Electrical Engineering and Computer Sciences

EECS 16A

#### **Head TAs**

• Email: <u>head-ta-ee16a@berkeley.edu</u>

Email Harrison with:

- Questions not for piazza
- Conflicts
- Emergencies

#### Introduce TAs

• Many are returning 16A staff members

## Introduce Faculty

• Babak Ayazifar

<u>ayazifar@eecs.berkeley.edu</u> 517 Cory

- No surprise visits, please!
  - For one-on-one matters,
    - make appointment by e-mail;
    - provide your availability; and
    - we'll pick a mutually-convenient slot to meet.

# Introduce Faculty

- Vladimir Stojanović <u>vlada@eecs.berkeley.edu</u> 513 Cory
- Story...
- Other contributors to 16 (besides Babak/Vladimir):
  - Elad Alon, Anant Sahai, Ali Niknejad, Claire Tomlin, Gireeja Ranade, Michel Maharbiz, Laura Waller, Miki Lustig, Vivek Subramanian, Thomas Courtade

#### And we have even more!

An army of Academic Interns...
– Former 16A students just like you ...

- The path to being on 16A staff
  - Do great in 16A
  - Become a lab assistant, reader/tutor

#### Important Web Sites

• EECS 16A

http://inst.eecs.berkeley.edu/~ee16a/sp17/

• Piazza

http://piazza.com/

#### **Content Introduction**



 All of these extract information from the real world and interact with it; we will be learning how to design and understand these devices & systems!

#### 16A: Information Devices and Systems

#### Imaging/Tomography and Google PageRank (~5 wks)

- Topics: Linear algebraic thinking and graphs
- Lab: Single-pixel imager
- Touchscreens (5 wks)
  - Topics: Linear circuits and design
  - Lab: Home-made R and C touchscreens
- Locationing and Least-Squares (4 wks)
  - Topics: Linear-algebraic optimization
  - Lab: Acoustic localization "GPS"

### Some detailed topics for 16A

- Vectors and vector spaces
- Inner products, projection, orthogonality
- Matrices and linear transformations
- Rank and solving systems of linear equations
- Graphs, flows, and matrices
- How to do design and synthesis
- KCL, KVL, Ohm's Law

- Equivalence, modeling, and abstraction
- Capacitance and charge
- Gain and feedback
- Correlation and interference
- Linear regression and optimization
- Determinants, eigenvalues and eigenvectors
- Diagonalization

#### EECS Upper Divs: What 16AB feed

<b>16AB</b>	Modeling and Algorithms	170, 126, 188,	<b>189, 120,</b> 121, 123, 174, 144,	Specific Domains	
<del>20</del> 70				121, 122, 168 Comm+Net	176, 145B CompBio, Imaging
61B		12/	172	191 Quantum	128, <mark>106</mark> , 192 Control + Robotics
61A	General Software	162, 161,	160 <i>, 168,</i> 149	184 Graphics	186 Databases
61C	Soltware	169		164 Compilers	152 Computers
		105, 140,	130, 143, 145L	145MO Bio	147 MEMS
<del>40</del>	General Hardware 140, 151			117 Antennas	142 Comm ICs
16AB		151		118 Optics	113, 137AB, 134 Power+SolarEnergy

#### How Did We Get From This...













#### Moore's Law

#### Microprocessor Transistor Counts 1971-2011 & Moore's Law



Gordon Moore Intel Cofounder

B.S. Cal 1950!



Date of introduction



Source: Mark Bohr, IDF14

#### That's Just One Piece of the Puzzle...





1940's

#### Where This is Used:



Advanced Metering

Market Support

#### Whom We're Training You to Be



#### An example system: iPad Air 2



- Runs apps, but:
  - How is it charged / discharged?
  - What makes the display tick?
  - How does the Wi-Fi work?
  - How does it sense touch on the touch screen?
  - How does it sense motion?
  - How do the "brains" operate?

... and how can I learn stuff, so I can work on such cool technology?

#### Inside an iPad Air 2



#### The Camera

Goal: Convert light into electrical signals









# Get color spatial distribution by using an array of "light" detectors, each under a color filter

#### Cameras: "Mathematical" Guts



#### Medical Imaging ca. 1895



Need to find a way to see inside without "light"

#### Medical Imaging Today



All of these were enabled/dramatically advanced by the mathematical and hardware design techniques you will learn in this class!





#### Imaging In General



#### **Imaging System**

(electronics, control, computing, algorithms, visualization, ...)

## Simplest Imaging System

 What is the absolute smallest number of components you need to make an imaging system?

#### Simple Imager Example

#### Simple Imager Example

# Imaging Lab #1



#### Your Setup



#### An Imager with Just One Sensor?

- After all, today's cameras have millions of pixels...
- Great teaching vehicle: you can actually get a lot out of surprisingly simple designs
  - Once you know the right techniques!
- In some systems the sources and/or detectors might actually be expensive
  - Take this opportunity to learn a little more about how detectors usually work
  - And how we get them to "talk" to our electronic systems

#### More Complex Imaging Scenario

- What if we can't shine light (i.e., focus energy) either uniformly on all spots or in just one spot?
- The signal we receive on our detector will be a **linear combination** of several features of the image from different points.
- Can we recover the original image?
  - In many cases, yes!
  - Will start to see how next...