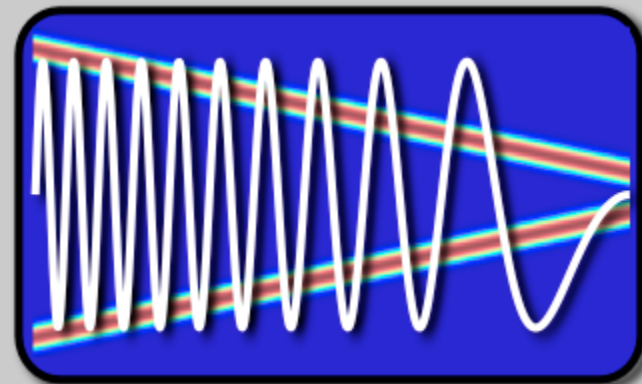


EE123



Digital Signal Processing

Lecture 24

Compressed Sensing III

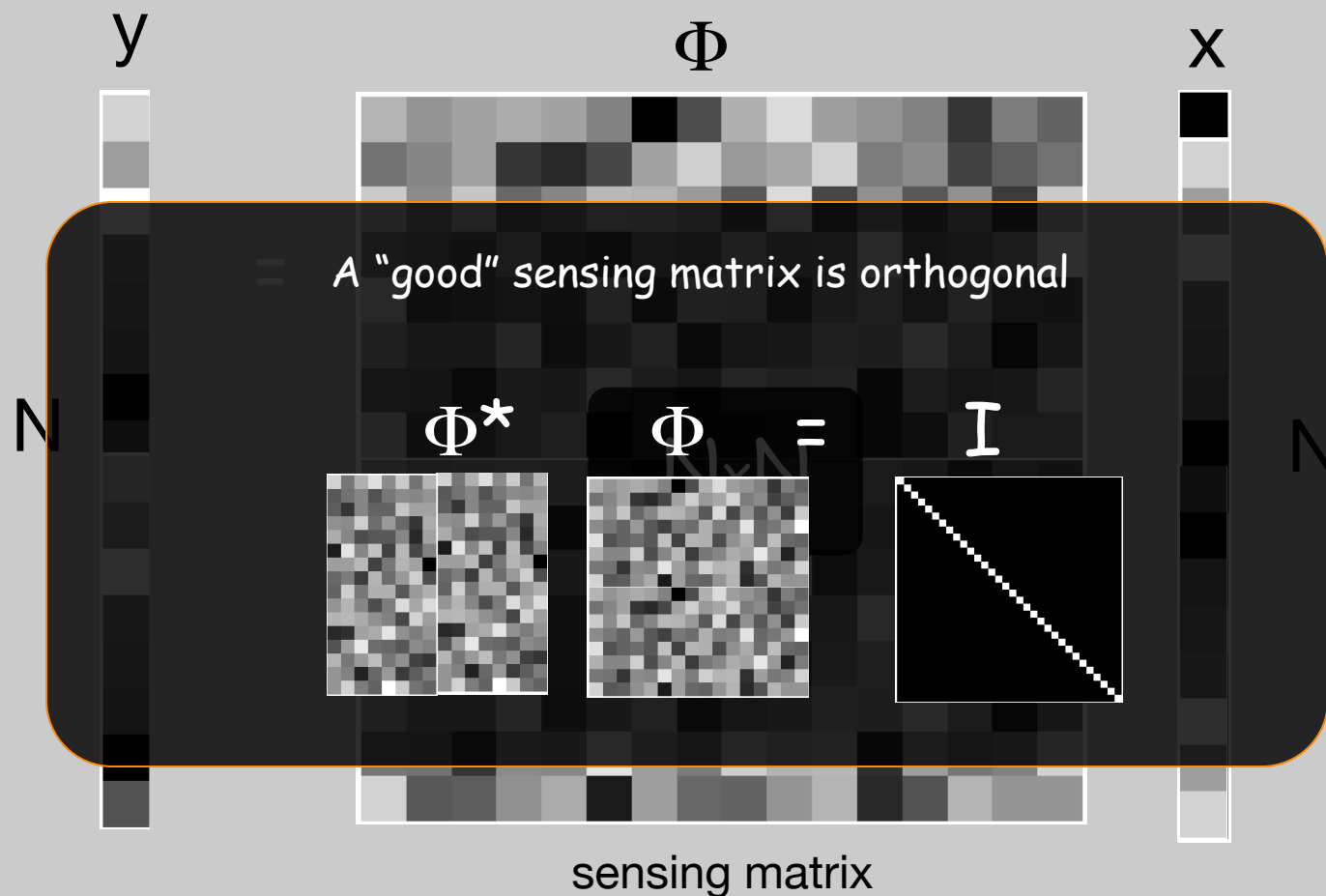
RADIOS

- <https://inst.eecs.berkeley.edu/~ee123/sp15/radio.html>
- Interfaces and radios on Wednesday -- please come to pick up
- Midterm II this Friday -- same deal - open everything covers everything including 2D

Traditional Sensing

- $x \in \mathbb{R}^N$ is a signal
- Make N linear measurements

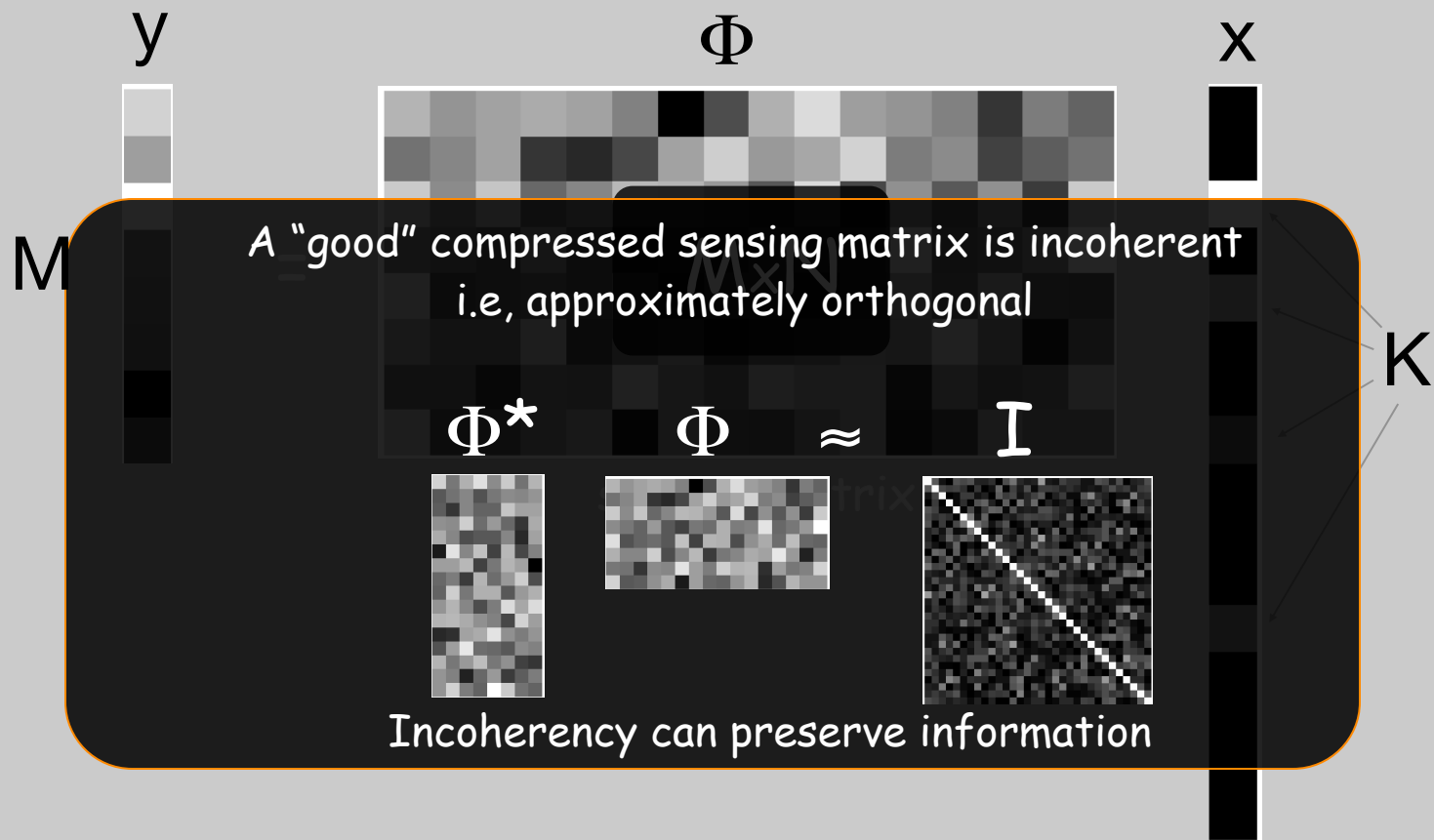
Arbitrary sensing



Compressed Sensing

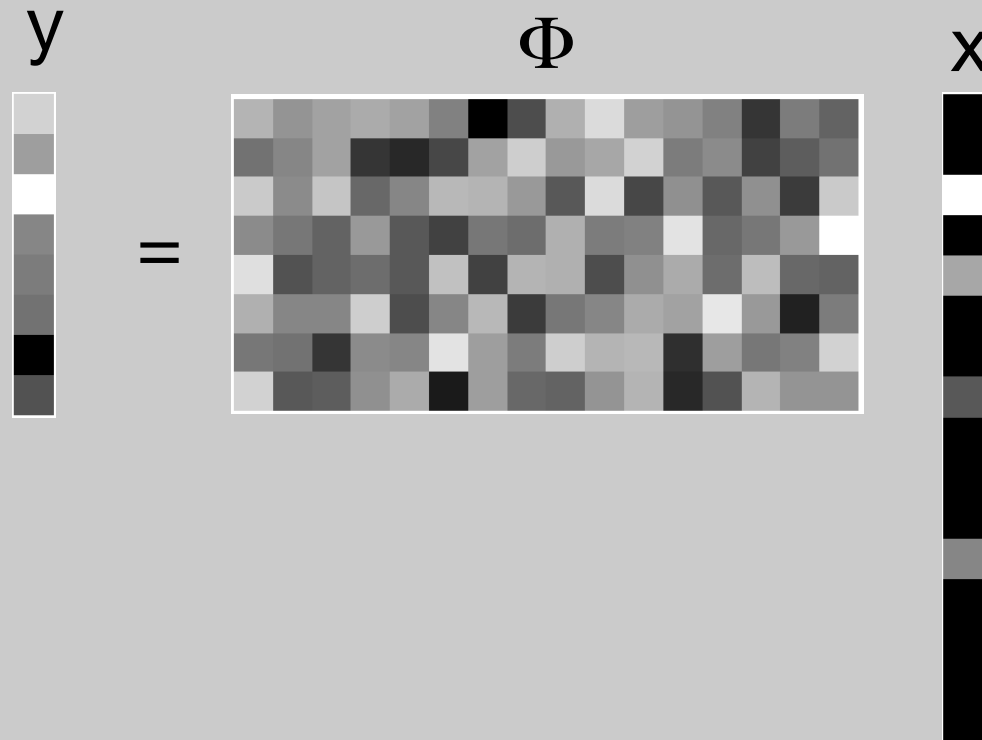
(Candes, Romber, Tao 2006; Donoho 2006)

- $x \in \mathbb{R}^N$ is a **K-sparse** signal ($K \ll N$)
- Make **M** ($K < M \ll N$) **incoherent** linear projections



CS recovery

- Given $y = \Phi x$
find x
 - But there's hope, x is sparse!
- } Under-determined



CS recovery

- Given $y = \Phi x$
find x



Under-determined

- But there's hope, x is sparse!

CS recovery

- Given $y = \Phi x$
find x
 - But there's hope, x is sparse!
- } Under-determined

$$\begin{aligned} & \text{minimize } \|x\|_2 \\ & \text{s.t. } y = \Phi x \end{aligned}$$

WRONG!

CS recovery

- Given $y = \Phi x$
find x
 - But there's hope, x is sparse!
- } Under-determined

minimize $\|x\|_0$

s.t. $y = \Phi x$

HARD!

CS recovery

- Given $y = \Phi x$
find x
 - But there's hope, x is sparse!
- } Under-determined

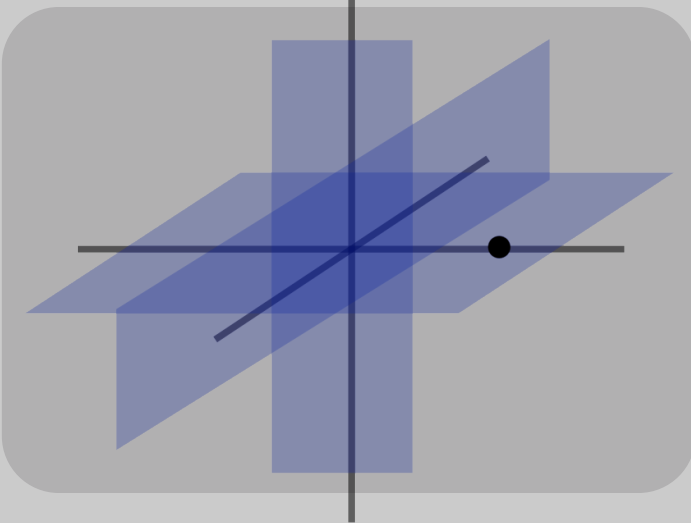
$$\begin{aligned} & \text{minimize } \|x\|_1 \\ & \text{s.t. } y = \Phi x \end{aligned}$$

need $M \approx K \log(N) \ll N$

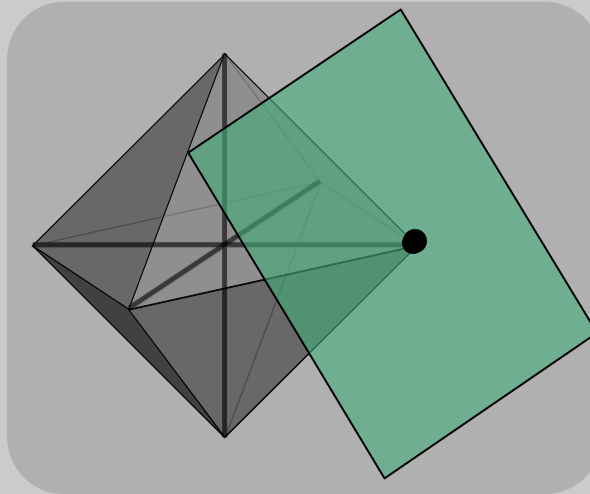
Solved by linear-programming

Geometric Interpretation

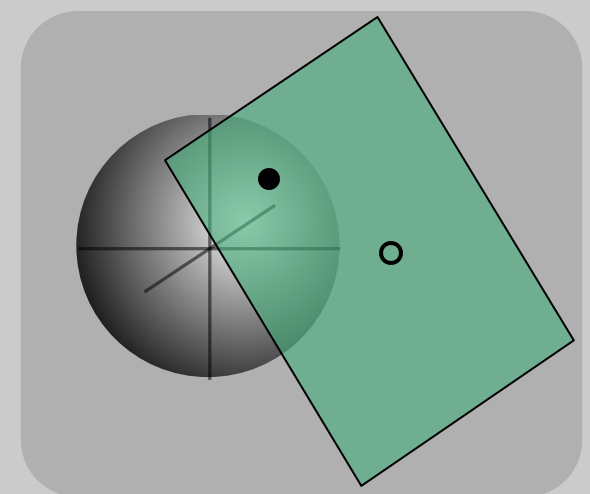
domain of sparse signals



minimum $\|x\|_1$



minimum $\|x\|_2$



$$\begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = y_1$$

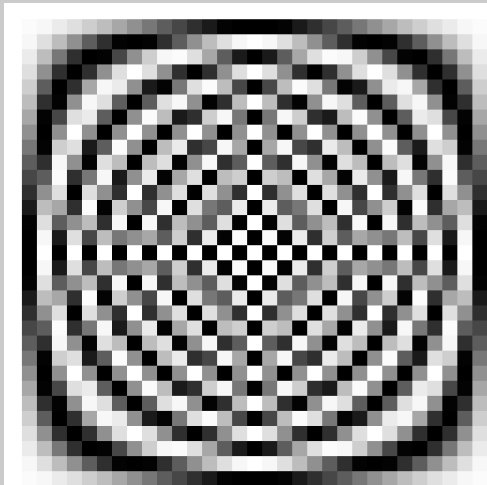
A non-linear sampling theorem

- $f \in C^N$ supported on a set Ω in Fourier
- Shannon:
 - Ω is known connected set, size B
 - Exact recovery from B equispaced time samples
 - Linear reconstruction by sinc interpolation
- Non-linear sampling theorem
 - Ω is an arbitrary, unknown set of size B
 - Exact recovery from $\sim B \log N$ (almost) arbitrary placed samples
 - Nonlinear reconstruction by convex programming

Practicality of CS

- Can such sensing system exist in practice?

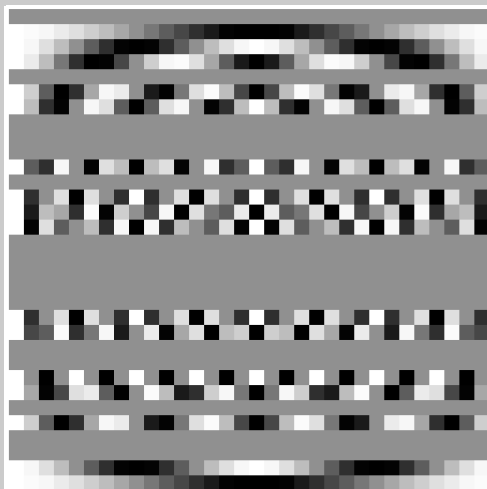
Fourier matrix



Practicality of CS

- Can such sensing system exist in practice?

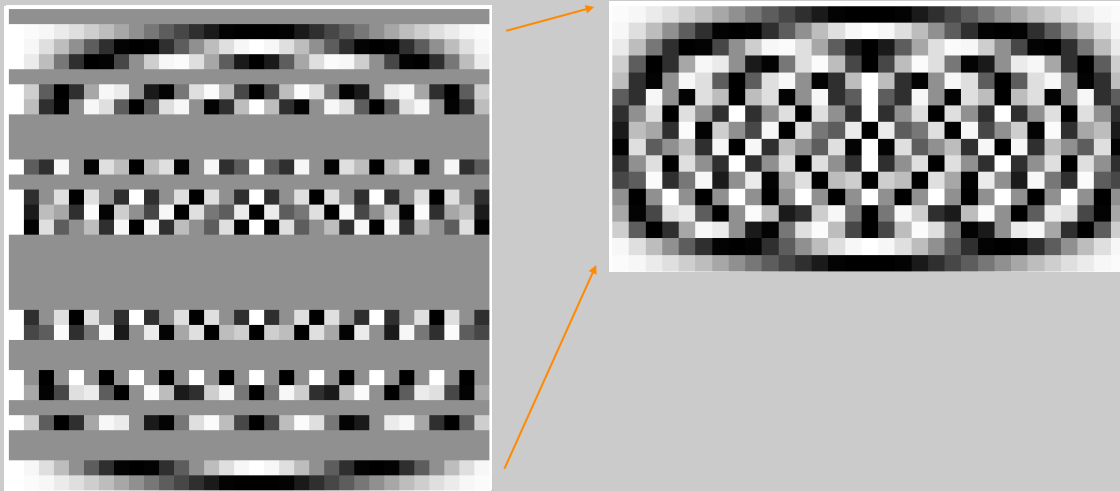
Fourier matrix



Practicality of CS

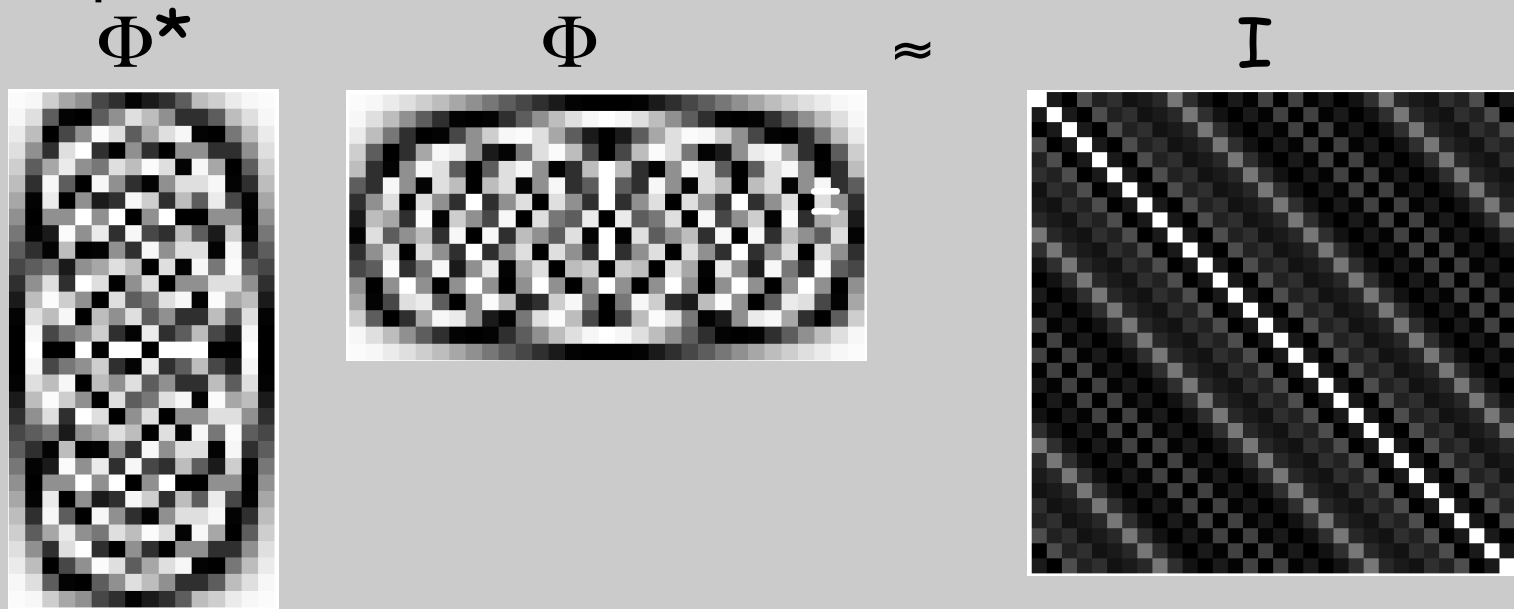
- Can such sensing system exist in practice?

Fourier matrix

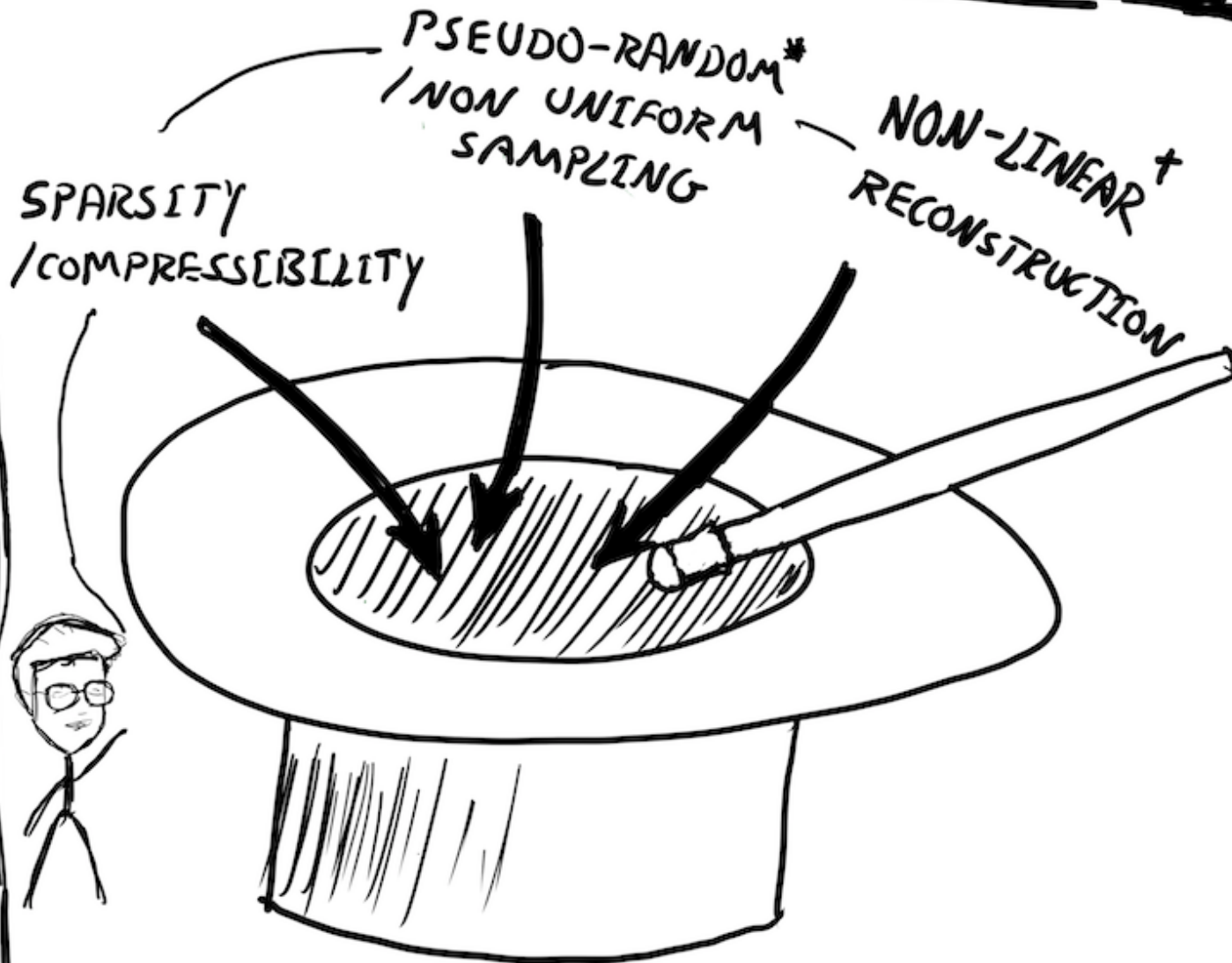


Practicality of CS

- Can such sensing system exist in practice?
- Randomly undersampled Fourier is incoherent
- MRI samples in the Fourier domain!

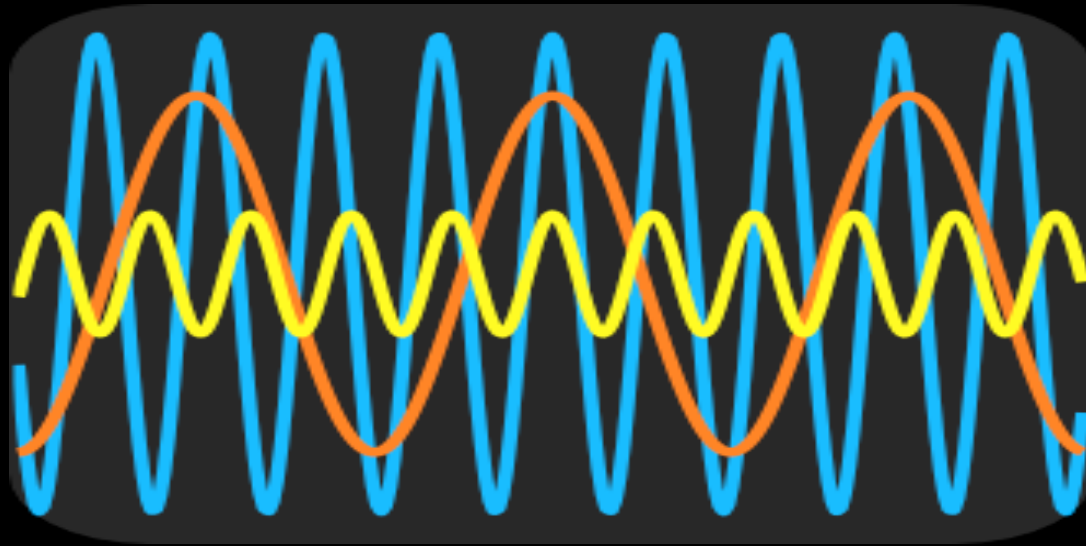
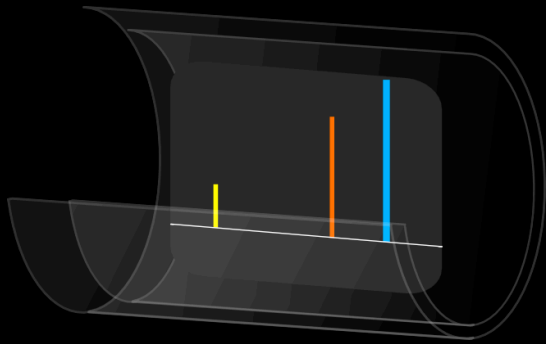


COMPRESSED SENSING RECIPE

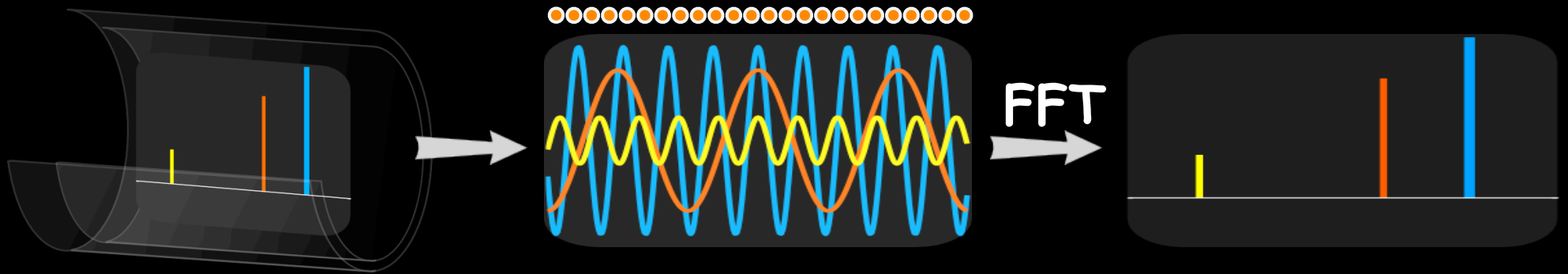


* VARIABLE DENSITY RANDOM, RADIAL, SPIRALS...
† SPARSITY ENFORCING RECONSTRUCTION,
SUCH AS: MINIMUM ℓ_1 -NORM

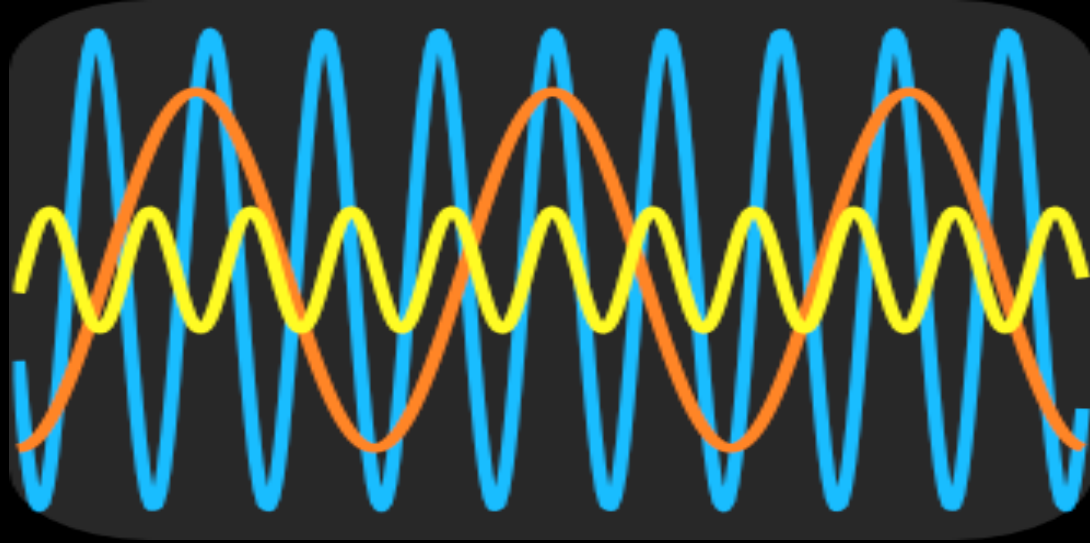
Intuitive example of CS



Intuitive example of CS



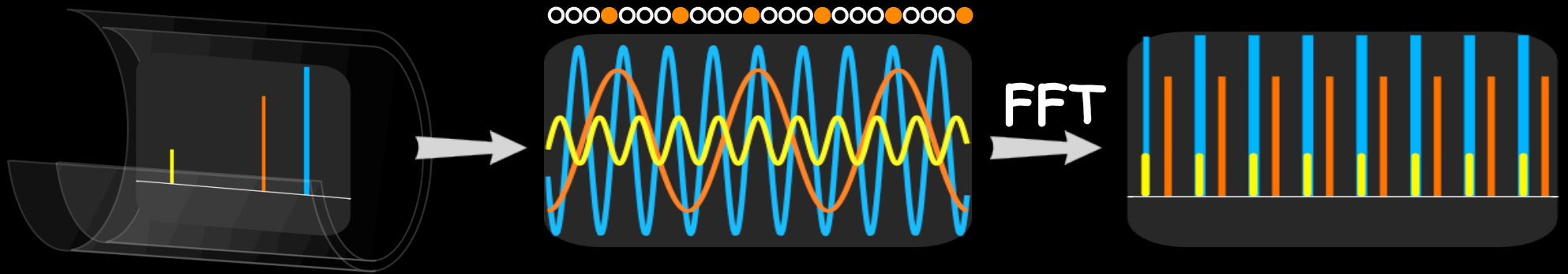
sampling →



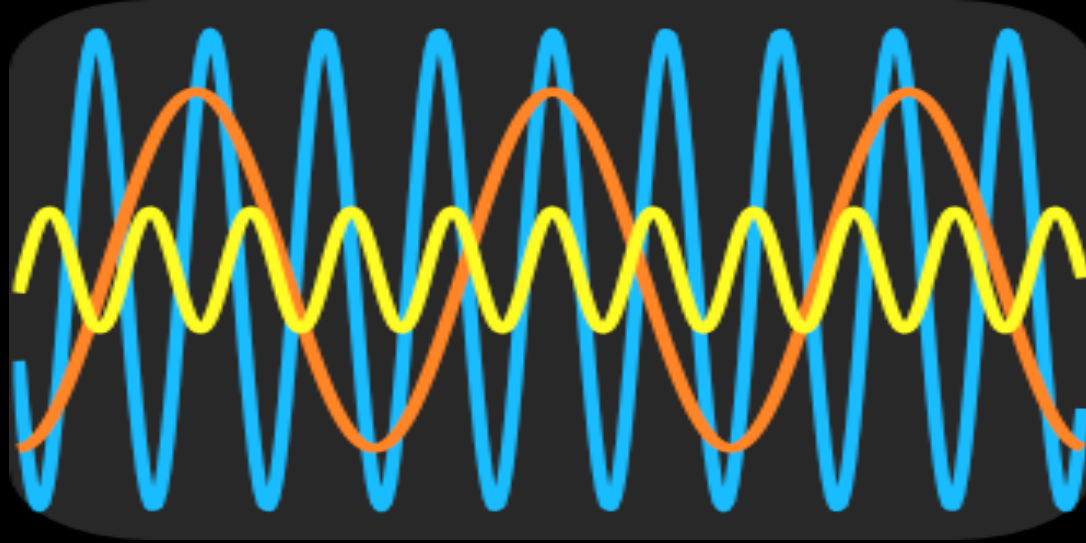
Nyquist



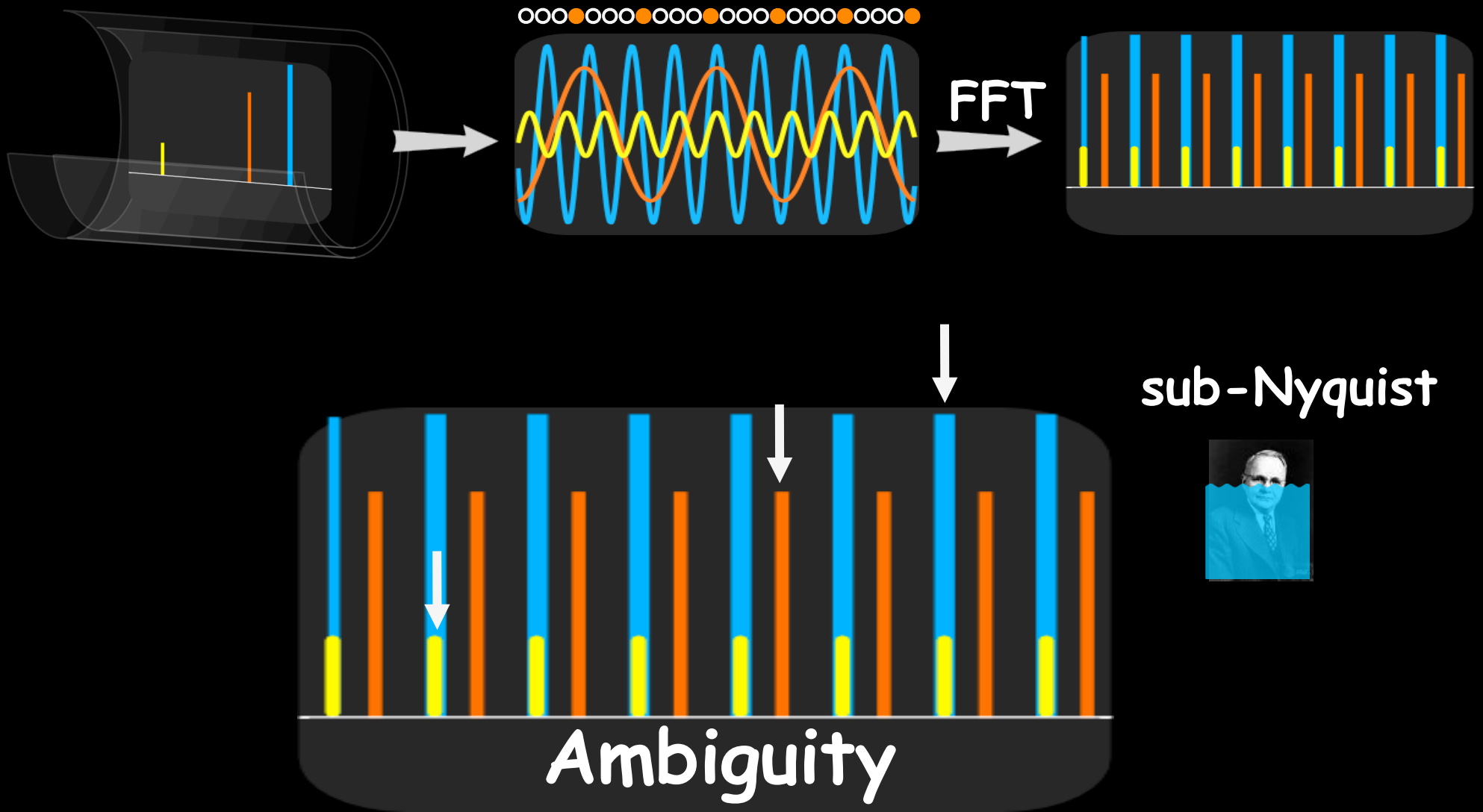
Intuitive example of CS



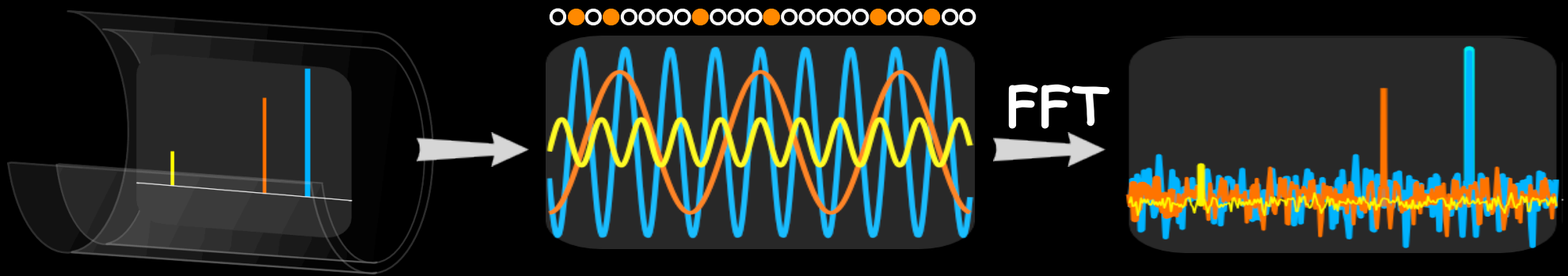
equispaced \longrightarrow  sub-Nyquist



Intuitive example of CS



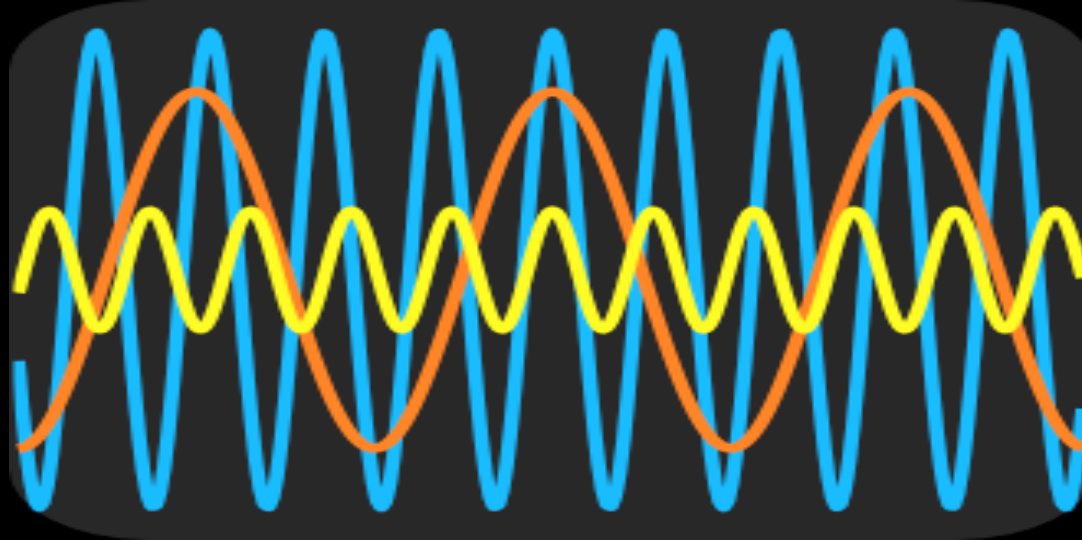
Intuitive example of CS



random



sub-Nyquist



RANDOM SUBSAMPLING

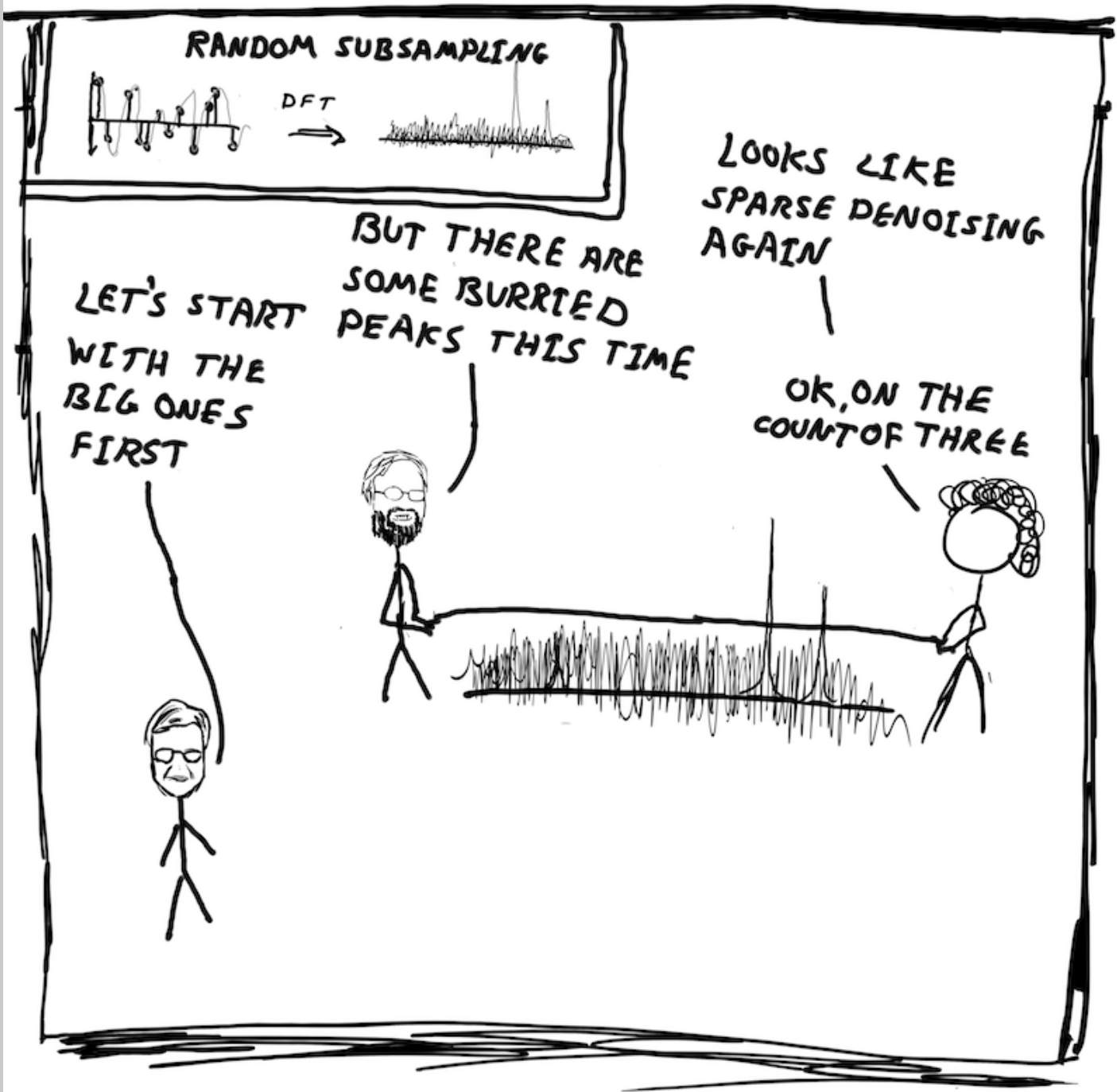


LOOKS LIKE
SPARSE DENOISING
AGAIN

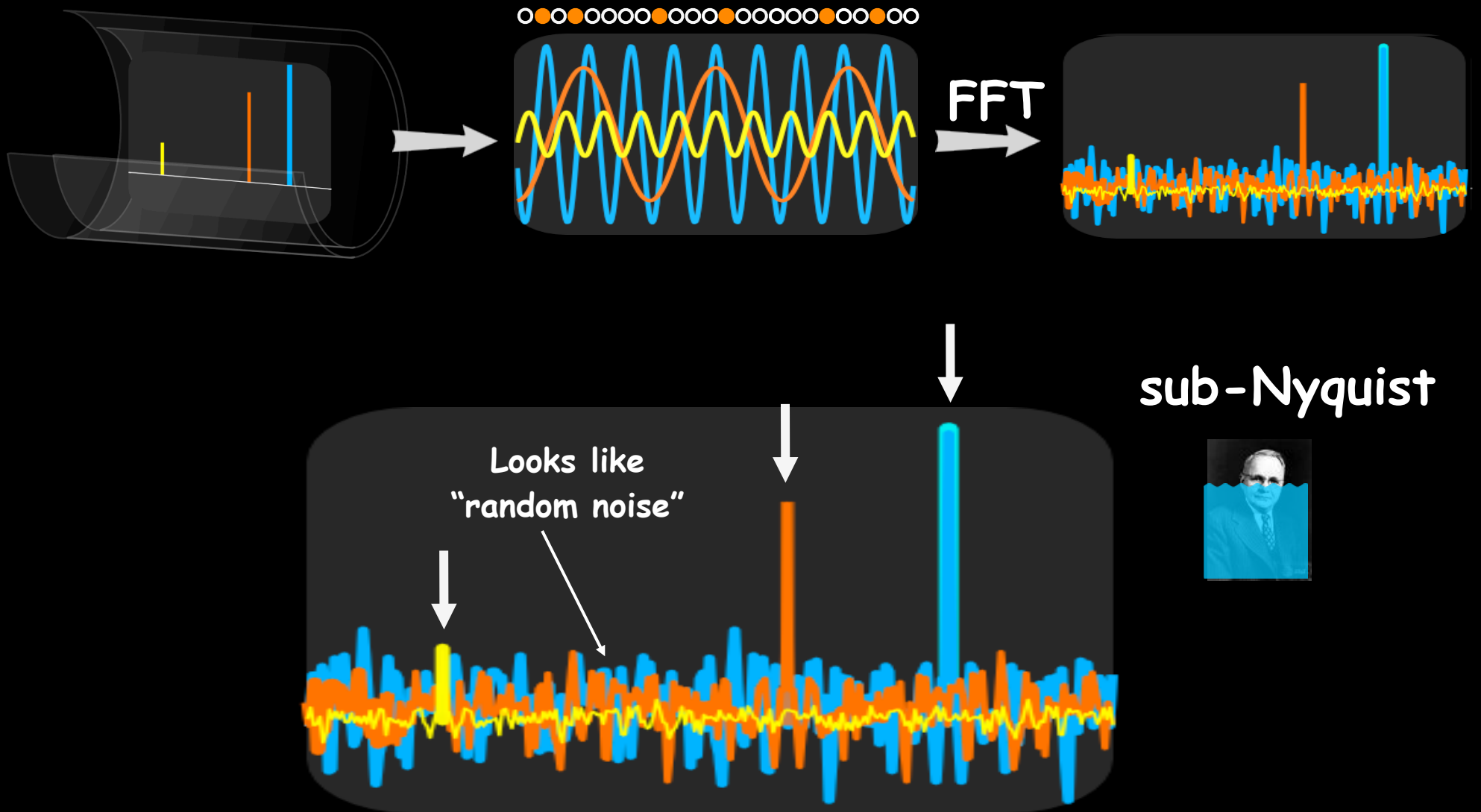
BUT THERE ARE
SOME BURRIED
PEAKS THIS TIME

LET'S START
WITH THE
BIG ONES
FIRST

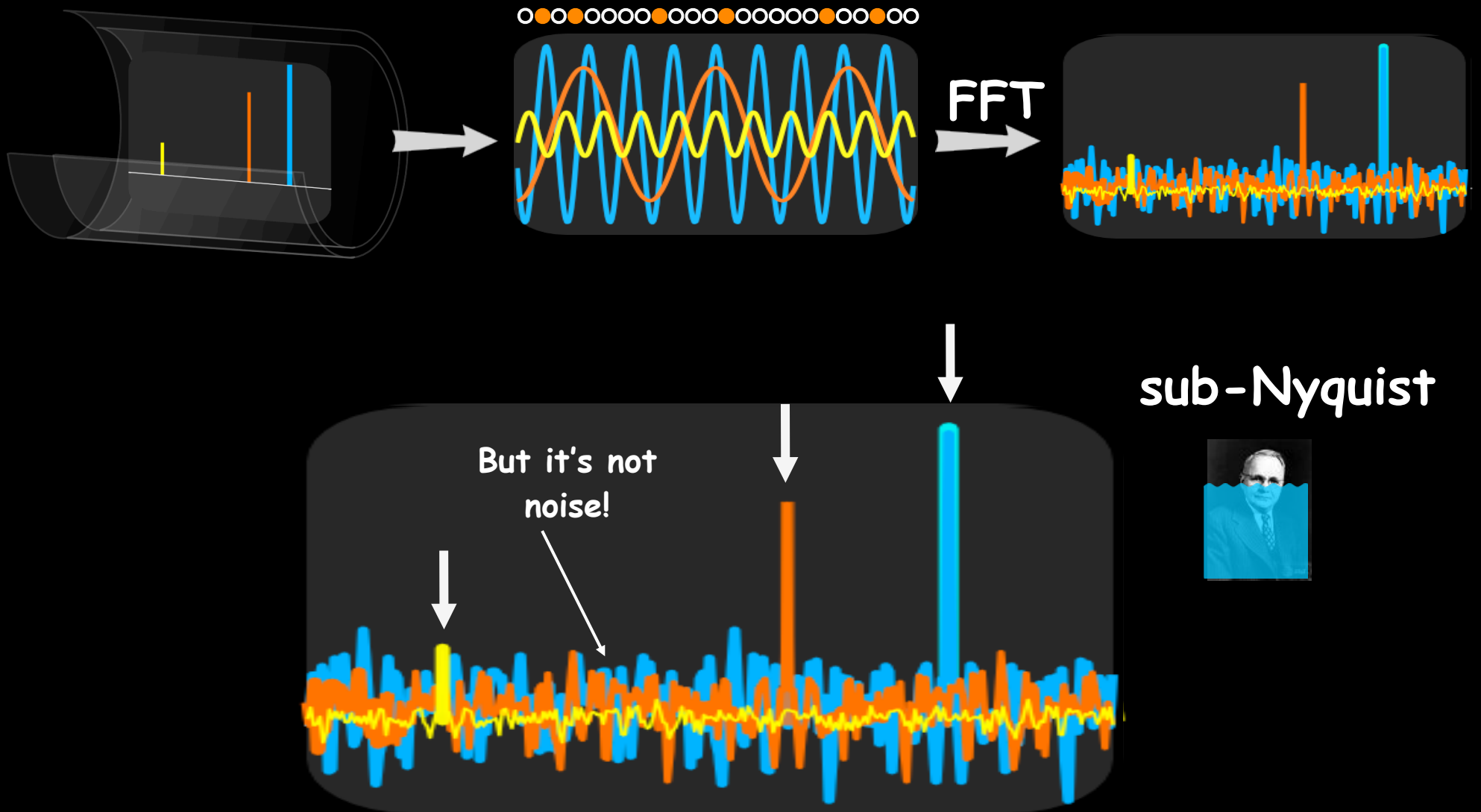
OK, ON THE
COUNT OF THREE



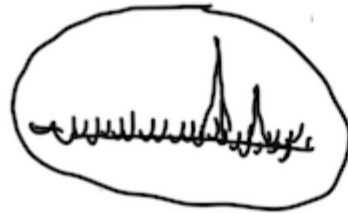
Intuitive example of CS



Intuitive example of CS



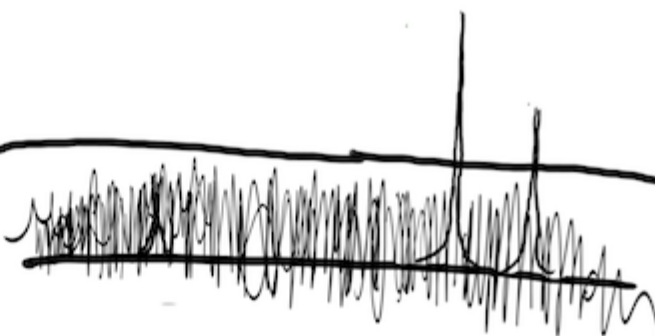
RANDOM SUBSAMPLING



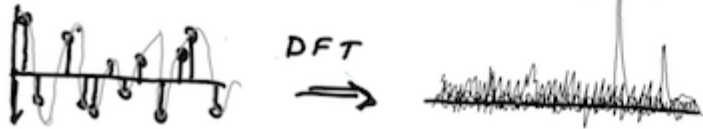
TWO

ONE

WE CAN
CALCULATE
THE INTERFERENCE
THEY CREATE AND
REMOVE IT



RANDOM SUBSAMPLING



INTERFERENCE
SHOULD BE LOWER
NOW

GOOD!
LET'S CLEAN
IT UP AND
PUT TOGETHER

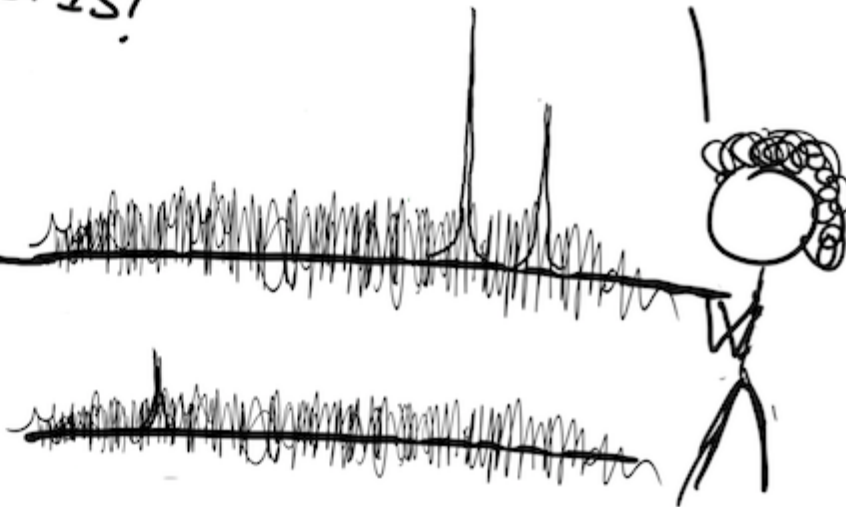


THERE IT IS!

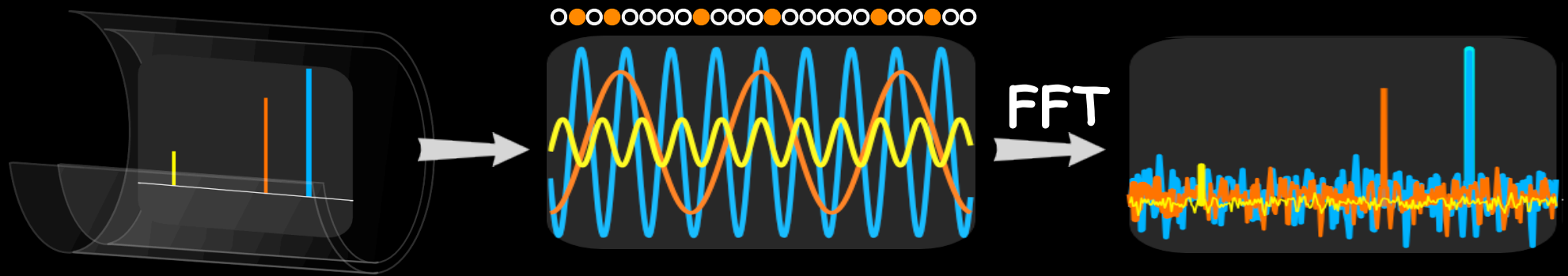


THREEÉ

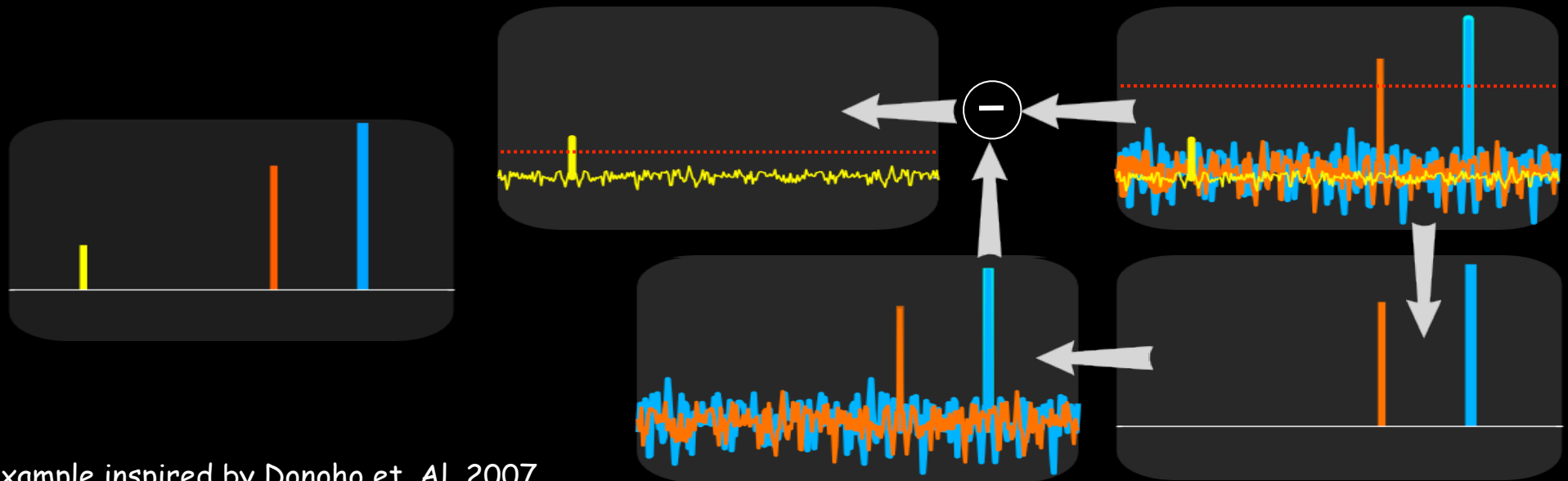
AH!



Intuitive example of CS

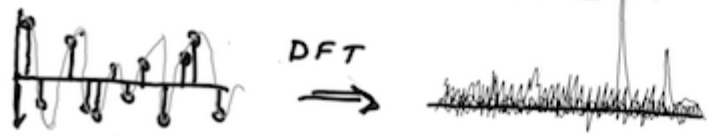


Recovery



Example inspired by Donoho et. Al, 2007

RANDOM SUBSAMPLING



CHEERS

D'NB



Question!

- What if this was the signal?
- Would CS still work?

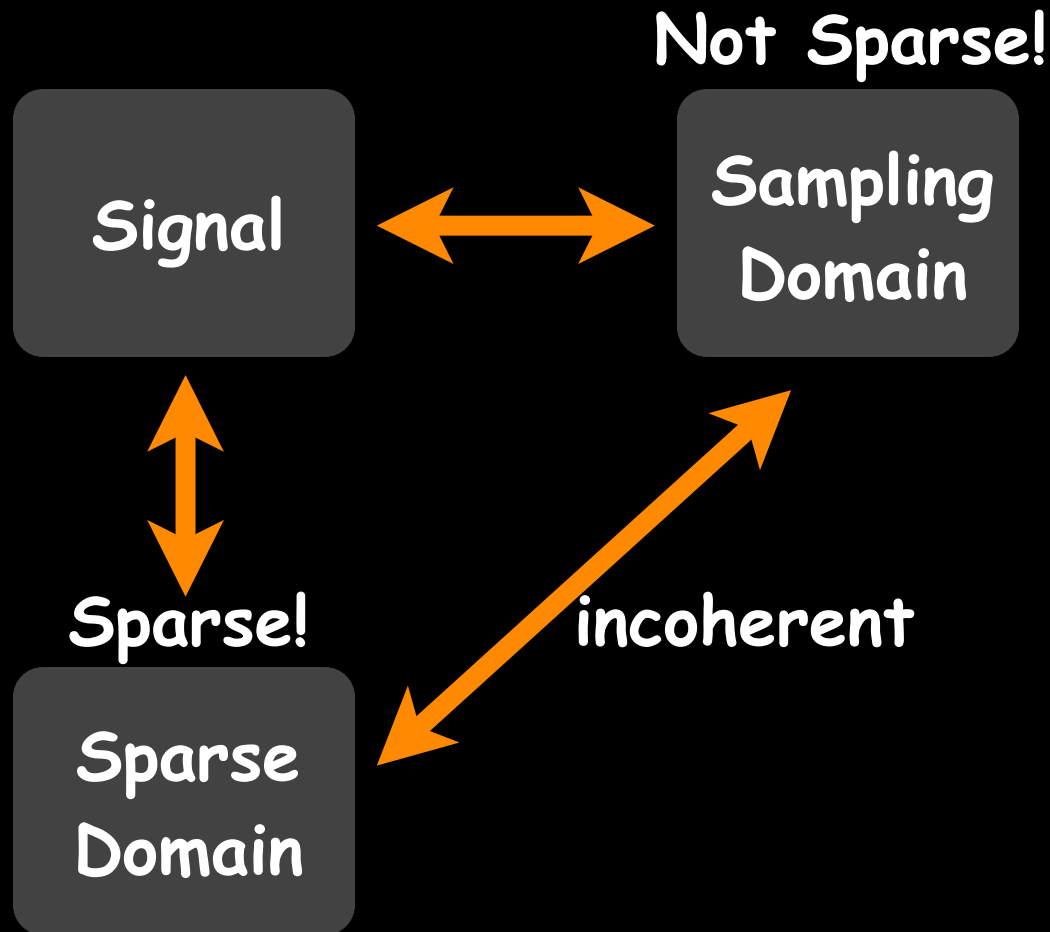
random →



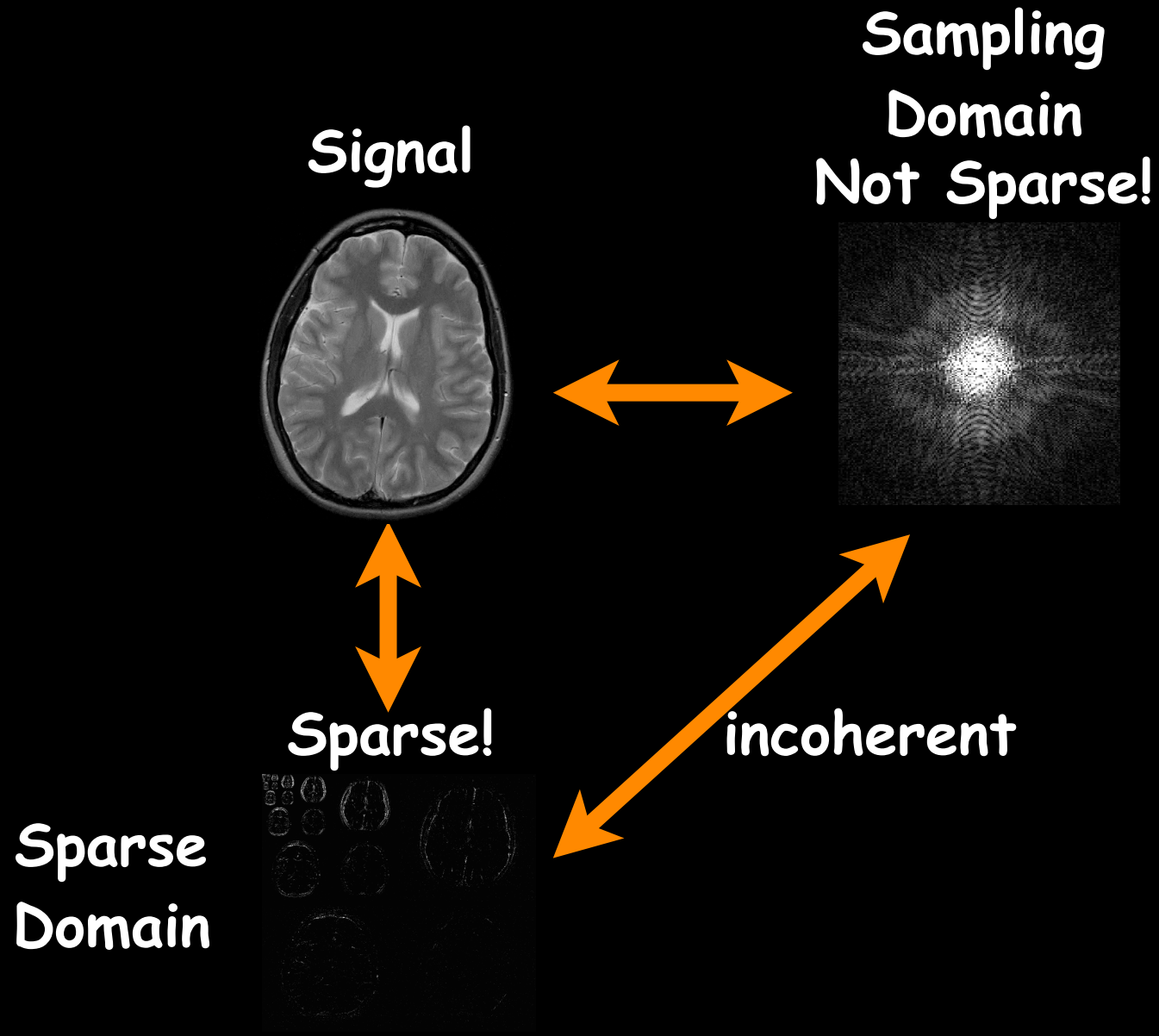
sub-Nyquist



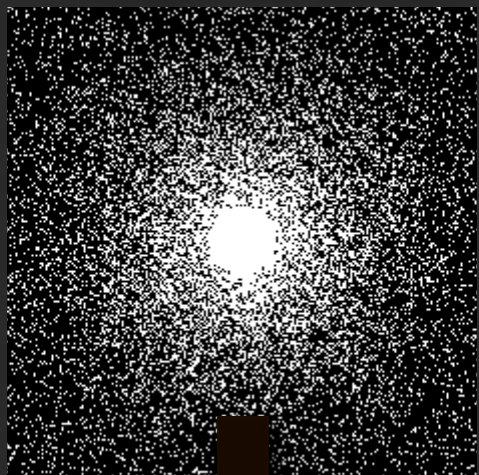
Domains in Compressed Sensing



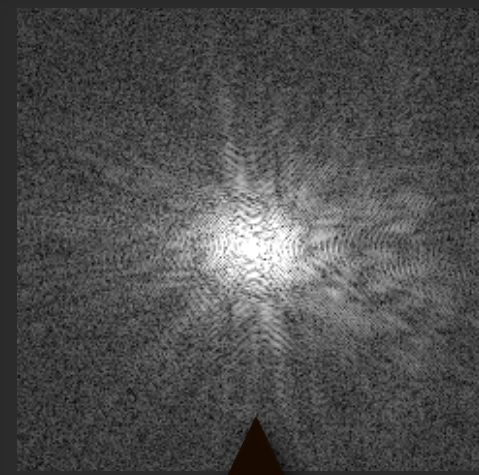
MRI



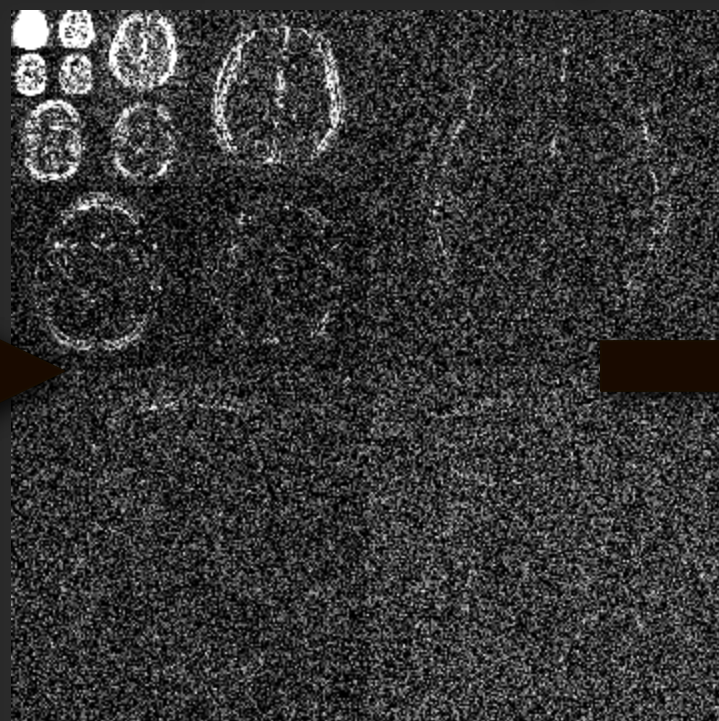
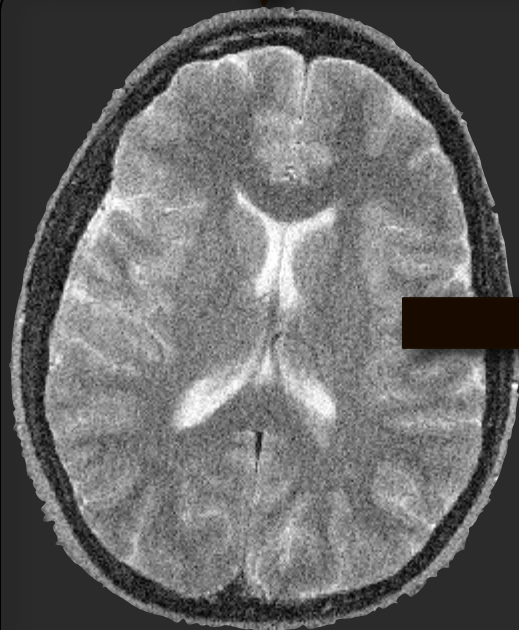
Acquired Data



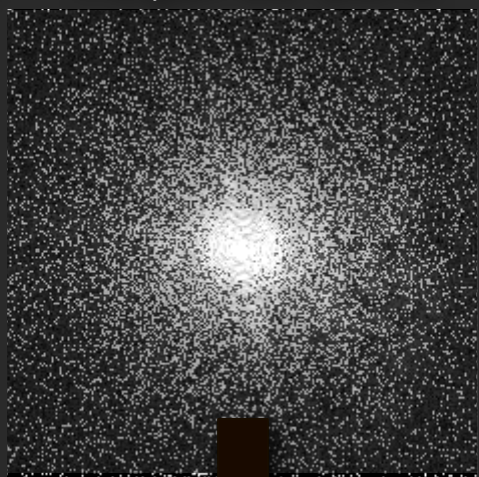
Compressed Sensing
Reconstruction



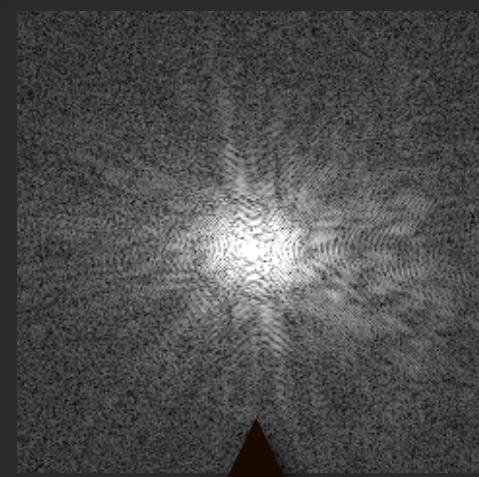
Sparse "denoising"



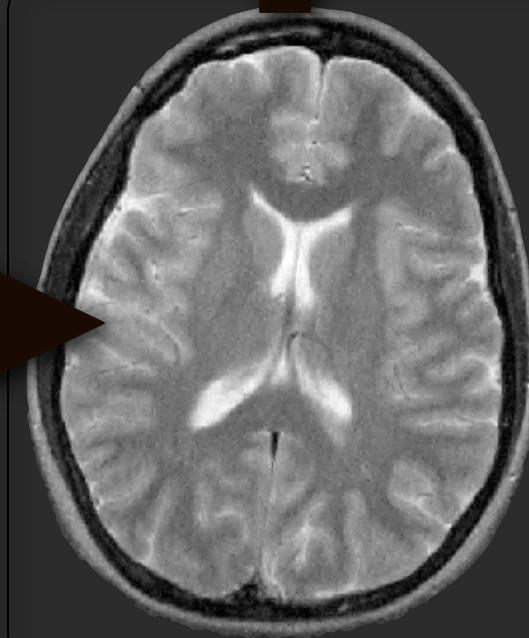
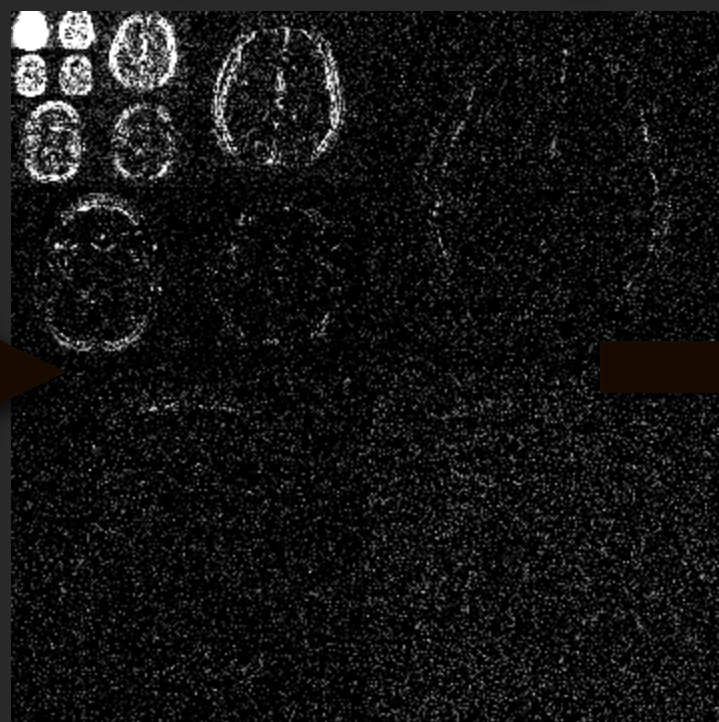
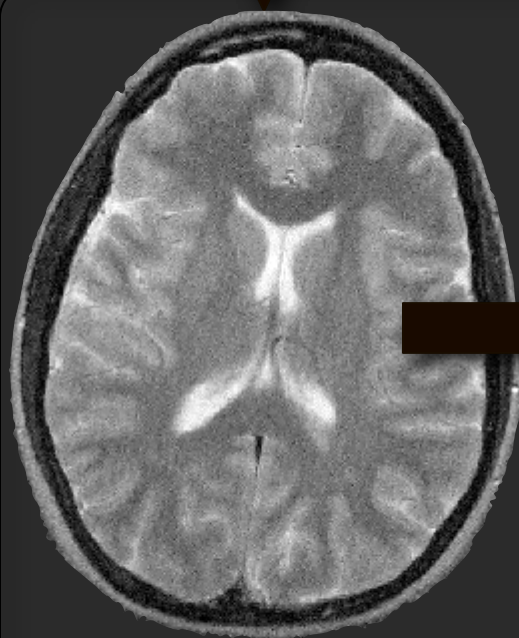
Acquired Data



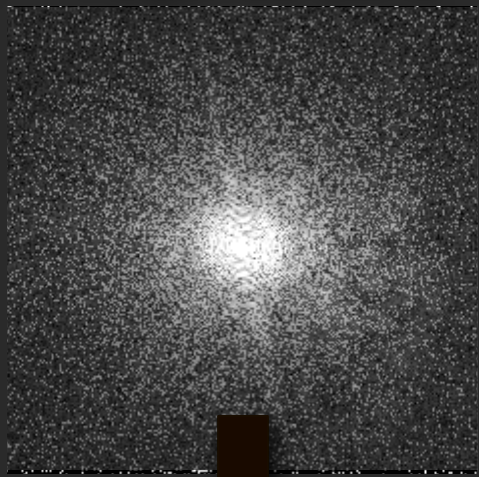
Compressed Sensing
Reconstruction



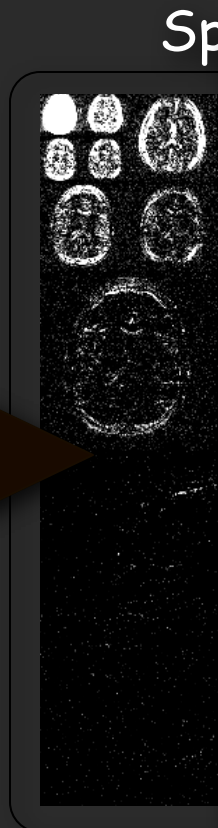
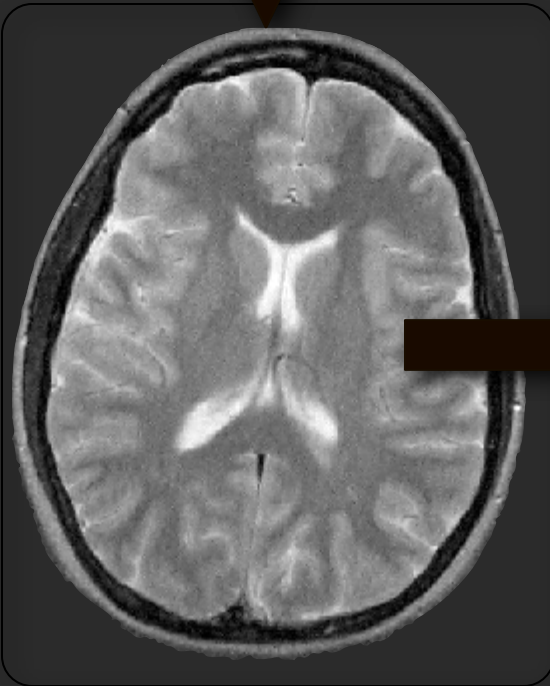
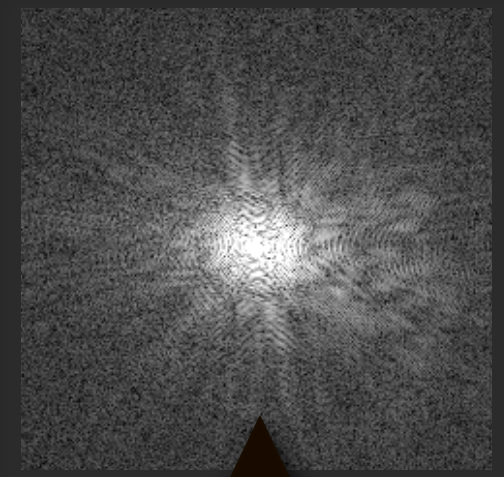
Sparse "denoising"



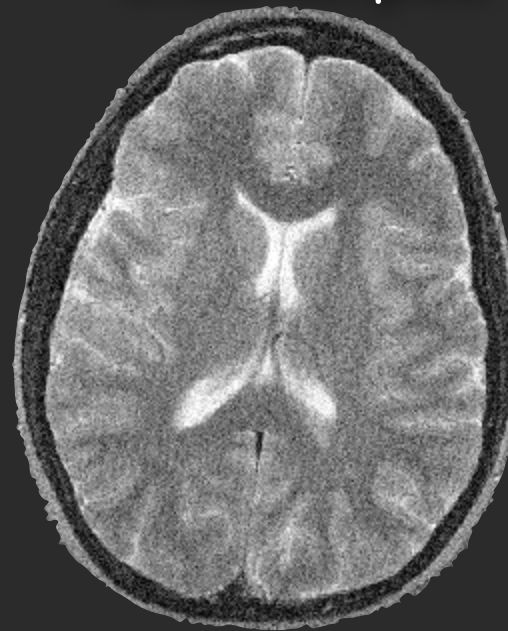
Acquired Data



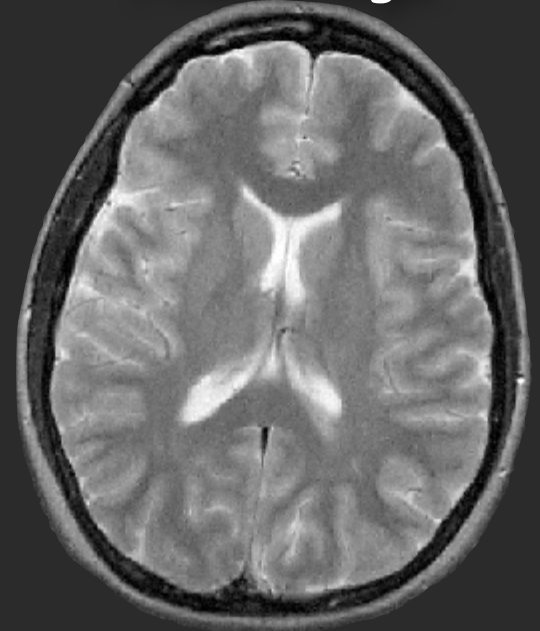
Compressed Sensing
Reconstruction



Undersampled



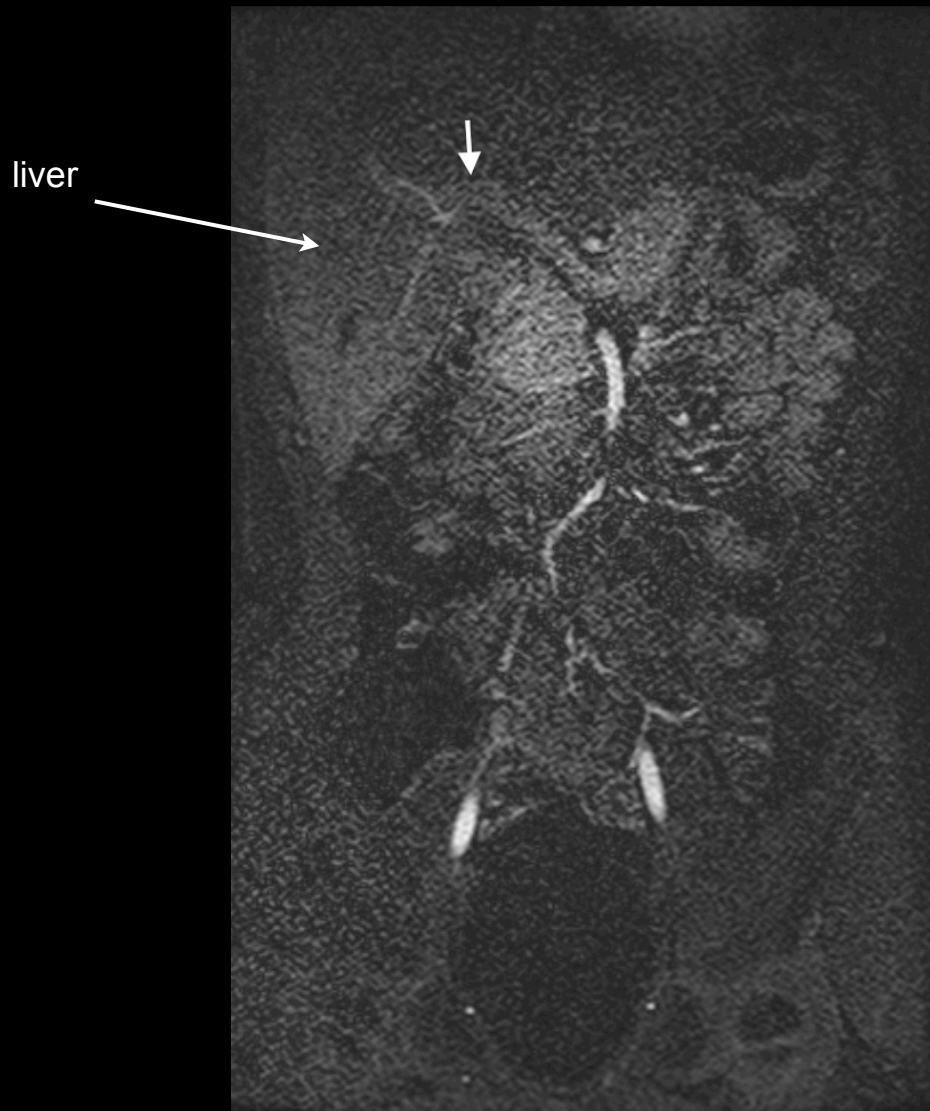
Final Image



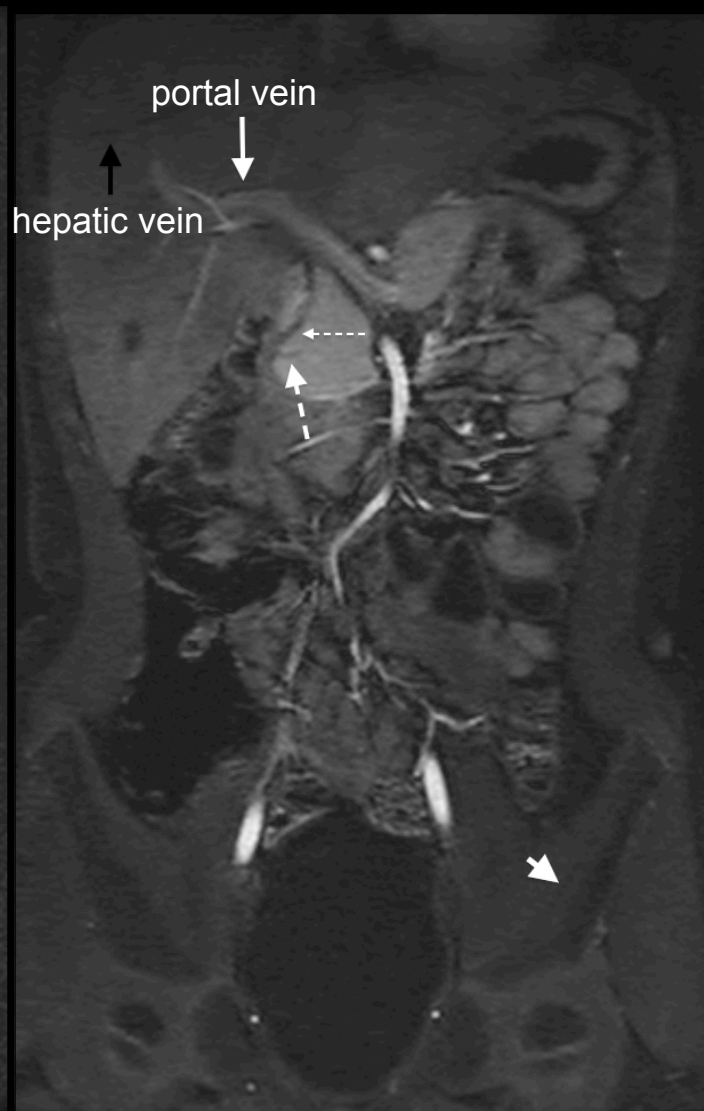
Tutorial & code available at <http://www.mlustig.com>

6 year old male abdomen. Fine structures (arrows) are buried in noise (artifactual + noise amplification) and are recovered by CS with L1-wavelets. x8 acceleration

Linear Reconstruction



Compressed sensing

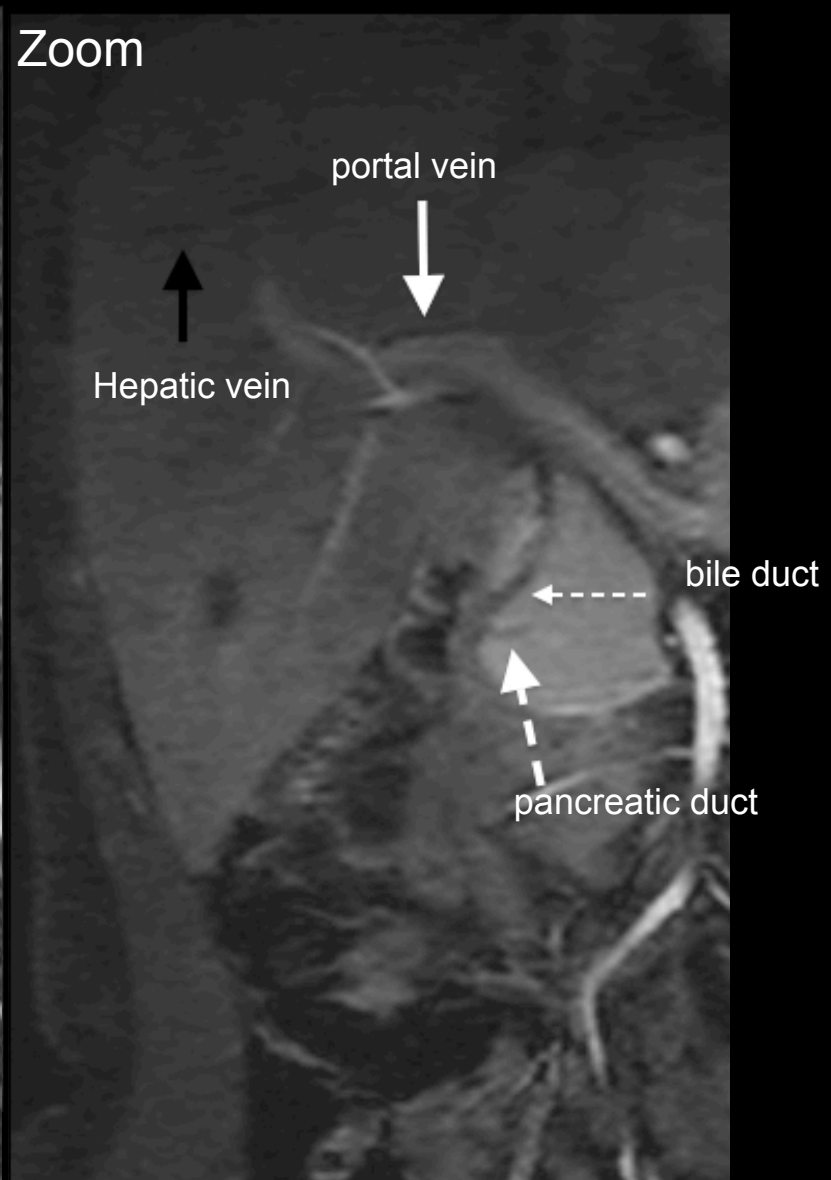


6 year old male abdomen. Fine structures (arrows) are buried in noise (artifactual + noise amplification) and are recovered by CS with L1-wavelets.

Linear Reconstruction

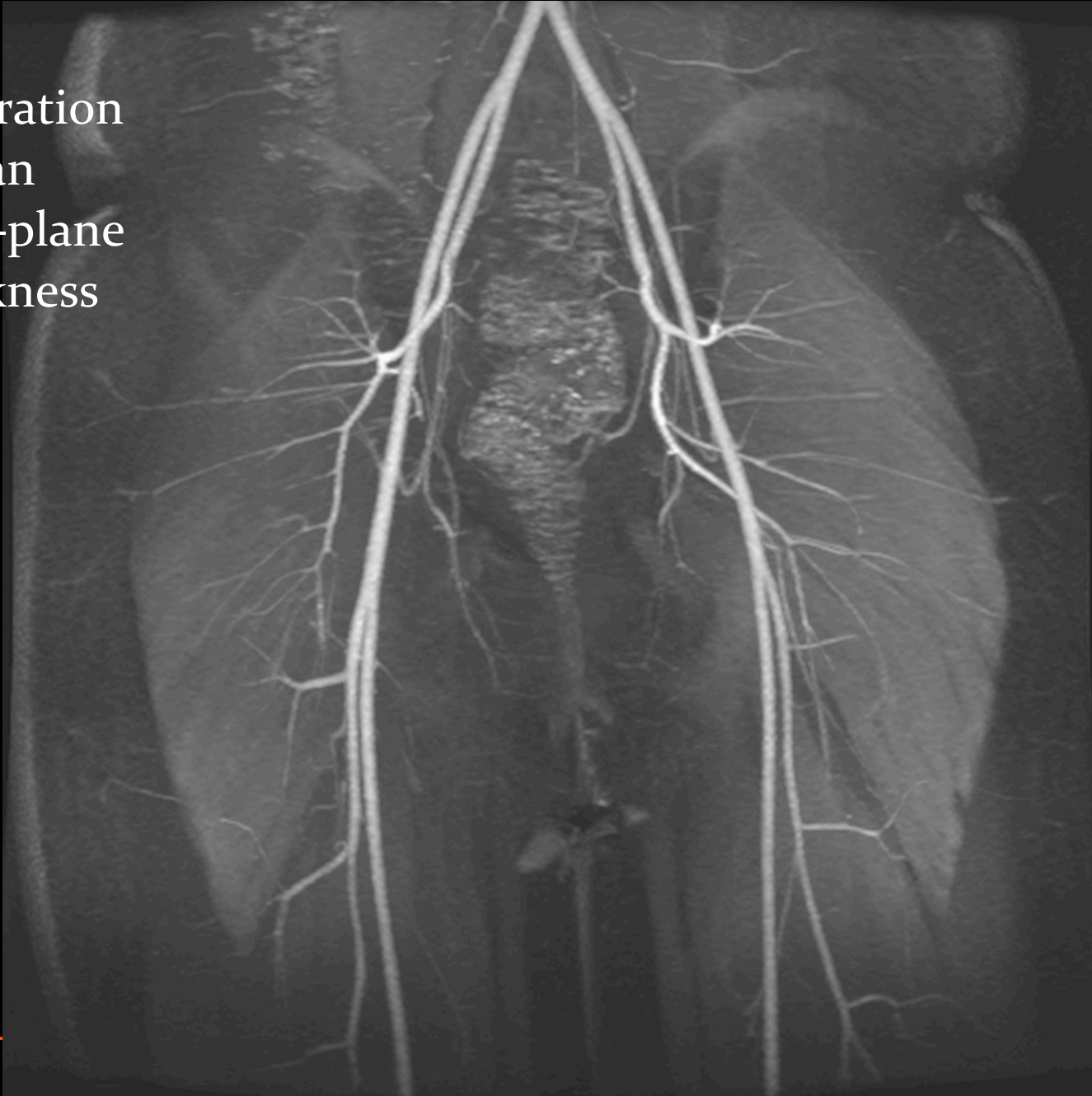


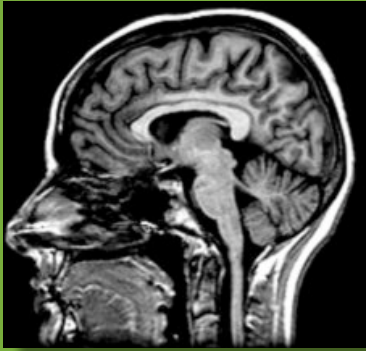
Compressed sensing



Back to Results

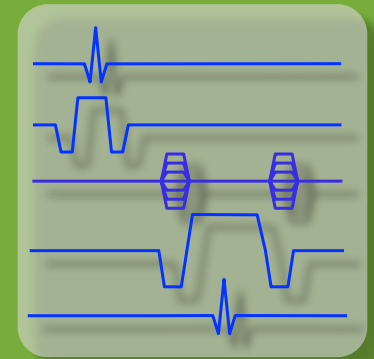
6 year old
8-fold acceleration
16 second scan
0.875 mm in-plane
1.6 slice thickness





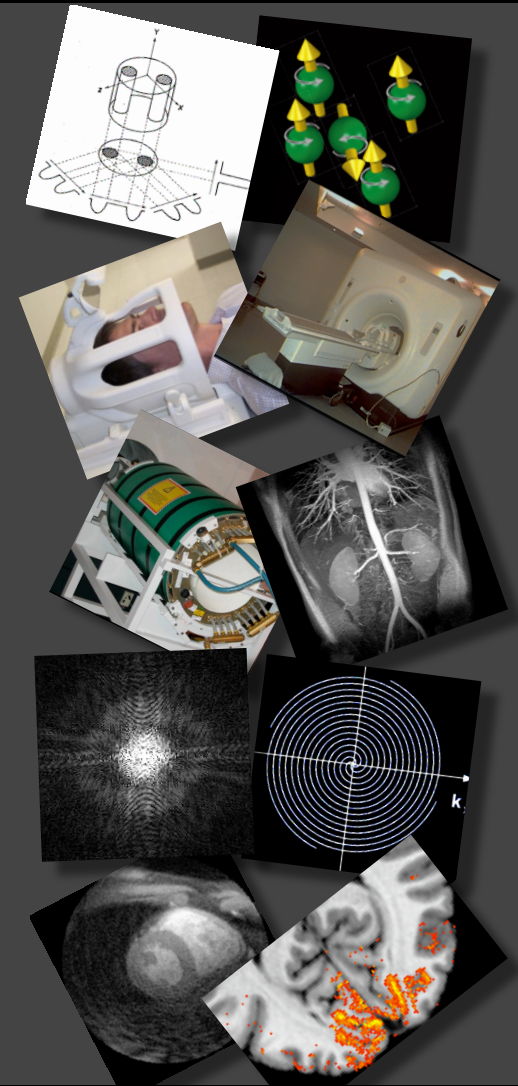
Principles of Magnetic Resonance Imaging

EE c225E / BIOE c265



Spring 2016

Shameless Promotion



Other Applications

- Compressive Imaging
 - Medical Imaging
 - Analog to information conversion
 - Biosensing
 - Geophysical Data Analysis
 - Compressive Radar
 - Astronomy
 - Communications
 - More
-

Resources

- CS + parallel imaging matlab code, examples
<http://www.eecs.berkeley.edu/~mlustig/software/>
- Rice University CS page: papers, tutorials, codes, ...
<http://www.dsp.ece.rice.edu/cs/>
- IEEE Signal Processing Magazine, special issue on compressive sampling 2008;25(2)
- March 2010 Issue Wired Magazine: "Filling the Blanks"
- Igor Caron Blog: <http://nuit-blanche.blogspot.com/>

Thank you!
תודה רבה