CS 61C: Great Ideas in Computer Architecture (Machine Structures)  
*Thread-Level Parallelism (TLP)*  
and *OpenMP Intro*

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http://inst.eecs.berkeley.edu/~cs61c/
Review

• Amdahl’s Law: Serial sections limit speedup
• Flynn Taxonomy
• Intel SSE SIMD Instructions
  – Exploit data-level parallelism in loops
  – One instruction fetch that operates on multiple operands simultaneously
  – 128-bit XMM registers
• SSE Instructions in C
  – Embed the SSE machine instructions directly into C programs through use of intrinsics
  – Achieve efficiency beyond that of optimizing compiler
New-School Machine Structures
(It’s a bit more complicated!)

- **Parallel Requests**
  Assigned to computer
e.g., Search “Katz”

- **Parallel Threads**
  Assigned to core
e.g., Lookup, Ads

- **Parallel Instructions**
  >1 instruction @ one time
e.g., 5 pipelined instructions

- **Parallel Data**
  >1 data item @ one time
e.g., Add of 4 pairs of words

- **Hardware descriptions**
  All gates @ one time

- **Programming Languages**
Simple Multiprocessor
Multithreaded Execution Model

- Each processor has its own PC and executes an independent stream of instructions (MIMD)
- Different processors can access the same memory space
  - Processors can communicate via shared memory by storing/loading to/from common locations
- Two ways to use a multiprocessor:
  1. Deliver high throughput for independent jobs via job-level parallelism
  2. Improve the run time of a single program that has been specially crafted to run on a multiprocessor - a parallel-processing program

Use term *core* for processor (“Multicore”) because “Multiprocessor Microprocessor” too redundant
Transition to Multicore

Data partially collected by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond
Parallelism Only Path to Higher Performance

• Sequential processor performance not expected to increase much, and might go down
• If want apps with more capability, have to embrace parallel processing (SIMD and MIMD)
• In mobile systems, use multiple cores and GPUs
• In warehouse-scale computers, use multiple nodes, and all the MIMD/SIMD capability of each node
Multiprocessors and You

• Only path to performance is parallelism
  – Clock rates flat or declining
  – SIMD: 2X width every 3-4 years
    • 128b wide now, 256b 2011, 512b in 2014, 1024b in 2018?
  – MIMD: Add 2 cores every 2 years: 2, 4, 6, 8, 10, ...

• Key challenge is to craft parallel programs that have high performance on multiprocessors as the number of processors increase – i.e., that scale
  – Scheduling, load balancing, time for synchronization, overhead for communication

• Project 3: fastest code on 8-core computers
  – 2 chips/computer, 4 cores/chip
## Potential Parallel Performance
(assuming SW can use it)

<table>
<thead>
<tr>
<th>Year</th>
<th>Cores</th>
<th>SIMD bits /Core</th>
<th>Core * SIMD bits</th>
<th>Peak DP FLOPs/Cycle</th>
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<tr>
<td>2003</td>
<td>MIMD 2</td>
<td>SIMD 128</td>
<td>256</td>
<td>MIMD 4</td>
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<tr>
<td>2005</td>
<td>+2/ 4</td>
<td>2X/ 128</td>
<td>512</td>
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<td>2yrs 6</td>
<td>4yrs 128</td>
<td>768</td>
<td>12</td>
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<tr>
<td>2009</td>
<td>8</td>
<td></td>
<td>1024</td>
<td>16</td>
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<tr>
<td>2011</td>
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<td>40</td>
</tr>
<tr>
<td>2013</td>
<td>12</td>
<td>256</td>
<td>3072</td>
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</tr>
<tr>
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<td>2.5X 14</td>
<td>8X 512</td>
<td>7168</td>
<td>20X 112</td>
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<tr>
<td>2017</td>
<td>16</td>
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<tr>
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<td>20</td>
<td>1024</td>
<td>20480</td>
<td>320</td>
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</table>
Threads

- **Thread**: a sequential flow of instructions that performs some task
- Each thread has a PC + processor registers and accesses the shared memory
- Each processor provides one (or more) *hardware* threads (or *harts*) that actively execute instructions
- Operating system multiplexes multiple *software* threads onto the available hardware threads
Operating System Threads

Give the illusion of many active threads by time-multiplexing software threads onto hardware threads

• Remove a software thread from a hardware thread by interrupting its execution and saving its registers and PC into memory
  – Also if one thread is blocked waiting for network access or user input

• Can make a different software thread active by loading its registers into a hardware thread’s registers and jumping to its saved PC
Hardware Multithreading

• Basic idea: Processor resources are expensive and should not be left idle
• Long memory latency to memory on cache miss?
• Hardware switches threads to bring in other useful work while waiting for cache miss
• Cost of thread context switch must be much less than cache miss latency
• Put in redundant hardware so don’t have to save context on every thread switch:
  – PC, Registers
• Attractive for apps with abundant TLP
  – Commercial multi-user workloads
Hardware Multithreading

- Two copies of PC and Registers inside processor hardware
- Looks like two processors to software (hardware thread 0, hardware thread 1)
- Control logic decides which thread to execute an instruction from next
Multithreading vs. Multicore

• Multithreading => Better Utilization
  – ≈1% more hardware, 1.10X better performance?
  – Share integer adders, floating-point units, all caches (L1 I$, L1 D$, L2$, L3$), Memory Controller

• Multicore => Duplicate Processors
  – ≈50% more hardware, ≈2X better performance?
  – Share outer caches (L2$, L3$), Memory Controller

• Modern machines do both
  – Multiple cores with multiple threads per core
Krste’s MacBook Air

• /usr/sbin/sysctl -a | grep hw\.
  hw.model = MacBookAir5,1
  hw.physicalcpu: 2
  hw.logicalcpu: 4
  hw.cpusfrequency = 2,000,000,000
  hw.memsizer = 8,589,934,592
  hw.cachelinesizer = 64
  hw.l1icachesizer: 32,768
  hw.l1dcachesizer: 32,768
  hw.l2cachesizer: 262,144
  hw.l3cachesizer: 4,194,304
Machines in (old) 61C Lab

• `/usr/sbin/sysctl -a | grep hw\.`
  hw.model = MacPro4,1
  hw.physicalcpu: 8
  hw.logicalcpu: 16
  hw.cpufreqencty = 2,260,000,000
  hw.physmem = 2,147,483,648
  hw.cachelinesize = 64
  hw.l1icachesize: 32,768
  hw.l1dcachesize: 32,768
  hw.l2cachesize: 262,144
  hw.l3cachesize: 8,388,608

Therefore, should try up to 16 threads to see if performance gain even though only 8 cores
Administrivia
### 100s of (Mostly Dead) Parallel Programming Languages

<table>
<thead>
<tr>
<th>ActorScript</th>
<th>Concurrent Pascal</th>
<th>JoCaml</th>
<th>Orc</th>
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<tbody>
<tr>
<td>Ada</td>
<td>Concurrent ML</td>
<td>Join</td>
<td>Oz</td>
</tr>
<tr>
<td>Afnix</td>
<td>Concurrent Haskell</td>
<td>Java</td>
<td>Pict</td>
</tr>
<tr>
<td>Alef</td>
<td>Curry</td>
<td>Joule</td>
<td>Reia</td>
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<td>CUDA</td>
<td>Joyce</td>
<td>SALSA</td>
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<tr>
<td>APL</td>
<td>E</td>
<td>LabVIEW</td>
<td>Scala</td>
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<tr>
<td>Axum</td>
<td>Eiffel</td>
<td>Limbo</td>
<td>SISAL</td>
</tr>
<tr>
<td>Chapel</td>
<td>Erlang</td>
<td>Linda</td>
<td>SR</td>
</tr>
<tr>
<td>Cilk</td>
<td>Fortan 90</td>
<td>MultiLisp</td>
<td>Stackless Python</td>
</tr>
<tr>
<td>Clean</td>
<td>Go</td>
<td>Modula-3</td>
<td>SuperPascal</td>
</tr>
<tr>
<td>Clojure</td>
<td>Io</td>
<td>Occam</td>
<td>VHDL</td>
</tr>
<tr>
<td>Concurrent C</td>
<td>Janus</td>
<td>occam-п</td>
<td>XC</td>
</tr>
</tbody>
</table>
OpenMP

• OpenMP is a language extension used for multi-threaded, shared-memory parallelism
  – Compiler Directives (inserted into source code)
  – Runtime Library Routines (called from your code)
  – Environment Variables (set in your shell)

• Portable

• Standardized

• Easy to compile: `cc -fopenmp name.c`
Shared Memory Model with Explicit Thread-based Parallelism

• Multiple threads in a shared memory environment, explicit programming model with full programmer control over parallelization

• **Pros:**
  – Takes advantage of shared memory, programmer need not worry (that much) about data placement
  – Compiler directives are simple and easy to use
  – Legacy serial code does not need to be rewritten

• **Cons:**
  – Code can only be run in shared memory environments
  – Compiler must support OpenMP (e.g. gcc 4.2)
OpenMP in CS61C

• OpenMP is built on top of C, so you don’t have to learn a whole new programming language
  – Make sure to add `#include <omp.h>`
  – Compile with flag: `gcc -fopenmp`
  – Mostly just a few lines of code to learn
• You will NOT become experts at OpenMP
  – Use slides as reference, will learn to use in lab
• **Key ideas:**
  – Shared vs. Private variables
  – OpenMP directives for parallelization, work sharing, synchronization
OpenMP Programming Model

- **Fork - Join Model:**
  - **OpenMP programs begin as single process** (*master thread*) **and executes sequentially until the first parallel region construct is encountered**
  - **FORK:** Master thread then creates a team of parallel threads
  - **JOIN:** When the team threads complete the statements in the parallel region construct, they synchronize and terminate, leaving only the master thread
OpenMP Extends C with Pragmas

• *Pragmas* are a preprocessor mechanism C provides for language extensions

• Commonly implemented pragmas: structure packing, symbol aliasing, floating point exception modes (not covered in 61C)

• Good mechanism for OpenMP because compilers that don't recognize a pragma are supposed to ignore them
  – Runs on sequential computer even with embedded pragmas
**parallel Pragma and Scope**

- **Basic OpenMP construct for parallelization:**
  ```
  #pragma omp parallel
  {
    /* code goes here */
  }
  ```
  - Each thread runs a copy of code within the block
  - Thread scheduling is *non-deterministic*

- **OpenMP default is *shared* variables**
  - To make private, need to declare with pragma:
  ```
  #pragma omp parallel private (x)
  ```
  This is annoying, but curly brace MUST go on separate line from #pragma
Thread Creation

• How many threads will OpenMP create?
• Defined by **OMP_NUM_THREADS** environment variable (or code procedure call)
  – Set this variable to the *maximum* number of threads you want OpenMP to use
  – Usually equals the number of cores in the underlying hardware on which the program is run
What Kind of Threads?

• OpenMP threads are operating system (software) threads.
• OS will multiplex requested OpenMP threads onto available hardware threads.
• Hopefully each gets a real hardware thread to run on, so no OS-level time-multiplexing.
• But other tasks on machine can also use hardware threads!
• Be careful when timing results for project 3!
OpenMP intrinsic to set number of threads:
omp_set_num_threads(x);

OpenMP intrinsic to get number of threads:
num_th = omp_get_num_threads();

OpenMP intrinsic to get Thread ID number:
th_ID = omp_get_thread_num();
Parallel Hello World

#include <stdio.h>
#include <omp.h>
int main () {
    int nthreads, tid;

    /* Fork team of threads with private var tid */
    #pragma omp parallel private(tid)
    {
        tid = omp_get_thread_num(); /* get thread id */
        printf("Hello World from thread = %d\n", tid);

        /* Only master thread does this */
        if (tid == 0) {
            nthreads = omp_get_num_threads();
            printf("Number of threads = %d\n", nthreads);
        }
    } /* All threads join master and terminate */}
Data Races and Synchronization

• Two memory accesses form a data race if from different threads to same location, and at least one is a write, and they occur one after another.

• If there is a data race, result of program can vary depending on chance (which thread first?)

• Avoid data races by synchronizing writing and reading to get deterministic behavior.

• Synchronization done by user-level routines that rely on hardware synchronization instructions.

• (more later)
Analogy: Buying Milk

• Your fridge has no milk. You and your roommate will return from classes at some point and check the fridge.

• Whoever gets home first will check the fridge, go and buy milk, and return.

• What if the other person gets back while the first person is buying milk?
  – You’ve just bought twice as much milk as you need!

• It would’ve helped to have left a note...
Lock Synchronization (1/2)

• Use a “Lock” to grant access to a region (critical section) so that only one thread can operate at a time
  – Need all processors to be able to access the lock, so use a location in shared memory as the lock

• Processors read lock and either wait (if locked) or set lock and go into critical section
  – 0 means lock is free / open / unlocked / lock off
  – 1 means lock is set / closed / locked / lock on
Lock Synchronization (2/2)

• Pseudocode:

  Check lock
  Set the lock
  Critical section
  (e.g. change shared variables)
  Unset the lock

  Can loop/idle here if locked
Possible Lock Implementation

• **Lock (a.k.a. busy wait)**

  Get_lock:
  ```
  addiu $t1,$zero,1
  # t1 = Locked value
  ```

  Loop:
  ```
  lw $t0,0($s0)
  bne $t0,$zero,Loop
  # loop if locked
  ```

  Lock:
  ```
  sw $t1,0($s0)
  # Unlocked, so lock
  ```

• **Unlock**

  Unlock:
  ```
  sw $zero,0($s0)
  ```

• **Any problems with this?**
Possible Lock Problem

• Thread 1
  
  addiu $t1,$zero,1
  Loop: lw $t0,0($s0)

  bne $t0,$zero,Loop

Lock: sw $t1,0($s0)

• Thread 2
  
  addiu $t1,$zero,1
  Loop: lw $t0,0($s0)

  bne $t0,$zero,Loop

Lock: sw $t1,0($s0)

Both threads think they have set the lock! Exclusive access not guaranteed!
Hardware Synchronization

• Hardware support required to prevent an interloper (another thread) from changing the value
  – *Atomic* read/write memory operation
  – No other access to the location allowed between the read and write

• How best to implement in software?
  – Single instr? Atomic swap of register ↔ memory
  – Pair of instr? One for read, one for write
Synchronization in MIPS

• **Load linked:**  
  \[\text{ll } rt, \text{off}(rs)\]

• **Store conditional:**  
  \[\text{sc } rt, \text{off}(rs)\]
  – Returns **1** (success) if location has not changed since the \text{ll}
  – Returns **0** (failure) if location has changed

• Note that \text{sc} *clobbers* the register value being stored \((rt)\)!
  – Need to have a copy elsewhere if you plan on repeating on failure or using value later
Synchronization in MIPS Example

• Atomic swap (to test/set lock variable)
  Exchange contents of register and memory:
  \$s4 \leftrightarrow \text{Mem(}\$s1\text{)}

try: add \$t0,\$zero,\$s4 #copy value
ll \$t1,0(\$s1) #load linked
sc \$t0,0(\$s1) #store conditional
beq \$t0,\$zero,try #loop if sc fails
add \$s4,\$zero,\$t1 #load value in \$s4

sc would fail if another threads executes sc here
Test-and-Set

• In a single atomic operation:
  – *Test* to see if a memory location is set (contains a 1)
  – *Set* it (to 1) if it isn’t (it contained a zero when tested)
  – Otherwise indicate that the Set failed, so the program can try again
  – While accessing, no other instruction can modify the memory location, including other Test-and-Set instructions

• Useful for implementing lock operations
Test-and-Set in MIPS

- Example: MIPS sequence for implementing a T&S at ($s1)

Try:
```
addiu $t0,$zero,1
ll  $t1,0($s1)
bne $t1,$zero,Try
```

Locked:
```
# critical section
```

Unlock:
```
sw $zero,0($s1)
```

Idea is that not for programmers to use this directly, but as a tool for enabling implementation of parallel libraries.
**Clickers:** Consider the following code when executed *concurrently* by two threads.

What possible values can result in *($s0)?*

```assembly
# *($s0) = 100
lw   $t0,0($s0)
addi $t0,$t0,1
sw   $t0,0($s0)
```

A: 101 or 102
B: 100, 101, or 102
C: 100 or 101
D: 102
OpenMP Directives (Work-Sharing)

- These are defined within a parallel section

 Shares iterations of a loop across the threads  
 Each section is executed by a separate thread  
 Serializes the execution of a thread
Parallel Statement Shorthand

```c
#pragma omp parallel
{
    #pragma omp for
    for(i=0; i<len; i++) { ... }
}
```

can be shortened to:

```c
#pragma omp parallel for
for(i=0; i<len; i++) { ... }
```

- Also works for sections
Building Block: \texttt{for} loop

\begin{verbatim}
for (i=0; i<max; i++) zero[i] = 0;
\end{verbatim}

• Break \textit{for loop} into chunks, and allocate each to a separate thread
  – e.g. if $\text{max} = 100$ with 2 threads:
    assign 0-49 to thread 0, and 50-99 to thread 1

• Must have relatively simple “shape” for an OpenMP-aware compiler to be able to parallelize it
  – Necessary for the run-time system to be able to determine how many of the loop iterations to assign to each thread

• No premature exits from the loop allowed
  – i.e. No \texttt{break, return, exit, goto statements}

In general, don’t jump outside of any pragma block
Parallel `for pragma`

```c
#pragma omp parallel for
for (i=0; i<max; i++) zero[i] = 0;
```

- Master thread creates additional threads, each with a separate execution context.
- All variables declared outside for loop are shared by default, except for loop index which is `private` per thread (Why?)
- Implicit synchronization at end of for loop.
- Divide index regions sequentially per thread:
  - Thread 0 gets 0, 1, ..., \((\text{max}/n)-1\);
  - Thread 1 gets \(\text{max}/n\), \(\text{max}/n+1\), ..., \(2*(\text{max}/n)-1\)
  - Why?
OpenMP Timing

• Elapsed wall clock time:

  ```c
  double omp_get_wtime(void);
  ```

  – Returns elapsed wall clock time in seconds
  – Time is measured per thread, no guarantee can be made that two distinct threads measure the same time
  – Time is measured from “some time in the past,” so subtract results of two calls to `omp_get_wtime` to get elapsed time
Matrix Multiply in OpenMP

```c
start_time = omp_get_wtime();
#pragma omp parallel for private(tmp, i, j, k)
  for (i=0; i<Mdim; i++){
    for (j=0; j<Ndim; j++){
      tmp = 0.0;
      for( k=0; k<Pdim; k++){
        /* C(i,j) = sum(over k) A(i,k) * B(k,j)*/
        tmp += *(A+(i*Pdim+k)) * *(B+(k*Ndim+j));
      }
      *(C+(i*Ndim+j)) = tmp;
    }
  }
run_time = omp_get_wtime() - start_time;
```

Outer loop spread across N threads; inner loops inside a single thread
Notes on Matrix Multiply Example

• More performance optimizations available:
  – Higher *compiler optimization* (-O2, -O3) to reduce number of instructions executed
  – *Cache blocking* to improve memory performance
  – Using SIMD SSE instructions to raise floating point computation rate (*DLP*)
And in Conclusion, ...

- Sequential software is slow software
  - SIMD and MIMD only path to higher performance
- Multithreading increases utilization, Multicore more processors (MIMD)
- OpenMP as simple parallel extension to C
  - Threads, Parallel for, private, critical sections, ...
  - ≈ C: small so easy to learn, but not very high level and it’s easy to get into trouble