

1. Inverses

In general, an *inverse* of a matrix "undoes" the operation that that matrix performs. Mathematically, we write this as

$$A^{-1}A = I \tag{1}$$

where A^{-1} is the inverse of A . Intuitively, this means that applying a matrix to a vector and then subsequently applying its inverse is the same as leaving the vector untouched.

Properties of Inverses. For a matrix A , if its inverse exist, then:

$$A^{-1}A = AA^{-1} = I \tag{2}$$

$$(A^{-1})^{-1} = A \tag{3}$$

$$(kA)^{-1} = k^{-1}A^{-1} \quad \text{for a nonzero scalar } k \tag{4}$$

$$(A^T)^{-1} = (A^{-1})^T \tag{5}$$

$$(AB)^{-1} = B^{-1}A^{-1} \quad \text{assuming } A, B \text{ are both invertible} \tag{6}$$

(a) Prove that $(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$

(b) Now consider the three matrices.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \quad D = \begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ \frac{2}{5} & \frac{4}{5} \end{bmatrix}$$

- i. What do each of these matrices do when you multiply them by a vector \vec{x} ? Draw a picture.
- ii. Intuitively, can these operations be undone? Why or why not? Make an intuitive argument.
- iii. Are the matrices A, B, C, D invertible?
- iv. Can you find anything in common about the rows (and columns) of A, B, C, D ? (Bonus: How does this relate to the invertibility of A, B, C, D ?)
- v. Are all square matrices invertible?
- vi. How can you find the inverse of a general $n \times n$ matrix?

Reference Definitions

Vector spaces: A vector space V is a set of elements that is closed under vector addition and scalar multiplication. For V to be a vector space, the following conditions must hold for every $\vec{u}, \vec{v}, \vec{z} \in V$ and for every $c, d \in \mathbb{R}$

No escape property (addition) $\vec{u} + \vec{v} \in V$,

No escape property (scalar multiplication) $c\vec{u} \in V$,

Commutativity $\vec{u} + \vec{v} = \vec{v} + \vec{u}$,

Associativity of vector addition $(\vec{u} + \vec{v}) + \vec{z} = \vec{u} + (\vec{v} + \vec{z})$,

Additive identity There is $\vec{0} \in V$ such that for all \vec{u} , $\vec{0} + \vec{u} = \vec{u} + \vec{0} = \vec{u}$,

Existence of inverse For every \vec{u} , there is element $-\vec{u}$ such that $\vec{u} + (-\vec{u}) = 0$,

Associativity of scalar multiplication $c(d(\vec{u})) = (cd)\vec{u}$,

Distributivity of scalar sums $(c + d)\vec{u} = c\vec{u} + d\vec{u}$,

Distributivity of vector sums $c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$,

Scalar multiplication identity There is $1\vec{u} = \vec{u}$.

The most important of the above properties are the *no escape properties*. These demonstrate that the vector space is closed under addition and scalar multiplication. That is, if you add two vectors in V , your resulting vector will still be in V . If you multiply a vector in V by a scalar, your resulting vector will still be in V .

Subspaces: A subset W of a *vector space* V is a *subspace* of V if the following two conditions hold for any two vectors $\vec{u}, \vec{v} \in W$, and any scalar $c \in \mathbb{R}$:

No escape property (addition) $\vec{u} + \vec{v} \in W$

No escape property (scalar multiplication) $c\vec{u} \in W$

Note that these are the only properties we need to establish to show that a subset of a vector space is a subspace! The other properties of the underlying vector space come for free, so to speak.

The vector spaces we will work with most commonly are \mathbb{R}^n and \mathbb{C}^n , as well as their subspaces.

Basis: A *basis* for a vector space is a *set of linearly independent vectors that spans the vector space*.

So, if we want to check whether a set of vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ forms a basis for a vector space V , we check for two important properties:

(a) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ are linearly independent.

(b) $\text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k) = V$

As we move along, we'll learn how to identify and/or construct a basis, and we'll also learn some interesting properties of bases.

2. Identifying a subspace: Proof exercise!

Is the set

$$V = \left\{ \vec{v} : c \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + d \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \text{ where } c, d \in \mathbb{R} \right\}$$

a subspace of \mathbb{R}^3 ? Why/why not?

3. Identifying a basis

Does each of these sets describe a basis of some vector space?

$$V_1 = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\} \quad V_2 = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\} \quad V_3 = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

4. Exploring dimensionality, linear independence and bases

In this problem, we are going to talk about the connections between several concepts we have learned about in linear algebra – linear independence, dimensionality of a vector space/subspace, and basis.

Let's consider the vector space \mathbb{R}^m , and a set of n vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ in \mathbb{R}^m .

- For the first part of the problem, let $m > n$. Can $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ form a basis of \mathbb{R}^m ? Why/why not? What conditions would we need?
- Let $m = n$. Can $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ form a basis of \mathbb{R}^m ? Why/why not? What conditions would we need?
- Now, let $m < n$. Can $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ form a basis of \mathbb{R}^m ? What vector space could they form a basis for? (Hint: think about whether the vectors can now be linearly independent.)

5. Constructing a basis

Let's consider a subspace of \mathbb{R}^3 , V , that has the following property: for every vector in V , the first entry is equal to two times the sum of the second and third entries. That is, if $\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \in V$, we have $a_1 = 2(a_2 + a_3)$.

Find a basis for V . What is the dimension of V ?