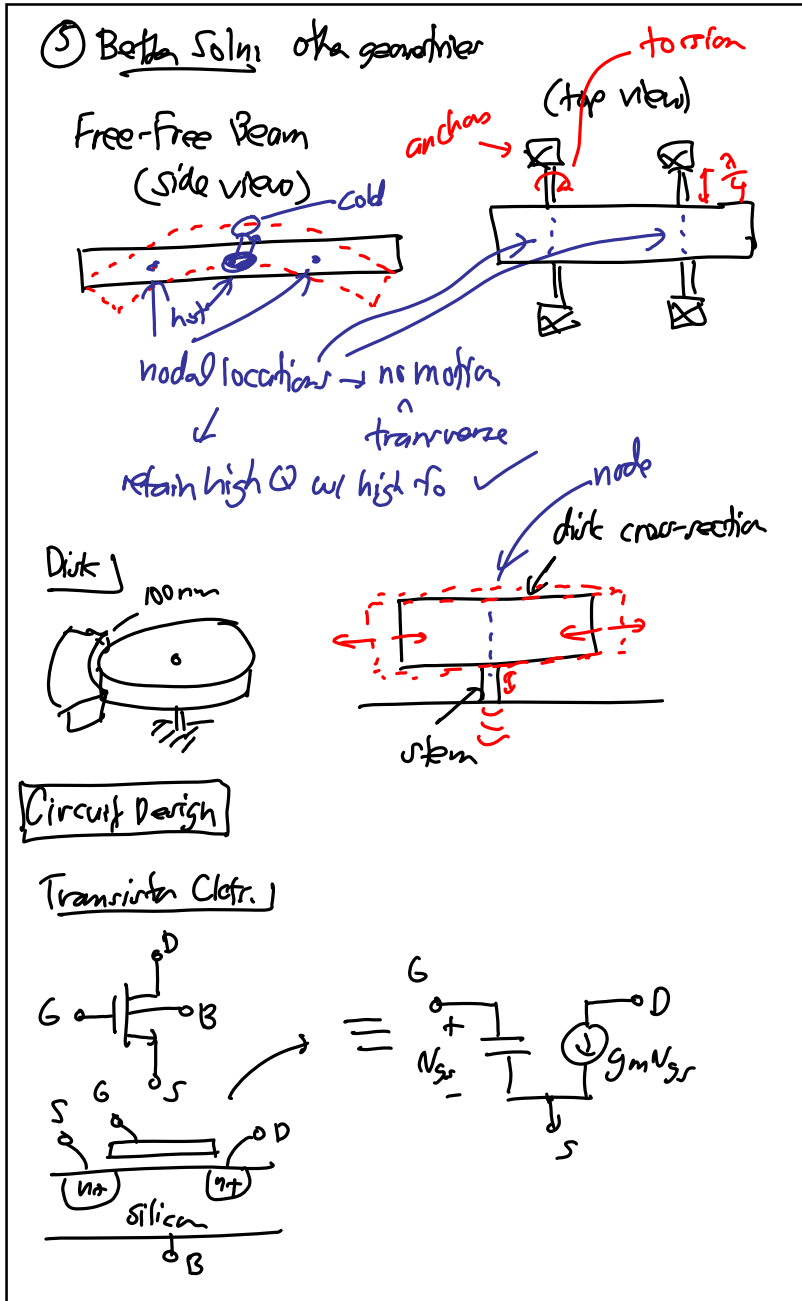


(top view)

Even Better Approach



disk
 mode shape
 $f_0 = 500\text{ MHz}$
 $Q = 100,000$
 disk



Review Electrical Resistance First
 (then attack the thermal R analogy)

$l = \text{length}$
 $A = hw$ ← cross-sectional area
 d ← thickness
 w ← width
 h ← height

$R_e \triangleq \text{electrical resistance} = \frac{l}{\sigma A}$
 \uparrow electrical conductivity

$C_e = \text{capacitance} = \frac{\epsilon_0 \omega L}{d}$
 \uparrow permittivity

$\hookrightarrow \text{Stored Energy (charge energy)} = \frac{1}{2} CV^2 = E$
 \uparrow voltage across the capacitor
 \uparrow capacitance

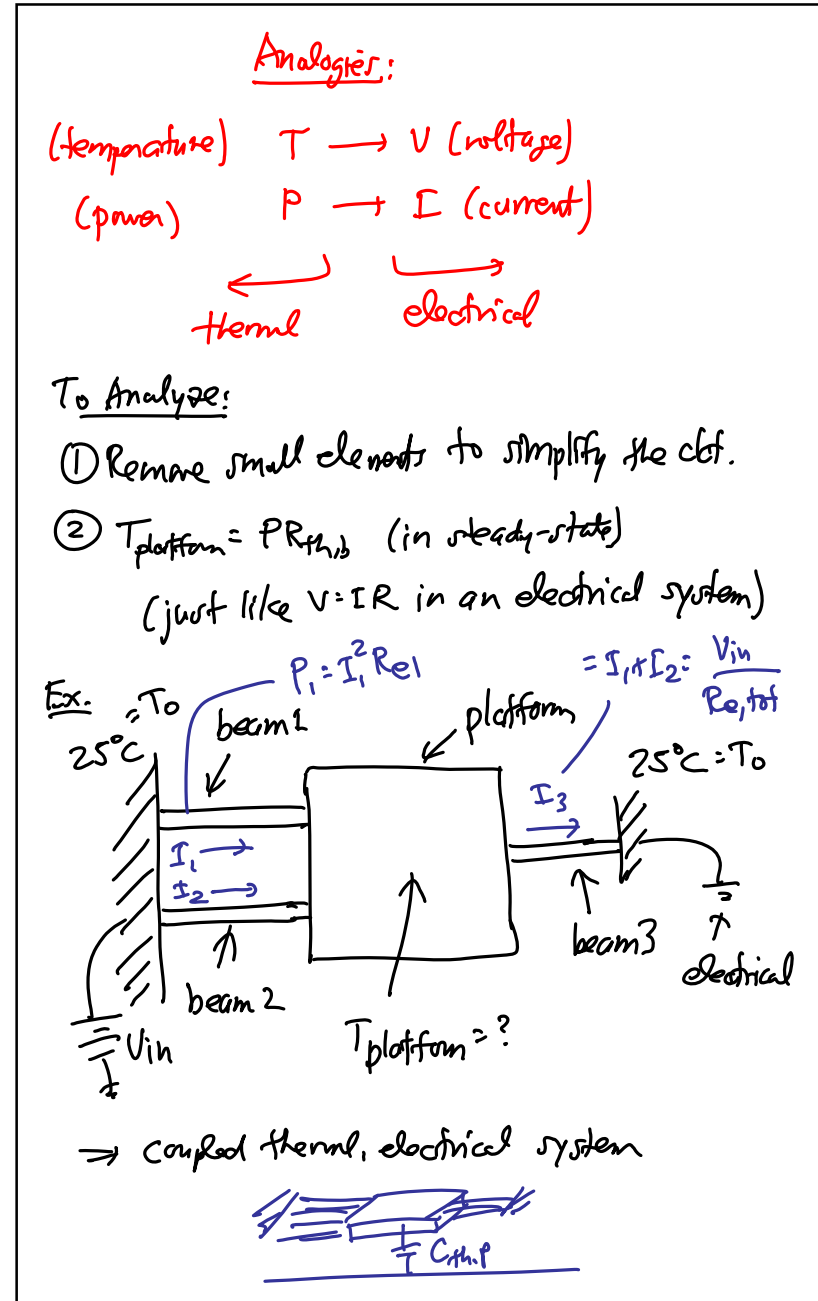
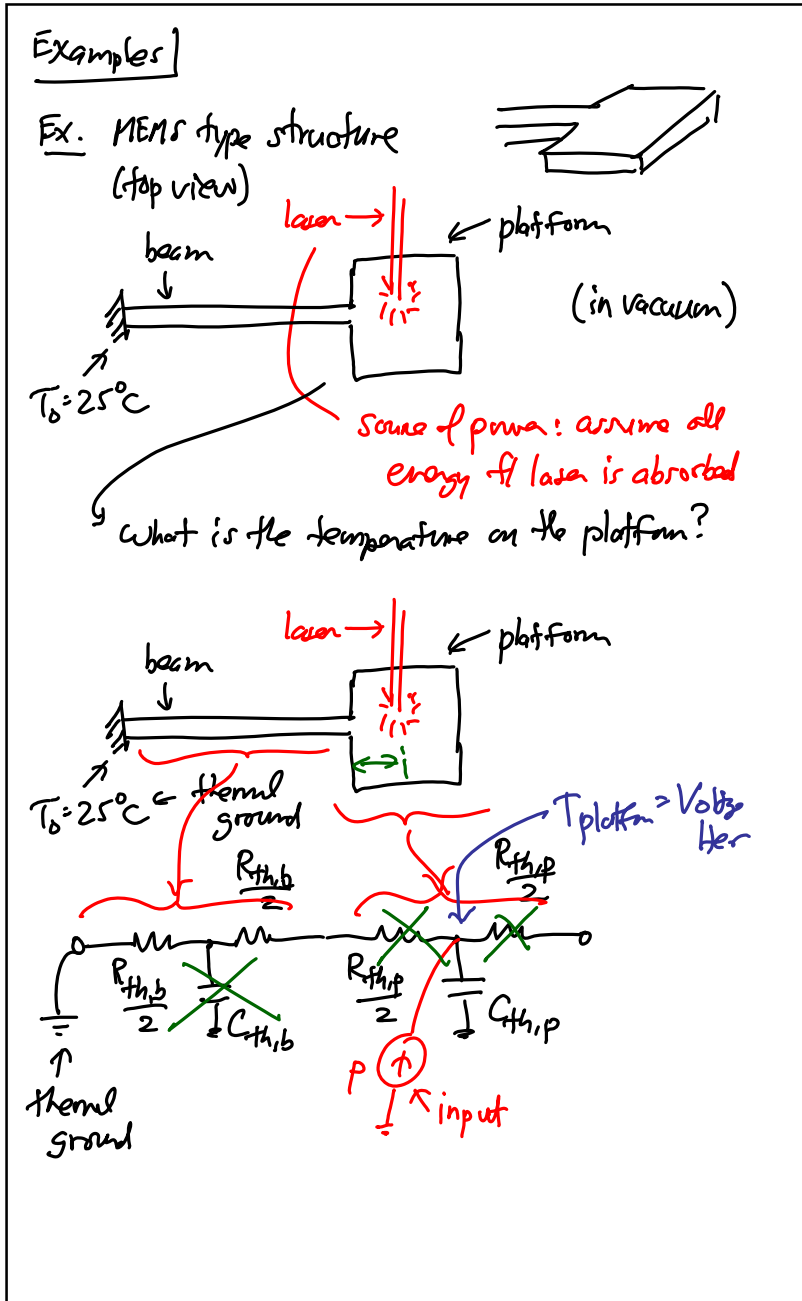
\Rightarrow if want to be more exact:

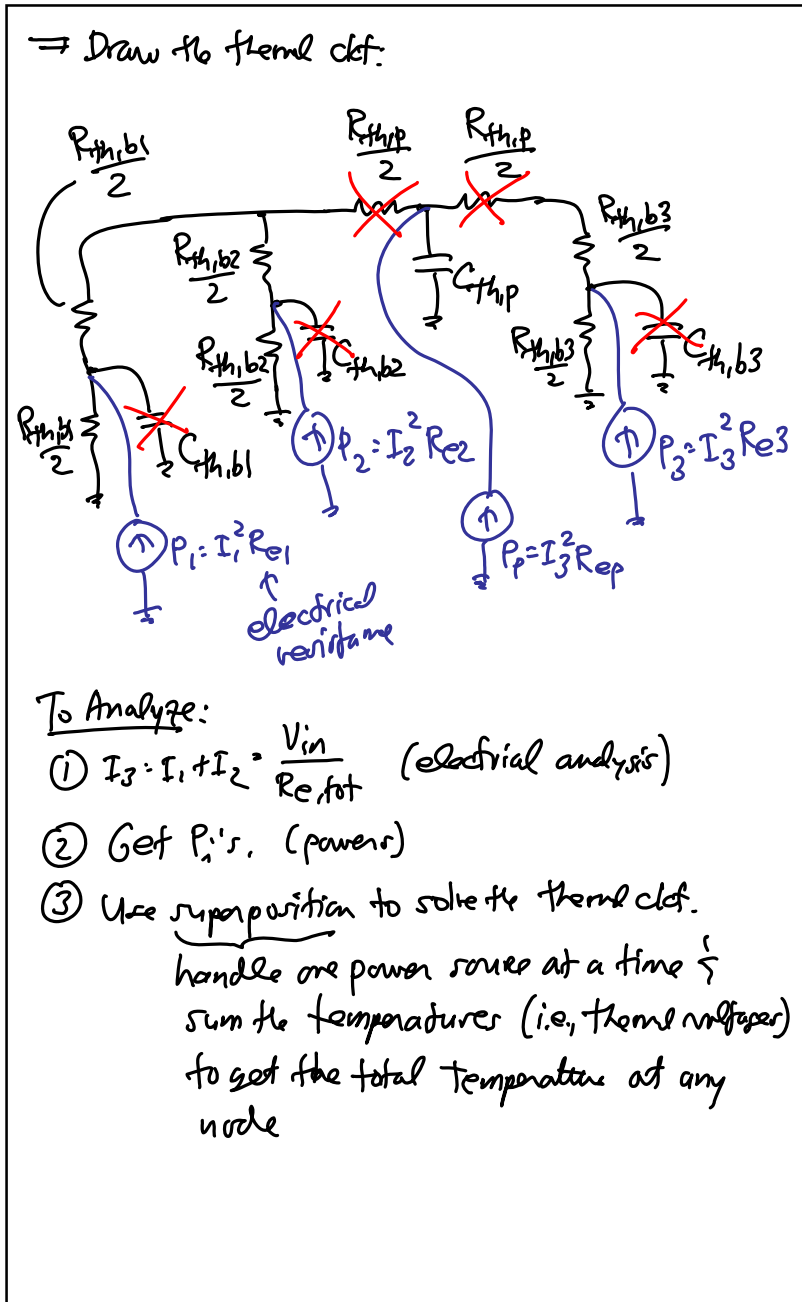
Thermal Ckt.:

$A = hw$

\Rightarrow thermal capacitance: $C_{th} = \rho V C_p$
 \uparrow density
 \uparrow volume
 \uparrow specific heat
 \rightarrow stores thermal energy

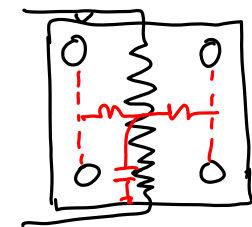
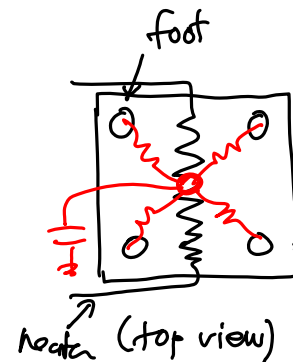
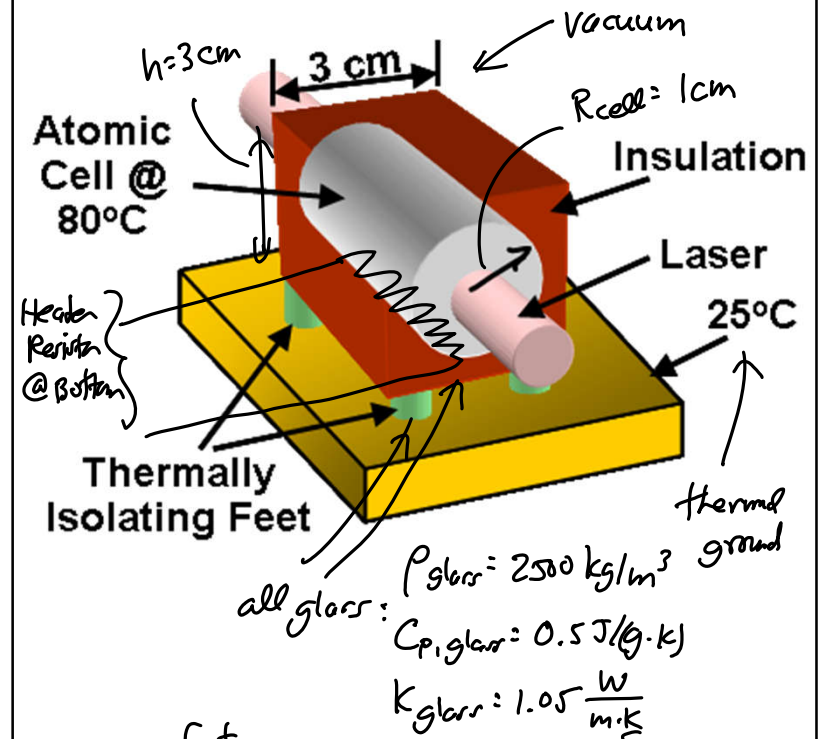
\Rightarrow thermal resistance:
 $R_{th} = \frac{l}{kA}$
 \uparrow thermal conductivity
 \uparrow cross-sectional area
 \leftarrow length

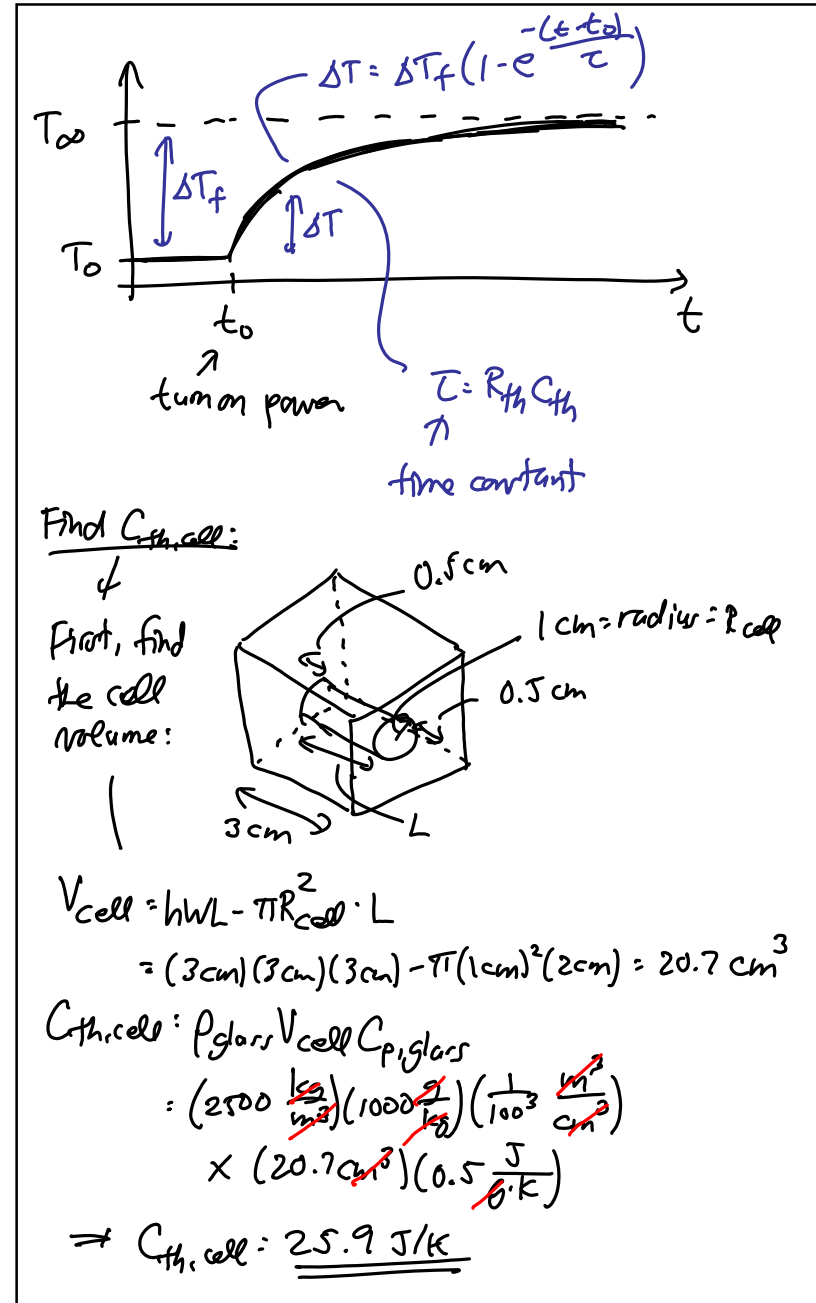
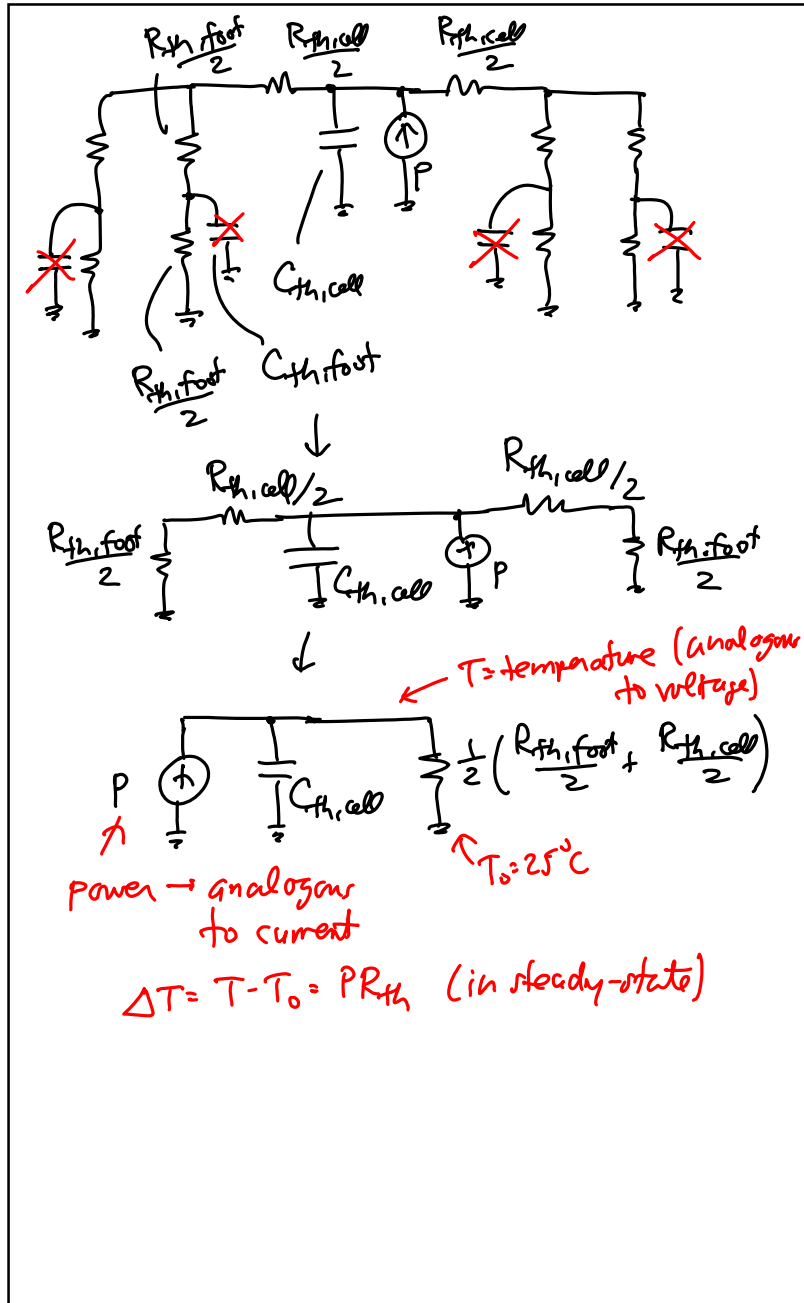




Example: Thermal Ckt.

⇒ determine the power needed to get this atomic cell to 80°C (from RT) & how fast





Find $\frac{R_{th,cell}}{2}$:

large R
↑
negl.

(cross-section)

$R_{th,cell}/2$

0.25 cm
0.25 cm
0.5 cm
foot
foot

$C_{th,cell}$

3 cm
0.5 cm
0.25 cm

$$\frac{R_{th,cell}}{2} = \frac{\frac{3}{4}}{k(3)(\frac{1}{2})} + \frac{\frac{3}{4}}{k(3)(1)} = \frac{1}{k} \left(\frac{1}{8} + \frac{1}{4} \right) = \frac{3}{8} \frac{1}{k}$$

$[R_{th} = \frac{l}{kA}] \quad \therefore \frac{R_{th,cell}}{2} = \frac{3}{8} \frac{1}{1.05} \times (100 \frac{cm}{m})$

$$= 35.7 \text{ kW}$$

neglect

lot more current here than here

Find $R_{th,foot}$:

$A_{foot} = \pi R_{foot}^2$

$R_{foot} = 2 \text{ mm}$

$l_{foot} = 2 \text{ mm}$

$$\therefore R_{th,foot} = \frac{l_{foot}}{kA_{foot}} = \frac{2 \text{ mm}}{(1.05 \frac{W}{m \cdot K}) \pi (2 \text{ mm})^2} = 151.6 \frac{K}{W}$$

Then:

$$R_{th} = \frac{1}{2} \left(\frac{R_{th,foot}}{2} + \frac{R_{th,cell}}{2} \right) = \frac{1}{2} \left(\frac{151.6}{2} + 35.7 \right)$$

$$\Rightarrow R_{th} = 55.8 \text{ kW}$$

\Rightarrow Find the power req'd to maintain $T_{oo} = 80^\circ C$ in steady-state:

$$P = \frac{T_{oo} - T_o}{R_{th}} = \frac{(80 - 25)}{55.8} = 0.99 \text{ W} \sim (1 \text{ W})$$

\Rightarrow Find the time constant:

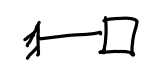
$$\tau = R_{th} C_{th,cell} = (55.8) (25.9) = 24 \text{ min.}$$

\hookrightarrow It takes $\sim 3\tau$ to reach steady-state

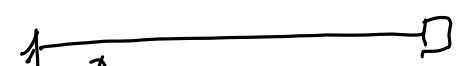
\therefore must wait 72 min. before using this atomic cell

How about using MEMS?


- ⇒ same question as: "How about scaling this?"
- ⇒ much smaller cell volume → weight ↓
- ⇒ can get away from feet support. → Volume ↓ → Gravitational force ↓ → more to tethers

Macro: 

↓ Shrink dimensions

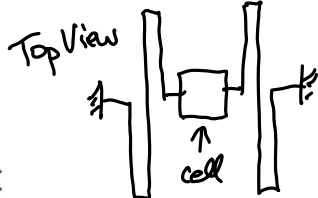
Micro: 

much longer, thinner support to suspend the cell (w/o droop)

 droop

MEMS Atomic Cell

300x300x300 μm^3
 Atomic Cell @ 80°C

Top View 

Heater
 Laser
 T Sensor (underneath)
 Long, Thin Polysilicon Tethers

25°C

Cell is hollow w/ 10 μm -thick walls.

folded to save space & relieve stress
 Unfolded length = 500 μm -long
 10 μm -thick, 20 μm -wide

$$V_{\text{cell}} = (300\mu)(300\mu)(300\mu) - (280\mu)(280\mu)(280\mu)$$

$$= 5.048 \times 10^{-12} \text{ m}^3$$

(much smaller than macro cell!)

$$C_{th, cell} = \rho_{glass} V_{cell} C_{p, glass}$$

$$= (2500 \frac{kg}{m^3}) (5.048 \times 10^{-12} m^3) (500 \frac{J}{kg \cdot K})$$

$$= 6.31 \times 10^{-6} J/K \leftarrow \sim 4 \text{ million } \times \text{ smaller than macro!}$$

$$R_{th, supp} = \frac{R_{supp}}{k_{poly} W_{supp} \cdot h_{supp}} = \frac{500 \mu}{(30 \frac{W}{mK}) (20 \mu) (10 \mu)}$$

$$\Rightarrow R_{th, supp} = \underline{83,333 \text{ kW}} \rightarrow 1493 \times \text{ larger than macro!}$$

and...

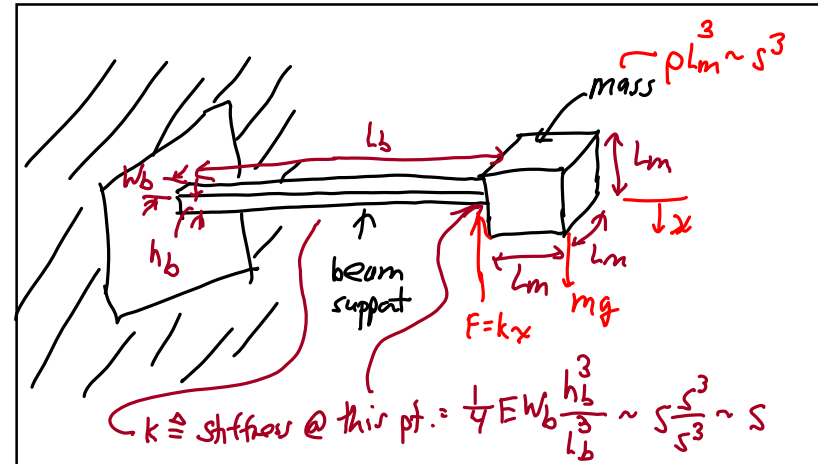
$$P = \frac{(80-25)}{83,333} = \underline{0.66 \text{ mW}} \leftarrow 1493 \times \text{ smaller than macro!}$$

$$\tau = \underline{0.535} \leftarrow 2727 \times \text{ faster than macro!}$$

All due to scaling!

Remarks. (What makes this possible?)

- ① Scaling reduces $C_{th} \sim l^3 \rightarrow s^3$
 $\downarrow s \rightarrow C_{th, cell}$
- ② Scaling allows the use of long, thin tethers
 $R_{th, MTT}$



@ static equilibrium:

Force due to Gravity = Spring Force

acceleration due to gravity $mg = kx$ \leftarrow displacement x

$$x = \frac{m}{k} g \sim \frac{s^3}{s} \sim s^2$$

\downarrow
as $s \downarrow \rightarrow x \downarrow$

drop

$$R_{th} = \frac{L_b}{k_{th} w_b h_b} \rightarrow \text{want to raise this (for a lower power consuming atomic cell) but maintain the same drop } x$$

$$\begin{aligned} * \quad \rho L_m g &= \frac{1}{4} E W_b \frac{h_b^3}{L_b^3} \alpha \\ \frac{L_b}{W_b h_b} &= \frac{1}{4} E \frac{h_b^2}{L_b^2} \alpha \frac{1}{\rho L_m g} \sim \frac{s^2}{s^2} \frac{1}{s^3} \sim \frac{1}{s^3} \\ &\sim R_{TA} \end{aligned}$$

as $s \downarrow \rightarrow \frac{L_b}{W_b h_b} \sim R_{TA} \uparrow \uparrow \uparrow$

- Go through slides 30-31 and 37-48 in Module 2 to finish up Thermal Circuits and cover Micro Gas Analyzers