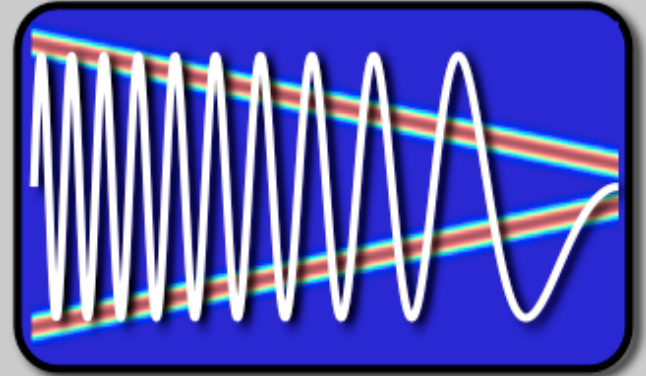


EE123



# Digital Signal Processing

## Lecture 23 Compressed Sensing

# RADIOS

---

- <https://inst.eecs.berkeley.edu/~ee123/sp15/radio.html>

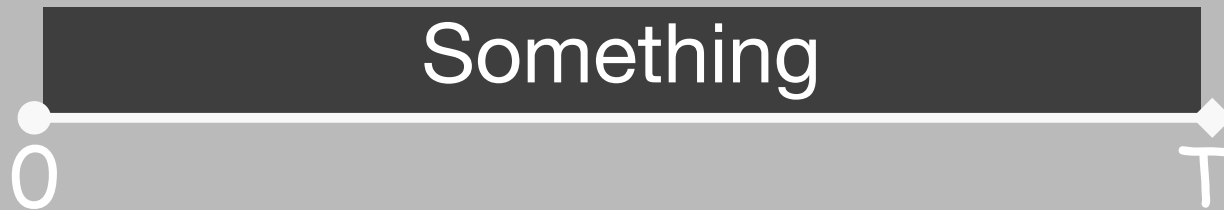
# Compressive Sampling



Q: What is the rate you need to sample at?

A: At least Nyquist!

# Compressive Sampling



Q: What is the rate you need to sample at?

A: Maybe less than Nyquist....

# Image Compression

Images are compressible

Standard approach: First collect, then compress



```
1001101001101
0001001110101
0100110100010
0010101101010
1010101100101
1101110111010
1010110110110
10100111111
```



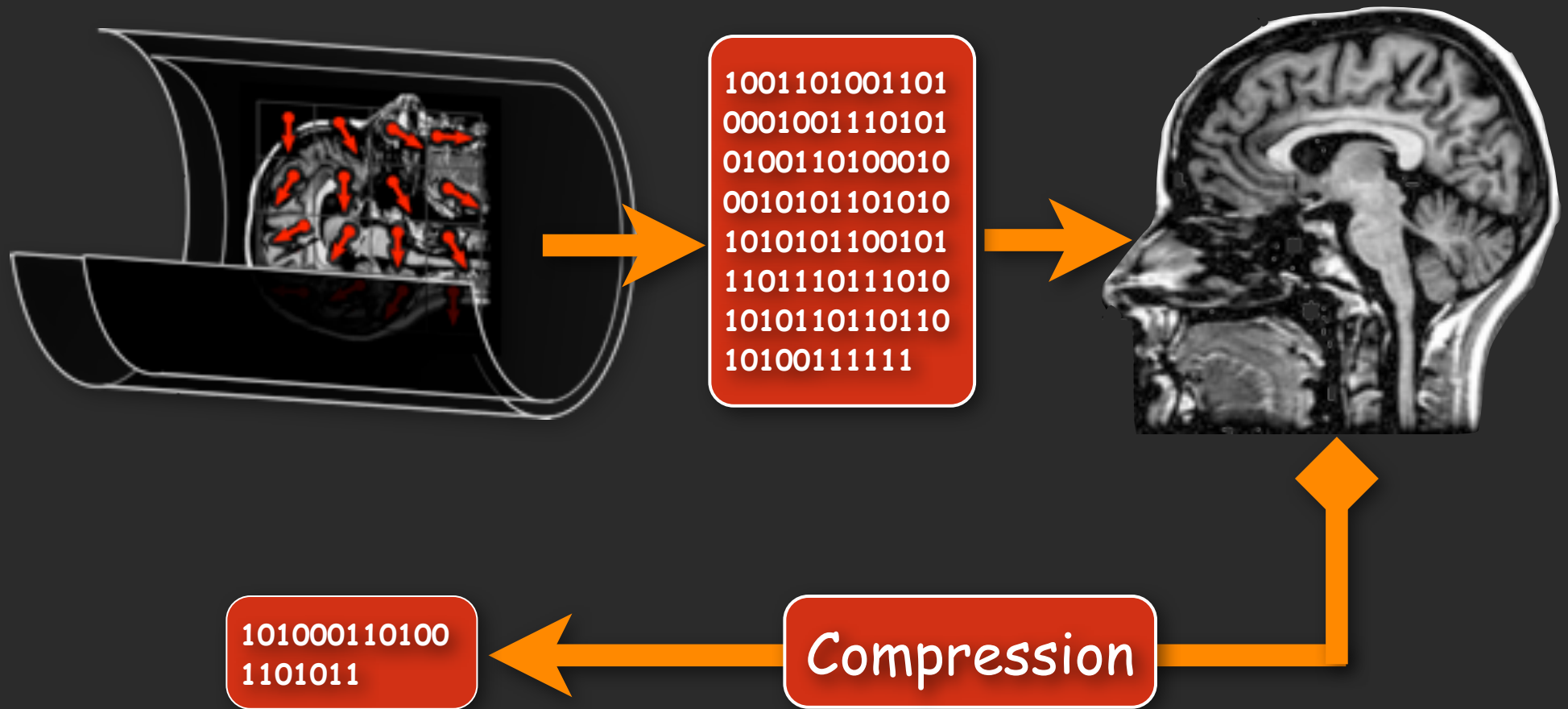
Compression



```
101000110100
1101011
```

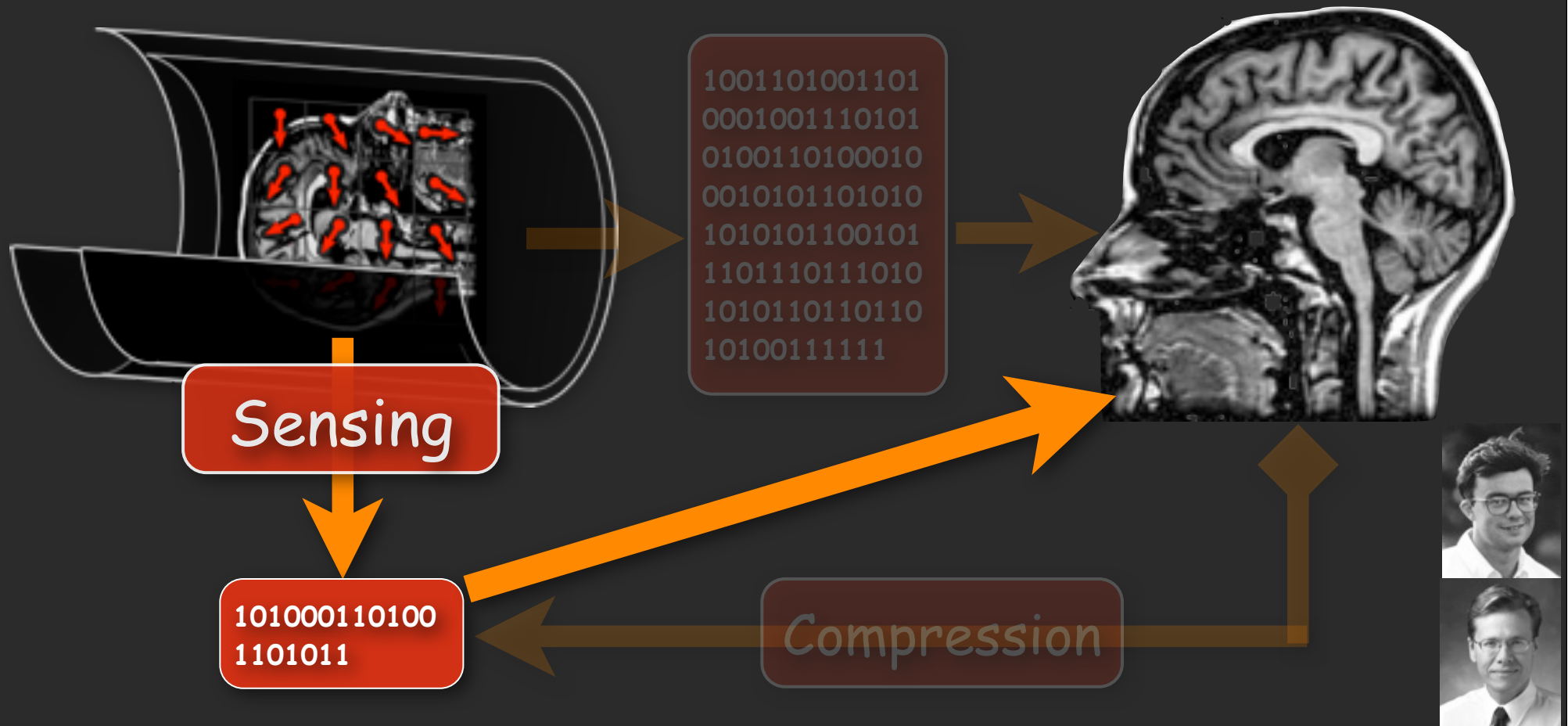
# Image Compression

Medical images are compressible  
Standard approach: First collect, then compress



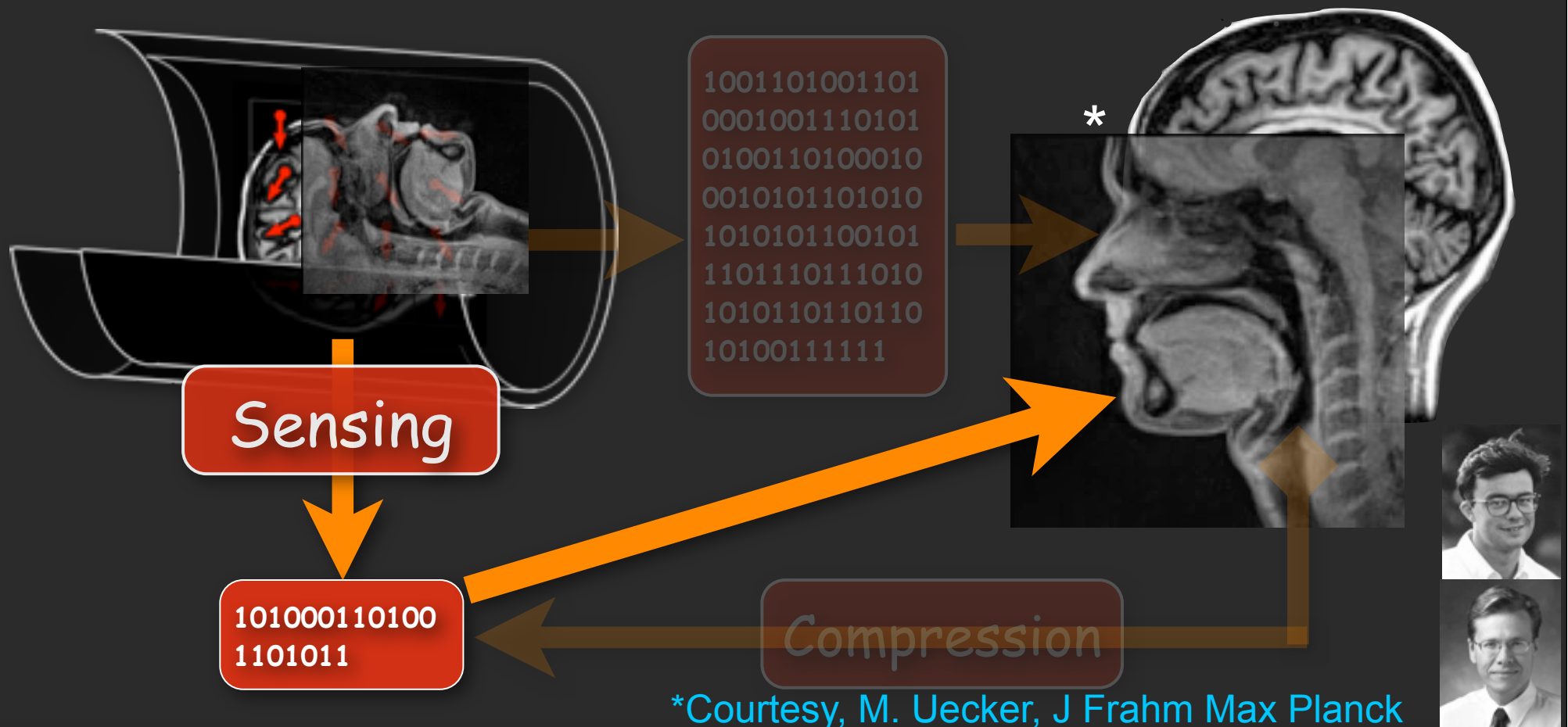
# Compressed Sensing

Medical images are compressible  
Standard approach: First collect, then compress



# Compressed Sensing

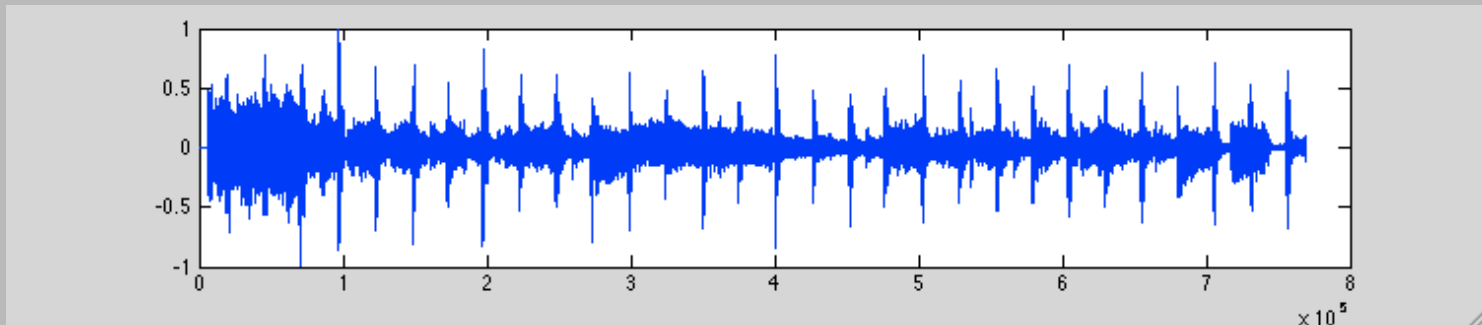
Medical images are compressible  
Standard approach: First collect, then compress



\*Courtesy, M. Uecker, J Frahm Max Planck



# Example I: Audio



Raw audio: 44.1Khz, 16bit, stereo = 1378 Kbit/sec

MP3: 44.1Khz, 16bit, stereo = 128 Kbit/sec

10.76 fold!

# Example II: Images



Raw image ( RGB ): 24 bit/pixel

JPEG : 1280x960, normal = 1.09 bit/pixel

22 fold!

# Example III: Videos



Raw Video:  $(480 \times 360)_p \times 24b/p \times 24fps + 44.1Khz \times 16b \times 2 = 98,578 \text{ Kb/s}$

MPEG4 : 1300 Kb/s

75 fold!

# Compression

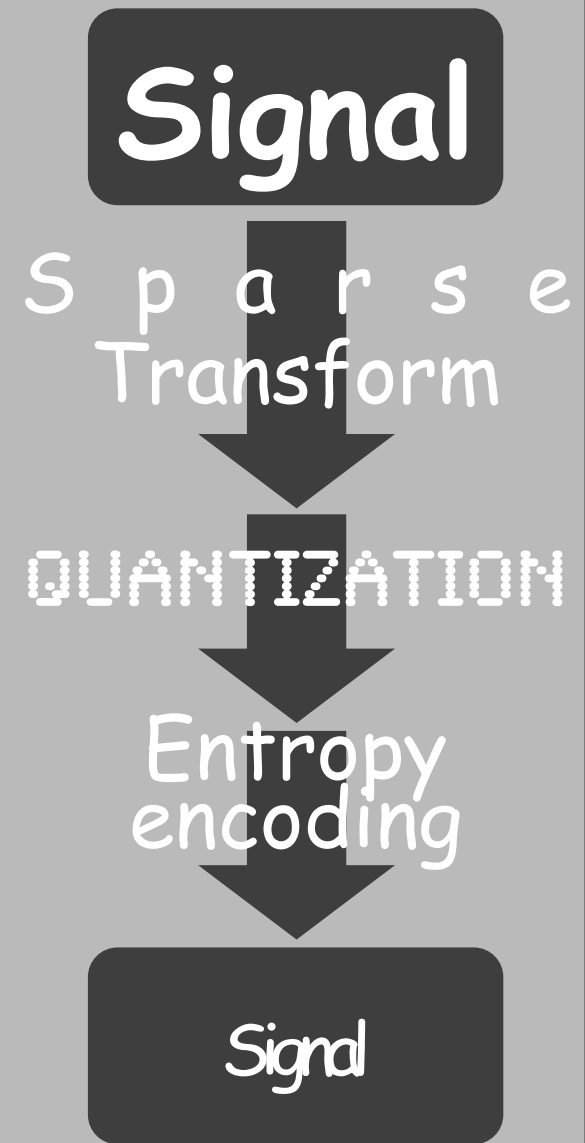
Almost all compression algorithm use transform coding

mp3: DCT

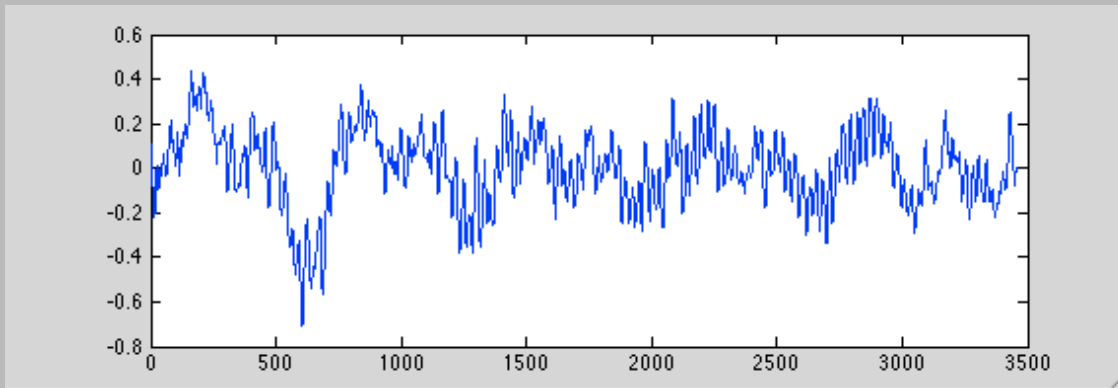
JPEG: DCT

JPEG2000: Wavelet

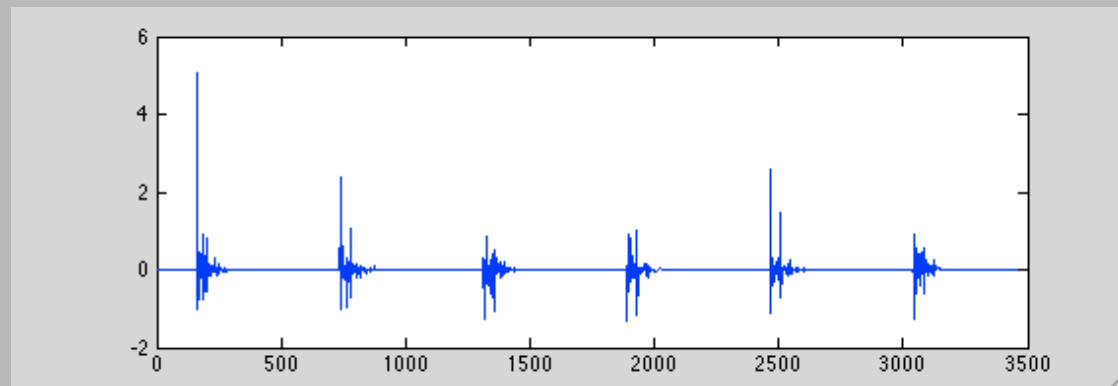
MPEG: DCT & time-difference



# Sparse Transform



DCT



Signal

S p a r s e  
T r a n s f o r m

QUANTIZATION

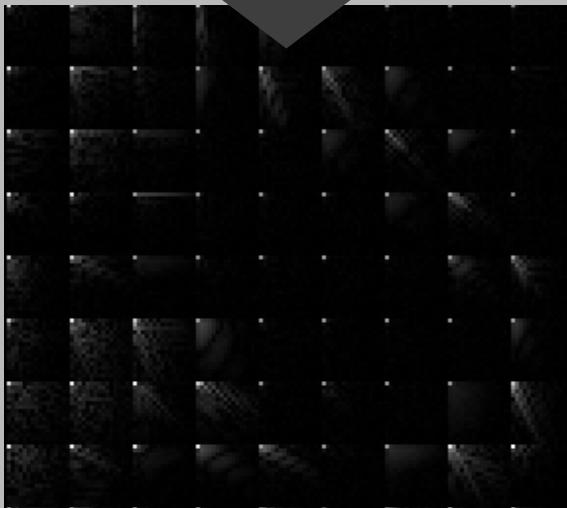
Entropy  
encoding

Signal

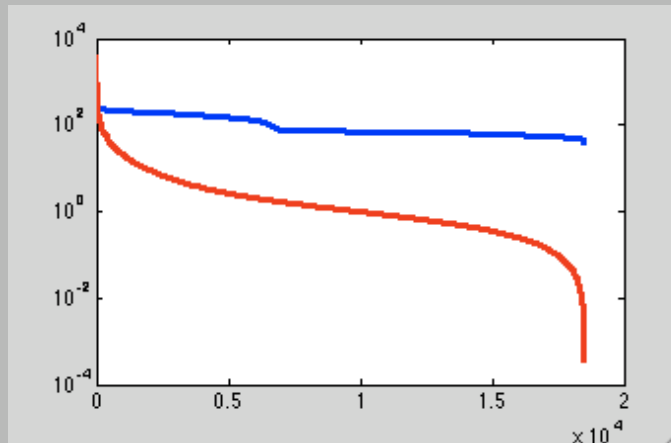
# Sparse Transform



DCT



sorted coefficients



Signal

Sparse Transform

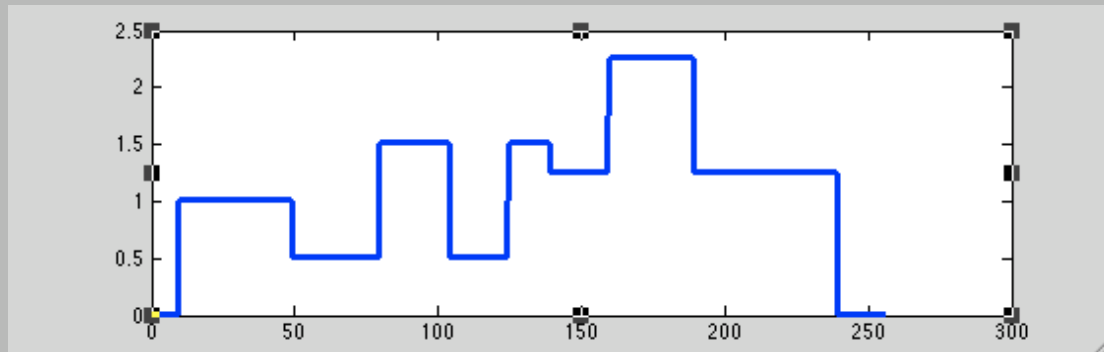
QUANTIZATION

Entropy encoding

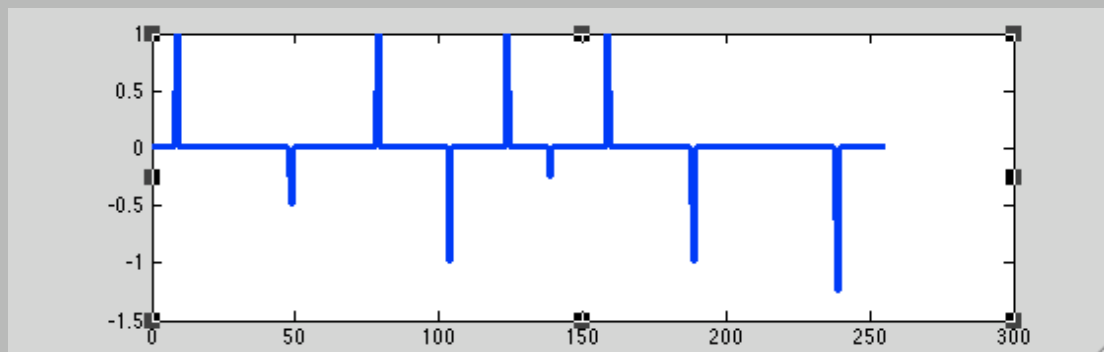
Signal

# Sparse Transform

What sparsifying transform would you use here?



Difference



Signal

Sparse Transform

QUANTIZATION

Entropy encoding

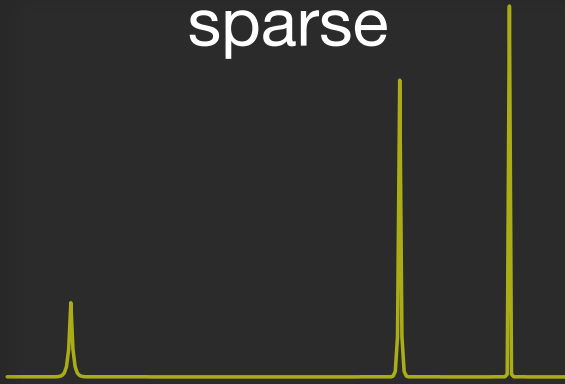
Signal

S p a r s i t y  
&  
Compressibility



# Sparsity and Noise

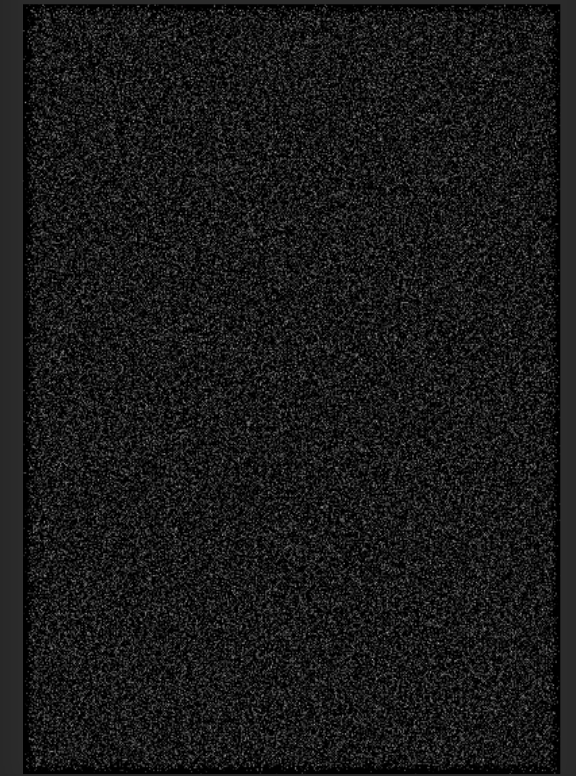
sparse



\*

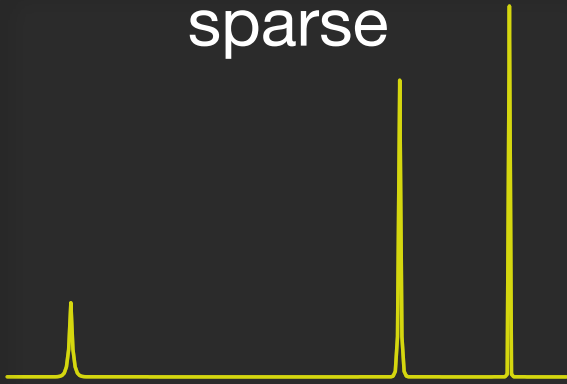


not sparse

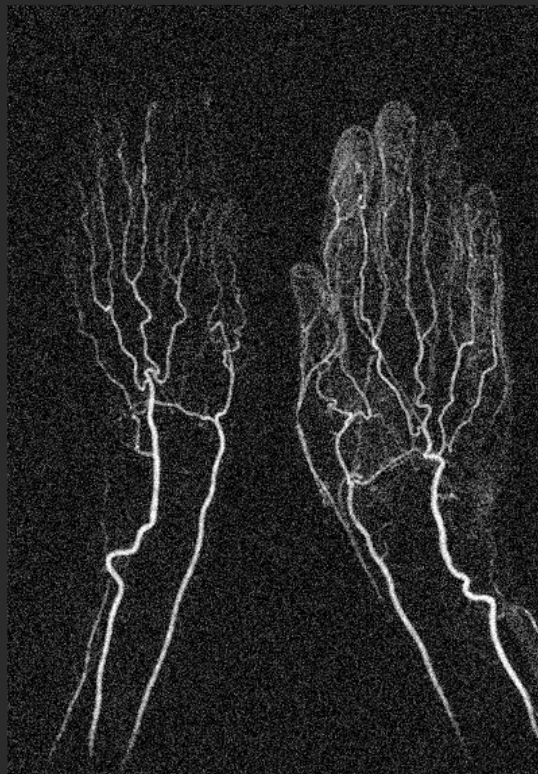
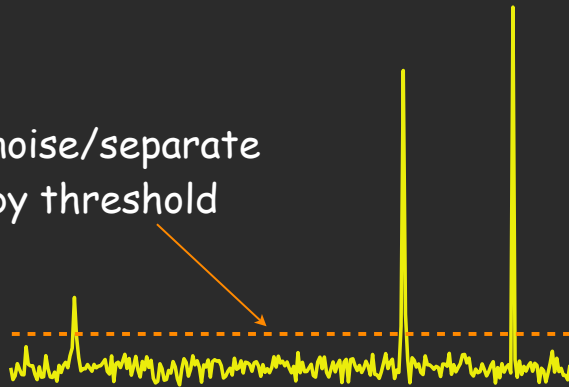


# Sparsity and Noise

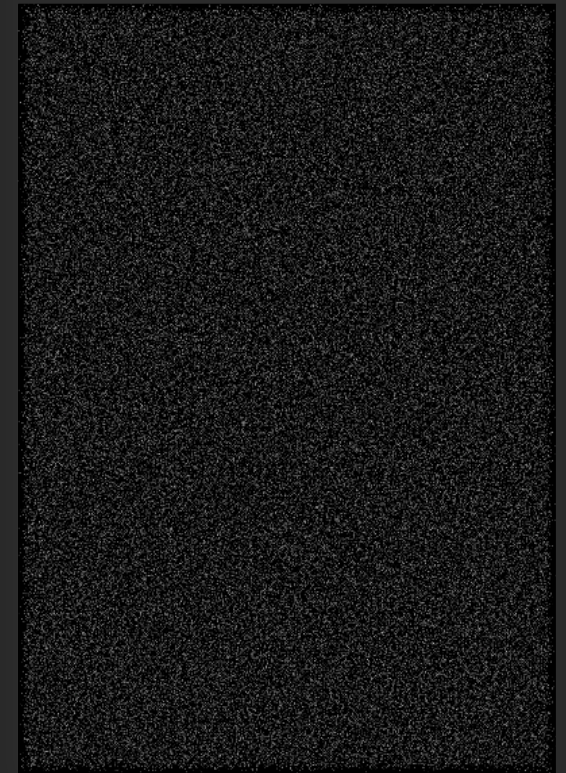
sparse

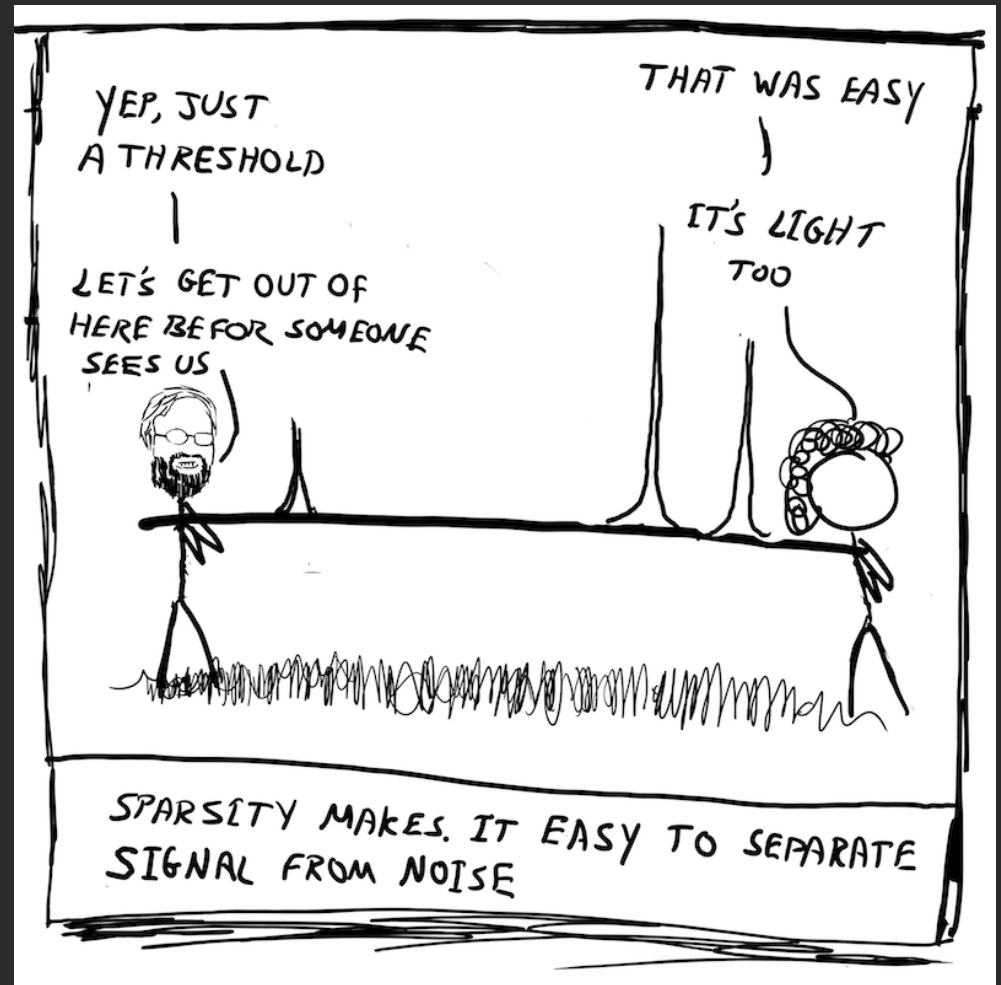
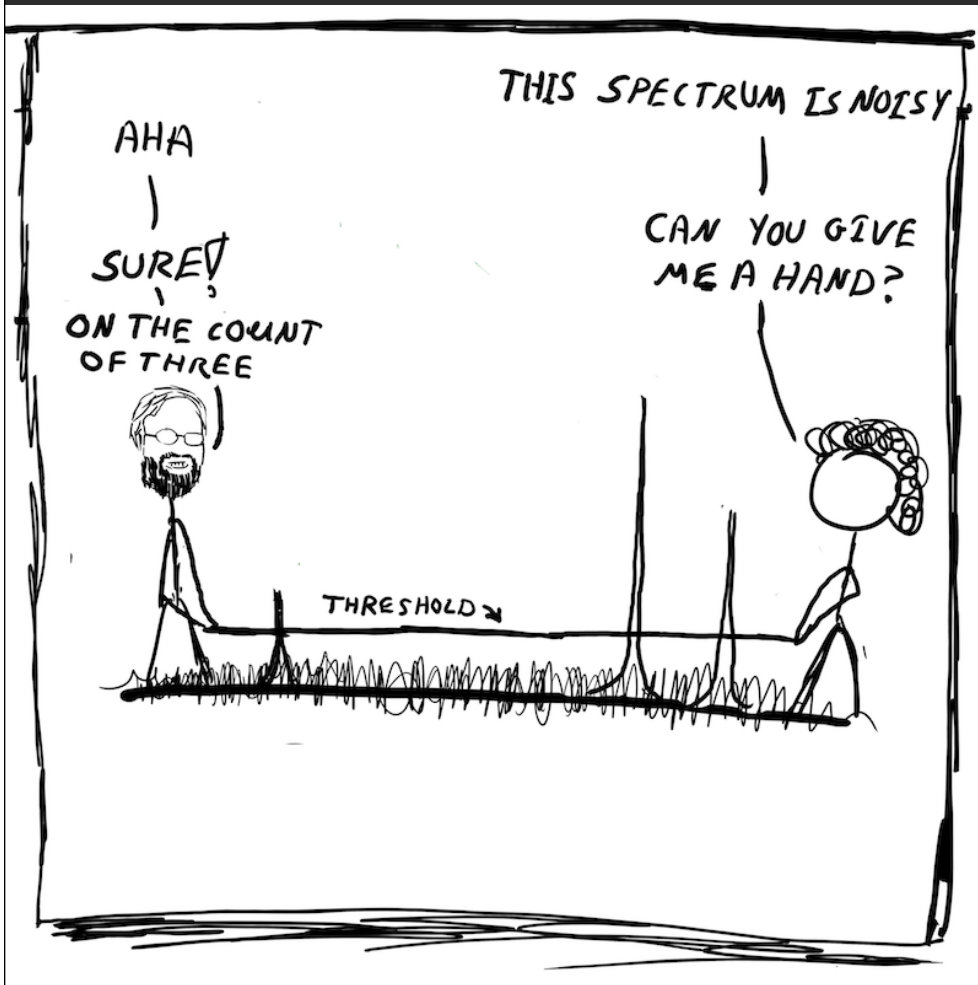


denoise/separate  
by threshold



not sparse





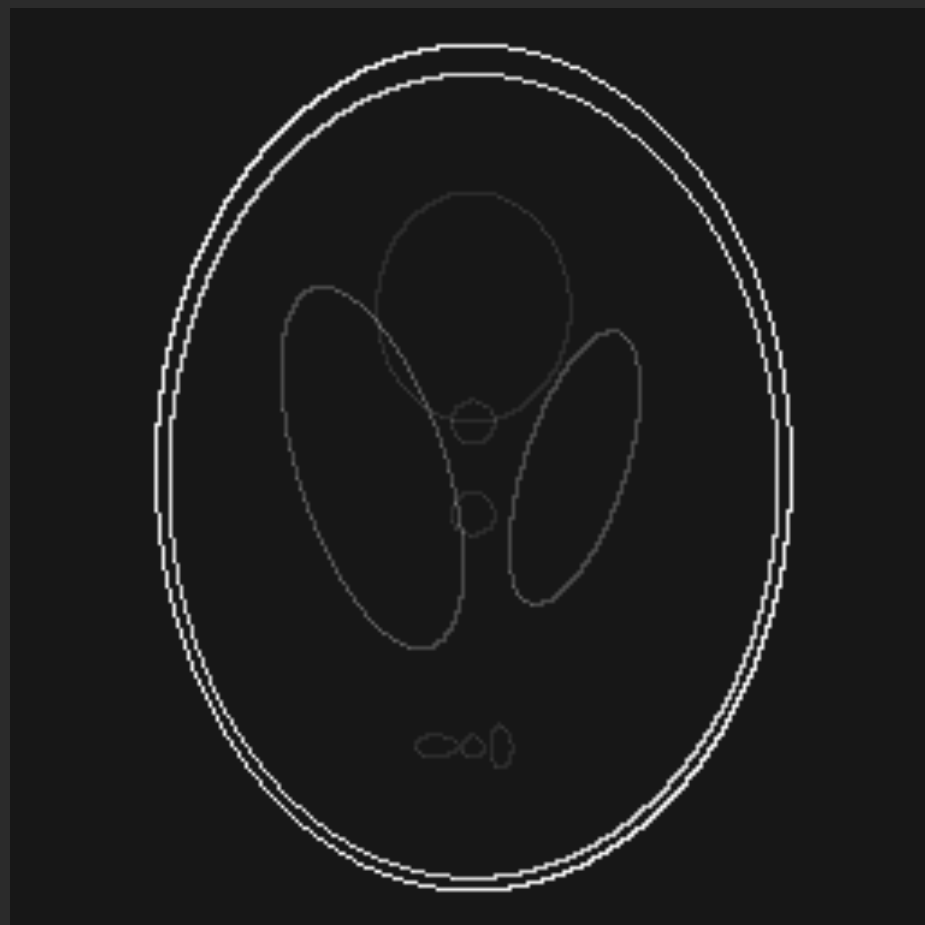
# Transform Sparsity

---

not sparse



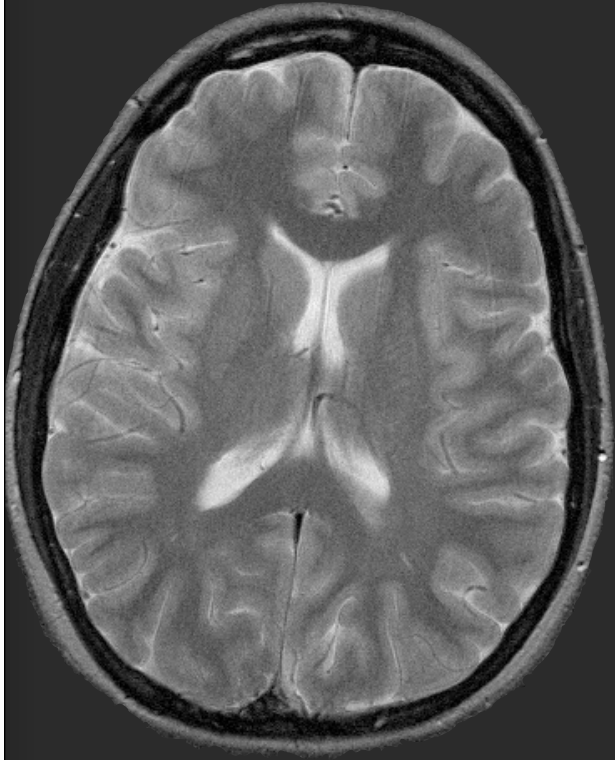
Sparse Edges





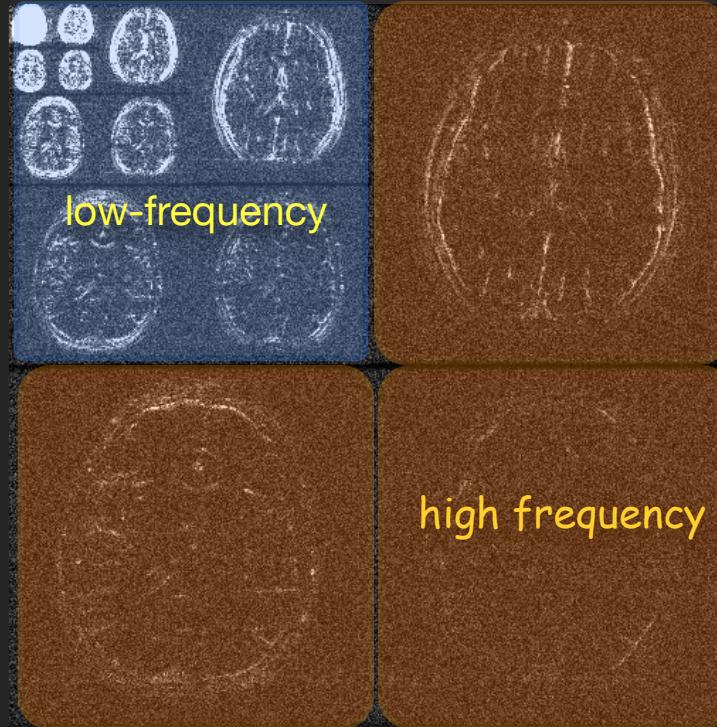
# Transform Sparsity and Denoising

not sparse



sparse

wavelet transform

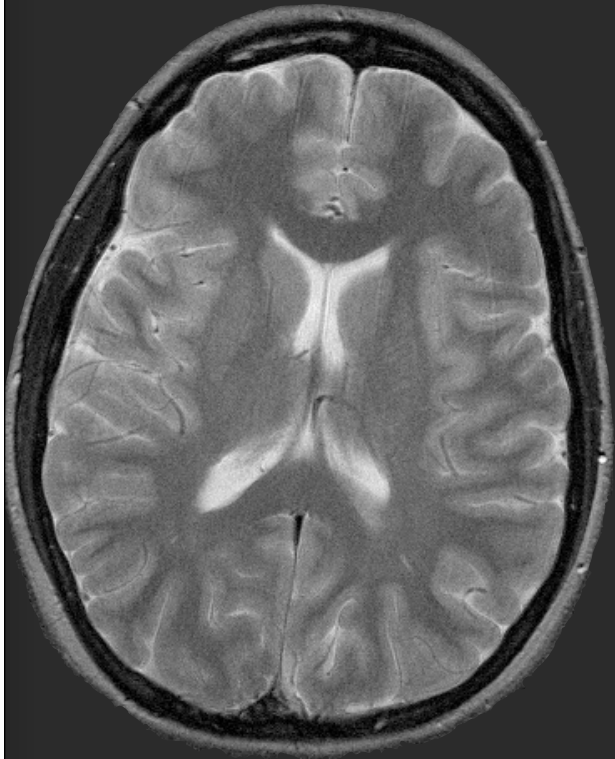


denoised

DL Donoho, I Johnstone Biometrika 1994;81(3):425-55

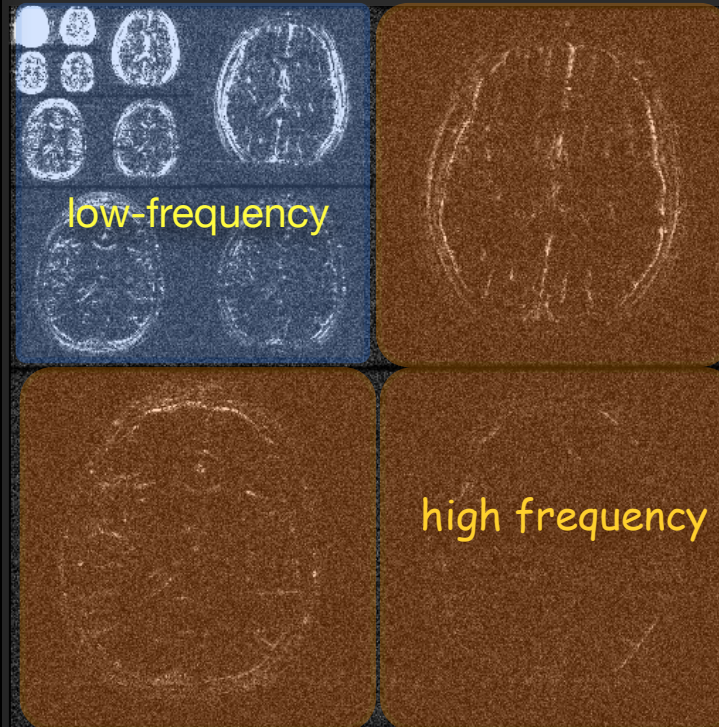
# Transform Sparsity and Denoising

not sparse



sparse

wavelet transform



denoised

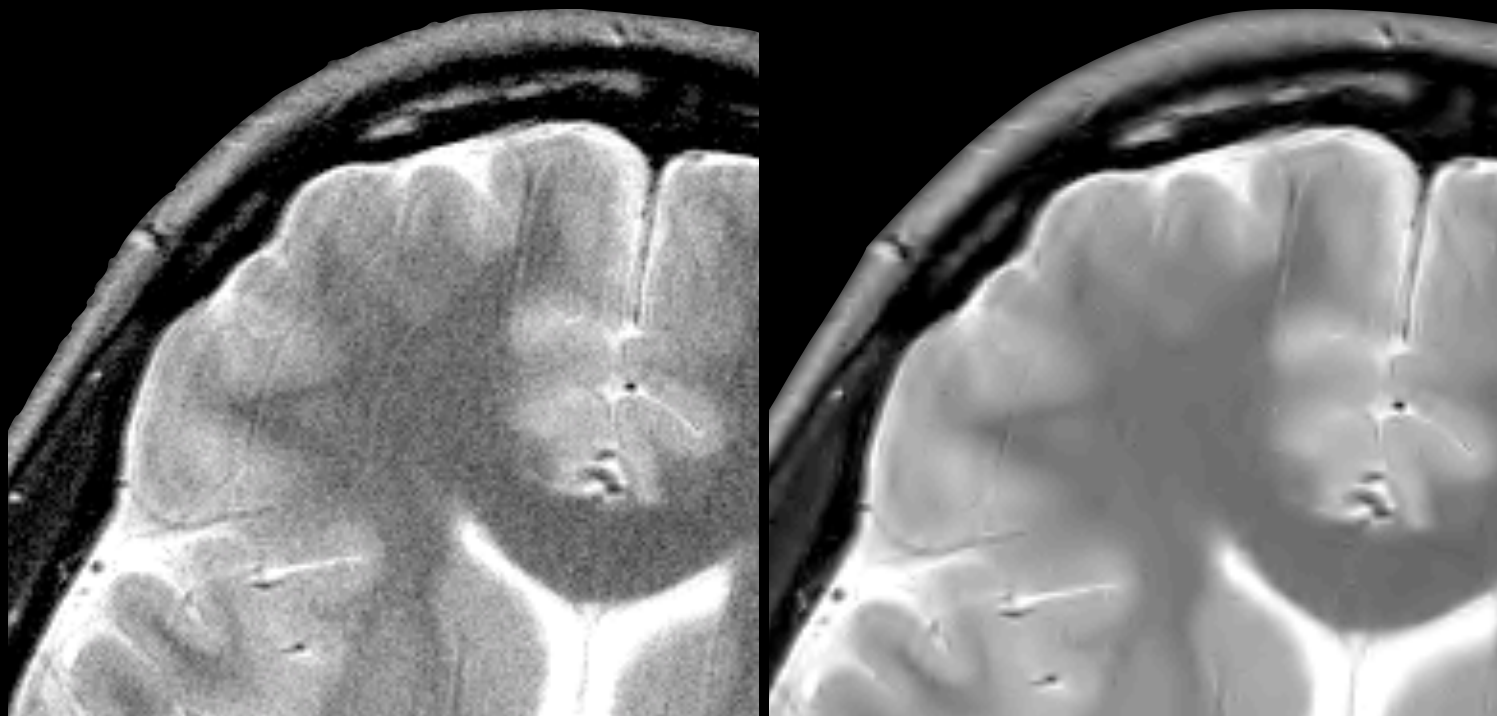


DL Donoho, I Johnstone Biometrika 1994;81(3):425-55

## Transform Sparsity and Denoising

---

wavelet denoising



DL Donoho, I Johnstone *Biometrika* 1994;81(3):425-55

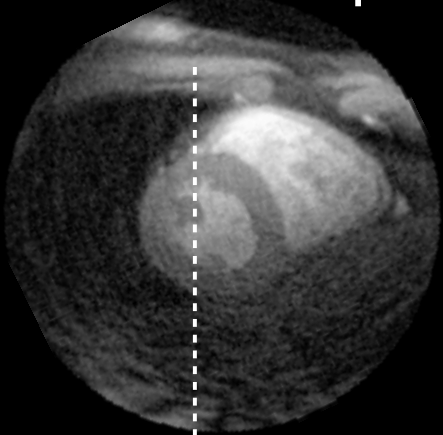
M. Lustig, EECS UC Berkeley



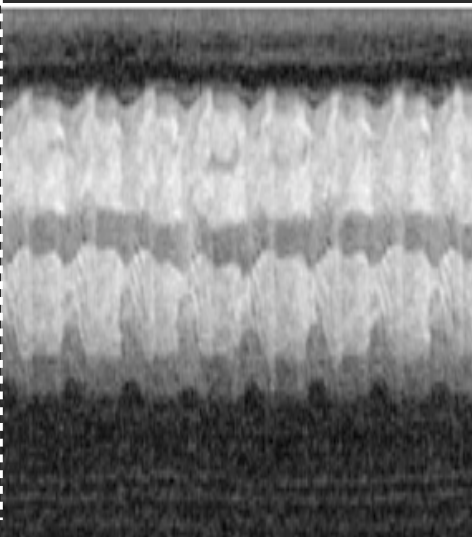
# More Sparse Transforms

\*Video courtesy of Juan Santos, Heart Vista

not Sparse



position

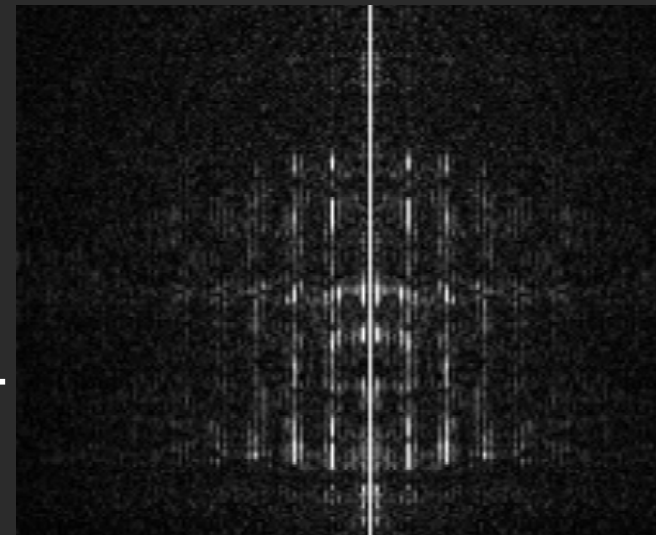


time



position

Sparse

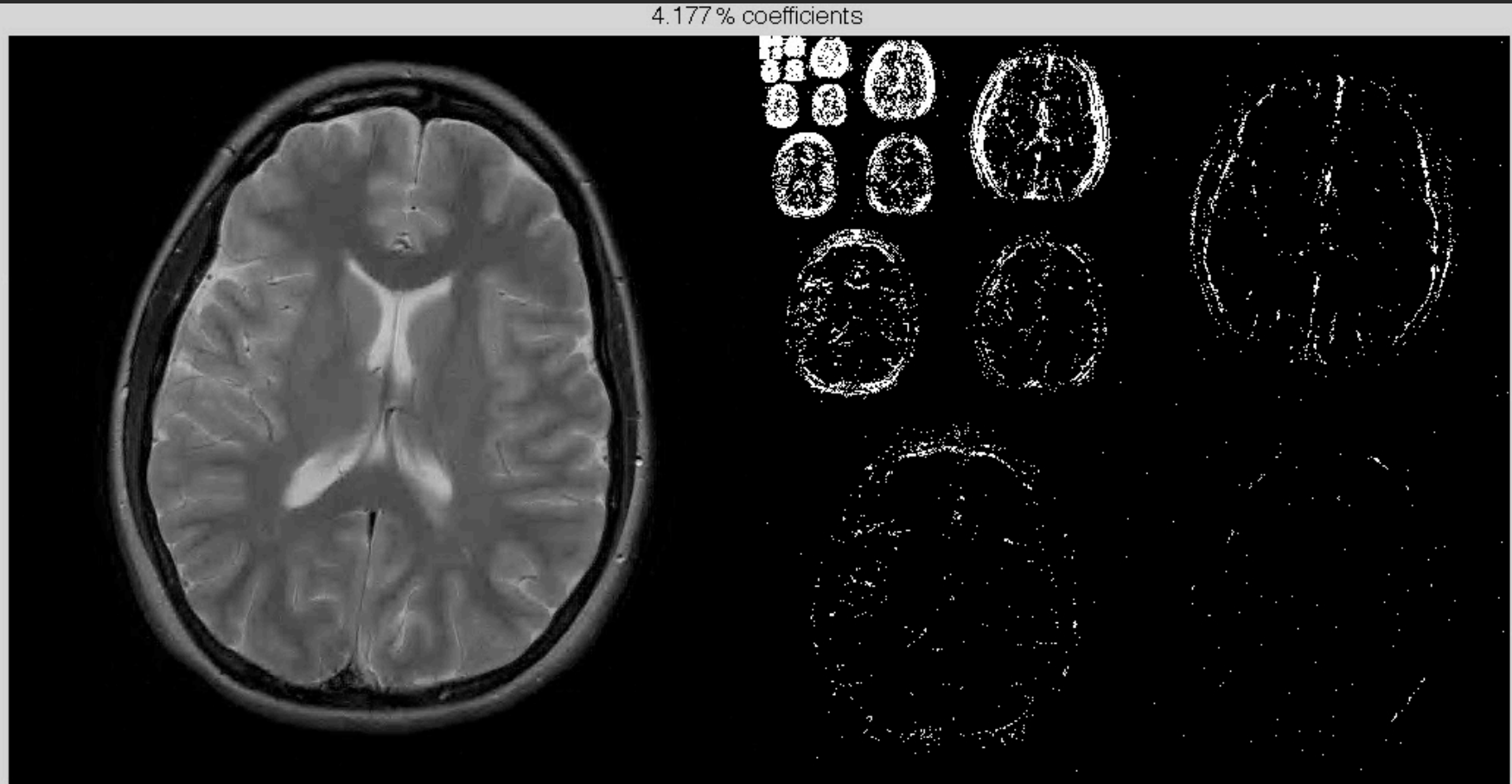


temporal frequency



# Sparsity and Compression

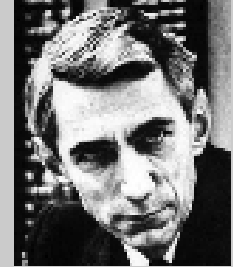
- Only need to store non-zeros



# From Samples to Measurements

---

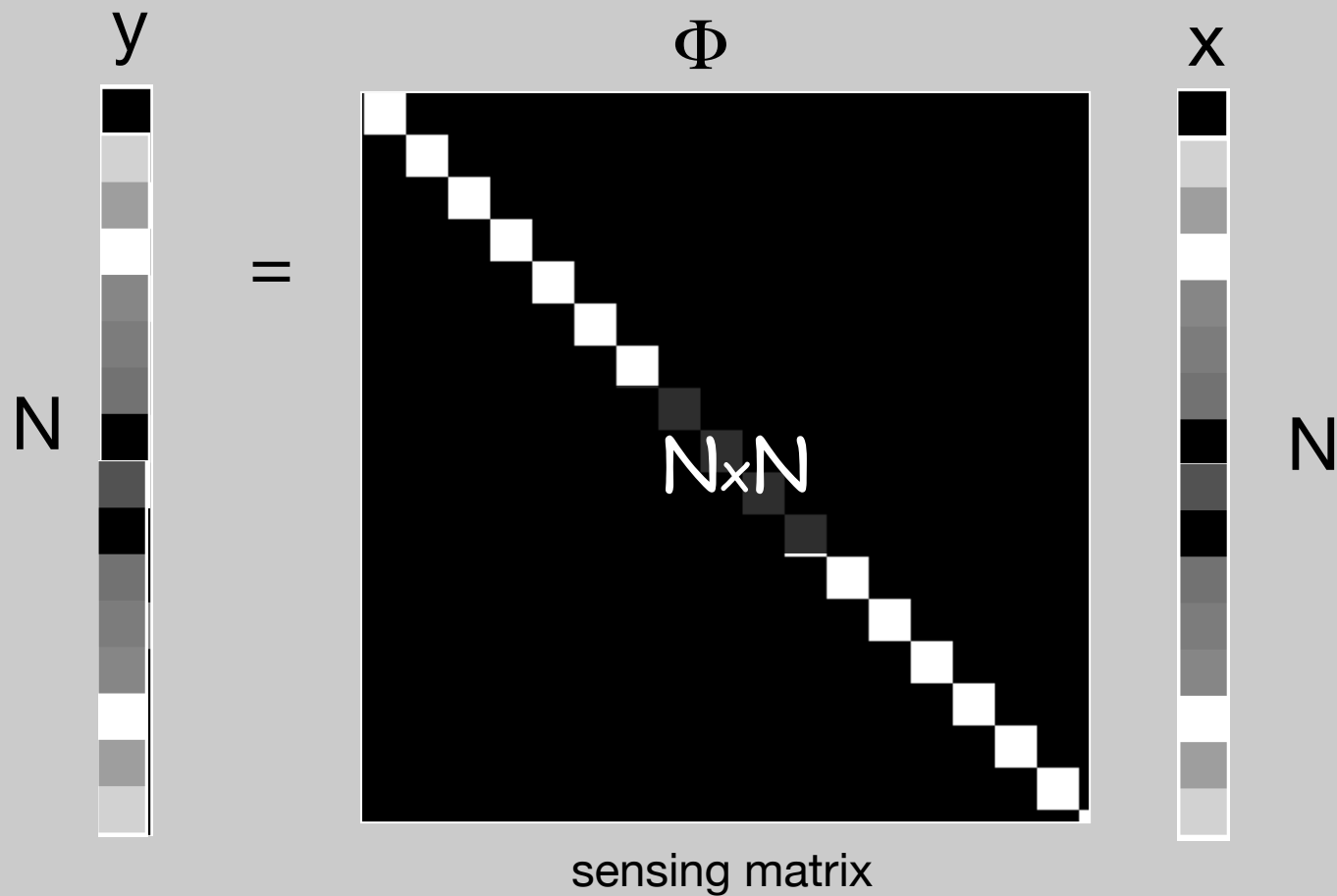
- Shannon-Nyquist sampling
  - Worst case for ANY bandlimited data
- Compressive sampling (CS)
  - “Sparse signals statistics can be recovered from a small number of non-adaptive linear measurements”
  - Integrated sensing, compression and processing.
  - Based on concepts of incoherency between signal and measurements



# Traditional Sensing

Desktop scanner/ digital camera sensing

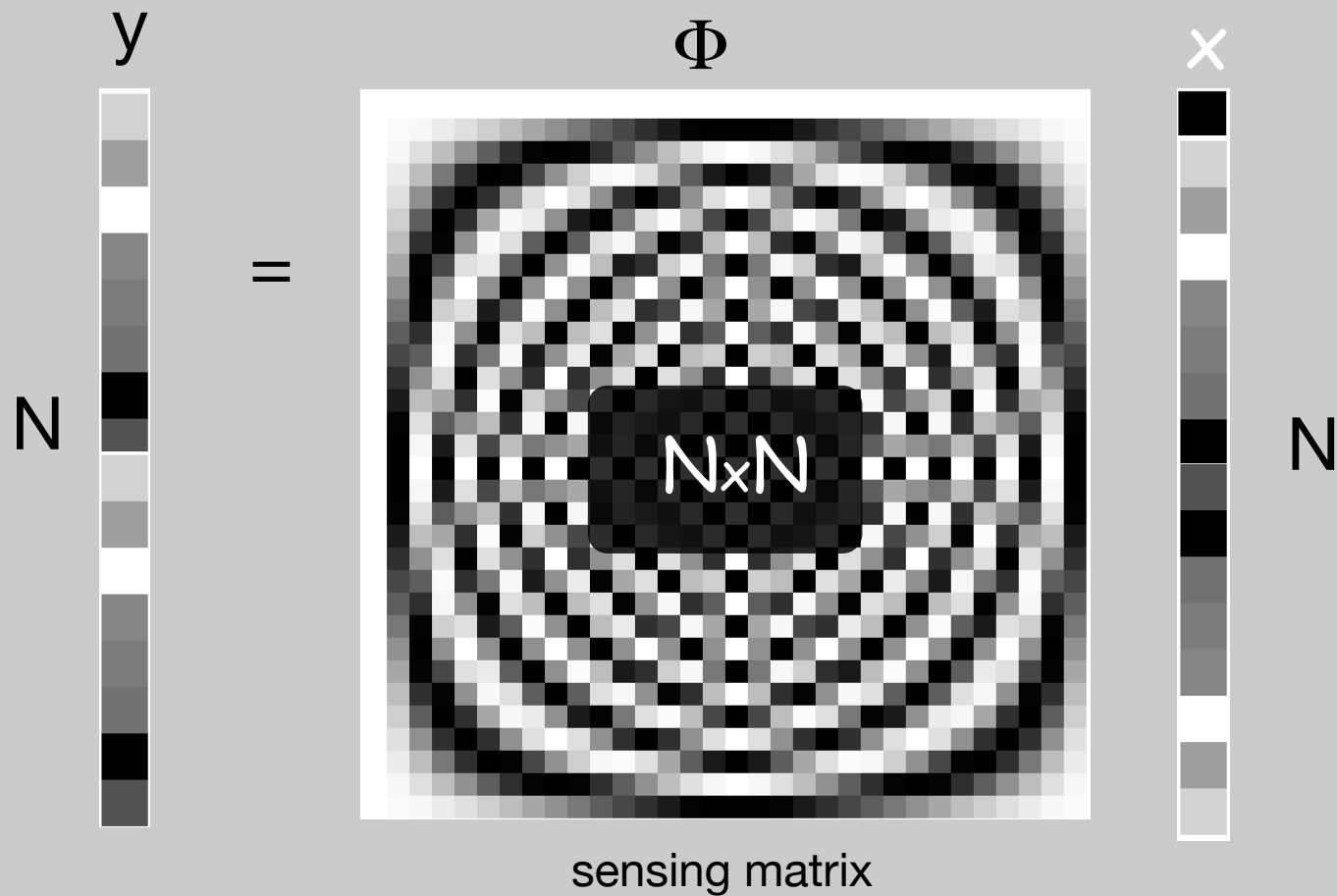
- $x \in \mathbb{R}^N$  is a signal
- Make  $N$  linear measurements



# Traditional Sensing

MRI Fourier Imaging

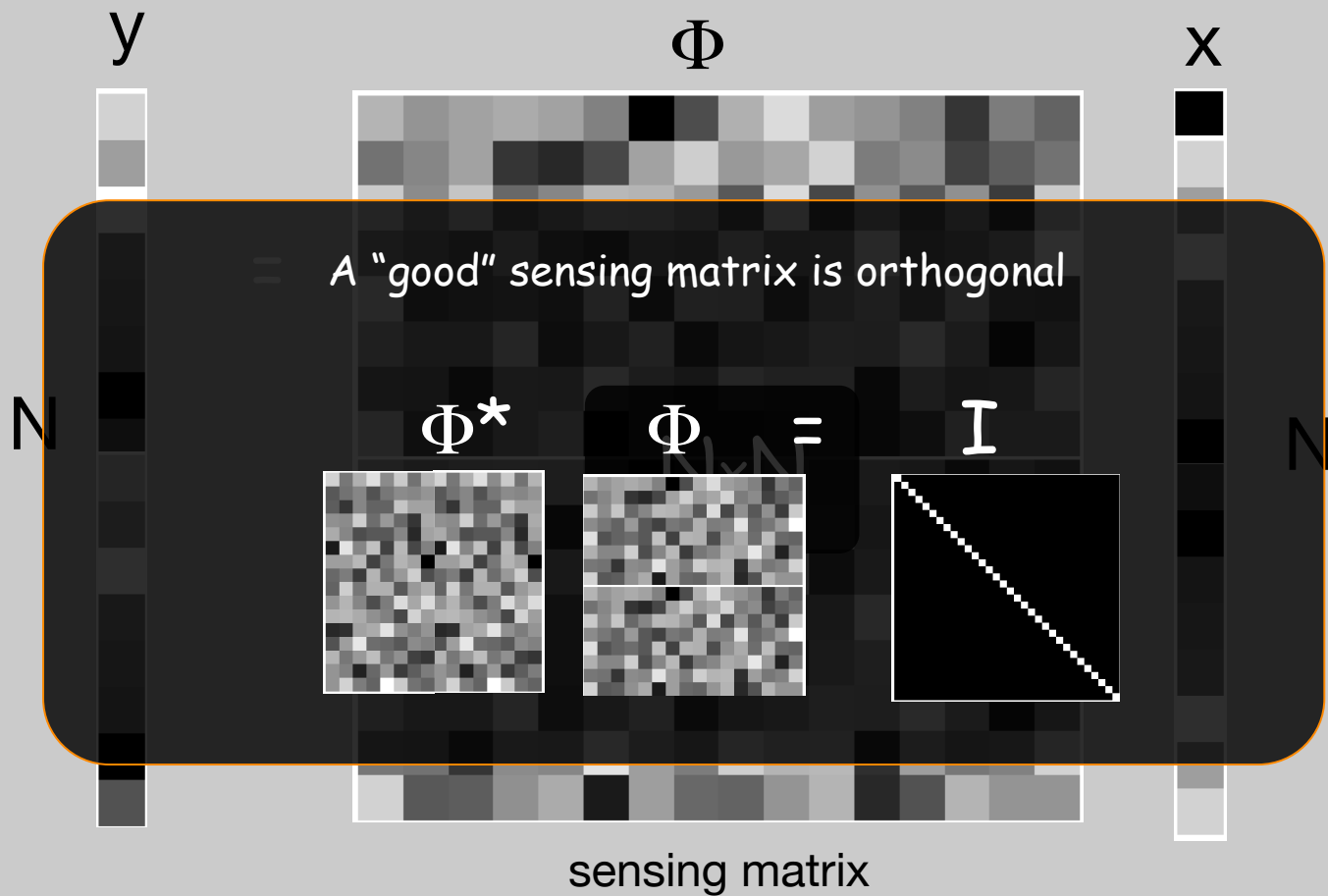
- $x \in \mathbb{R}^N$  is a signal
- Make  $N$  linear measurements



# Traditional Sensing

Arbitrary sensing

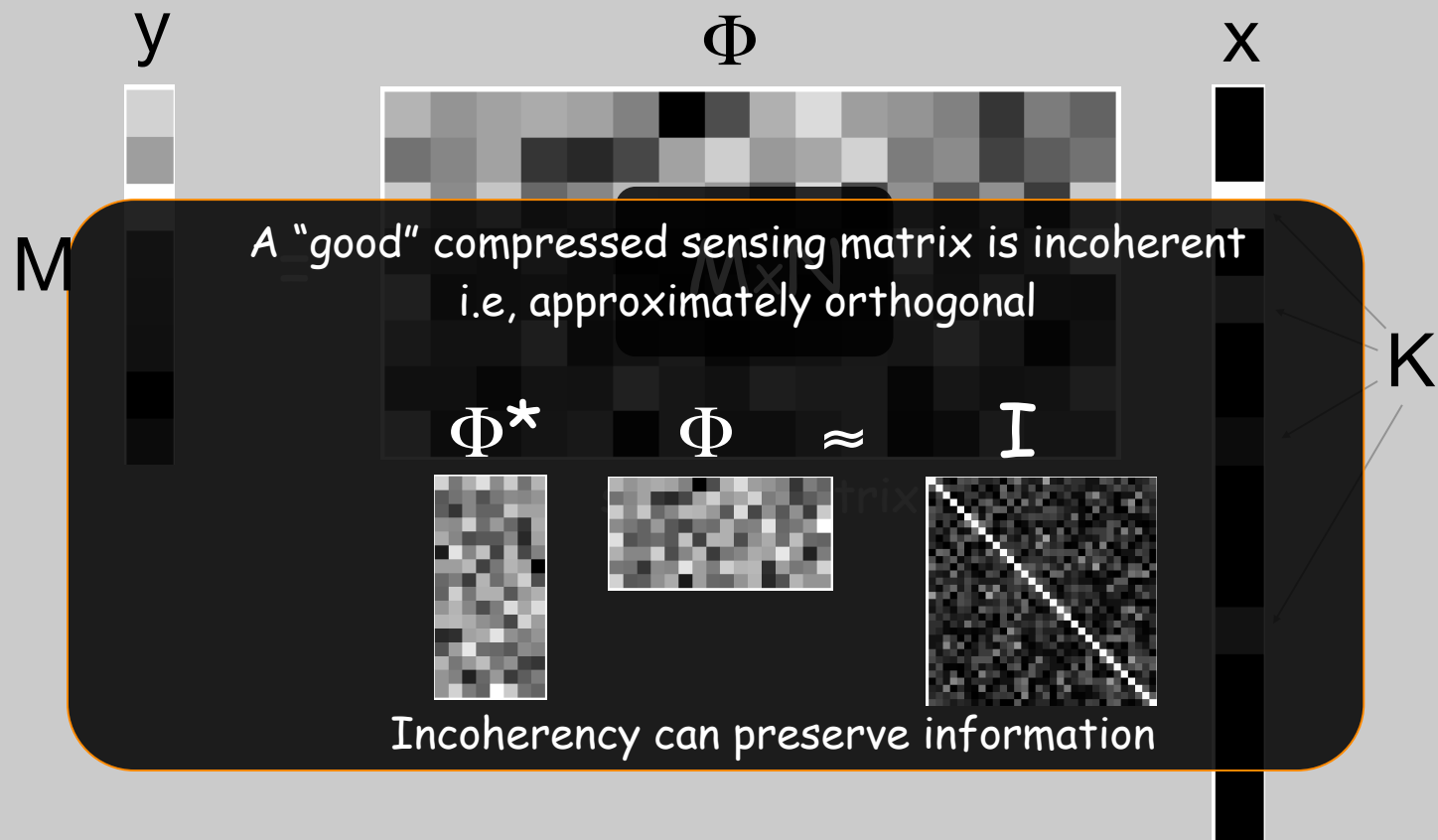
- $x \in \mathbb{R}^N$  is a signal
- Make  $N$  linear measurements



# Compressed Sensing

(Candes, Romber, Tao 2006; Donoho 2006)

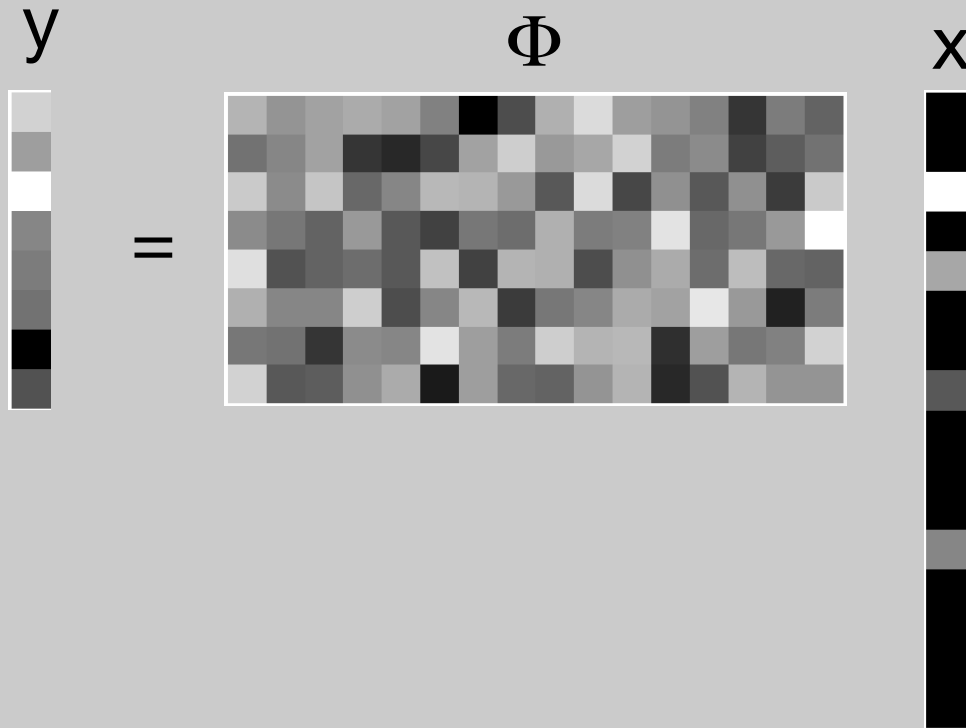
- $x \in \mathbb{R}^N$  is a **K-sparse** signal ( $K \ll N$ )
- Make **M** ( $K < M \ll N$ ) **incoherent** linear projections



# CS recovery

---

- Given  $y = \Phi x$   
find  $x$
  - But there's hope,  $x$  is sparse!
- } Under-determined



## CS recovery

---

- Given  $y = \Phi x$   
find  $x$
  - But there's hope,  $x$  is sparse!
- } Under-determined



## CS recovery

---

- Given  $y = \Phi x$   
find  $x$
  - But there's hope,  $x$  is sparse!
- } Under-determined

$$\begin{aligned} & \text{minimize } \|x\|_2 \\ & \text{s.t. } y = \Phi x \end{aligned}$$

WRONG!

## CS recovery

---

- Given  $y = \Phi x$   
find  $x$
  - But there's hope,  $x$  is sparse!
- } Under-determined

$$\begin{aligned} & \text{minimize } \|x\|_0 \\ & \text{s.t. } y = \Phi x \end{aligned}$$

HARD!

## CS recovery

---

- Given  $y = \Phi x$   
find  $x$
  - But there's hope,  $x$  is sparse!
- } Under-determined

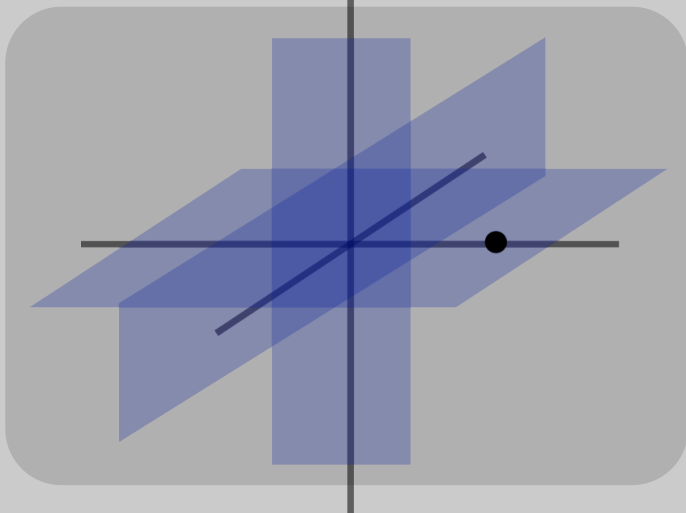
$$\begin{aligned} & \text{minimize } \|x\|_1 \\ & \text{s.t. } y = \Phi x \end{aligned}$$

need  $M \approx K \log(N) \ll N$

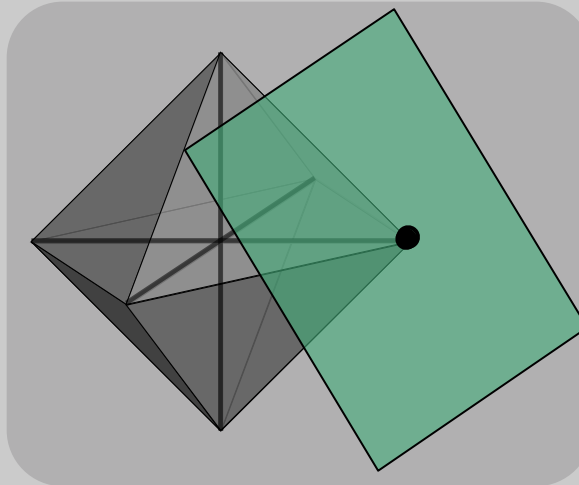
Solved by linear-programming

# Geometric Interpretation

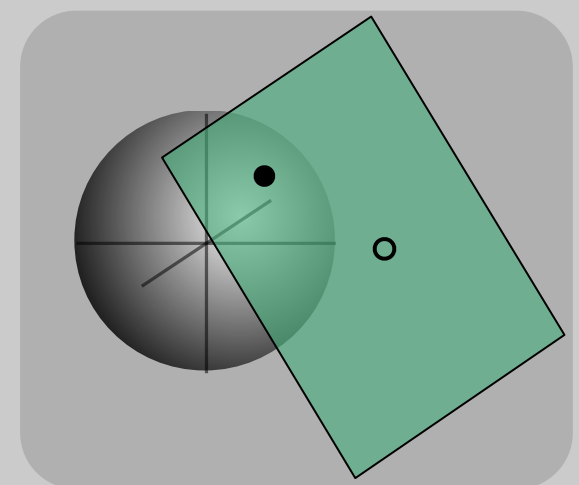
domain of sparse signals



minimum  $\|x\|_1$



minimum  $\|x\|_2$



$$\begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \end{bmatrix}$$