

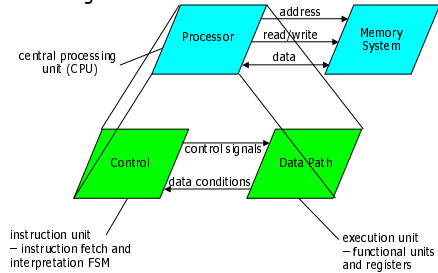
Computer Organization

- Computer design as an application of digital logic design procedures
- Computer = processing unit + memory system
- Processing unit = control + datapath
- Control = finite state machine
 - Inputs = machine instruction, datapath conditions
 - Outputs = register transfer control signals, ALU operation codes
 - Instruction interpretation = instruction fetch, decode, execute
- Datapath = functional units + registers
 - Functional units = ALU, multipliers, dividers, etc.
 - Registers = program counter, shifters, storage registers

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Structure of a Computer

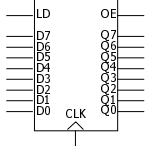
Block diagram view



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Registers

- Selectively loaded - EN or LD input
- Output enable - OE input
- Multiple registers - group 4 or 8 in parallel



OE asserted causes FF state to be connected to output pins; otherwise they are left unconnected (high impedance)

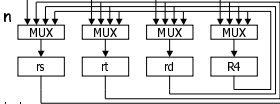
LD asserted during a b-to-hi clock transition loads new data into FFs

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Register Transfer

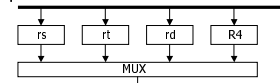
Point-to-point connection

- Dedicated wires
- Muxes on inputs of each register



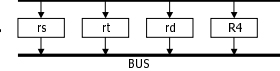
Common input from multiplexer

- Load enables for each register
- Control signals for multiplexer



Common bus with output enables

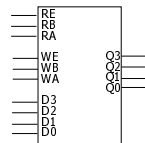
- Output enables and load enables for each register



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Register Files

- Collections of registers in one package
 - Two-dimensional array of FFs
 - Address used as index to a particular word
 - Separate read and write addresses so can do both at same time
- 4 by 4 register file
 - 16 D-FFs
 - Organized as four words of four bits each
 - Write-enable (load)
 - Read-enable (output enable)



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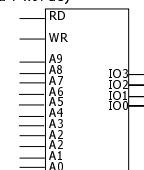
Memories

Larger Collections of Storage Elements

- Implemented not as FFs but as much more efficient latches
- High-density memories use 1-5 switches (transistors) per bit

Static RAM - 1024 words each 4 bits wide

- Once written, memory holds forever (not true for denser dynamic RAM)
- Address lines to select word (10 lines for 1024 words)
- Read enable
 - Same as output enable
 - Often called chip select
 - Permits connection of many chips into larger array
- Write enable (same as load enable)
- Bi-directional data lines
 - output when reading, input when writing



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Instruction Sequencing

- Example - an instruction to add the contents of two registers (Rx and Ry) and place result in a third register (Rz)
 - Step 1: Get the ADD instruction from memory into an instruction register
 - Step 2: Decode instruction
 - Instruction in IR has the code of an ADD instruction
 - Register indices used to generate output enables for registers Rx and Ry
 - Register index used to generate load signal for register Rz
 - Step 3: execute instruction
 - Enable Rx and Ry output and direct to ALU
 - Setup ALU to perform ADD operation
 - Direct result to Rz so that it can be loaded into register

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Instruction Types

- Data Manipulation
 - Add, subtract
 - Increment, decrement
 - Multiply
 - Shift, rotate
 - Immediate operands
- Data Staging
 - Load/store data to/from memory
 - Register-to-register move
- Control
 - Conditional/unconditional branches in program flow
 - Subroutine call and return

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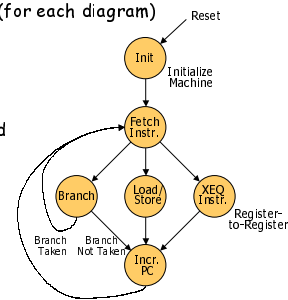
Elements of the Control Unit (aka Instruction Unit)

- Standard FSM Elements
 - State register
 - Next-state logic
 - Output logic (datapath/control signaling)
 - Moore or synchronous Mealy machine to avoid loops unbroken by FF
- Plus Additional "Control" Registers
 - Instruction register (IR)
 - Program counter (PC)
- Inputs/Outputs
 - Outputs control elements of data path
 - Inputs from data path used to alter flow of program (test if zero)

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Instruction Execution

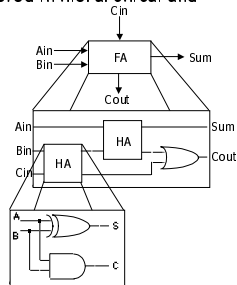
- Control State Diagram (for each diagram)
 - Reset
 - Fetch instruction
 - Decode
 - Execute
- Instructions partitioned into three classes
 - Branch
 - Load/store
 - Register-to-register
- Different sequence through diagram for each instruction type



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Data Path (Hierarchy)

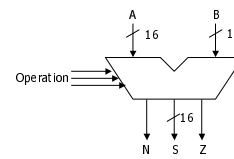
- Arithmetic circuits constructed in hierarchical and iterative fashion
 - each bit in datapath is functionally identical
 - 4-bit, 8-bit, 16-bit, 32-bit datapaths



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Data Path (ALU)

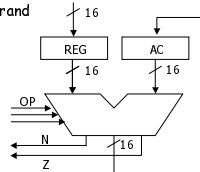
- ALU Block Diagram
 - Input: data and operation to perform
 - Output: result of operation and status information



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Data Path (ALU + Registers)

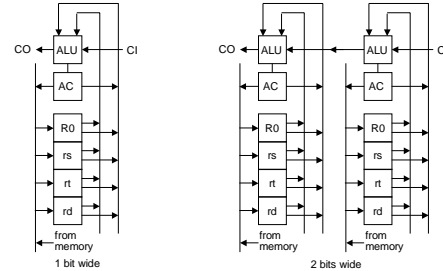
- **Accumulator**
 - Special register
 - One of the inputs to ALU
 - Output of ALU stored back in accumulator
- **One-address instructions**
 - Operation and address of one operand
 - Other operand and destination is accumulator register
 - $AC \leftarrow AC \text{ op Mem}[\text{addr}]$
 - "Single address instructions" (AC implicit operand)
- **Multiple registers**
 - Part of instruction used to choose register operands



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Data Path (Bit-slice)

- **Bit-slice concept: iterate to build n-bit wide datapaths**



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Instruction Path

- **Program Counter**
 - Keeps track of program execution
 - Address of next instruction to read from memory
 - May have auto-increment feature or use ALU
- **Instruction Register**
 - Current instruction
 - Includes ALU operation and address of operand
 - Also holds target of jump instruction
 - Immediate operands
- **Relationship to Data Path**
 - PC may be incremented through ALU
 - Contents of IR may also be required as input to ALU

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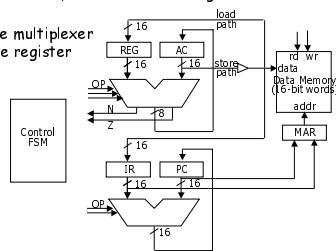
Data Path (Memory Interface)

- **Memory**
 - Separate data and instruction memory (Harvard architecture)
 - Two address buses, two data buses
 - Single combined memory (Princeton architecture)
 - Single address bus, single data bus
- **Separate memory**
 - ALU output goes to data memory input
 - Register input from data memory output
 - Data memory address from instruction register
 - Instruction register from instruction memory output
 - Instruction memory address from program counter
- **Single memory**
 - Address from PC or IR
 - Memory output to instruction and data registers
 - Memory input from ALU output

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Block Diagram of Processor

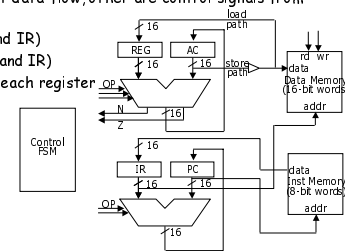
- **Register Transfer View of Princeton Architecture**
 - Which register outputs are connected to which register inputs
 - Arrows represent data-flow, other are control signals from control FSM
 - MAR may be a simple multiplexer rather than separate register
 - MBR is split in two (REG and IR)
 - Load control for each register



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Block Diagram of Processor

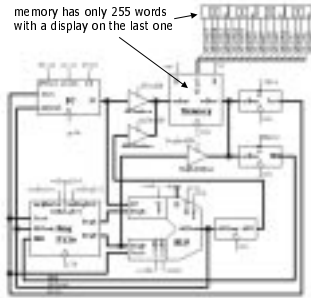
- **Register transfer view of Harvard architecture**
 - Which register outputs are connected to which register inputs
 - Arrows represent data-flow, other are control signals from control FSM
 - Two MARs (PC and IR)
 - Two MBRs (REG and IR)
 - Load control for each register



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A simplified Processor Data-path and Memory

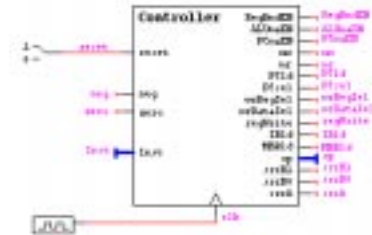
- Princeton architecture
- Register file
- Instruction register
- PC incremented through ALU
- Modeled after MIPS r1000 (used in 61C textbook by Patterson & Hennessy)
 - Really a 32 bit machine
 - We'll do a 16 bit version



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Processor Control

- Synchronous Mealy machine
- Multiple cycles per instruction



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Processor Instructions

- Three principal types (16 bits in each instruction)

type	op	rs	rt	rd	funct
R(egister)	3	3	3	3	4
I(mmediate)	3	3	3	7	
J(ump)	3	13			

- Some of the instructions

	op	rs	rt	rd	offset	funct	description
R	add	0	rs	rt	rd	0	rd = rs + rt
	sub	0	rs	rt	rd	1	rd = rs - rt
	and	0	rs	rt	rd	2	rd = rs & rt
	or	0	rs	rt	rd	3	rd = rs rt
	sll	0	rs	rt	rd	4	rd = (rs < rt)
I	lw	1	rs	rt	offset		rt = mem[rs + offset]
	sw	2	rs	rt	offset		mem[rs + offset] = rt
	beq	3	rs	rt	offset		pc = pc + offset, if (rs == rt)
	addi	4	rs	rt	offset		rt = rs + offset
J	j	5			target address		pc = target address
	halt	7					stop execution until reset

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Tracing an Instruction's Execution

- Instruction: r3 = r1 + r2

R 0 | rs=r1 | rt=r2 | rd=r3 | funct=0

- Instruction fetch
 - Move instruction address from PC to memory address bus
 - Assert memory read
 - Move data from memory data bus into IR
 - Configure ALU to add 1 to PC
 - Configure PC to store new value from ALUout
- Instruction decode
 - Op-code bits of IR are input to control FSM
 - Rest of IR bits encode the operand addresses (rs and rt)
 - These go to register file

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Tracing an Instruction's Execution (cont'd)

- Instruction: r3 = r1 + r2

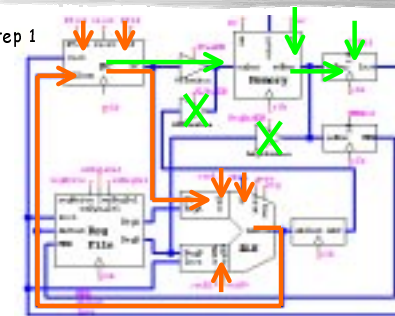
R 0 | rs=r1 | rt=r2 | rd=r3 | funct=0

- Instruction execute
 - Set up ALU inputs
 - Configure ALU to perform ADD operation
 - Configure register file to store ALU result (rd)

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Tracing an Instruction's Execution (cont'd)

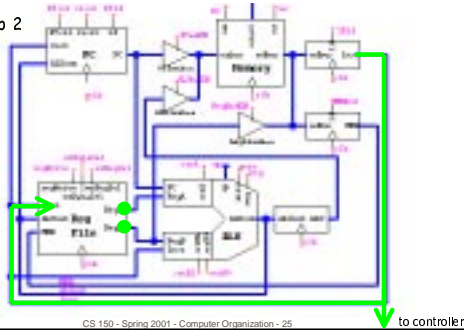
- Step 1



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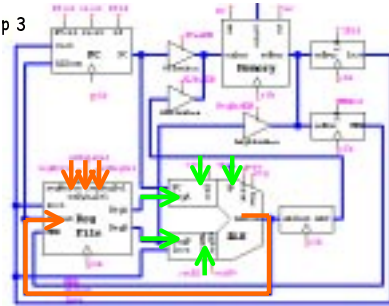
Tracing an Instruction's Execution (cont'd)

Step 2



Tracing an Instruction's Execution (cont'd)

Step 3



Register-Transfer-Level Description

- Control
 - Transfer data btwn registers by asserting appropriate control signals
- Register transfer notation: work from register to register
 - Instruction fetch:
 - mabus PC: - move PC to memory address bus (PCmEN, ALUmEN)
 - memory read: - assert memory read signal (mr, RegBmEN)
 - IR memory: - load IR from memory data bus (IRld)
 - op add: - send PC into A input, 1 into B input, add (srcA, srcB0, scrB1, op)
 - PC ALUOut: - load result of incrementing in ALU into PC (PCld, PCsel)
 - Instruction decode:
 - IR to controller
 - values of A and B read from register file (rs, rt)
 - Instruction execution:
 - op add: - send regA into A input, regB into B input, add (srcA, srcB0, scrB1, op)
 - rd ALUOut: - store result of add into destination register (regWrite, wrDataSel, wrRegSel)

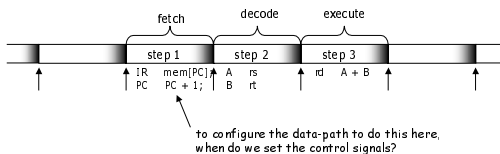
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Register-Transfer-Level Description (cont'd)

- How many states are needed to accomplish these transfers?
 - Data dependencies (where do values that are needed come from?)
 - Resource conflicts (ALU, buses, etc.)
- In our case, it takes three cycles
 - One for each step
 - All operation within a cycle occur between rising edges of the clock
- How do we set all of the control signals to be output by the state machine?
 - Depends on the type of machine (Mealy, Moore, synchronous Mealy)

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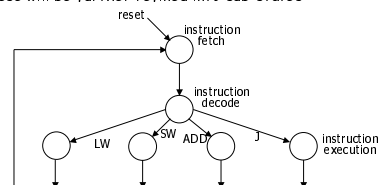
Review of FSM Timing



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FSM Controller for CPU (skeletal Moore FSM)

- First pass at deriving the state diagram (Moore machine)
 - These will be further refined into sub-states

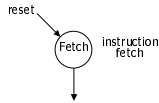


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FSM Controller for CPU (reset and inst. fetch)

- Assume Moore machine
 - Outputs associated with states rather than arcs
- Reset state and instruction fetch sequence
- On reset (go to Fetch state)
 - Start fetching instructions
 - PC will set itself to zero

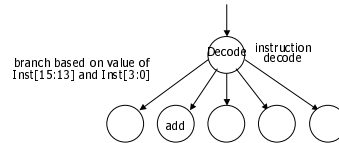
mabus PC;
memory read;
IR memory data bus;
PC PC + 1;



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FSM Controller for CPU (decode)

- Operation Decode State
 - Next state branch based on operation code in instruction
 - Read two operands out of register file
 - What if the instruction doesn't have two operands?

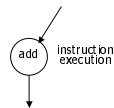


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FSM Controller for CPU (Instruction Execution)

- For add instruction
 - Configure ALU and store result in register
- Other instructions may require multiple cycles

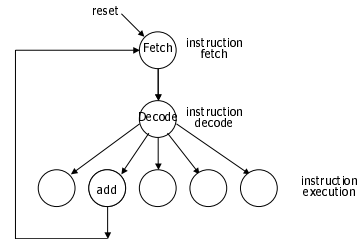
rd A + B



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FSM Controller for CPU (Add Instruction)

- Putting it all together and closing the loop
 - the famous instruction fetch decode execute cycle



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FSM Controller for CPU

- Now we need to repeat this for all the instructions of our processor
 - Fetch and decode states stay the same
 - Different execution states for each instruction
 - Some may require multiple states if available register transfer paths require sequencing of steps

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