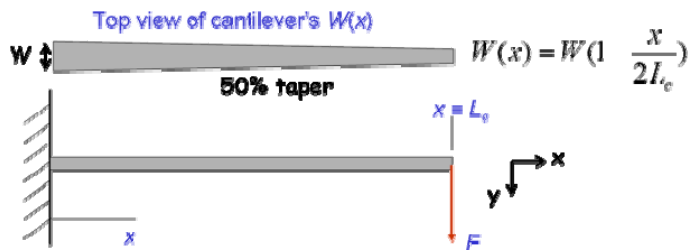


Lecture 18: Energy Methods

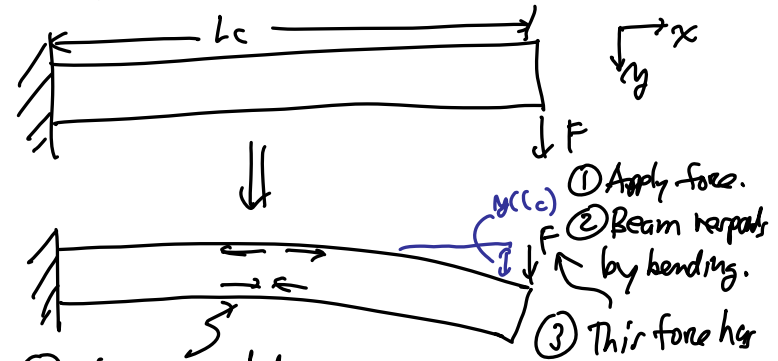
- Announcements:
- Midterm is nearing: Thursday, Oct. 27
 - ↳ I passed out materials associated with the midterm, including an information sheet and old exams, last Tuesday
- HW#5 due today
 - ↳ Solutions will be posted tonight (or emailed)
- My office hours right after class
 - ↳ No office hours for me on Wednesday (since I'll be traveling)
 - ↳ But there are extra TA office hours

-
- Reading: Senturia, Chpt. 10
 - Lecture Topics:
 - ↳ Energy Methods
 - ↳ Virtual Work
 - ↳ Energy Formulations
 - ↳ Tapered Beam Example
 - ↳ Estimating Resonance Frequency

-
- Last Time:
 - **Objective:** Find an expression for displacement as a function of location x under a point load F applied at the tip of the free end of a cantilever with tapered width $W(x)$



Same problem as before: Take a beam, apply a force.



- ① Apply force.
- ② Beam responds by bending.
- ③ This force has done work: $W = F \cdot y(L_c)$
- ④ Strain generated
 - ↳ So the beam has received an influx of stored energy
 - ↳ magnitude of " " determined by shape

⑤ Then

$$U = \text{Stored Energy} - \text{Work Done} \rightarrow 0$$

↳ transfer function $y(x) = f(x)$

When we choose the right shape.

↳ This is how we get the beam's response to F .

Fundamentals: Energy Density

General Definition of Work.

$$W(q_i) = \int_0^{q_i} e(q) dq \quad \begin{array}{l} q = \text{displacement} \\ e = \text{effort} \end{array}$$

↳ for EE: $W(Q) = \int_0^Q \frac{Q}{C} dQ$

Strain Energy Density

value of strain @ position (x, y, z)

$$W = \int_0^{\epsilon_x} \sigma_x d\epsilon_x$$

$\sigma_x(\epsilon_x)$ → relates stress to strain @ position (x, y, z)

$[\sigma_x = E\epsilon_x]$ ↓

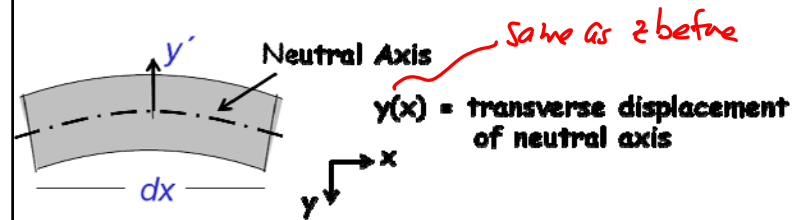
$$W = \int_0^{\epsilon_x} E\epsilon_x d\epsilon_x = \frac{1}{2} E\epsilon_x^2$$

Total Strain Energy: [J]

$$W = \iiint \left(\frac{1}{2} E (\epsilon_x^2 + \epsilon_y^2 + \epsilon_z^2) + \frac{1}{2} G (\gamma_{xy}^2 + \gamma_{xz}^2 + \gamma_{yz}^2) \right) dV$$

volume ↓

Bending Energy Density



First, find the bending energy dW_{bend} in an infinitesimal length dx :

$$dW_{\text{bend}} = W dx \int_{-\frac{h}{2}}^{\frac{h}{2}} \frac{1}{2} E \epsilon_x^2(y') dy'$$

$$\left[\frac{1}{R} = \frac{d^2 y}{dx^2}, \epsilon_x = \frac{y'}{R} \right] \Rightarrow \epsilon_x(y') = y' \frac{d^2 y}{dx^2}$$

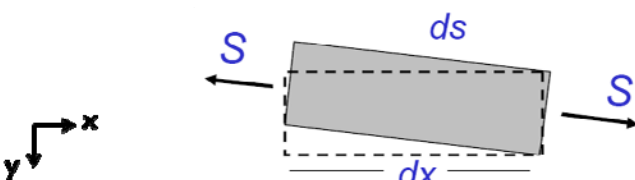
$$dW_{\text{bend}} = W dx \int_{-\frac{h}{2}}^{\frac{h}{2}} \frac{1}{2} E \left[y' \frac{d^2 y}{dx^2} \right]^2 dy'$$

$$= \frac{1}{2} E \left(\frac{Wh^3}{12} \right) \left(\frac{d^2 y}{dx^2} \right)^2 dx$$

I_2

$$\therefore W_{\text{bend}} = \frac{1}{2} EI_2 \int_0^L \left(\frac{d^2 y}{dx^2} \right)^2 dx$$

Energy Due to Axial Load



≠ energy related to lengthening:

$$ds = [(dx)^2 + (dy)^2]^{1/2} = dx \left[1 + \left(\frac{dy}{dx} \right)^2 \right]^{1/2}$$

binomial theorem $\rightarrow \approx dx \left[1 + \frac{1}{2} \left(\frac{dy}{dx} \right)^2 \right]$

$$\therefore E_x = \frac{ds - dx}{dx} = \frac{1}{2} \left(\frac{dy}{dx} \right)^2$$

$$dW_{axial} = S E_x dx = \frac{1}{2} S \left(\frac{dy}{dx} \right)^2 dx$$


$$W_{axial} = \frac{1}{2} S \int_0^l \left(\frac{dy}{dx} \right)^2 dx$$

↑
Axial Strain Energy

⇒ look @ shear strain energy in your module.

- Go through Module 9 pages 10-18.

Estimating Resonance Frequency



$x(t) = X_0 \cos \omega t$

Potential Energy

$$W(t) = \frac{1}{2} k x^2(t) = \frac{1}{2} k X_0^2 \cos^2 \omega t$$

Kinetic Energy

$$K(t) = \frac{1}{2} M \dot{x}^2(t) = \frac{1}{2} M X_0^2 \omega^2 \sin^2 \omega t$$

↑
 $\dot{x} = \frac{dx}{dt} = \text{velocity}$

Remarks.

- ① Energy must be conserved.
- ② Total Energy = Potential Energy + Kinetic Energy at all times & locations on the structure

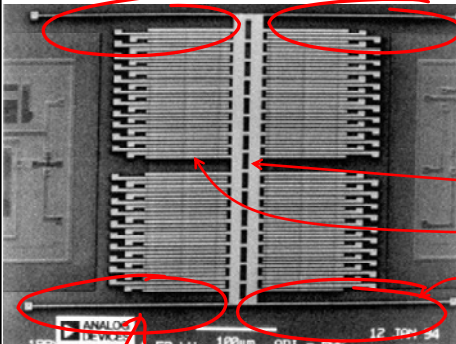
$$W_{max} = \frac{1}{2} k X_0^2 = K_{max} = \frac{1}{2} M \omega^2 X_0^2$$

Annotations for the equation above:

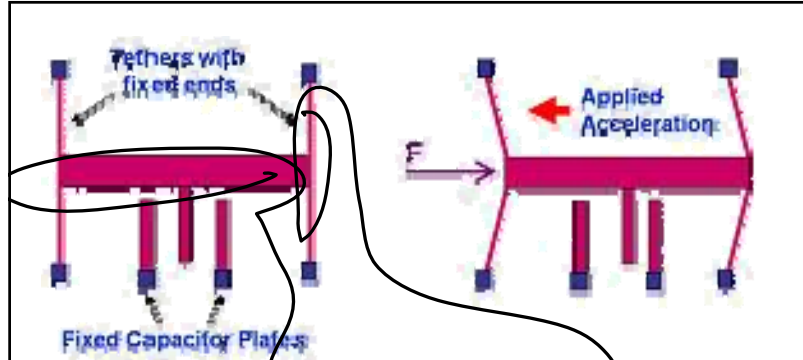
- ↑ maximum potential energy (points to $\frac{1}{2} k X_0^2$)
- ↑ peak displacement (points to X_0^2)
- ↑ maximum kinetic energy (points to $\frac{1}{2} M \omega^2 X_0^2$)
- ↑ radian frequency (points to ω^2)

* $\omega_0 = \sqrt{\frac{k}{M}}$ \Rightarrow good for problems where mass & stiffness can be separated, i.e., are distinct

- The proof mass of the ADXL-50 is many times larger than the effective mass of its suspension beams
 - Can ignore the mass of the suspension beams (which greatly simplifies the analysis)
- Suspension Beam: $L = 260 \mu\text{m}$, $h = 2.3 \mu\text{m}$, $W = 2 \mu\text{m}$



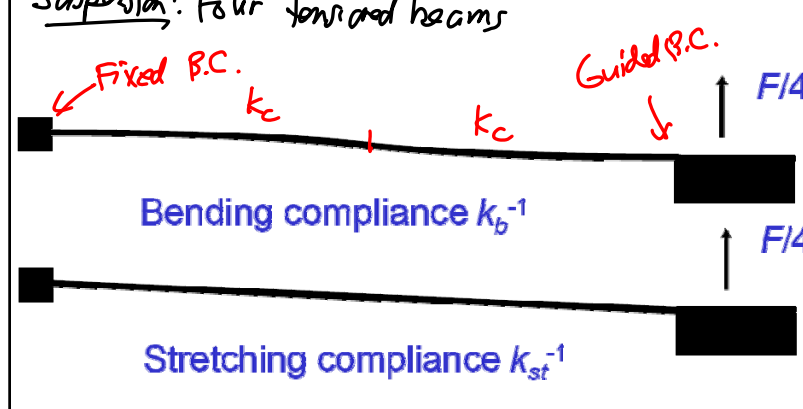
In fabrication: purposely introduce a tensile stress in the beams!
a large one!



mass of structure \gg mass of springs
 \therefore ignore the mass of the springs
 stiffness of springs \ll stiffness of structure
 \therefore ignore the stiffness of the structure

For the ADXL-50: 60% of the mass from sense fingers $\rightarrow M = 162 \text{ ng}$

Suspension: Four tensioned beams



Fixed B.C. k_c k_c Guided B.C.

Bending compliance k_b^{-1}

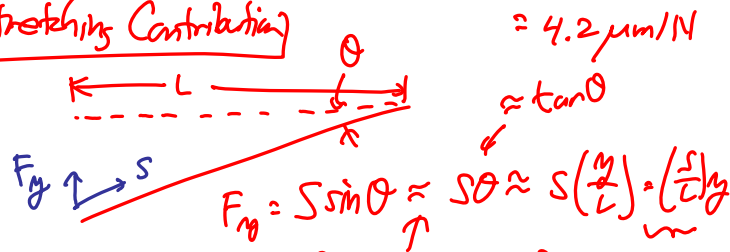
Stretching compliance k_{st}^{-1}

$F/4$ $F/4$

Bending Contribution

$$k_b^{-1} = \left(\frac{1}{k_c} + \frac{1}{k_c} \right) = 2 \left(\frac{(L/2)^3}{3E(wh^3/12)} \right) = \frac{L^3}{Ewh^3}$$

Stretching Contribution



(assume small displacement) \rightarrow k_{st}

$$k_{st}^{-1} = \frac{L}{s} = \frac{L}{\sigma_r wh} = 1.14 \mu\text{m}/\mu\text{N} \quad \text{stretching stiffness}$$

To get the total spring constant
 add to bending stiffness
 to the stretching:

$$k = 4(k_b + k_{st}) = 4(0.24 + 0.88) = 4.5 \mu\text{N}/\mu\text{m}$$

Now, 1st resonance freq.:

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{4.48 \text{ N/m}}{162 \times 10^{-12} \text{ kg}}} = 26.5 \text{ kHz}$$

ADXL-50 Data sheet: $f_0 = 24 \text{ kHz}$ difference?

Capacitive transducer
 electrical stiffness