

# *A Framework for Comparing Models of Computation*

[1998 by Edward Lee & Alberto Sangiovanni-Vincentelli]

Tobias Welp



University of California at Berkeley  
EECS Department

# Agenda:



## **1. Introduction**

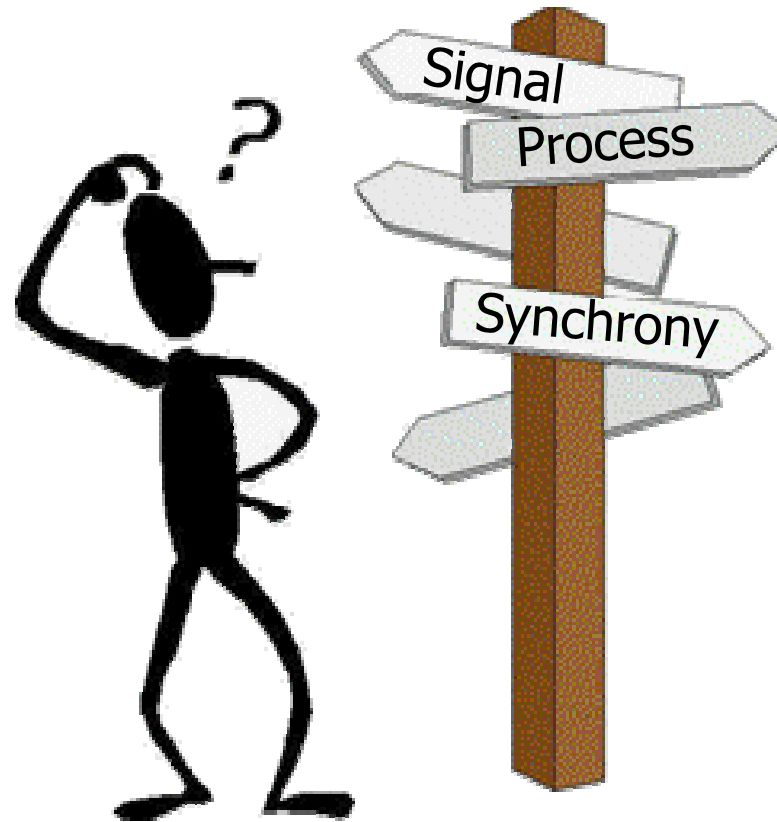
2. Tagged Signal Model

3. Modeling of Time and Causality

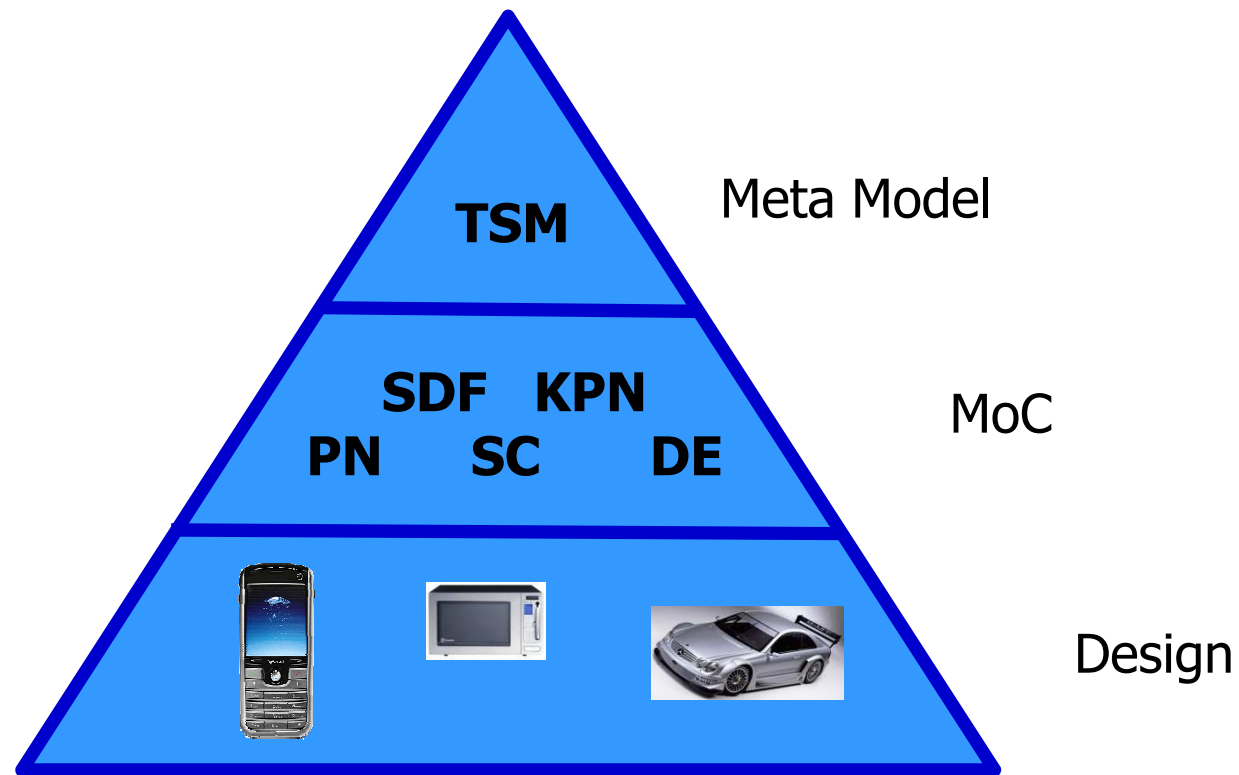
4. Transformations of Tag Systems

5. Summary

# Confusion



# Meta Model



# Agenda:

1. Introduction



**2. Tagged Signal Model**

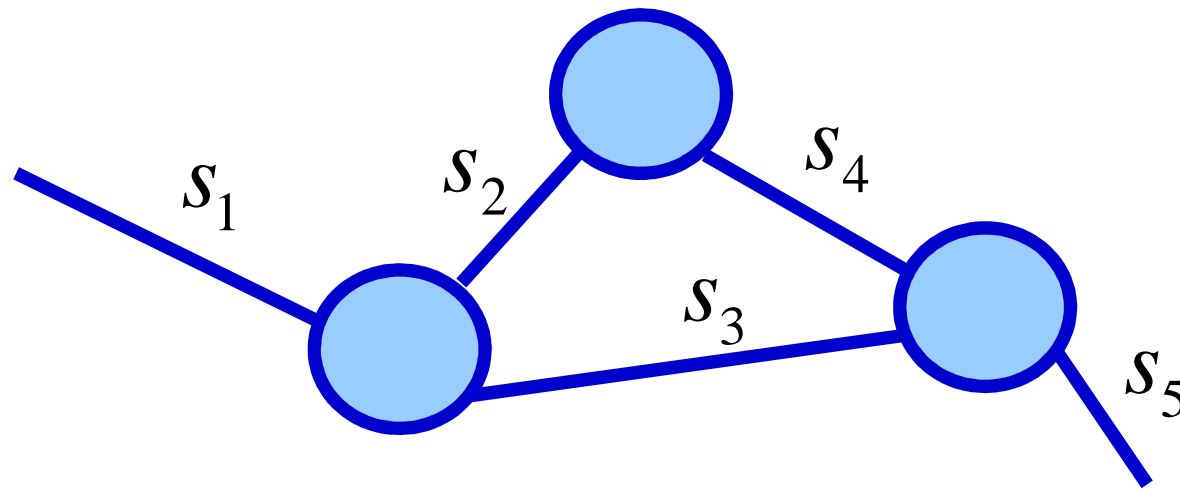
3. Modeling of Time and Causality

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2. Tagged Signal Model

# Signals



## 2. Tagged Signal Model

## Preliminary Definitions

Values  $V = \{v_1, v_2, \dots\}$

Tags  $T = \{t_1, t_2, \dots\}$

Event  $e \in T \times V$  e.g.  $e_1 = (t_2, v_1)$

Signal  $s = \{e_1, e_{10}, e_3 \dots\}$

e.g.  $s = \{(t_2, v_2), (t_6, v_3), (t_1, v_3)\}$

## 2. Tagged Signal Model

# Functional Signals

We call a signal  $S$  *functional* if for all two events

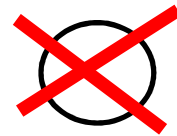
$$e_i = (t, v_i), e_j = (t, v_j) \in S$$

follows that  $v_i = v_j$

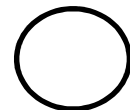
Quiz: 1.

$$S = \{(1,3), (2,2), (3,3)\}$$

Functional?



Yes



No



## 2. Tagged Signal Model

# Functional Signals

We call a signal  $S$  *functional* if for all two events

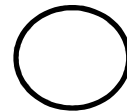
$$e_i = (t_i, v_i), e_j = (t_i, v_j) \in S$$

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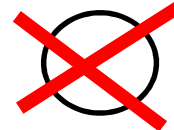
Quiz: 2.

$$S = \{(\blacksquare, a), (\blacksquare, b), (\blacksquare, a)\}$$

Functional?



Yes

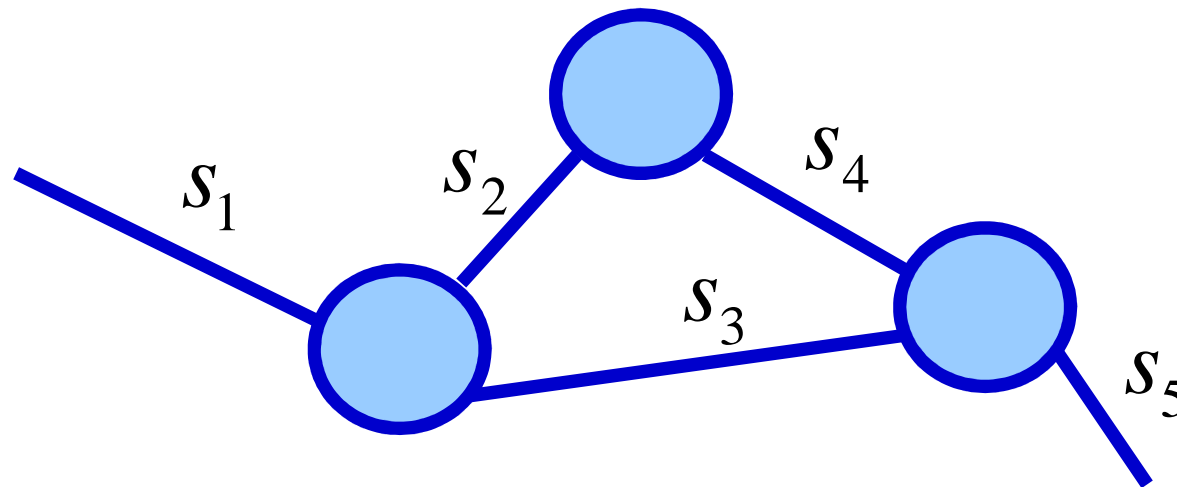


No

## 2. Tagged Signal Model

## Tuples of Signals

$$S^N = (s_1, s_2, \dots, s_N)$$



Set of all those tuples:  $S^N$

## 2. Tagged Signal Model

## Empty Signals

$$\lambda = \emptyset \in S$$
$$\Lambda = \underbrace{\{\lambda, \lambda, \dots, \lambda\}}_N \in S^N$$

By definition:

$$s \cup \lambda = s$$

$$s^N \cup \Lambda = \{s_1 \cup \lambda, s_2 \cup \lambda, \dots, s_N \cup \lambda\} = s^N$$

## 2. Tagged Signal Model

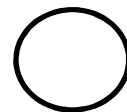
# Bottom Signal

From the discussion of synchronous languages, we know the bottom symbol

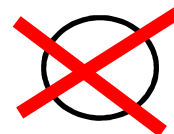
$$\perp$$

standing for the absence of a signal at a time step.

3. Holds  $\lambda = (t_i, \perp)$  ?



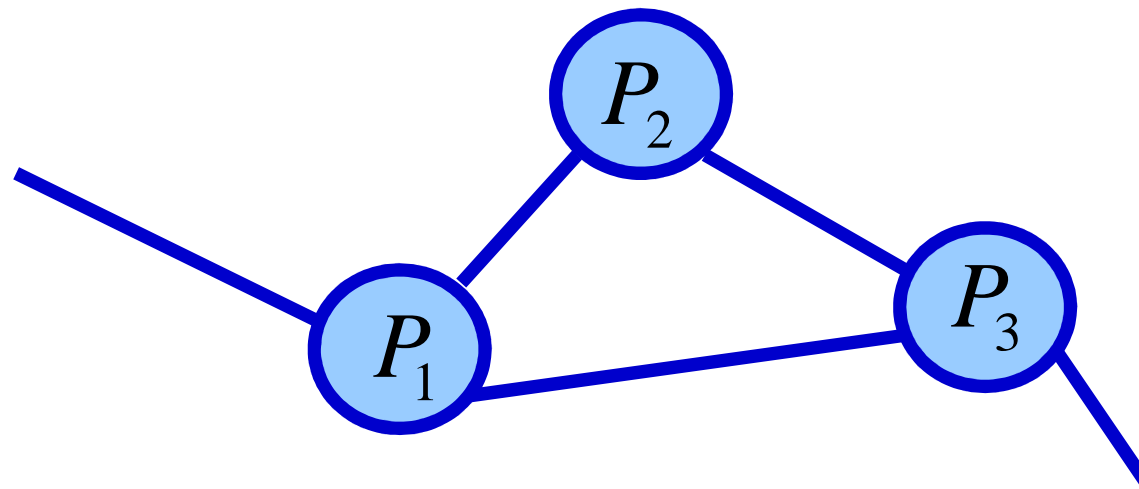
Yes



No

2. Tagged Signal Model

# Processes



## 2. Tagged Signal Model

## Process

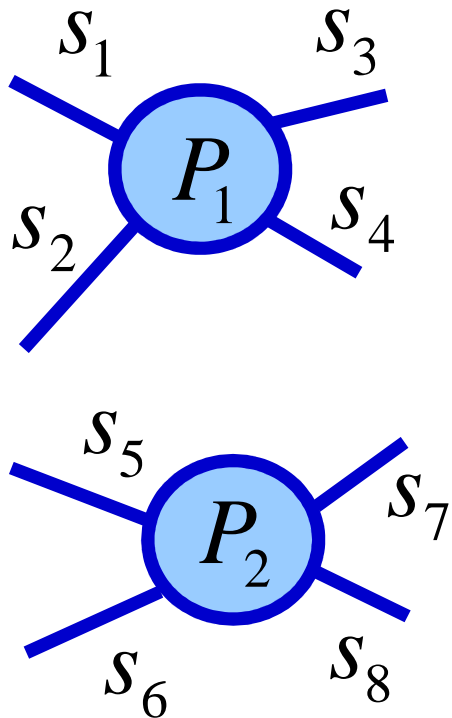
$$P \subseteq S^N$$

$s^N$  satisfies  $P$  if  $s^N \in P$

We call such an  $s^N$  a behavior of  $P$

## 2. Tagged Signal Model

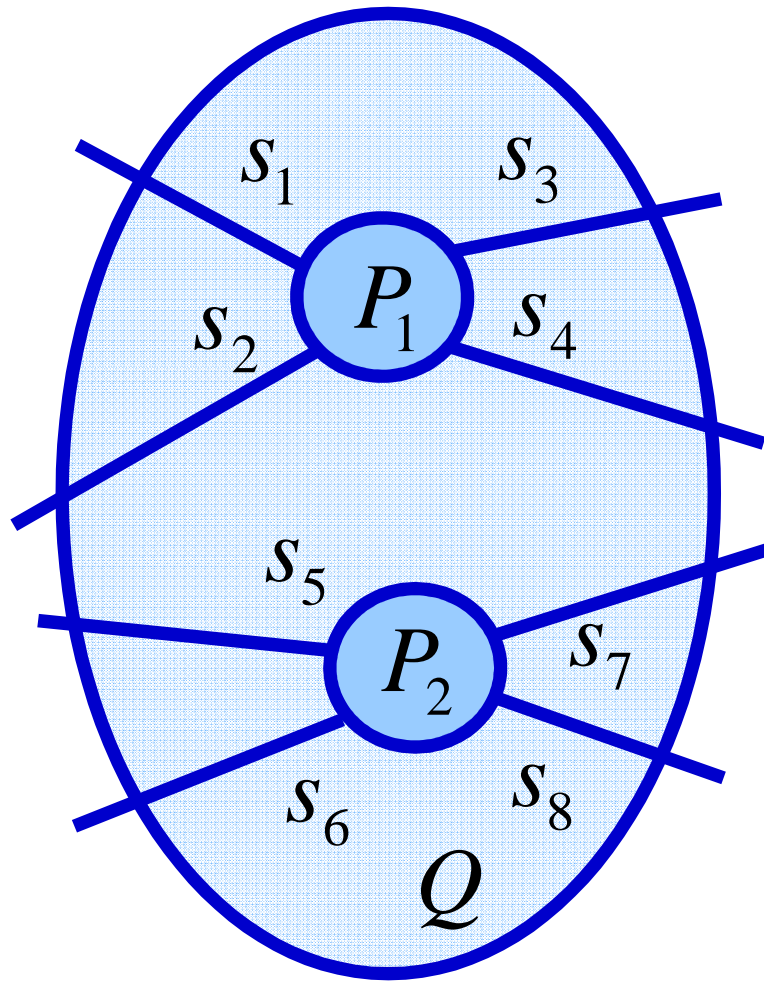
## Composition



The composite should only allow behaviors allowed both by  $P_1$  and  $P_2$ .

## 2. Tagged Signal Model

## Composition (cont'd)



Therefore,

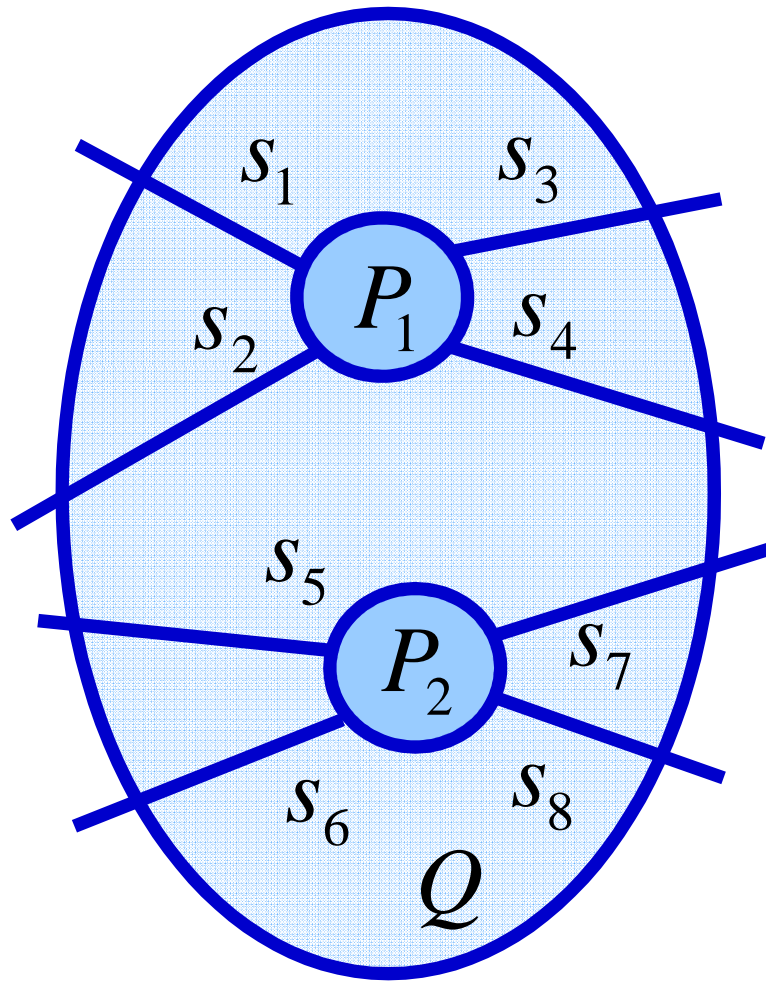
$$Q = P_1 \cap P_2$$

Is there a problem?



## 2. Tagged Signal Model

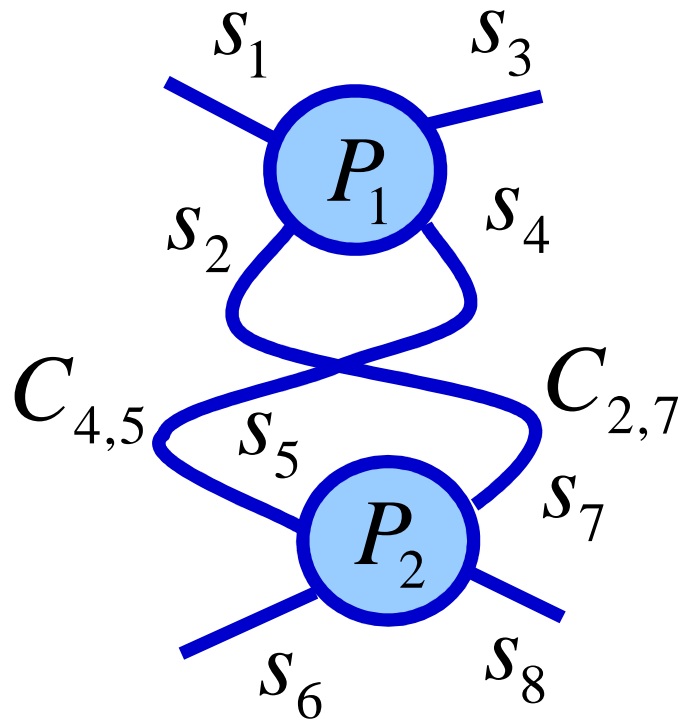
## Composition (cont'd)



$$Q = P_1 \times P_2$$

## 2. Tagged Signal Model

## Connections

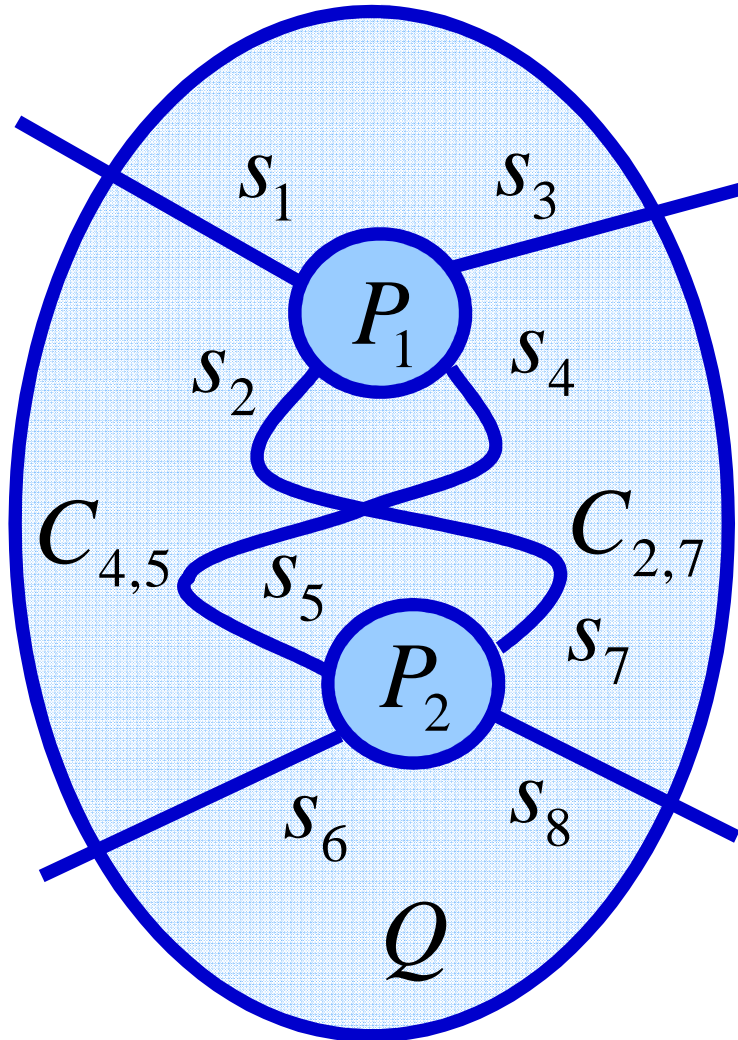


$$C_{4,5} = \{(s_4, s_5) : s_4 = s_5\}$$

$$C_{2,7} = \{(s_2, s_7) : s_2 = s_7\}$$

## 2. Tagged Signal Model

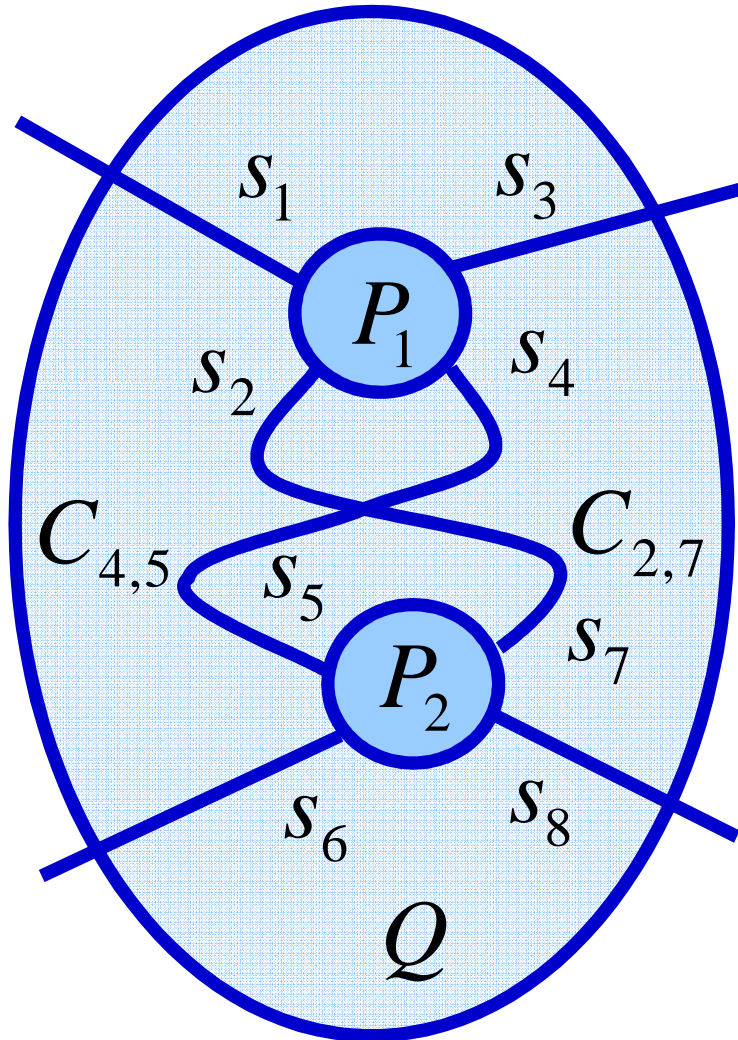
## Composition of Interacting Processes



$$Q = P_1 \times P_2 \times C_{4,5} \times C_{2,7}$$

## 2. Tagged Signal Model

## Projection



We want to hide

$$s_1, s_2, s_5, s_7$$

Define Projection function:

$$\text{Let } I = (i_1, i_2, \dots, i_M)$$

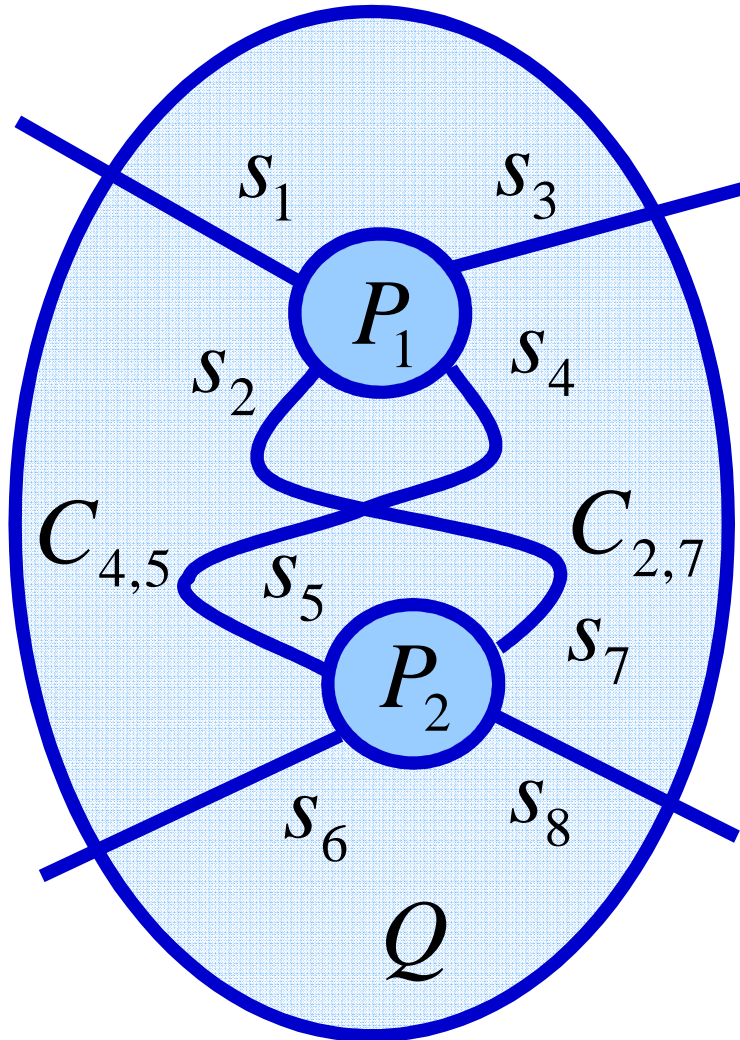
$$S^N = (s_1, s_2, \dots, s_N)$$

$$\text{then } \pi_I : S^N \rightarrow S^M \text{ s.t.}$$

$$\pi_I(S^N) = (s_{i_1}, s_{i_2}, \dots, s_{i_M})$$

## 2. Tagged Signal Model

## Projection



We want to hide

$$s_2, s_4, s_5, s_7$$

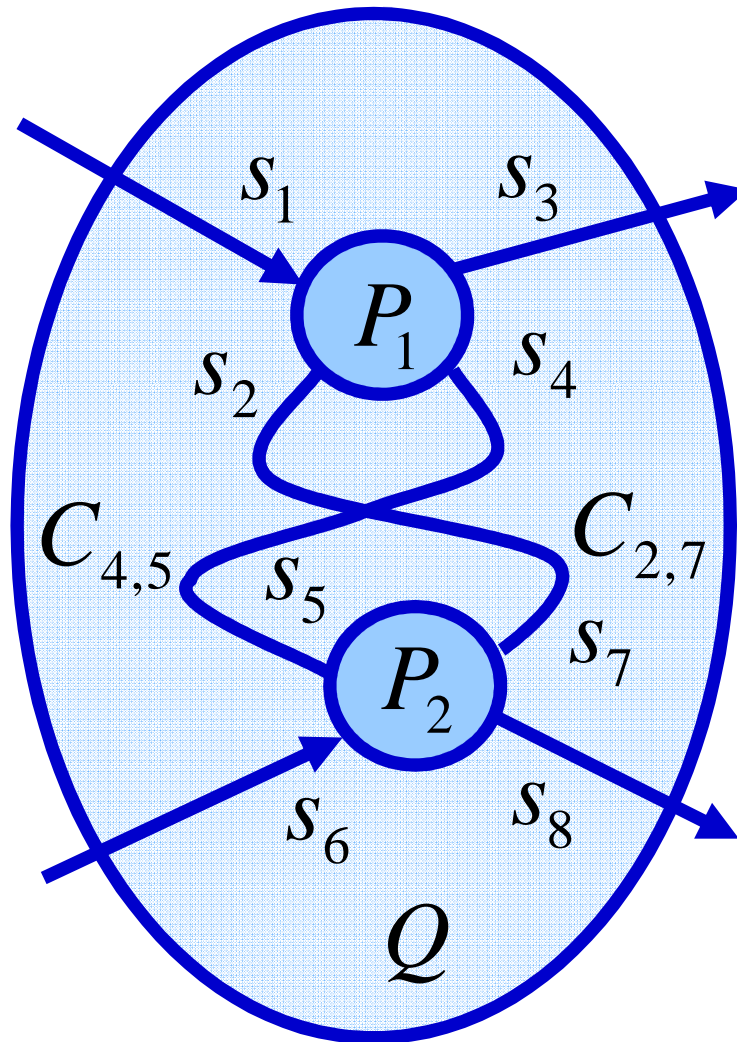
Projection function:

Let  $I = (1, 3, 6, 8)$

then  $Q' = \pi_I(Q)$

2. Tagged Signal Model

Inputs



Set of all possible Inputs

$B$

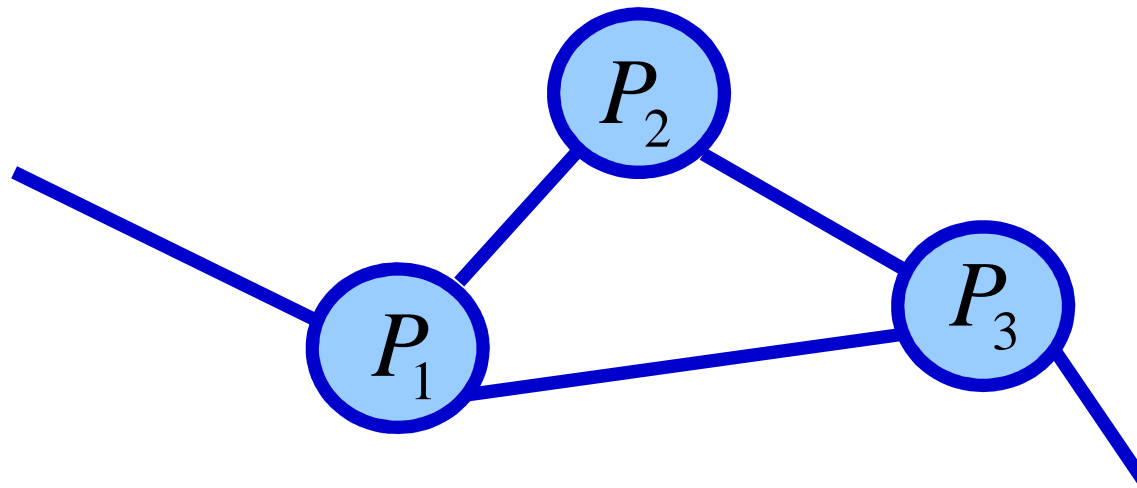
One specific input:

$A$

$A \times P$  are the possible behaviors

2. Tagged Signal Model

# Determinacy



## 2. Tagged Signal Model

# Functional Process

Let  $I$  be the indices of the inputs, let  $O$  be the indices of the outputs.

Then, a process is functional if

$$\pi_I(s) = \pi_I(s') \implies \pi_O(s) = \pi_O(s') \\ \forall s, s' \in P$$

Then there exists  $F$  s.t.  $\pi_O(s) = F(\pi_I(s))$   
 $\forall s \in P$

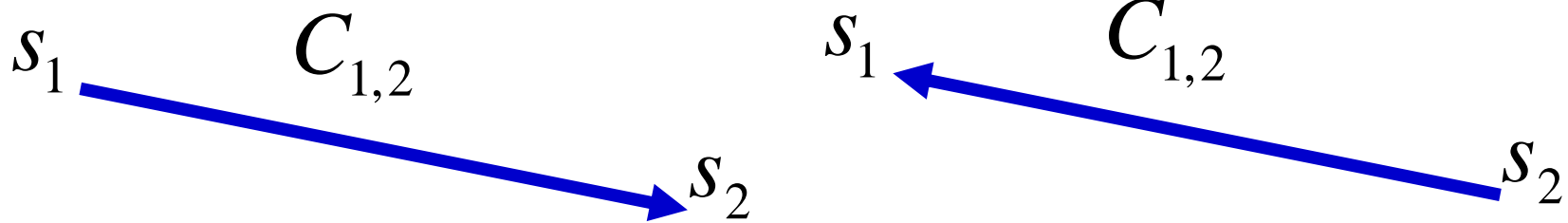


## 2. Tagged Signal Model

## Functional Process (cont'd)

A process may be functional with respect to different assignments for

$I$  and  $O$ :



## 2. Tagged Signal Model

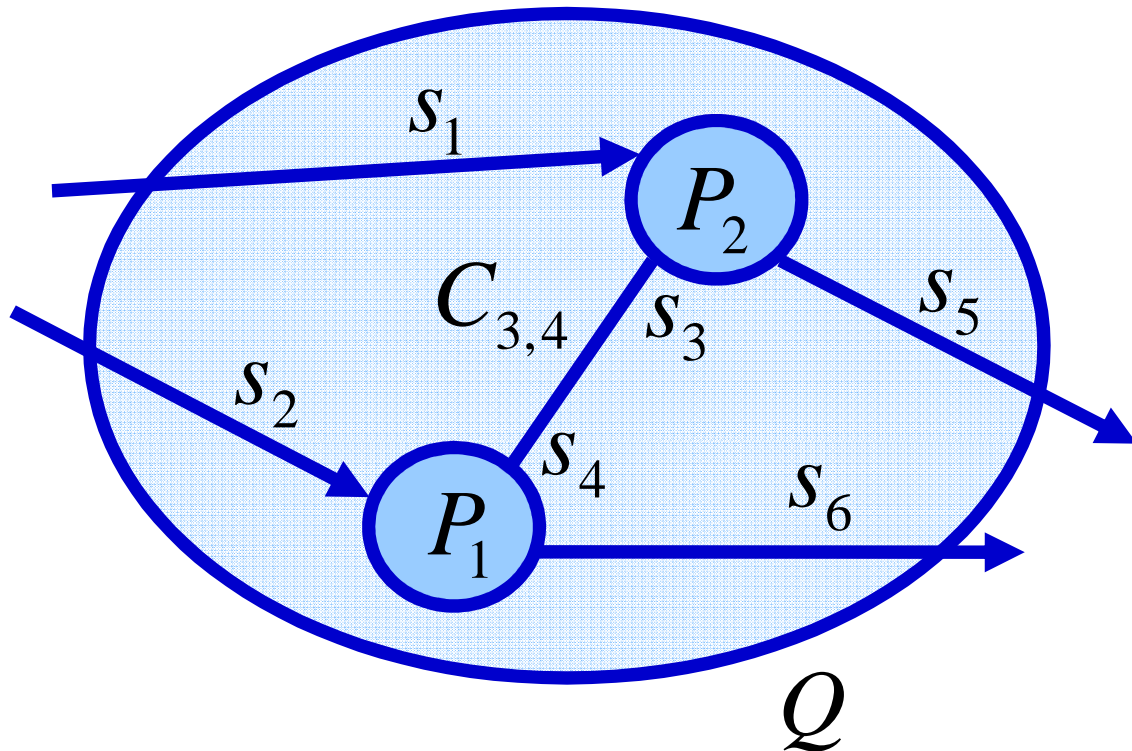
# Determinacy

A process is determinate iff

$$|A \times P| \leq 1$$

## 2. Tagged Signal Model

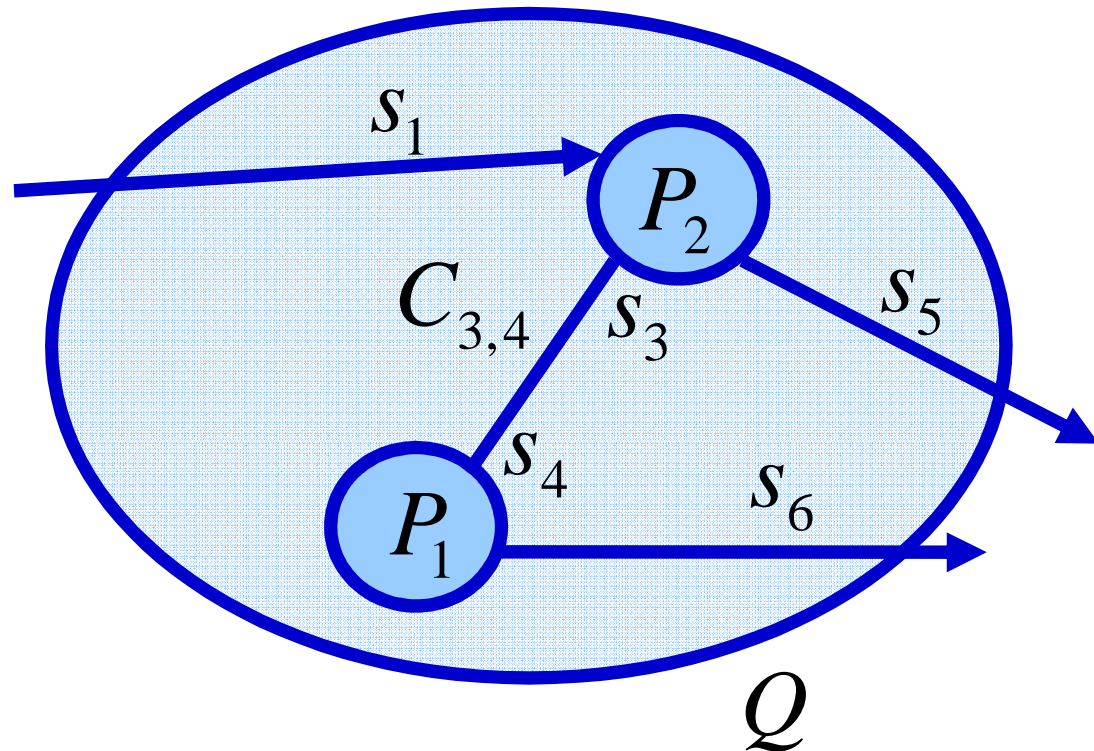
## Determinacy



4.  $Q$  determinant if  $P_1$  and  Yes  
 $P_2$  determinant?  No

## 2. Tagged Signal Model

## Determinacy



5.  $Q$  determinant if  $P_1$  and  Yes  
 $P_2$  determinant?  No

# Agenda:

1. Introduction

2. Tagged Signal Model



**3. Modeling of Time and Causality**

4. Transformations of Tag Systems

5. Summary

## 3. Modelling of Time and Causality

# The Role of Tags

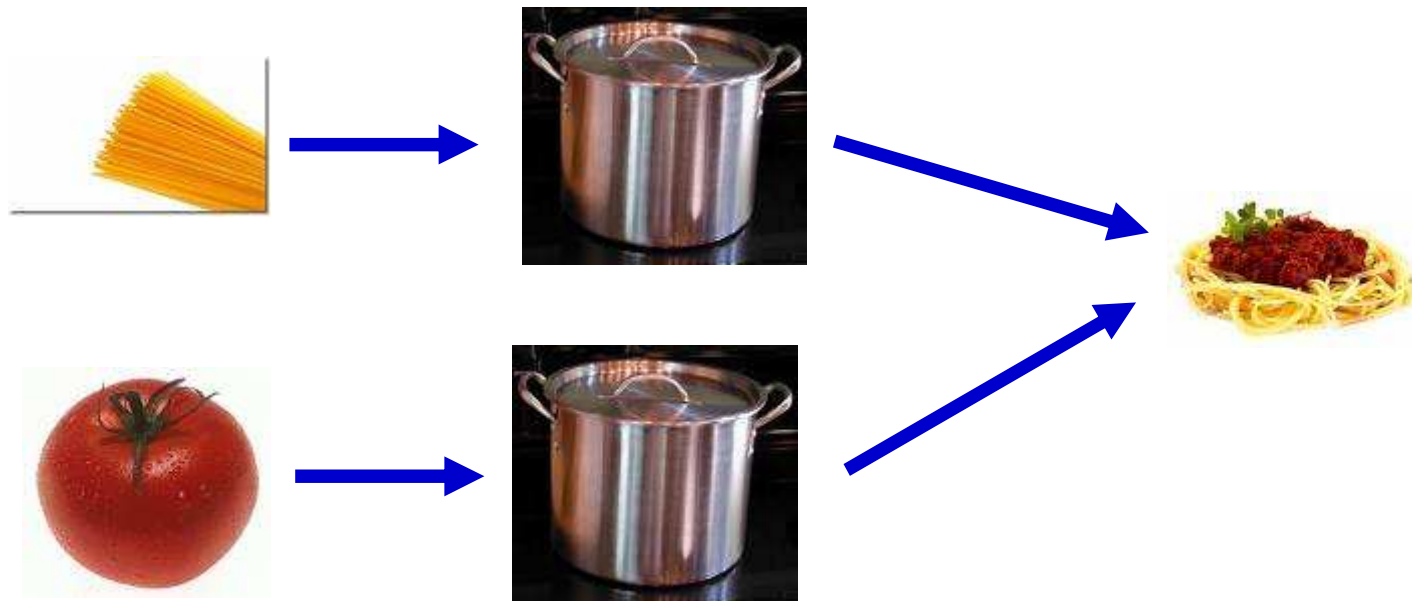
The natural interpretation



$$P_K = \{((\text{dry spaghetti}, 0), (\text{cooked spaghetti}, 15 \text{ min}))\}$$

Is this interpretation generally useful?

# Global Order vs. Partial Order



It does not matter in which order the items are cooked. Maybe they are cooked simultaneously?

# Establishing Order

Ordering of tags:

$$t_1 \leq t_2$$

Relation is

- reflexive
- transitive
- antisymmetric

$T$  with such a relation  $\leq$  is called ordered.

It is globally ordered if  $\forall i, j : t_i \leq t_j \text{ or } t_j \leq t_i$

partially ordered otherwise.



## Establishing Order (cont'd)

Event ordering depends on tag ordering:

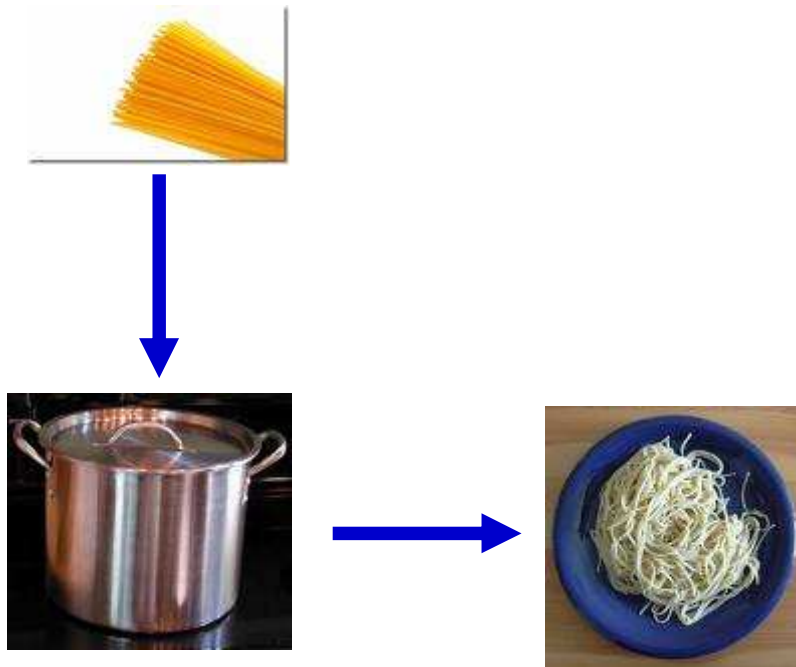
$$e_2 = (t_2, v_2)$$

$$e_1 = (t_1, v_1)$$

$$t_1 \leq t_2 \rightarrow e_1 \leq e_2$$

3. Modelling of Time and Causality

# Timed Models of Computation



The image displays two screenshots from a logic simulator. The top screenshot shows the 'structure' and 'source' windows. The 'structure' window shows a hierarchy of components including 'pc\_logic\_struct' and 'pc\_logic'. The 'source' window shows VHDL code for 'ENTITY pc\_logic IS'. The bottom screenshot shows the 'signals' and 'wave' windows. The 'signals' window shows a list of signals like 'ia', 'id', 'mc', 'ck', 'pc', etc. The 'wave' window shows a timing diagram with multiple signals plotted over time.

## 3. Modelling of Time and Causality

# Metric Time

The tags adhere to a metric:

$$d(t, t') = d(t', t)$$

$$d(t, t') = 0 \iff t' = t$$

$$d(t, t') \geq 0$$

$$d(t, t') + d(t', t'') \geq d(t, t'')$$



Frequently used:  $d(t, t') = |t_1 - t_2|$

## 3. Modelling of Time and Causality

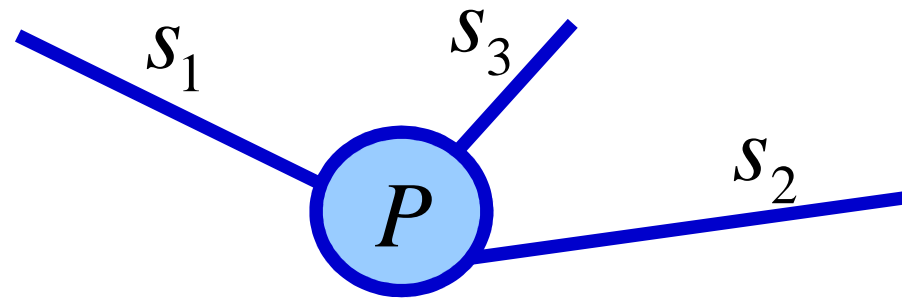
## Discrete Event

Given:  $P$ 

$$s^N \in P$$

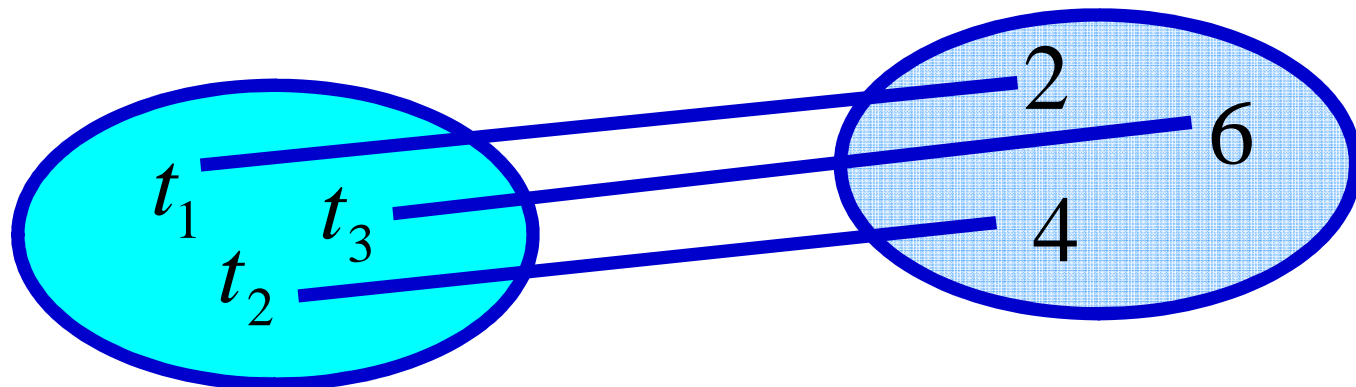
$$t(s^N) \subseteq T$$

$t(s^N)$  is order isomorphic to a subset of integers.



$$t_1 < t_2$$

$$t_2 < t_3$$



## 3. Modelling of Time and Causality

## Circuit Simulators

	$t_0$	$t_0+\Delta$	$t_0+2\Delta$	$t_1$
a	1	1	1	1
b	1	1	1	1
x	0	0	1	1
y	0	1	1	1

```
architecture foo_a of foo_e is
begin
    x <= a and y;
    y <= a or b,
end foo_a;
```

## 3. Modelling of Time and Causality

## Circuit Simulators (cont'd)

	$t_0$	$t_0+\Delta$	$t_0+2\Delta$	$t_1$
a	1	1	1	1
b	1	1	1	1
x	0	0	1	1
y	0	1	1	1

```
architecture foo_a of foo_e is
begin
    x <= a and y;
    y <= a or b;
end foo_a;
```

The tag consists of two parts:

$$t = (t_1, t_2) \in N \times N$$

Simulation Time

Delta Time

## 3. Modelling of Time and Causality

## Circuit Simulators (cont'd)

There is no order isomorphism between  $\mathbb{N} \times \mathbb{N}$  and a subset of integers.

This is because there can be an infinite number of delta steps between two simulation steps. Consider, e.g.

```
architecture foo_a of foo_e is
begin
    a <= not a;
end foo_a;
```

## Circuit Simulators (cont'd)

It can be proven that if a fix point is found, that it is unique

→ Determinacy

The fix point iteration converges under the condition that there is a delay on feedback loops.



## 3. Modelling of Time and Causality

# Synchrony

Greek: sun  $\leftrightarrow$  together  
khronos  $\leftrightarrow$  time



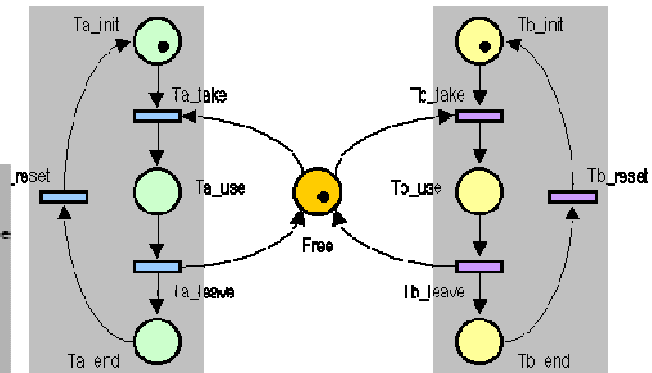
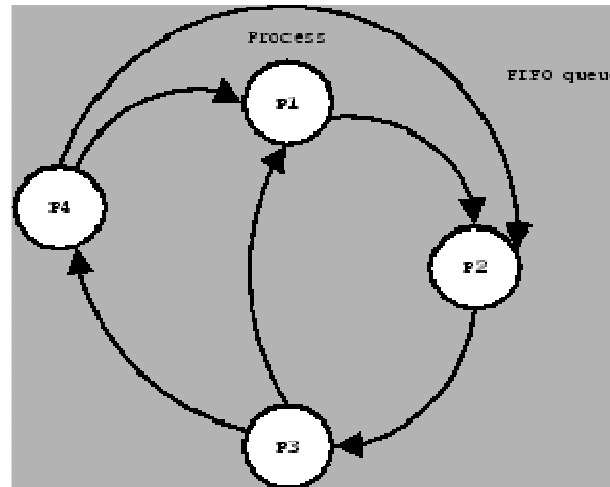
- Two events are synchronous have they have the same tag.
- Two signals are synchronous if for each event in the one signal, there is a synchronous event in the other signal.
- A tuple of signals is synchronous if each pairs of signals are synchronous.
- A process is synchronous if all its behaviors are synchronous.

# Synchrony: Results

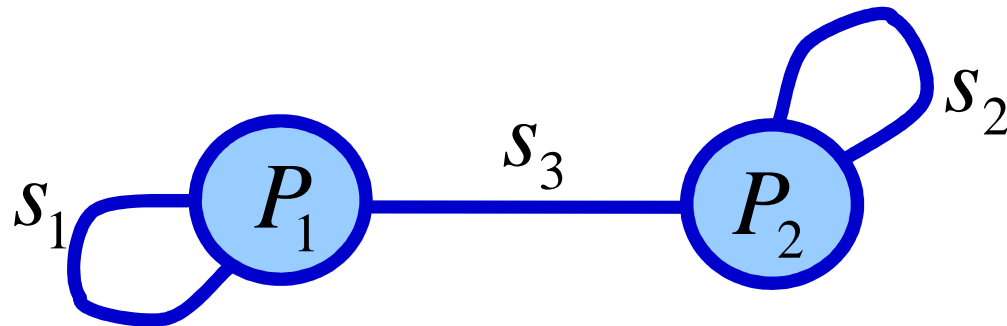
- Synchronous languages like Esterel are synchronous if  $\perp$  is considered to be a value.
- Synchronous Data Flow is **not** synchronous.

3. Modelling of Time and Causality

# Untimed Models of Computation



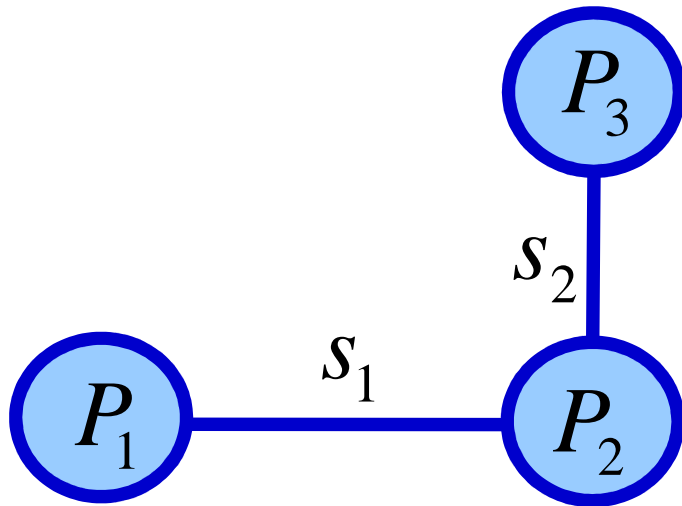
# Rendezvous



$T(s_1), T(s_2), T(s_3)$  are each totally ordered

Rendezvous:  $T(e_1) = T(e_2) = T(e_3)$

# Kahn Process Networks



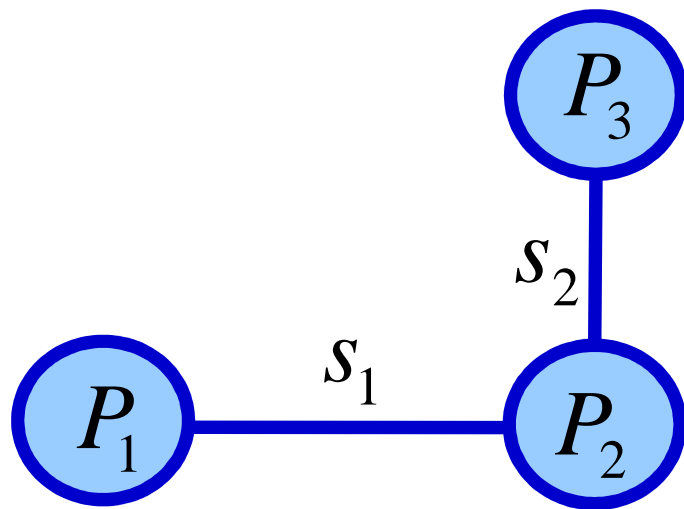
Channels of Kahn Process Networks are FIFO. Therefore,

$$T(s_1), T(s_2)$$

are totally ordered.

## 3. Modelling of Time and Causality

## Kahn Process Networks



Define sequence  $\sum (s)$

Then, a Kahn Process is defined by:

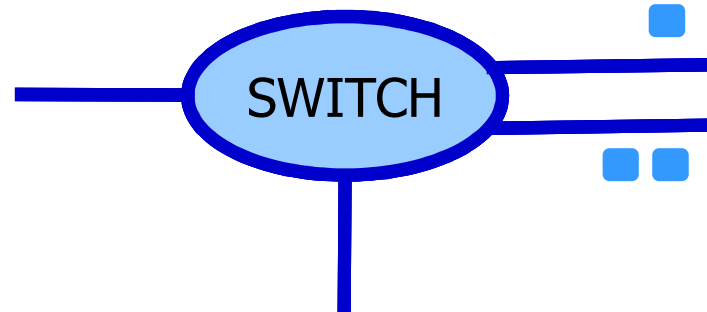
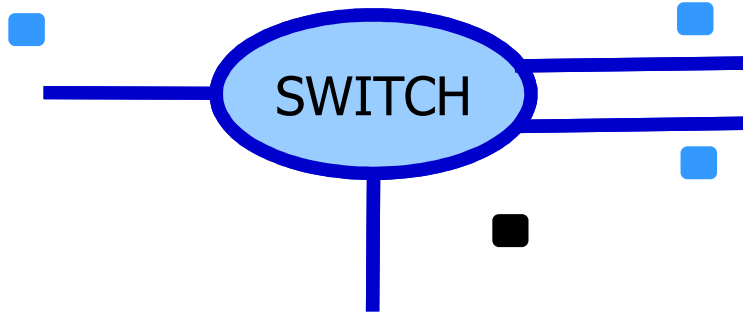
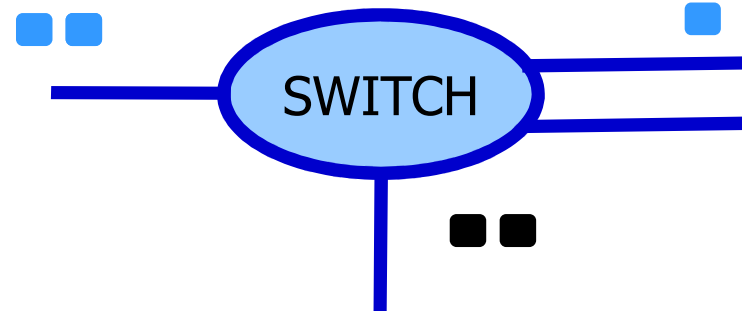
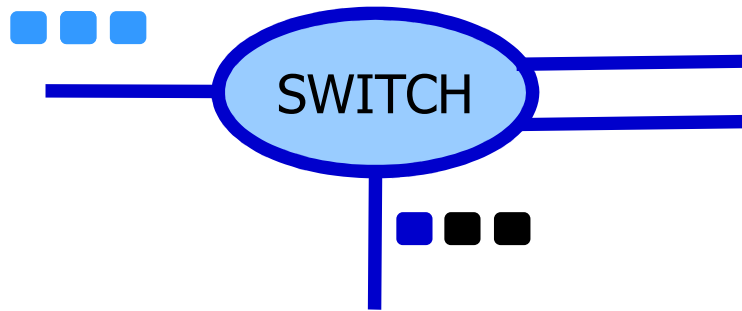
$$P = \left\{ s^N \in S^N : F \left( \sum \pi_I (s^N) \right) = \sum \pi_O (s^N) \right\}$$

What is the constraint on  $F$  s.t. the KPN is deterministic?

3. Modelling of Time and Causality

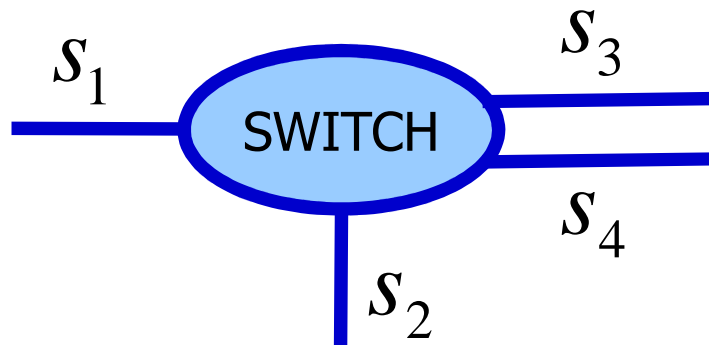
# Data Flow

■ 0  
■ 1



## 3. Modelling of Time and Causality

## Data Flow



$$b_k = \sum_{i=1}^k v_{2,i}$$

$$v_{3,m} = v_{1,b_m}$$

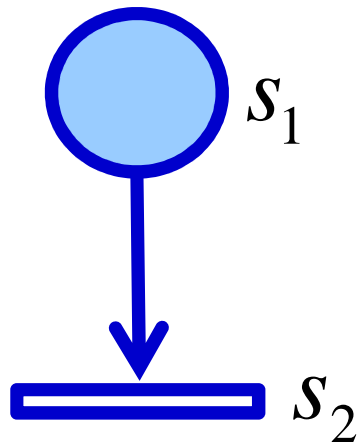
$$v_{4,n} = v_{2,n-b_n}$$

$$e_{3,m} > e_{1,b_m}$$

$$e_{4,n} > e_{2,n-b_n}$$



# Petri Nets



Very similar to data flow.

Notable exception:  $T(s_1), T(s_2)$

are **not** totally ordered

Semantics in TSM:  $f : s_2 \rightarrow s_1 \quad f(e) < e_2 \quad \forall e \in s_2$

# Agenda:

1. Introduction

2. Tagged Signal Model

3. Modeling of Time and Causality



**4. Transformations of Tag Systems**

5. Summary

## 4. Transformations of Tag Systems

# System Refinement

Suppose we have two tag systems  $T, T'$  and an order preserving mapping

$$f : T \rightarrow T'$$

Then we can refine the system by replacing each tag  $t$  in each event in every process by

$$f(t)$$

Obviously, this preserves the designs properties.

# Agenda:

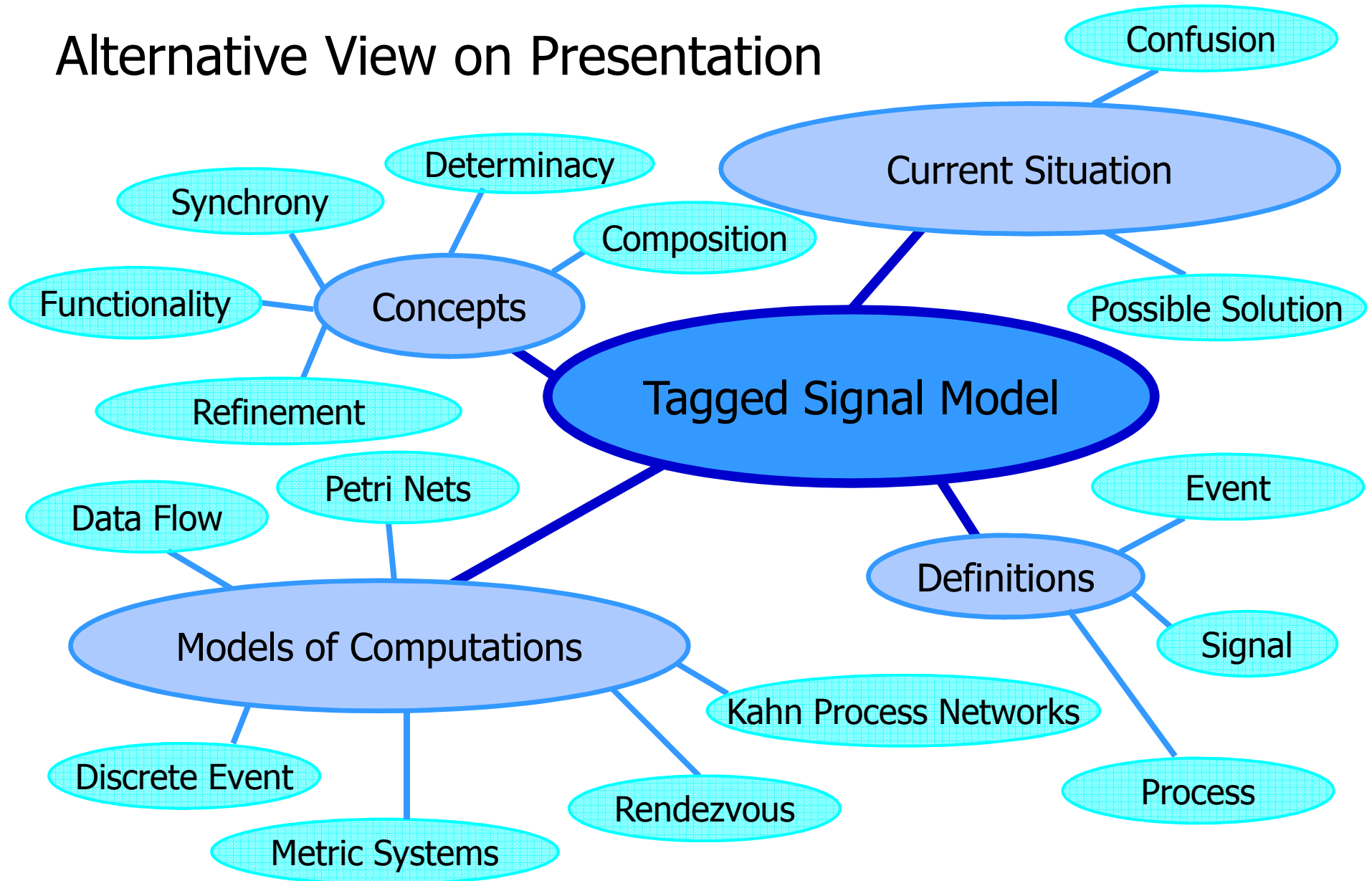
1. Introduction
2. Tagged Signal Model
3. Modeling of Time and Causality
4. Transformations of Tag Systems



## **5. Summary**

5. Summary

# Alternative View on Presentation



# Thank you

for your attention

Slides: [twelp@berkeley.edu](mailto:twelp@berkeley.edu)

## References:

1. Edward A. Lee, Alberto Sangiovanni-Vincentelli: *A Framework for Comparing Models of Computation*, TCAD 1998