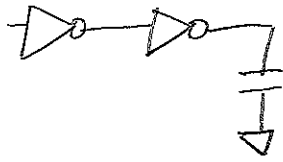


EE16B Section 6B

Warmup



$$t_{A \rightarrow B} = (10k)(1f + 2f) \ln 2 = 90.7 \text{ ps}$$

$$t_{B \rightarrow C} = (10k)(50f) \ln 2 = 345 \text{ ps}$$

$$t_{A \rightarrow C} = 366 \text{ ps}$$

$$C_{\text{tot}} = 56 \text{ fF}$$

$$\alpha = 0.5$$

$$P = \alpha C_{\text{tot}} V_{\text{DD}}^2 f$$

$$= 0.5 \cdot 56 \text{ fF} \cdot (1V)^2 \cdot 2.6 \text{ GHz}$$

$$= 5.6 \mu\text{W}$$

If inverter 2 is upsized:

$$t_{A \rightarrow B} = (10k)(12f) \ln 2 = 82.8 \text{ ps}$$

$$t_{B \rightarrow C} = (2.5k)(50f) \ln 2 = 86.3 \text{ ps}$$

$$t_{A \rightarrow C} = 169.1 \text{ ps}$$

$$C_{\text{tot}} = 65$$

$$P = 6.5 \mu\text{W}$$

50% less delay, 90% more power...

Feedback Debrief

Questions from Lecture

Sampling, continued

Highlights from lecture:

- $x_d(n) = x_c(nT_s)$ (This is how to sample a CT signal.)

- If $x_c(t) = e^{i\omega t}$, then $x_d(t) = e^{i\omega T_s n}$;

if $\hat{x}_c(t) = e^{i(\omega + k\omega_s)t}$, then $\hat{x}_d(t) = e^{i\omega T_s n}$; the signals are indistinguishable!

• If $x_{c1}(t) = \cos\left(\left(\frac{\omega_s}{2} + \Delta\omega\right)t\right)$ and $x_{c2}(t) = \cos\left[\left(\frac{\omega_s}{2} - \Delta\omega\right)t\right]$, then $x_{d1}(n) = x_{d2}(n)$!

Does the same hold for sine?

Define:

$$x_{c3}(t) = \sin\left[\left(\frac{\omega_s}{2} + \frac{\omega_s}{4}\right)t\right] = \sin\left(\frac{3\omega_s}{4}t\right) \quad x_{c4} = \sin\left[\left(\frac{\omega_s}{2} - \frac{\omega_s}{4}\right)t\right] = \sin\left(\frac{\omega_s}{4}t\right)$$

Then:

$$x_{d3}(n) = \sin\left(\frac{3\omega_s}{4} n T_s\right) = \sin\left(\frac{3n}{4} \omega_s \left(\frac{2\pi}{\omega_s}\right)\right) = \sin\left(\frac{3\pi}{2} n\right) = \sin\left(-\frac{\pi}{2} n\right) = -\sin\left(\frac{\pi}{2} n\right)$$

$$x_{d4}(n) = \sin\left(\frac{\omega_s}{4} n T_s\right) = \sin\left(\frac{\pi}{2} n\right)$$

So in general,

If $x_{c3}(t) = \sin\left[\left(\frac{\omega_s}{2} + \Delta\omega\right)t\right]$ and $x_{c4} = \sin\left[\left(\frac{\omega_s}{2} - \Delta\omega\right)t\right]$, then $x_{d3}(n) = -x_{d4}(n)$.