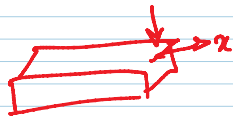
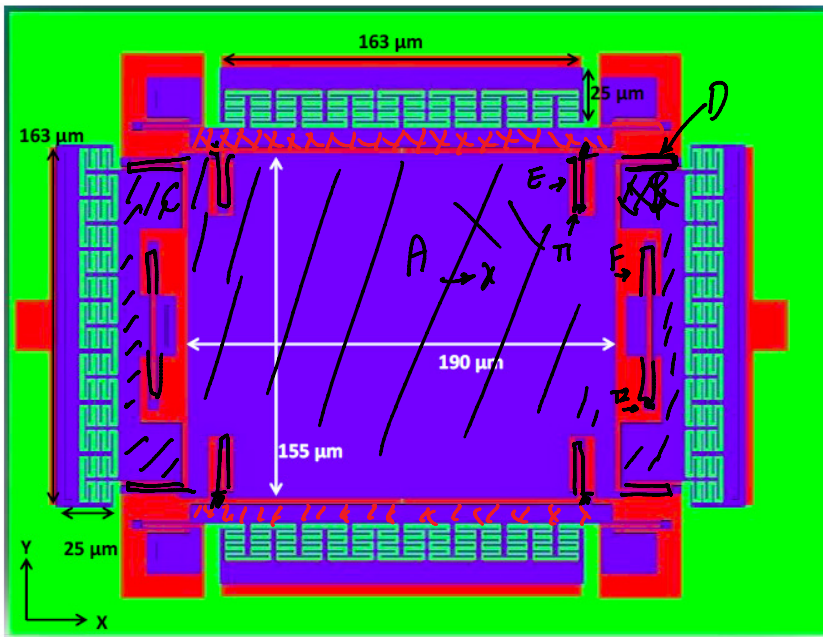
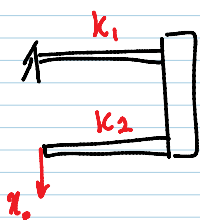


$\rightarrow k_x =$   
 $\rightarrow k_y =$   
 $\left\{ \begin{array}{l} m_x = \\ m_y = \end{array} \right.$



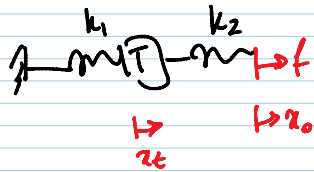
$m_x = m_A + m_B + m_C + m_D$  *includes fingers*  
 $+ m_E + m_F + (m_{\pi} + m_{\phi}) \left(\frac{1}{2}\right)^2 + m_{\text{fingers, bars}}$



$\downarrow x_0 = \frac{1}{2} x_0 = \frac{k_2}{k_1 + k_2} x_0$

$k_1$   $k_2$   $\dots$   $\dots$

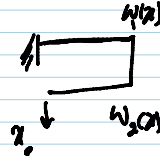
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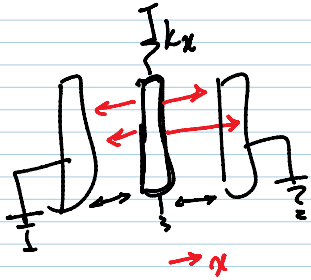
$$f = \alpha \cdot (k_1 || k_2) = \alpha \cdot k_1$$

$$\frac{1}{2} \alpha_0 \omega_0^2 m_{eff} = \frac{1}{2} \int$$

$$m_{eff} = m_{st} \int [\omega(x)]^2 dx$$

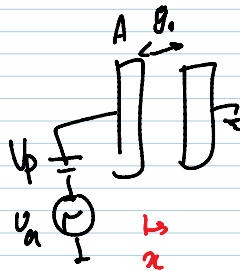


$$\omega_{n,x} = \sqrt{\frac{k_x}{m_x}} =$$



$$F = \frac{1}{2} V^2 \frac{dc}{dx}$$

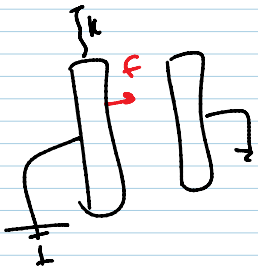
$$C = \frac{\epsilon A}{g_0 - x} \quad \frac{dc}{dx} = \frac{\epsilon A}{(g_0 - x)^2}$$



$$F = \frac{1}{2} (V_p + V_a)^2 \frac{\epsilon A}{(g_0 - x)^2} \rightarrow \frac{1}{2} (\epsilon \cdot x \cdot g_0)^2$$

$$F = \frac{1}{2} (V_p^2 + 2V_p V_a + \frac{V_a^2}{g_0}) \frac{\epsilon A}{g_0^2} \left( 1 + \frac{2x}{g_0} \dots \right)$$

$$F = \underbrace{\frac{1}{2} V_p^2 \frac{\epsilon A}{g_0^2}}_{\text{DC force}} + \underbrace{V_a V_p \frac{\epsilon A}{g_0^2}}_{\text{AC-term}} + \underbrace{\frac{1}{2} V_p^2 \frac{\epsilon A}{g_0^3}}_{\text{Electrical stiffness}} + \cancel{2V_p V_a \frac{\epsilon A}{g_0^3}}$$



$$g'_0 = g_0 - \delta$$

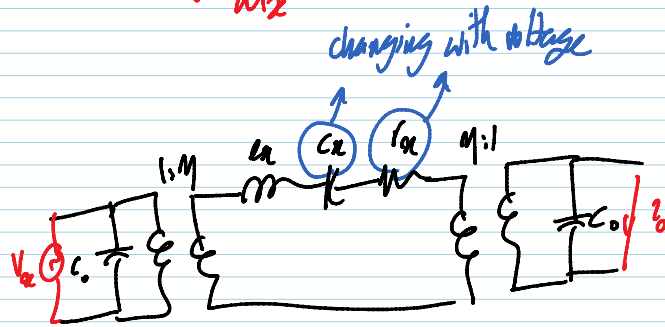
$$\omega_n = \sqrt{\frac{k_x}{m_x}}$$

$$\omega'_n = \sqrt{\frac{k_x - k_{es}}{m_x}}$$

$$m_x \rightarrow l_x$$

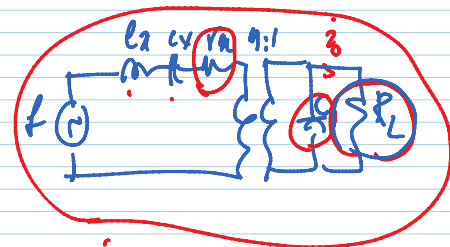
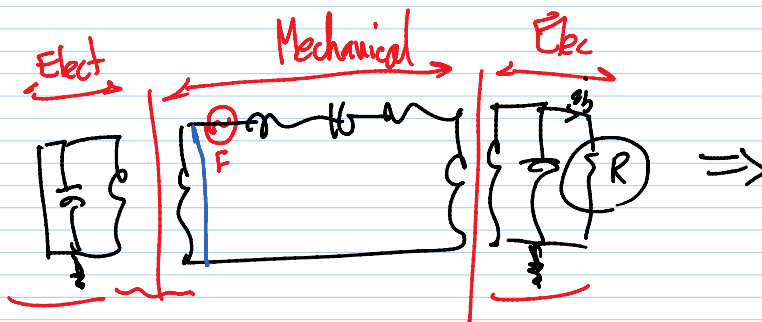
$$k_x - k_{es} \rightarrow \frac{1}{C_x}$$

$$C_{eff} \rightarrow r_x$$

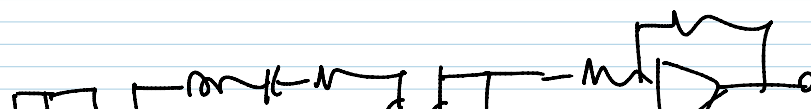


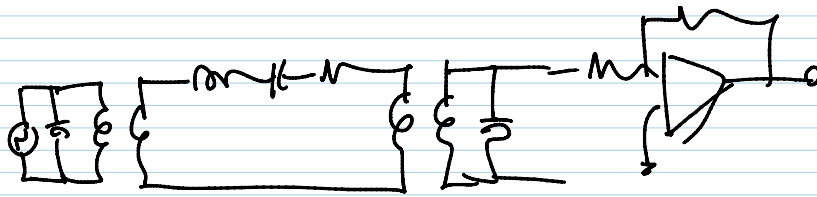
$$\frac{V_0}{V_a} = \dots$$

$$C_{eff} = \frac{m_x \omega_n}{Q}$$



$$\frac{V_0}{V_a} = \frac{1}{\frac{r_x}{n^2} + R_L}$$





$$\frac{v_o}{v_i} = \left( \frac{1}{1 - \frac{\omega^2 L^2}{R^2} + j \frac{\omega L}{R}} \right) \mathcal{I}(\omega)$$

$$= \frac{1}{1 - \frac{\omega^2 L^2}{R^2} + j \frac{\omega L}{R}}$$

